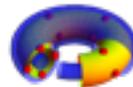




# Information Theory, Machine Learning and the Real-Space Renormalization Group

Maciej Koch-Janusz





**Zohar Ringel**

“Mutual Information, Neural Networks and the Renormalization Group”  
MKJ and Zohar Ringel, *Nature Physics* **14**, 578-582 (2018)



**Sebastian D. Huber**



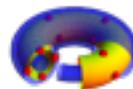
**Patrick Lenggenhager**



**Doruk Efe Gokmen**

“Optimal Renormalization Group Transformation from Information Theory”  
P. Lenngenhager, Z. Ringel, S.D. Huber and MKJ, *arXiv:1809.09632*

# Outline



# Outline

- Machine learning in condensed matter
- Information-theoretic approach to real-space RG:
  - The Real Space Mutual Information algorithm
  - Optimality of the RSMI algorithm
  - Disordered systems
- Conclusions and Outlook



# Why machine learning?

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- Machine learning has a lot of practical applications already

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- Machine learning has a lot of practical applications already



- Can science benefit in a more fundamental fashion?



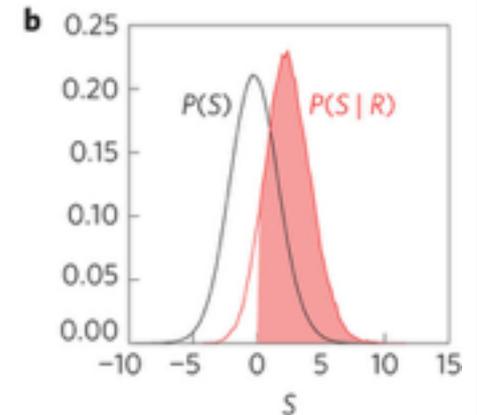
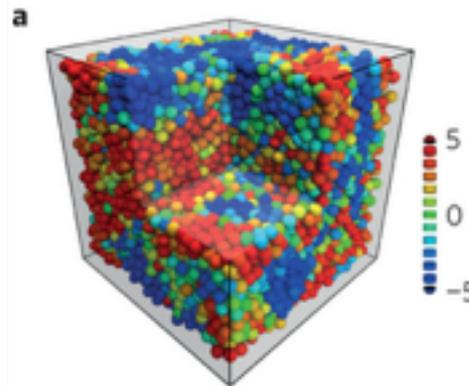
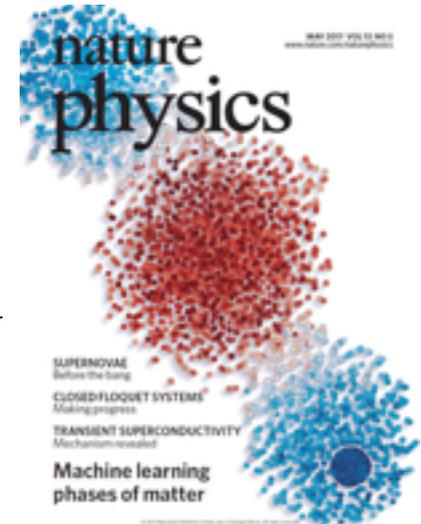
# Phase transitions and classification

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Lei Wang,  
*Phys. Rev. B* **94**, 195105 (2016)

J. Carrasquilla and R. Melko  
*Nature Physics* **13**, 431–434 (2017)

E.P. van Nieuwenburg, Y. Liu, S. Huber  
*Nature Physics* **13**, 435–439 (2017)



Schoenholz et al., *Nature* **12**, 469–471 (2016)

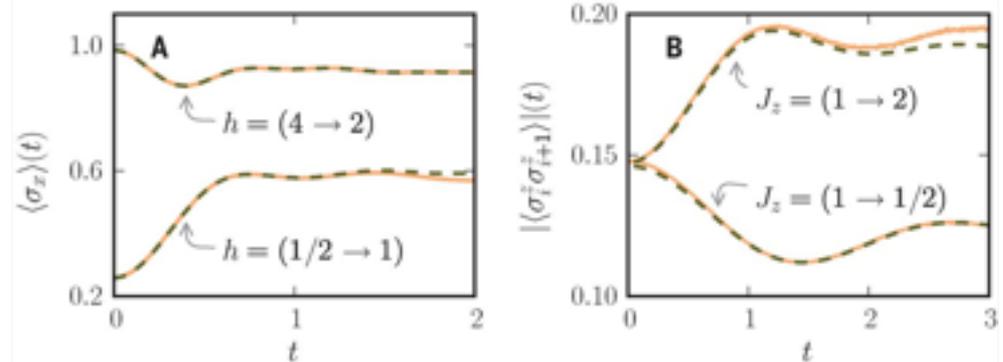
# Phase transitions and classification

**Phase transitions  
and classification**

**State compression  
and representation**

## Phase transitions and classification

## State compression and representation



G. Carleo, M. Troyer, *Science* **355**, 602–606 (2017)

G. Torlai et al., *Nature Physics* **314**, 447–450 (2018)

J. Carrasquilla et al., *arXiv:1810.10584*, (2018)

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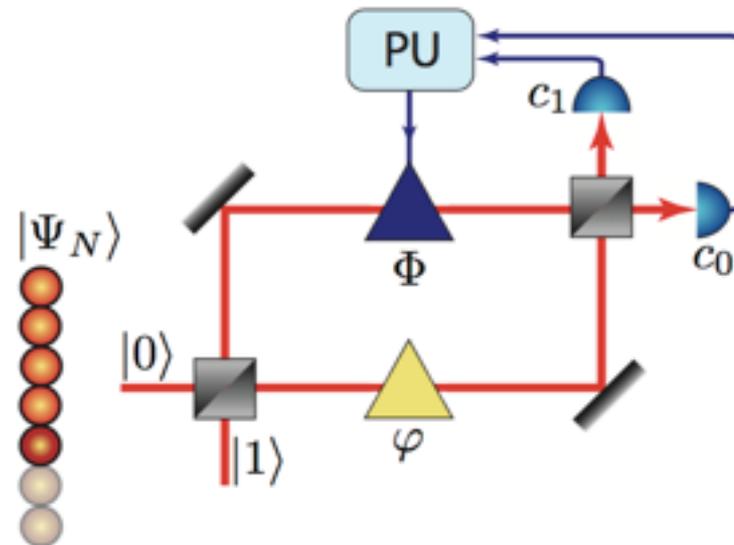
**State compression  
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**Experimental /  
numerical protocols /  
error correction**

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## Experimental / numerical protocols / error correction



A. Hentschel, B.Sanders, *PRL* **104**, 063603 (2010)

J. Wang et al., *Nature Physics* **13**, 551–555 (2017)

T. Foesel et al., *Phys. Rev. X* **8**, 031084 (2018)

R. Sweke et al., *arXiv*: 1810.07207 (2018)

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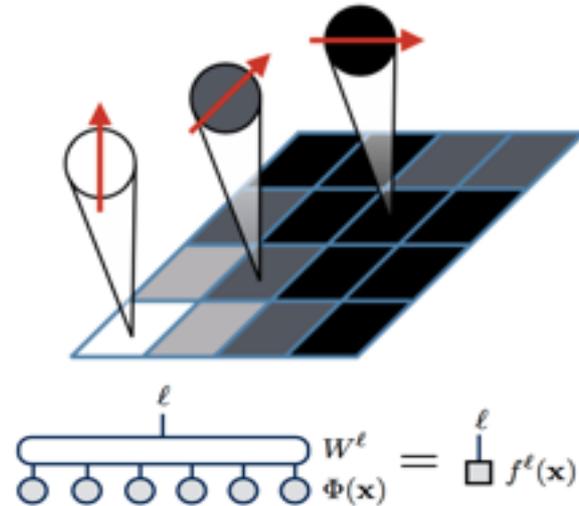
**physics -> ML**

Phase transitions  
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State compression  
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Experimental /  
numerical protocols /  
error correction

physics -> ML



M. Stoudenmire, D. Schwab,  
*Advances in Neural Information Processing Systems 29*, 4799 (2016)

T. Chao, P. Mazaheri, B. Sun, N. Weingartner, Z. Nussinov,  
*arXiv: 1708.05715* (2017)

Works of M. Mezard, G. Biroli, L. Zdeborova, ...



