



Swansea  
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Machine learning with quantum field theories

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Joint work with Profs. Gert Aarts and Biagio Lucini.

Can we view machine learning as part of  
quantum field theory?

And why?

## Probability distribution

A probability distribution is a product of **strictly positive** and appropriately normalized **factors** (or **potential functions**)  $\psi$ :

$$p(\phi) = \frac{\prod_{c \in C} \psi_c(\phi)}{\int_{\phi} \prod_{c \in C} \psi_c(\phi) d\phi},$$

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1. Factors are the fundamental building blocks of probability distributions.
2. By controlling the factors we are able to control the probability distribution.

## Representation

We require some form of **representation** to construct the probability distribution. We are going to use a finite set  $\Lambda$  that we express as a **graph**  $G(\Lambda, e)$  where  $e$  is the set of edges in  $G$ .

A **clique**  $c$  is a subset of  $\Lambda$  where the points are pairwise connected. A **maximal clique** is a clique where we cannot add another point that is pairwise connected with **all** the points in the subset.

# Representation

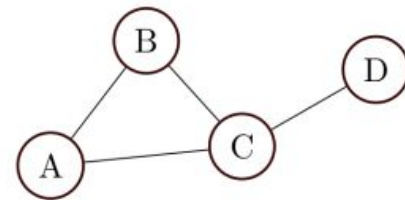
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There are **only two maximal cliques**, the subsets  $\{A, B, C\}$  and  $\{C, D\}$ .

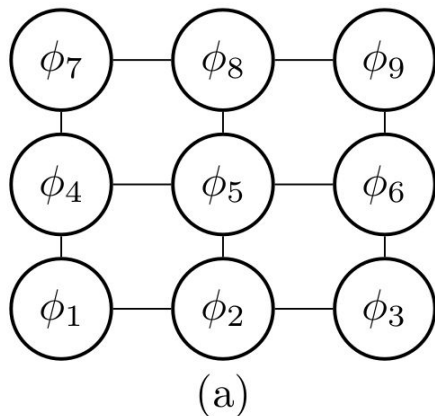
$\{A, B\}$  is a clique but it is **not** maximal because another point (C) can be included that is pairwise connected with both  $\{A, B\}$ .

$\{A, B, C, D\}$  is **not** a clique and **not** maximal because (D) is not pairwise connected with all other points (and vice versa).

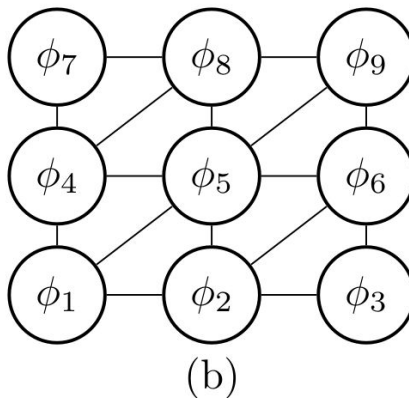


# Representation

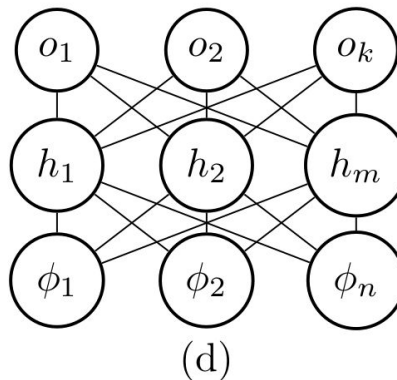
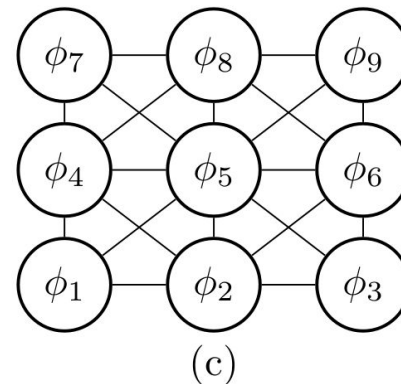
On the **square lattice** a  
**maximal clique** is an **edge**.



On a **triangular lattice** a  
**maximal clique** is a **triangle**.



On the **square lattice with  
both diagonals** a **maximal  
clique** is a **square**.



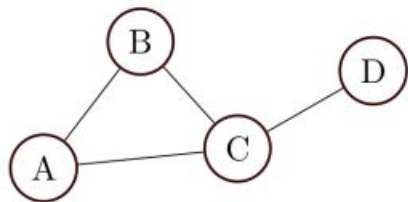
On the **bipartite graph**,  
which represents standard  
neural network  
architectures a **maximal  
clique** is an **edge**.



## Representation

Given a graph  $G(\Lambda, \mathbf{e})$ , the random variables  $\phi_i$  at each point  $i$  define a **Markov random field** if they fulfill the **local Markov property** with respect to  $G$ .

The local Markov property denotes that a random variable  $\phi_i$  depends only on its neighbors and it is conditionally independent of all other random variables in the set:



$$p(\phi_i | (\phi_j)_{j \in \Lambda - \phi_i}) = p(\phi_i | (\phi_j)_{j \in n_i}).$$

## Representation

### Hammersley-Clifford theorem

A strictly positive distribution  $p$  satisfies the local Markov property of an undirected graph  $G$ , if and only if  $p$  can be represented as a product of strictly positive potential functions  $\psi_c$  over  $G$ , one per maximal clique  $c$ , i.e.

$$p(\phi) = \frac{1}{Z} \prod_{c \in C} \psi_c(\phi), \quad Z = \int_{\phi} \prod_{c \in C} \psi_c(\phi) d\phi$$

where  $Z$  is the partition function and  $\phi$  are all possible states of the system.

# Representation

There are two different directions to pursue:

1. We can devise potential functions that satisfy the Hammersley-Clifford theorem to construct a Markov random field.

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1. We can devise potential functions that satisfy the Hammersley-Clifford theorem to construct a Markov random field.
2. We can evaluate if known physical systems can be recast within this mathematical framework by verifying instead if they satisfy the theorem.

**We will pursue the second direction.**

# Representation

## 2d $\phi^4$ theory:

$$\mathcal{L}_E = \frac{\kappa}{2} (\nabla \phi)^2 + \frac{\mu_0^2}{2} \phi^2 + \frac{\lambda}{4} \phi^4,$$

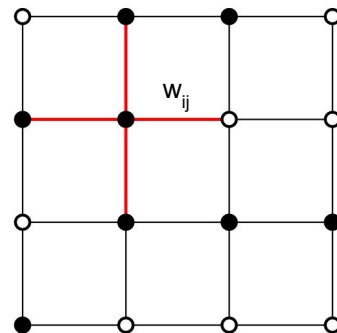
$$S_E = -\kappa_L \sum_{\langle ij \rangle} \phi_i \phi_j + \frac{(\mu_L^2 + 4\kappa_L)}{2} \sum_i \phi_i^2 + \frac{\lambda_L}{4} \sum_i \phi_i^4.$$

$\kappa_L, \mu_L, \lambda_L$  dimensionless parameters

$$w = \kappa_L, \quad a = (\mu_L^2 + 4\kappa_L)/2, \quad b = \lambda_L/4$$

## Inhomogeneous $\phi^4$ theory:

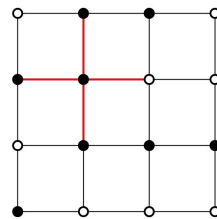
$$S(\phi; \theta) = - \sum_{\langle ij \rangle} w_{ij} \phi_i \phi_j + \sum_i a_i \phi_i^2 + \sum_i b_i \phi_i^4,$$



## Representation

The  $\phi^4$  lattice field theory is, by definition, formulated on a square lattice which is equivalent to a graph  $G(\Lambda, e)$ . A non-unique choice of potential function per each maximal clique is:

$$\psi_c = \exp \left[ -w_{ij} \phi_i \phi_j + \frac{1}{4} (a_i \phi_i^2 + a_j \phi_j^2 + b_i \phi_i^4 + b_j \phi_j^4) \right],$$



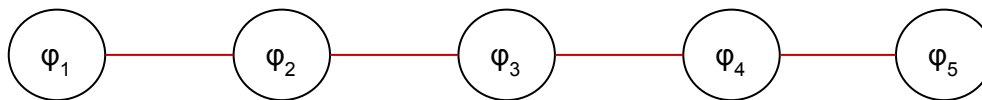
The probability distribution is expressed as a product of strictly positive potential functions  $\psi$ , over each maximal clique:

$$p(\phi; \theta) = \frac{\exp \left[ \sum_{c \in C} \ln \psi_c(\phi) \right]}{\int_{\phi} \exp \left[ \sum_{c \in C} \ln \psi_c(\phi) \right] d\phi} = \frac{1}{Z} \prod_{c \in C} \psi_c(\phi).$$

The  $\phi^4$  theory satisfies Markov properties and it is therefore a Markov random field.