# Machine Learning

**Machine Learning**

**Condensed Matter**

**Machine Learning**

**Condensed Matter**



Computational power,  
data-driven

Formalism,  
toy models,  
tools



**Machine Learning**

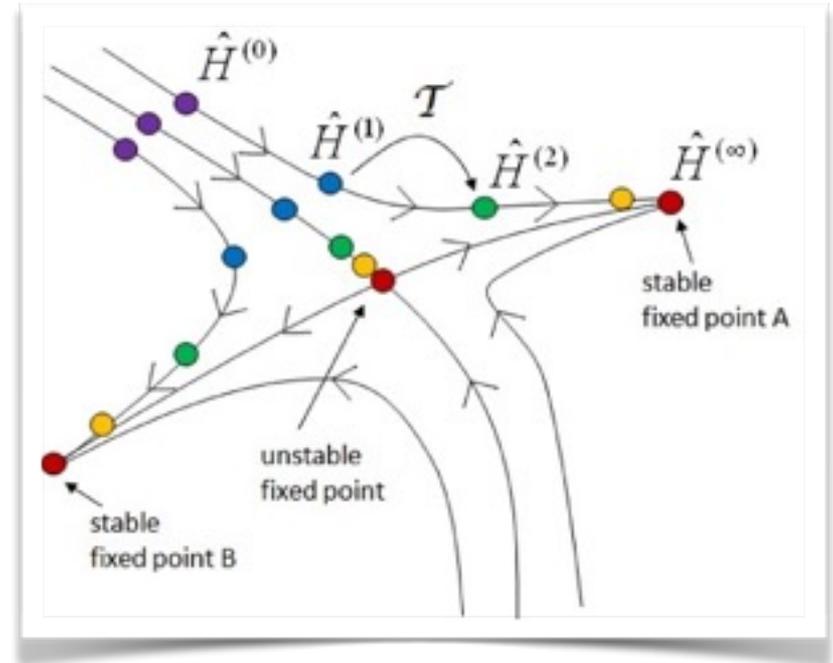
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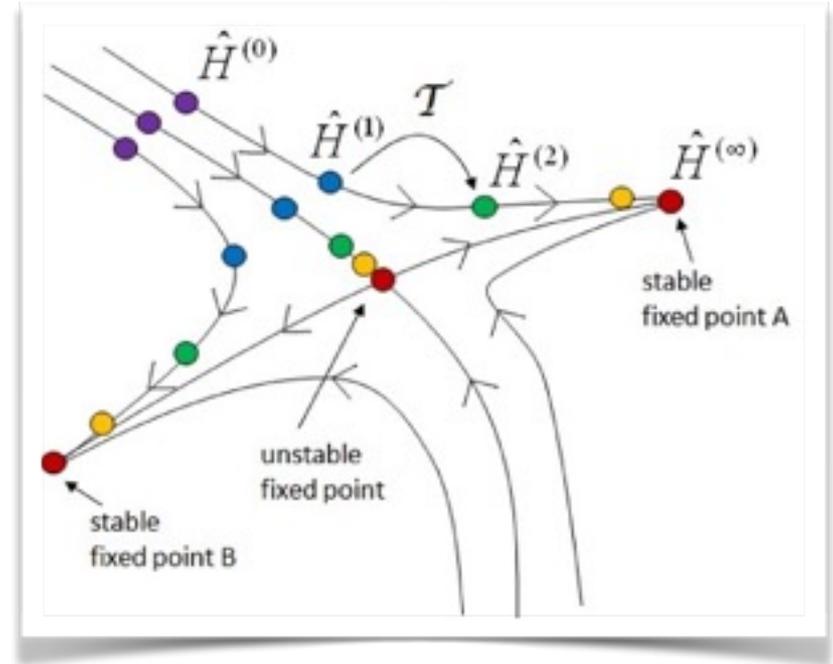
# Renormalization Group

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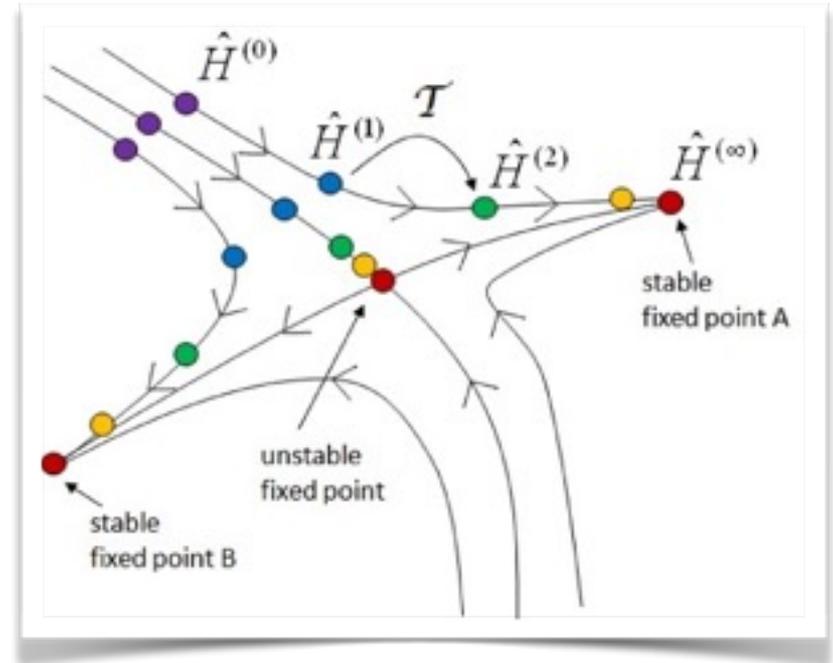
# Renormalization Group

- Conceptually important: formalizes the notion of universality



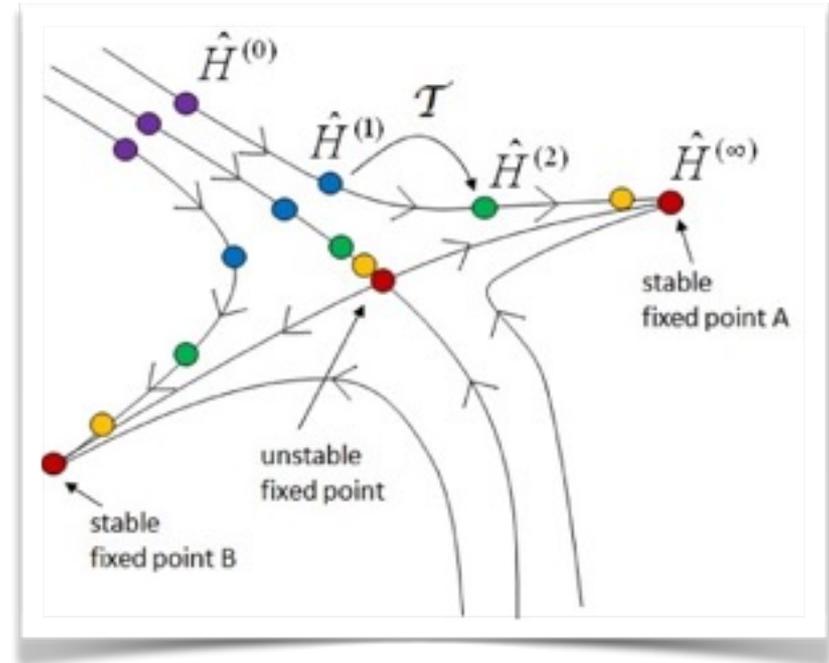
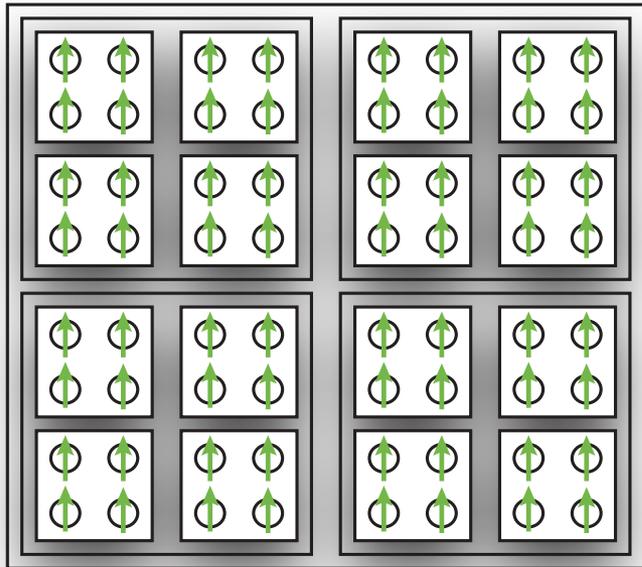
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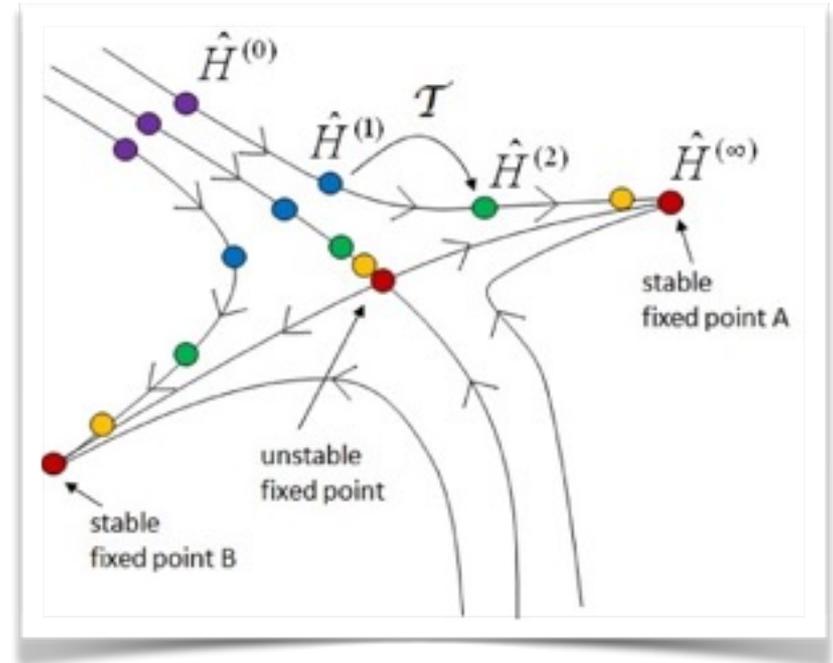
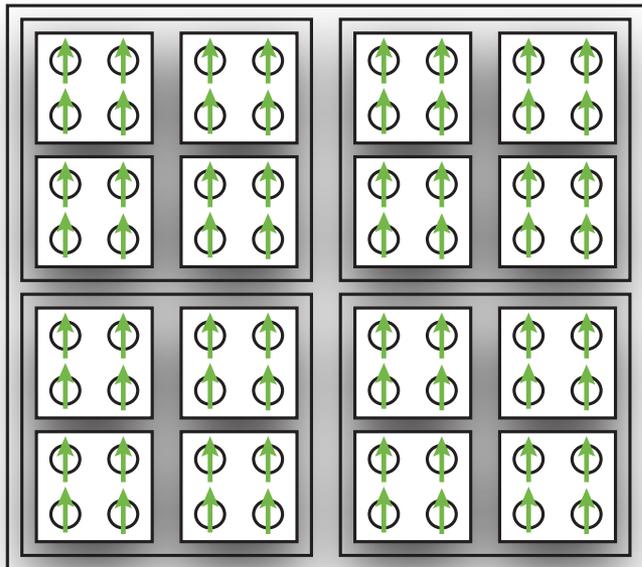
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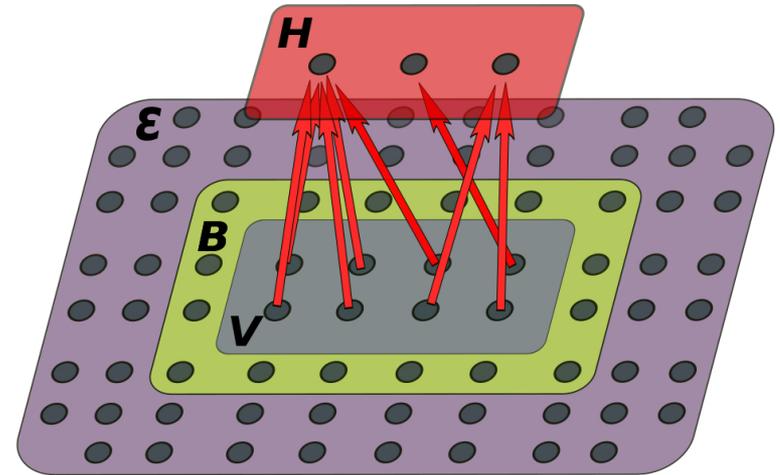
Leitmotiv: integrate out some 'fast' degrees of freedom to obtain effective theory of the 'slow' ones