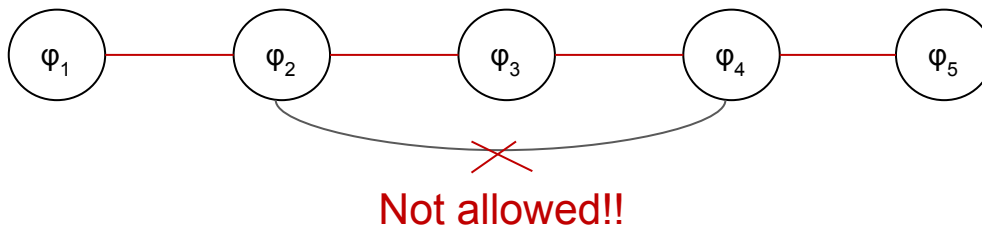
# Representation

The Markov property in a Markov chain



# Representation

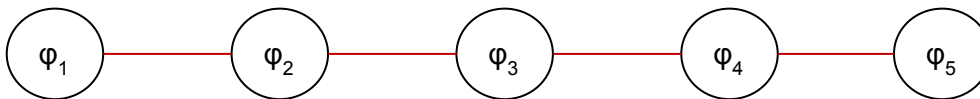
The Markov property in a Markov chain



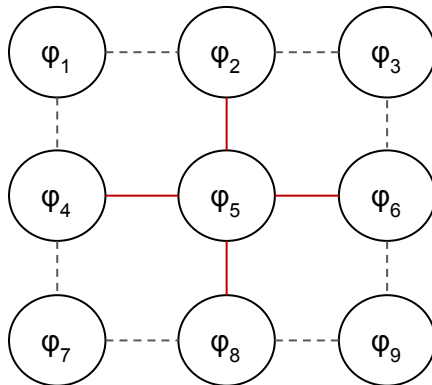


# Representation

The Markov property in a Markov chain



A Markov random field satisfies the Markov property in high-dimensions



# Learning

Having established that certain physical systems are Markov random fields, how do we use them for machine learning?

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Exactly in the same way as any other machine learning algorithm...

# Learning

The  $\phi^4$  theory has a **probability distribution**  $p(\phi;\theta)$  with action  $S(\phi;\theta)$ :

$$p(\phi; \theta) = \frac{\exp[-S(\phi; \theta)]}{\int_{\phi} \exp[-S(\phi, \theta)] d\phi}.$$

We now consider a quantum field theory with action  $\mathcal{A}$  and a **target probability distribution**  $q(\phi)$ :

$$q(\phi) = \exp[-\mathcal{A}]/Z_{\mathcal{A}}$$

## Learning

We can then define an asymmetric distance between the probability distributions  $p(\phi; \theta)$  and  $q(\phi)$ , which is called the **Kullback-Leibler divergence**:

$$KL(p||q) = \int_{-\infty}^{\infty} p(\phi; \theta) \ln \frac{p(\phi; \theta)}{q(\phi)} d\phi \geq 0.$$

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**We want to minimize the Kullback-Leibler divergence.**

By minimizing it we would make the two probability distributions equal. **We can then use the probability distribution  $p(\phi; \theta)$  of the  $\phi^4$  theory to draw samples from the target distribution  $q(\phi)$  of action A.**

# Learning

We substitute the two probability distributions in the Kullback-Leibler divergence to obtain:

$$F_{\mathcal{A}} \leq \langle \mathcal{A} - S \rangle_{p(\phi; \theta)} + F \equiv \mathcal{F},$$

Bogoliubov Inequality

There are two important observations on the above equation:

1. It sets a rigorous upper bound to the calculation of the free energy of the system with action  $\mathcal{A}$ .
2. The bound is dependent entirely on samples drawn from the distribution  $p(\phi; \theta)$  of the  $\phi^4$  theory.

## Learning

To minimize the variational free energy we implement a gradient-based approach:

$$\frac{\partial \mathcal{F}}{\partial \theta_i} = \langle \mathcal{A} \rangle \left\langle \frac{\partial S}{\partial \theta_i} \right\rangle - \left\langle \mathcal{A} \frac{\partial S}{\partial \theta_i} \right\rangle + \left\langle S \frac{\partial S}{\partial \theta_i} \right\rangle - \langle S \rangle \left\langle \frac{\partial S}{\partial \theta_i} \right\rangle,$$

We then update the coupling constants  $\theta$  at each step  $t$  until convergence.

$$\theta^{(t+1)} = \theta^{(t)} - \eta * \mathcal{L}, \quad \mathcal{L} = \partial \mathcal{F} / \partial \theta^{(t)}$$

After training we expect that, practically:

$$\mathcal{F} \approx F_A \quad p(\phi; \theta) \approx q(\phi).$$



# Learning

A first proof-of-principle demonstration is to use the inhomogeneous action S:

$$S(\phi; \theta) = - \sum_{\langle ij \rangle} w_{ij} \phi_i \phi_j + \sum_i a_i \phi_i^2 + \sum_i b_i \phi_i^4,$$

to learn a homogeneous action A:

$$\mathcal{A}(\phi) = - \sum_{\langle ij \rangle} \phi_i \phi_j + 1.52425 \sum_i \phi_i^2 + 0.175 \sum_i \phi_i^4$$

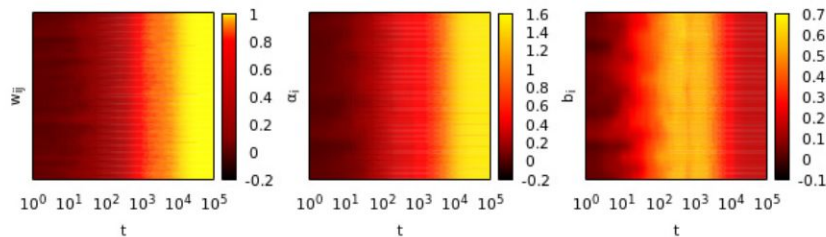


FIG. 2. Variational parameters  $\theta = \{w_{ij}, a_i, b_i\}$  versus epochs  $t$  on logarithmic scale. The figures depict the evolution of the parameters  $\theta$  towards the expected values of the coupling constants in the target homogeneous action.

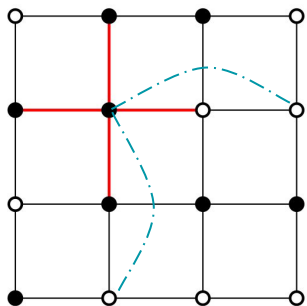
# Learning

Another proof-of-principle demonstration is to use the inhomogeneous action S:

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to learn an action that includes **longer-range interactions**:

$$\mathcal{A}_{\{4\}}(\phi) = - \sum_{\langle ij \rangle} \phi_i \phi_j + 1.52425 \sum_i \phi_i^2 + 0.175 \sum_i \phi_i^4 - \sum_{\langle ij \rangle_{nnn}} \phi_i \phi_j$$



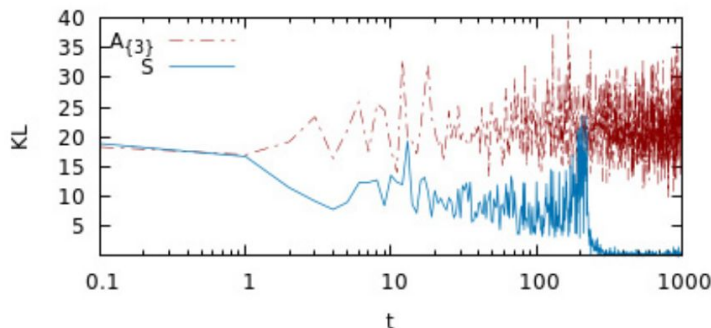
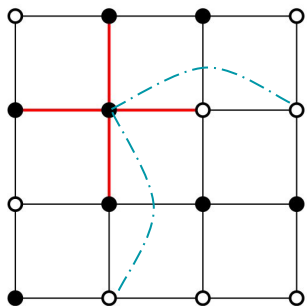
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# Learning

Three reweighting (simultaneous) steps: Make the (already trained) inhomogeneous action S:

$$S(\phi; \theta) = - \sum_{\langle ij \rangle} w_{ij} \phi_i \phi_j + \sum_i a_i \phi_i^2 + \sum_i b_i \phi_i^4,$$

Equal to the target action A (acts as a **correction** step):

$$\mathcal{A}_{\{4\}}(\phi) = - \sum_{\langle ij \rangle} \phi_i \phi_j + 1.52425 \sum_i \phi_i^2 + 0.175 \sum_i \phi_i^4 - \sum_{\langle ij \rangle_{nnn}} \phi_i \phi_j$$

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Equal to the target action  $A$  (acts as a **correction** step):

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Extrapolate in the parameter space along the **trajectory of a coupling constant  $g'$**  of  $A$