In a sense the relation of RG to information theory is obvious as  
averaging loses information

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- Can it be formalized?
- Is it useful in practice?

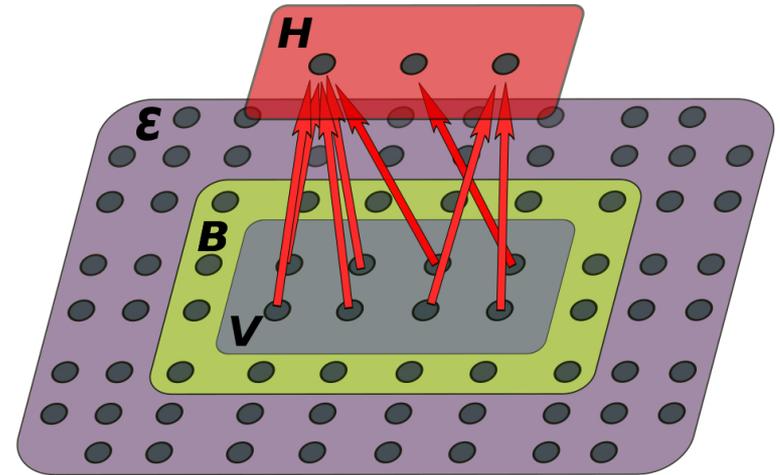
# Real-space RG from Information Theory perspective



$$P(\mathcal{X}) = \frac{1}{Z} e^{\kappa(\mathcal{X})}$$

# Real-space RG from Information Theory perspective

$$e^{\kappa'(\mathcal{X}')} = \sum_{\mathcal{X}} e^{\kappa(\mathcal{X})} P_{\Lambda}(\mathcal{X}'|\mathcal{X})$$

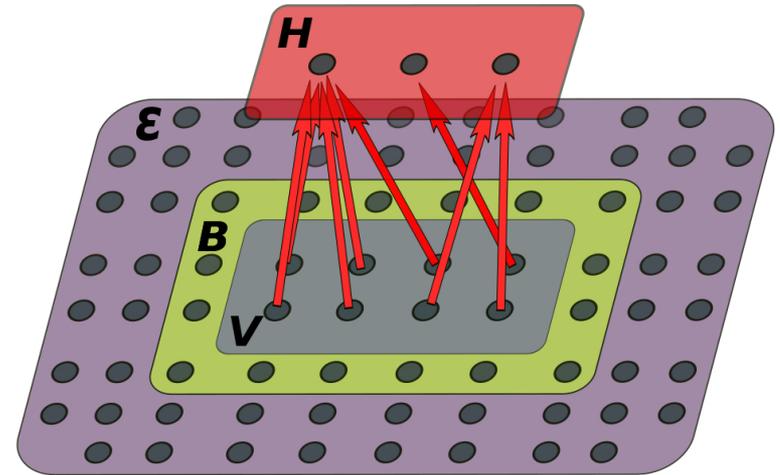


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**Task:** Learn  $P_{\Lambda}(\mathcal{H}|\mathcal{V})$   
 such that  $\mathcal{H}$  tracks the  
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 within region  $\mathcal{V}$



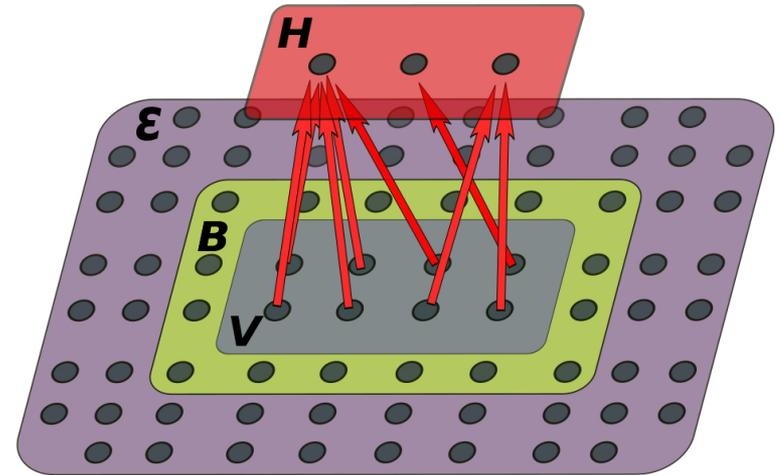
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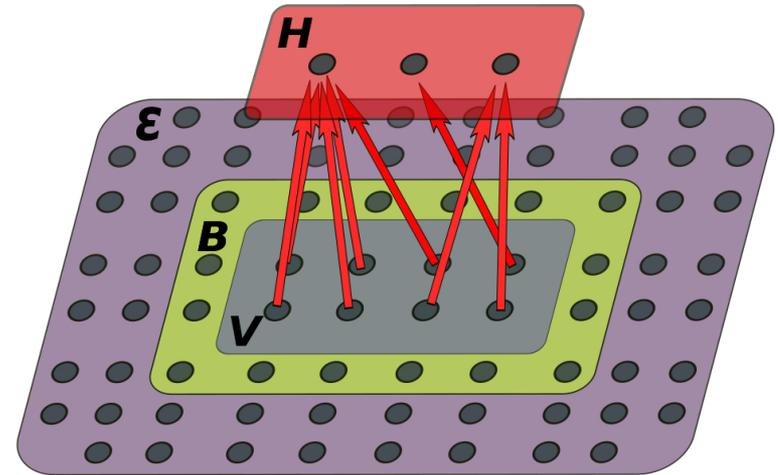
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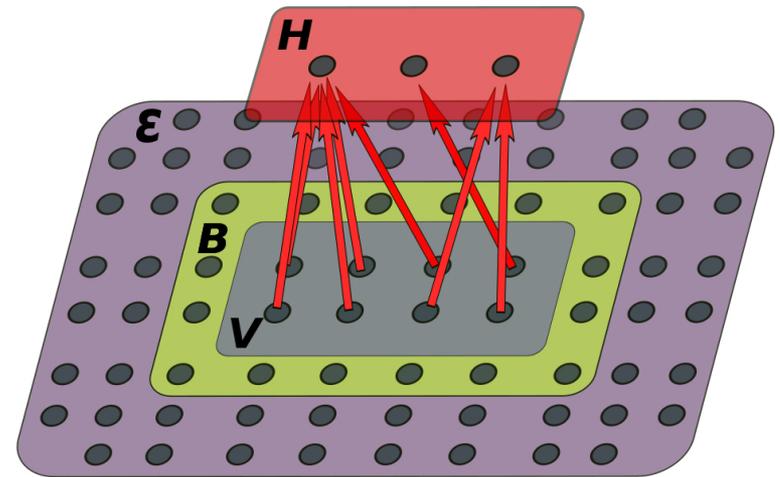
**Method:** Require that *slow degrees of freedom* maximize spatial mutual information