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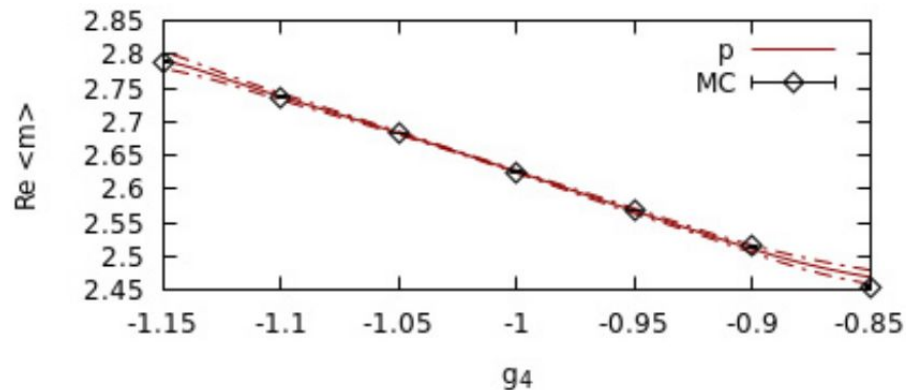
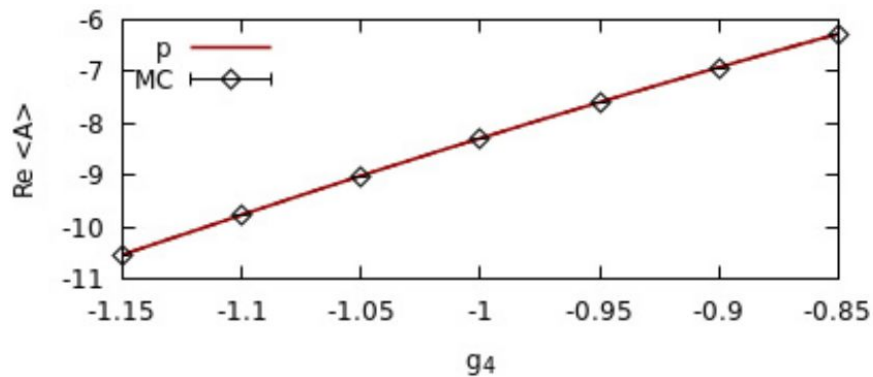
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Extrapolate to an **imaginary** term

$$\mathcal{A}_{\{5\}}(\phi) = - \sum_{\langle ij \rangle} \phi_i \phi_j + 1.52425 \sum_i \phi_i^2 + 0.175 \sum_i \phi_i^4 - \sum_{\langle ij \rangle_{nnn}} g' \phi_i \phi_j + i0.15 \sum_i \phi_i^2$$

# Learning



The results include reweighting to a complex-valued coupling constant on the mass term and extrapolations in parameter space along the trajectory of the coupling constant  $g_4$  in the longer-range interaction.

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# Learning

The previous results considered cases where data were not available but the form of the probability distribution  $q(\phi)$ , which was considered Boltzmann with action  $A$ , was known.



What if the target probability distribution  $q(\phi)$  is unknown?

Earlier we defined the Kullback-Leibler divergence as:

$$KL(p||q) = \int_{-\infty}^{\infty} p(\phi; \theta) \ln \frac{p(\phi; \theta)}{q(\phi)} d\phi \geq 0.$$

We will now consider the **opposite divergence**:

$$KL(q||p) = \int_{-\infty}^{\infty} q(\phi) \ln \frac{q(\phi)}{p(\phi; \theta)} d\phi.$$

## Learning

We can expand the Kullback-Leibler divergence and obtain:

$$KL(q||p) = \langle \ln q(\phi) \rangle_{q(\phi)} - \langle \ln p(\phi; \theta) \rangle_{q(\phi)}.$$

The first right-hand term is constant. **Minimizing the Kullback Leibler divergence is equivalent to maximizing the second right-hand term.**

We can do this by relying again on a gradient-based approach.

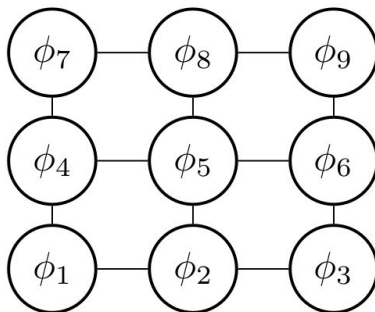
# Learning

The derivative of the log-likelihood is:

$$\frac{\partial \ln p(\phi; \theta)}{\partial \theta} = \frac{\partial}{\partial \theta} (-S(\phi; \theta)) - \left\langle \frac{\partial}{\partial \theta} (-S(\phi; \theta)) \right\rangle_{p(\phi; \theta)}$$

Calculated on the data

Calculated on samples  
from the equilibrium  
distribution



# Learning

We are searching for the optimal values of the coupling constants in the  $\phi^4$  action that are able to reproduce the data as configurations in the equilibrium distribution.

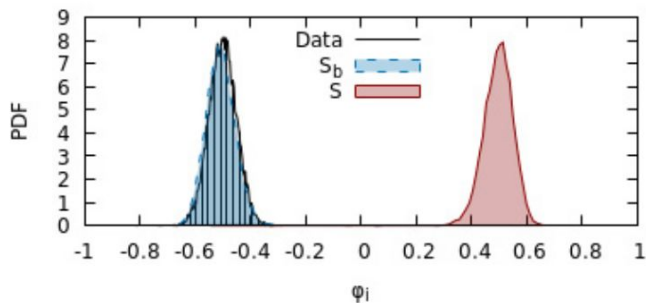
$$S(\phi; \theta) = - \sum_{\langle ij \rangle} w_{ij} \phi_i \phi_j + \sum_i a_i \phi_i^2 + \sum_i b_i \phi_i^4,$$

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Case of a Gaussian distribution:

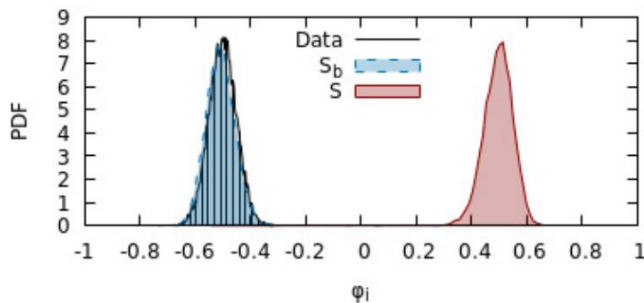


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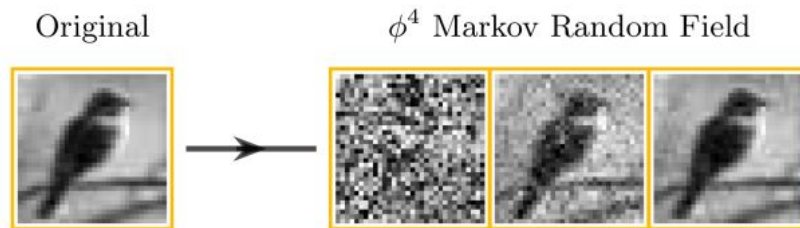


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Case of an image:





# Neural Networks

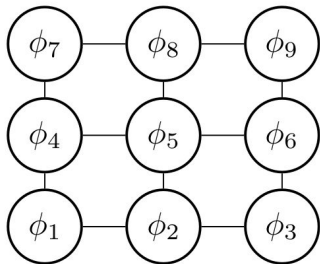
To increase the expressivity of the machine learning algorithm, we need to include a set of **latent/hidden variables** that extract dependencies on the training data used as input.

This can be achieved with neural networks.

We will derive neural networks from the  $\phi^4$  theory.

# Neural Networks

## $\phi^4$ Markov random field

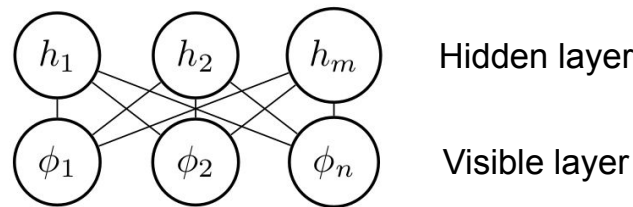


$$S(\phi; \theta) = - \sum_{\langle ij \rangle} w_{ij} \phi_i \phi_j + \sum_i a_i \phi_i^2 + \sum_i b_i \phi_i^4,$$

$$\theta = \{w_{ij}, a_i, b_i\}$$

$$p(\phi; \theta) = \frac{\exp[-S(\phi; \theta)]}{\int_{\phi} \exp[-S(\phi, \theta)] d\phi}.$$

## $\phi^4$ neural network



$$S(\phi, h; \theta) = - \sum_{i,j} w_{ij} \phi_i h_j + \sum_i r_i \phi_i + \sum_i a_i \phi_i^2$$

$$+ \sum_i b_i \phi_i^4 + \sum_j s_j h_j + \sum_j m_j h_j^2 + \sum_j n_j h_j^4,$$