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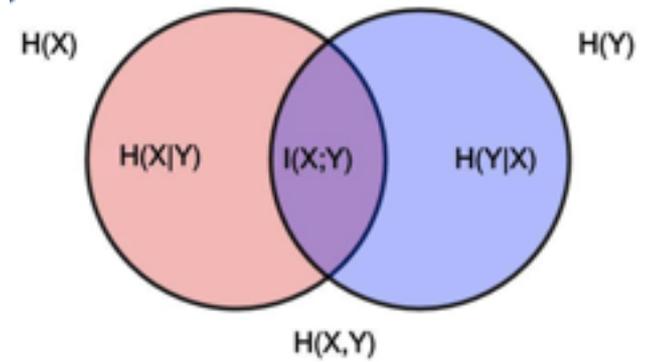


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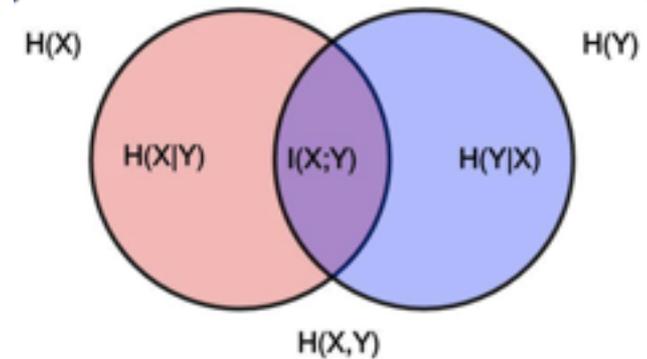
**Method:** Require that *slow degrees of freedom* maximize spatial mutual information

**Formally:** find  $\max[I_{\Lambda}(\mathcal{H}:\mathcal{E})]$  over parameters  $\Lambda$

# Mutual Information



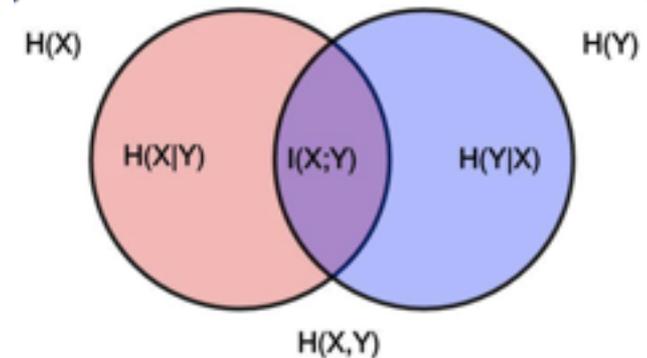
# Mutual Information



- Vanishes for independent variables
- Bounded from above by information entropy
- More general than correlation functions

# Mutual Information

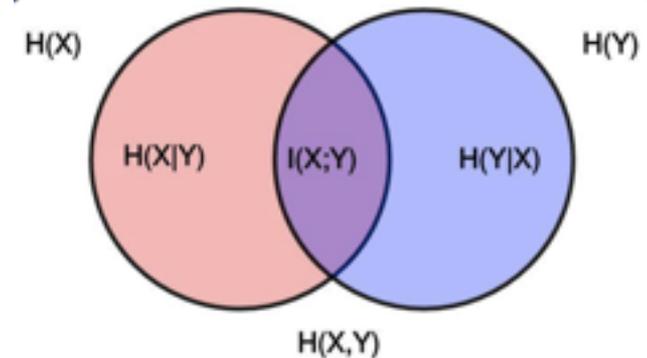
$$I_{\Lambda}(\mathcal{H} : \mathcal{E}) = \sum_{\mathcal{H}, \mathcal{E}} P_{\Lambda}(\mathcal{E}, \mathcal{H}) \log \left( \frac{P_{\Lambda}(\mathcal{E}, \mathcal{H})}{P_{\Lambda}(\mathcal{H})P(\mathcal{E})} \right)$$



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# Mutual Information

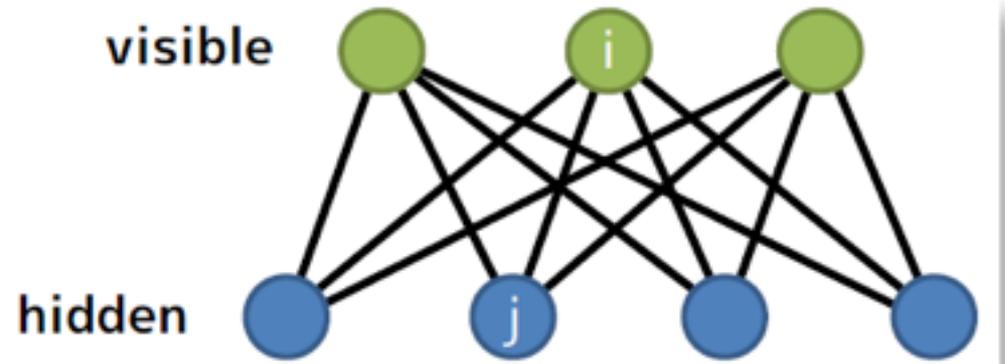
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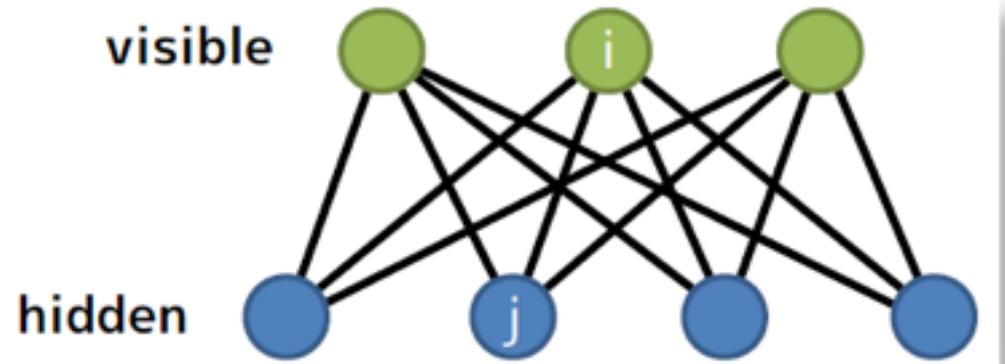
$$I_{\Lambda}(\mathcal{H} : \mathcal{E}) = H(\mathcal{H}) - H(\mathcal{H}|\mathcal{E})$$

# (Restricted) Boltzmann Machines



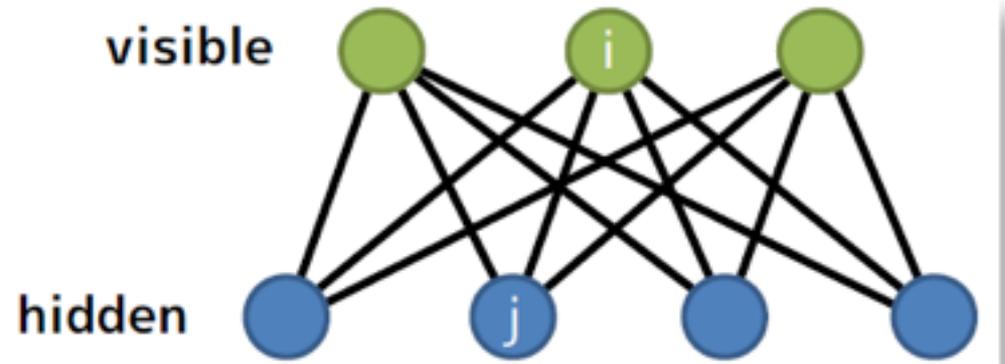
# (Restricted) Boltzmann Machines

- Stochastic networks



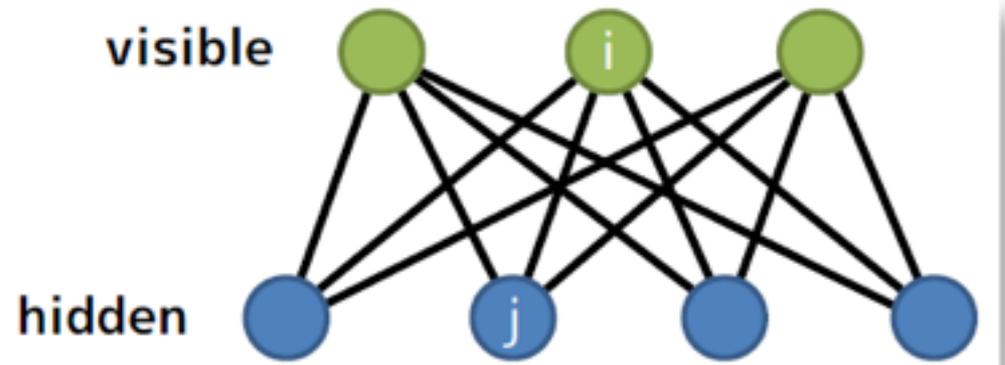
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# (Restricted) Boltzmann Machines