$$\theta = \{w_{ij}, r_i, a_i, b_i, s_j, m_j, n_j\}.$$

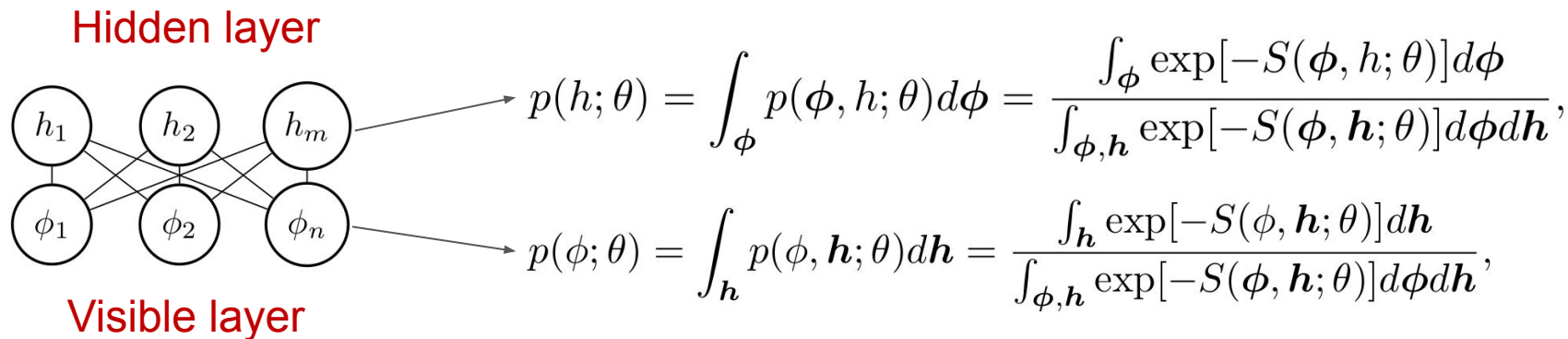
$$p(\phi, h; \theta) = \frac{\exp[-S(\phi, h; \theta)]}{\int_{\phi, \mathbf{h}} \exp[-S(\phi, \mathbf{h}; \theta)] d\phi d\mathbf{h}}.$$

# Neural Networks

From the **joint probability distribution** of the  $\phi^4$  neural network

$$p(\phi, h; \theta) = \frac{\exp[-S(\phi, h; \theta)]}{\int_{\phi, h} \exp[-S(\phi, h; \theta)] d\phi d\mathbf{h}}.$$

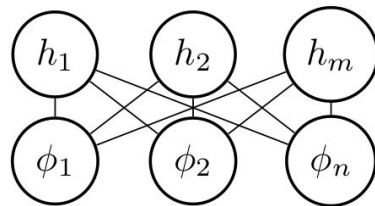
We are able to marginalize out variables and derive **marginal probability distributions**  $p(\phi; \theta)$  and  $p(h; \theta)$ :



# Neural Networks

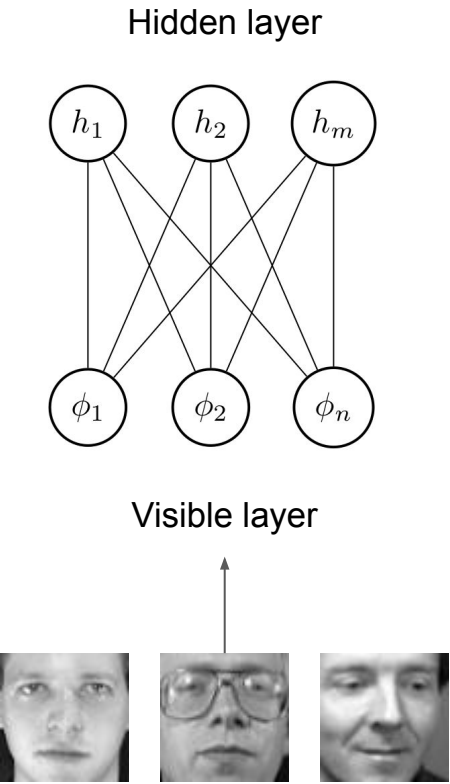
We now want to minimize the asymmetric distance between the **empirical probability distribution  $q(\phi)$**  and the **marginal probability distribution  $p(\phi; \theta)$** :

$$KL(q||p) = \int_{-\infty}^{\infty} q(\phi) \ln \frac{q(\phi)}{p(\phi; \theta)} d\phi.$$

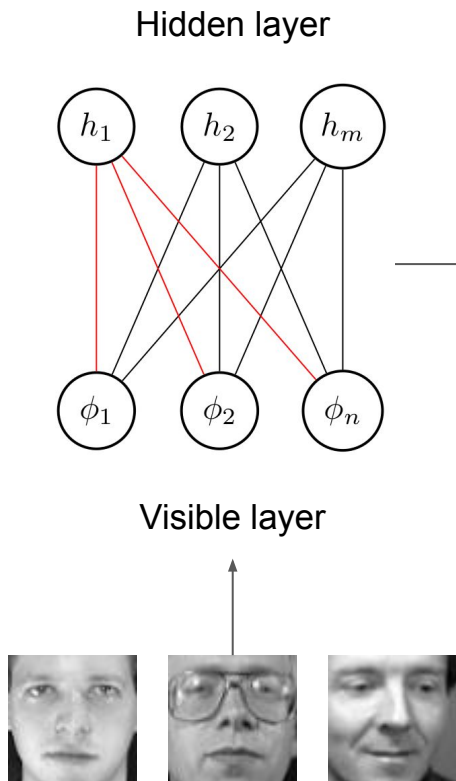


In other words, we want to reproduce the dataset in the visible layer. The hidden layer will then uncover dependencies on the data.