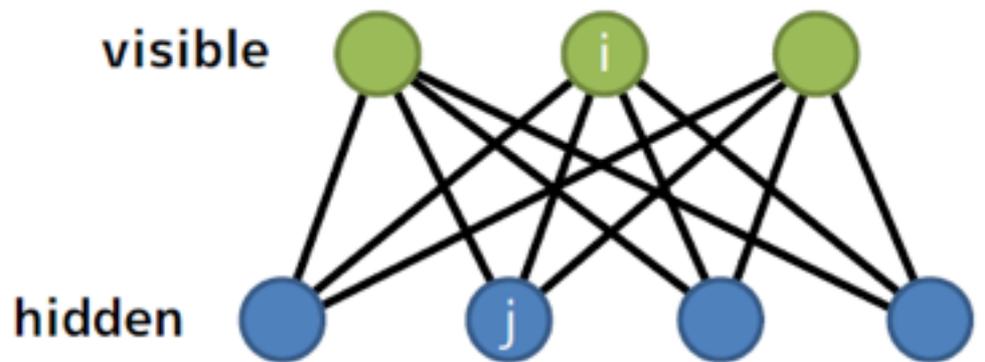
- Stochastic networks
- Model probability distributions



$$E_{\Theta} \equiv E_{a,b,\theta}(\mathcal{V}, \mathcal{H}) = -\sum_i a_i v_i - \sum_j b_j h_j - \sum_{ij} v_i \theta_{ij} h_j$$

# (Restricted) Boltzmann Machines

- Stochastic networks
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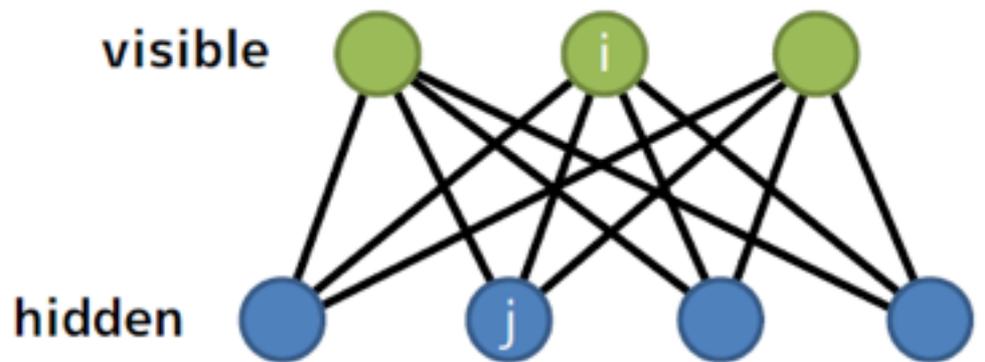


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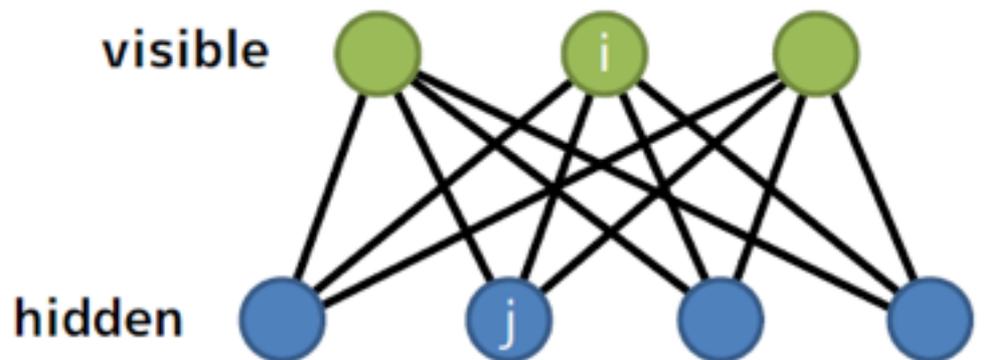
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$P_{\Theta}(\mathcal{V})$

$P_{\Theta}(\mathcal{H}|\mathcal{V})$

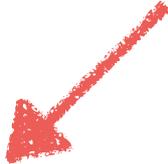
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- Stochastic networks
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- Can be used for efficient sampling



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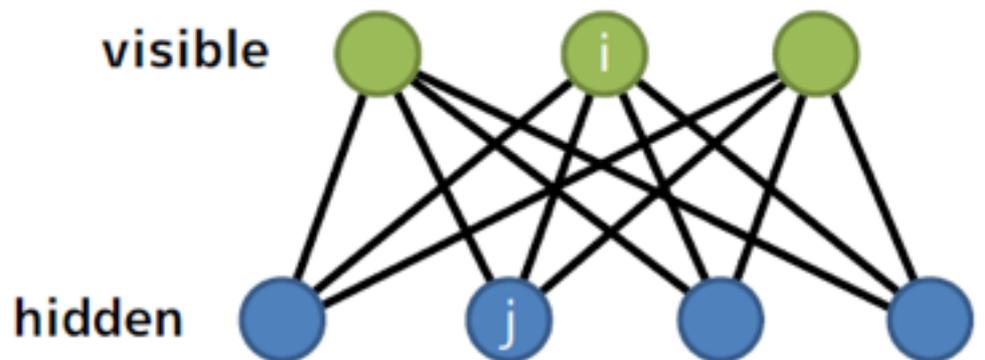
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$$P_{\Theta}(\mathcal{V})$$

$$P_{\Theta}(\mathcal{H}|\mathcal{V})$$

- How to choose the parameters?

# (R)BM training

$$P_{\Theta}(\mathcal{V}, \mathcal{H}) = \frac{1}{\mathcal{Z}} e^{-E_{a,b,\theta}(\mathcal{V}, \mathcal{H})}$$

# (R)BM training

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- First attempt: Maximal Likelihood (ML)

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$$\sum_{\mathcal{V} \in \text{data}} \log P_{\Theta}(\mathcal{V}) = \sum_{\text{all } \mathcal{V}} P_{\text{data}}(\mathcal{V}) \log P_{\Theta}(\mathcal{V})$$

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$$KL(P_{data} || P_{\Theta}) - KL(P_n || P_{\Theta})$$

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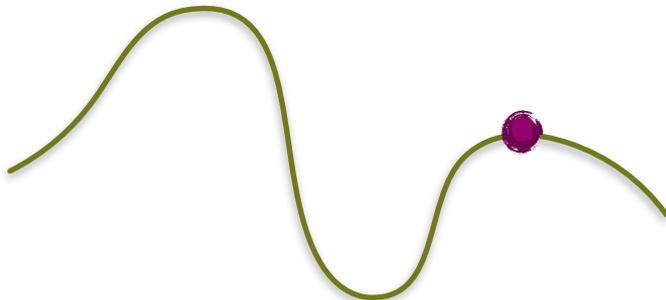
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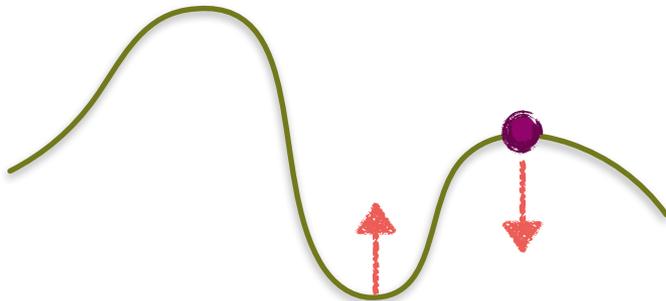
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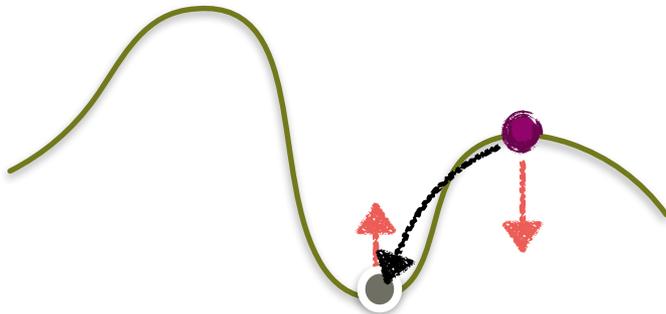
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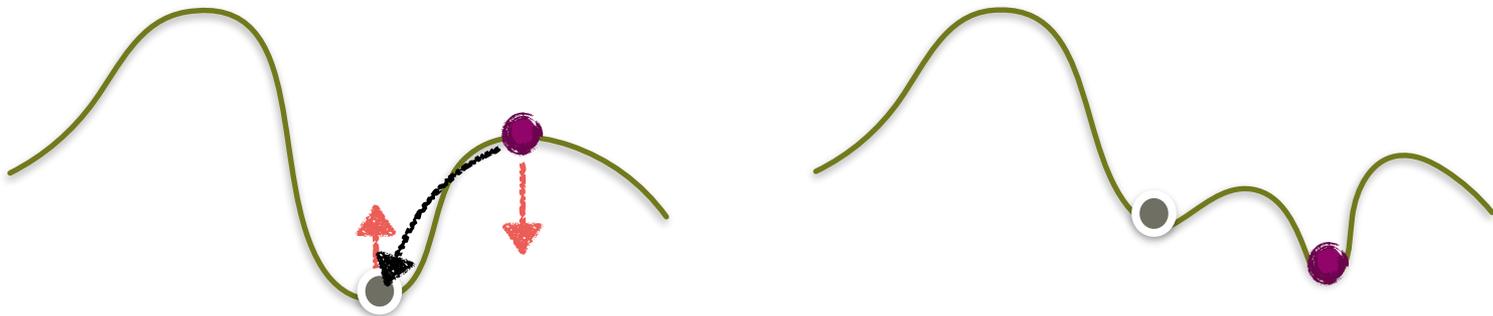
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- Better solution: Contrastive Divergence (CD)

$$KL(P_{data} || P_{\Theta}) - KL(P_n || P_{\Theta})$$





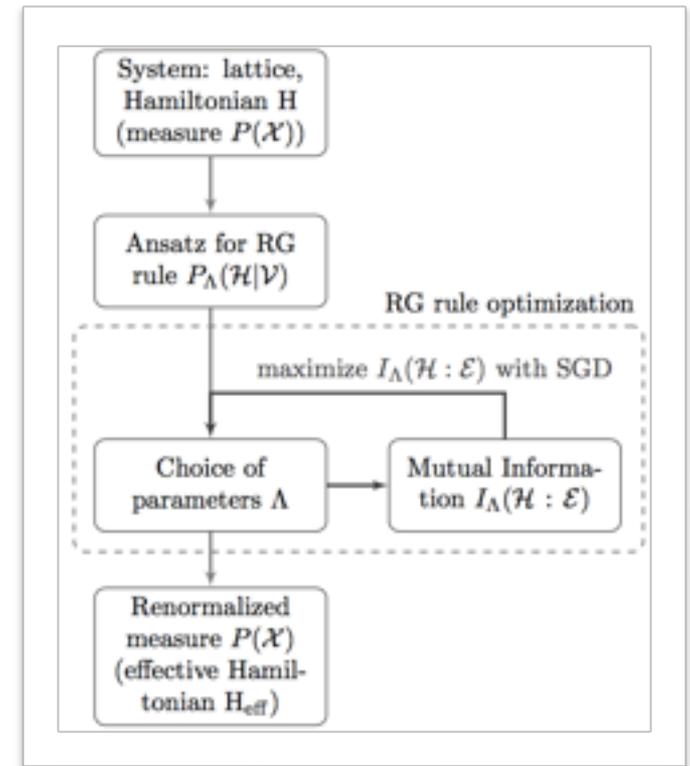
**Stage I.** - Train RBMs to reproduce  $P(V,E)$  and  $P(V)$  via contrastive divergence

$$P_{\Theta}(\mathcal{V}, \mathcal{H}) = \frac{1}{\mathcal{Z}} e^{-E_{a,b,\theta}(\mathcal{V}, \mathcal{H})}$$

**Stage I.** - Train RBMs to reproduce  $P(V,E)$  and  $P(V)$  via contrastive divergence

**Stage II.** - Model  $P_\lambda(H | V)$  as an RBM, obtain  $P_\lambda(H,E)$ , do SGD to maximize  $I(H:E)$  (involves Monte Carlo)

$$P_\Theta(\mathcal{V}, \mathcal{H}) = \frac{1}{\mathcal{Z}} e^{-E_{a,b,\theta}(\mathcal{V}, \mathcal{H})}$$



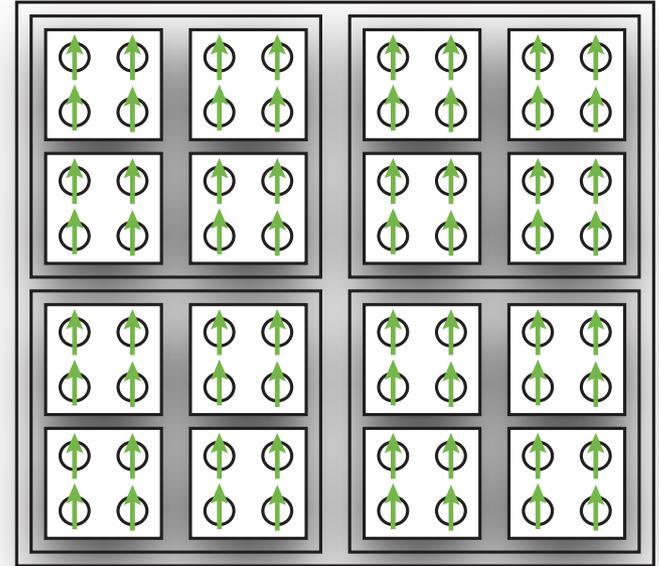
# Example 1: the 2D Ising model

$$H_I = - \sum_{\langle i,j \rangle} s_i s_j$$

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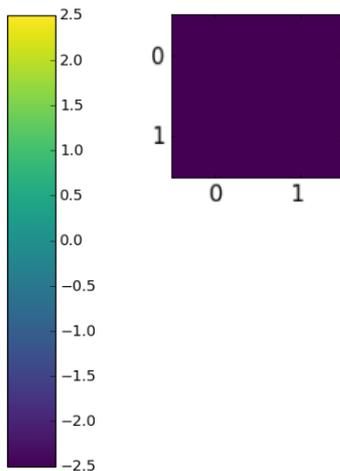
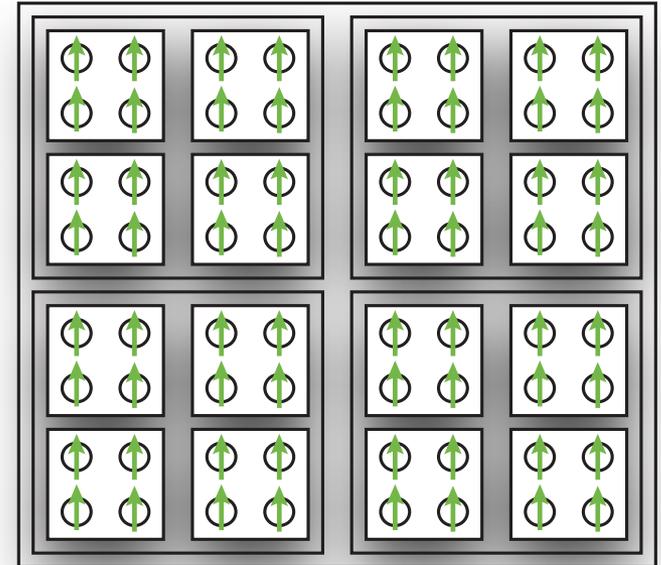
Migdal-Kadanoff block-spins:



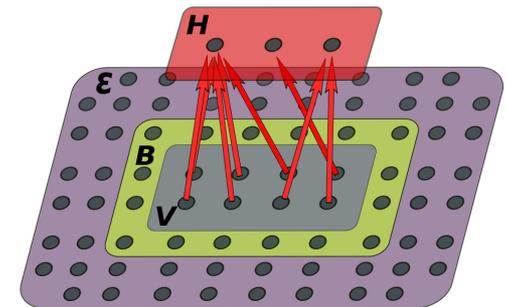
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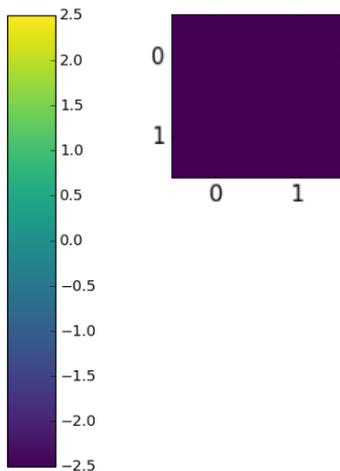
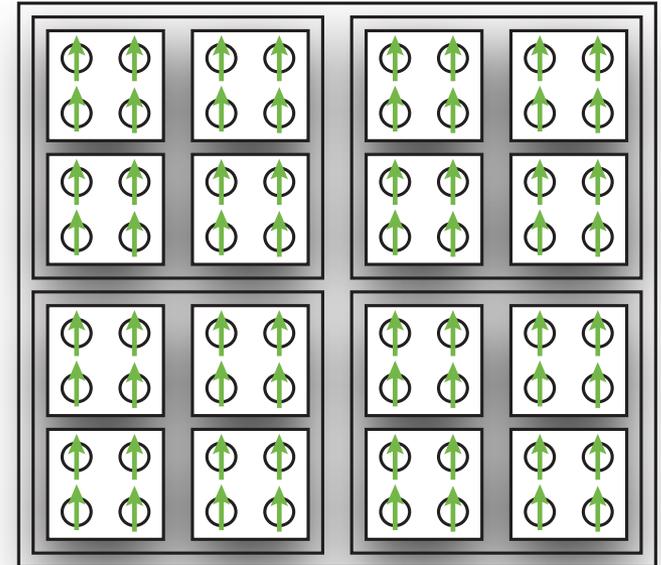
$N=1$