# Neural Networks



# Neural Networks



Examples of the **coupling constants**  $w_{ij}$  with  $j$  fixed

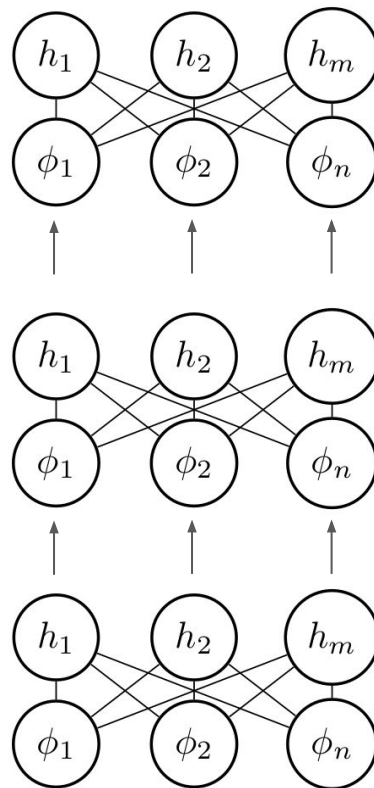


$$S(\phi, h; \theta) = - \sum_{i,j} w_{ij} \phi_i h_j + \sum_i r_i \phi_i + \sum_i a_i \phi_i^2 \\ + \sum_i b_i \phi_i^4 + \sum_j s_j h_j + \sum_j m_j h_j^2 + \sum_j n_j h_j^4,$$

# Neural Networks

The hidden layer can serve as input to a new stacked  $\phi^4$  neural network to progressively extract features of increased abstraction

Eventually we obtain an architecture that is **a universal approximator of a probability distribution.**



# Neural Networks

The  $\phi^4$  neural network:

$$S(\phi, h; \theta) = - \sum_{i,j} w_{ij} \phi_i h_j + \sum_i r_i \phi_i + \sum_i a_i \phi_i^2 \\ + \sum_i b_i \phi_i^4 + \sum_j s_j h_j + \sum_j m_j h_j^2 + \sum_j n_j h_j^4,$$

is a generalization of other neural network architectures:

**Gaussian-Gaussian**  
restricted Boltzmann  
machine:

$$b_i = n_j = 0$$

**Gaussian-Bernoulli**  
restricted Boltzmann  
machine:

$$b_i = n_j = m_j = 0 \\ h_j \text{ binary}$$

**Bernoulli-Bernoulli**  
restricted Boltzmann  
machine:

$$b_i = n_j = m_j = a_i = 0 \\ \phi_i, h_j \text{ binary}$$

**$\phi^4$ -Bernoulli** restricted  
Boltzmann machine:

$$m_j = n_j = 0 \\ h_j \text{ binary}$$

$\phi^4$  equivalence with the Ising model (under an appropriate limit)



## Conclusions

Are there any unique applications?

# Inverse Renormalization Group

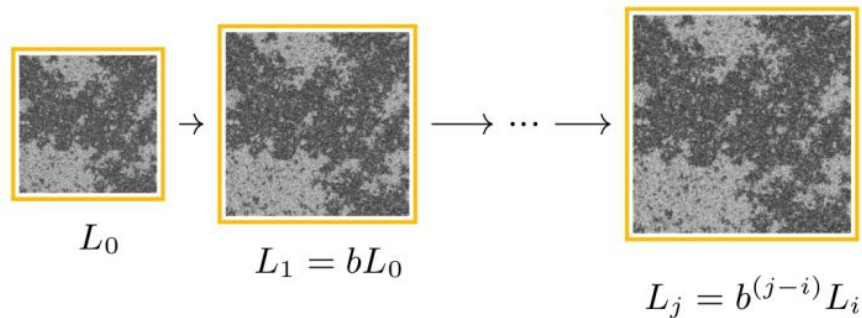


FIG. 1. Illustration of the inverse renormalization group. Inverse transformations are applied to iteratively increase the size  $L$  in each dimension by a factor of  $b$ , therefore evading the critical slowing down effect.

Inverse renormalization group in quantum field theory, D. Bachtis, G. Aarts, F. Di Renzo, and B. Lucini, (arXiv:2107.00466).

# Conclusions

1. What one needs to do machine learning is simply a probability distribution. Lattice field theories therefore emerge as natural machine learning algorithms. We can investigate machine learning as a physical concept within quantum field theory: e.g. what are the phase transitions of quantum field-theoretic machine learning algorithms? How do they behave when they interact with external fields?

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