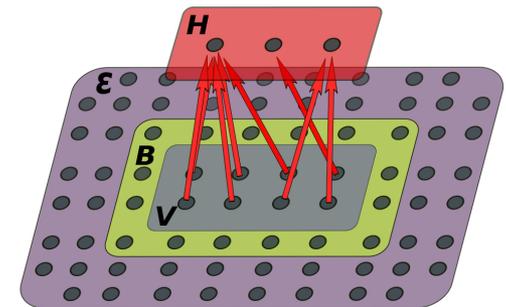
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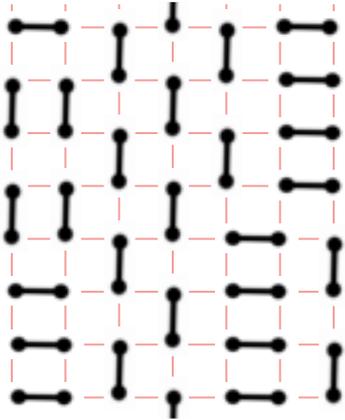
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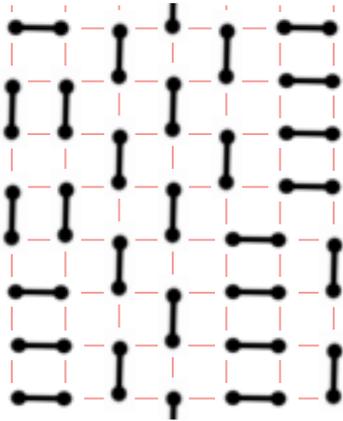
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## Example 2: the dimer model

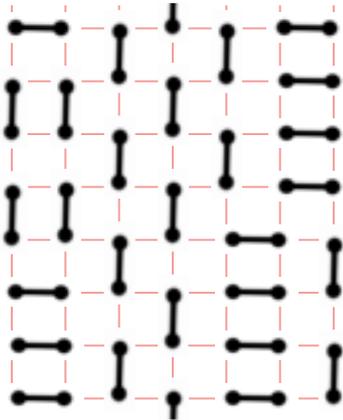


## Example 2: the dimer model



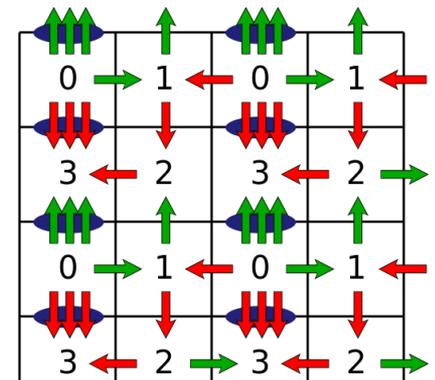
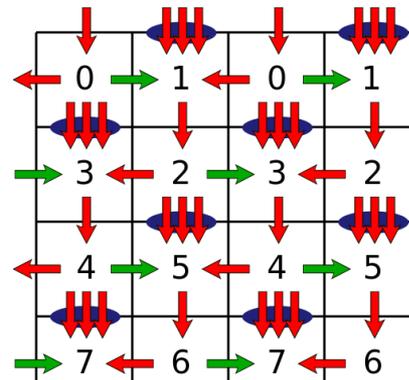
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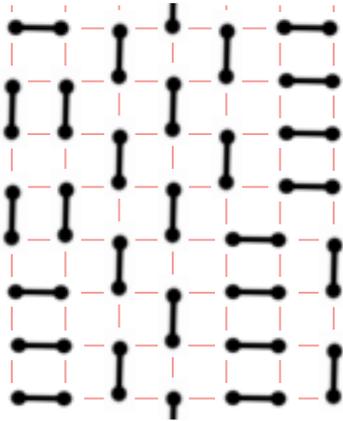


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RG of dimer model:  
mapping to height field  $h(x)$



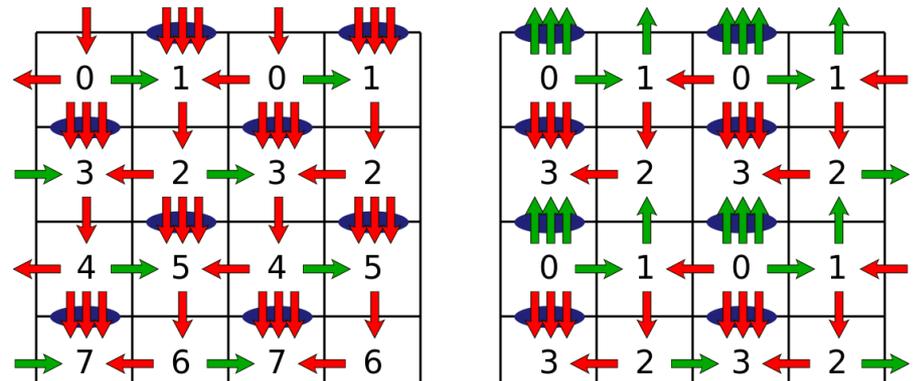
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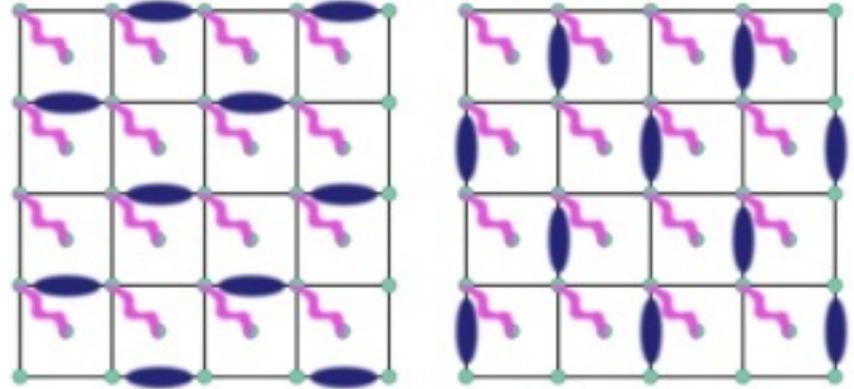
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$$S_{dim}[h] = \int d^2x (\nabla h(\vec{x}))^2 \equiv \int d^2x \vec{E}^2(\vec{x})$$

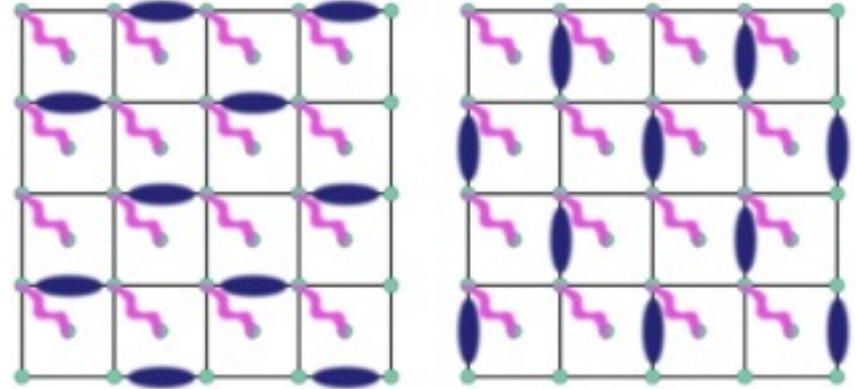


- Let's add noise!

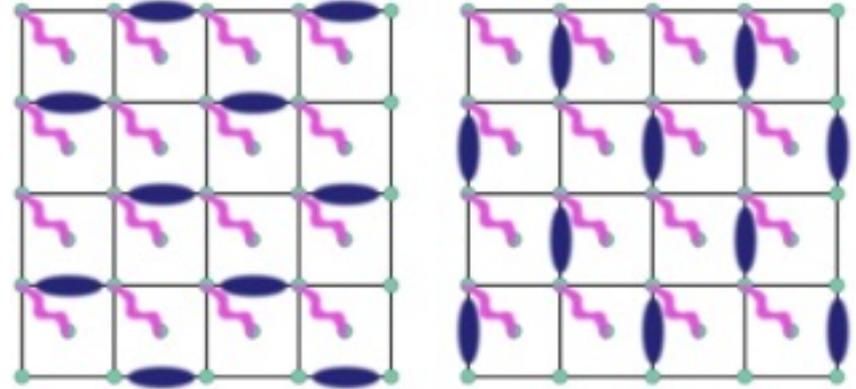
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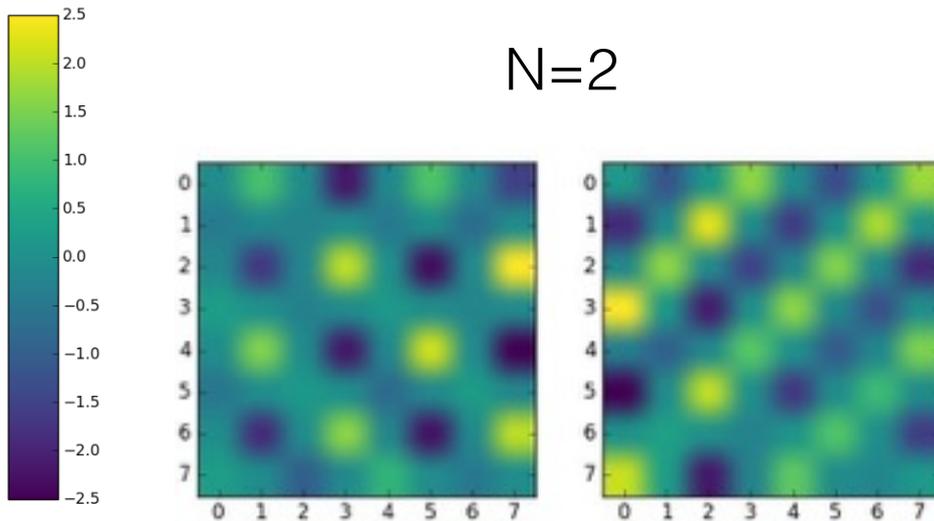
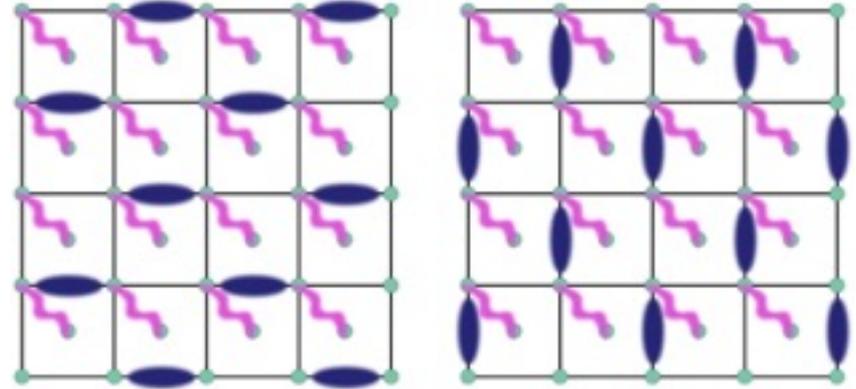
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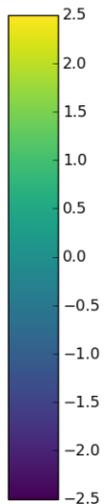
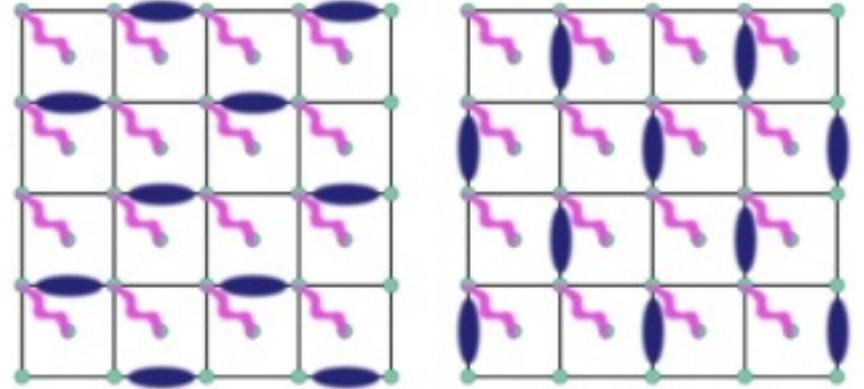
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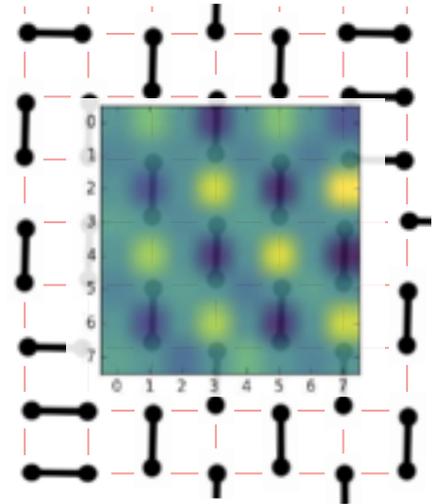
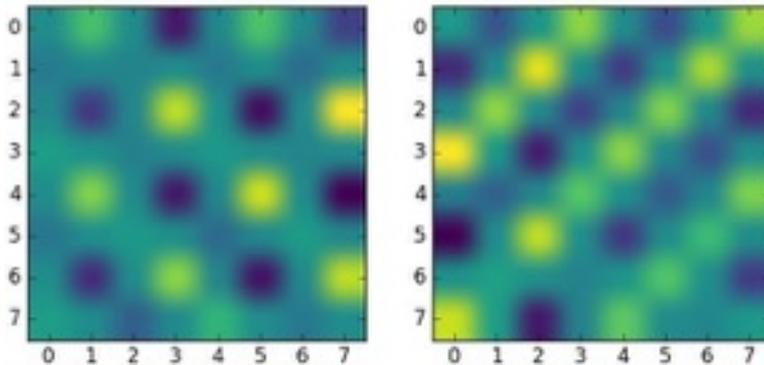
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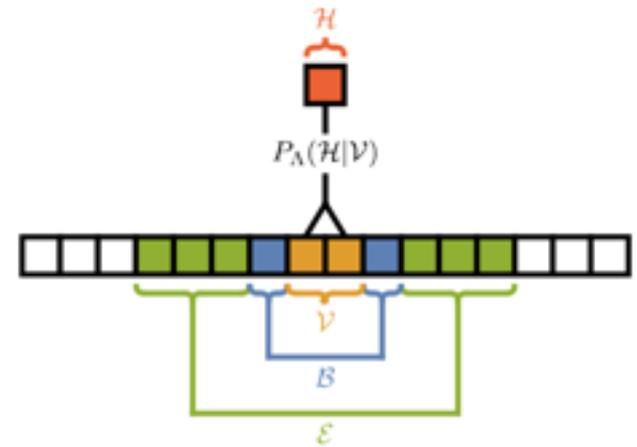
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$N=2$

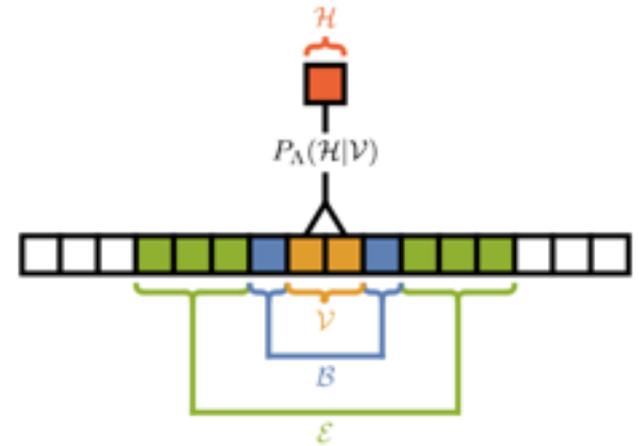


# Optimality of the RSMI approach



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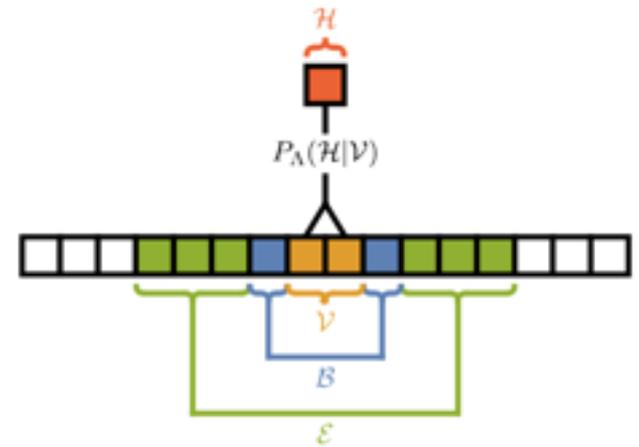
$$I_{\Lambda}(\mathcal{H} : \mathcal{E}) \leq I(\mathcal{V} : \mathcal{E})$$



# Optimality of the RSMI approach

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- Assume first perfect RSMI capture



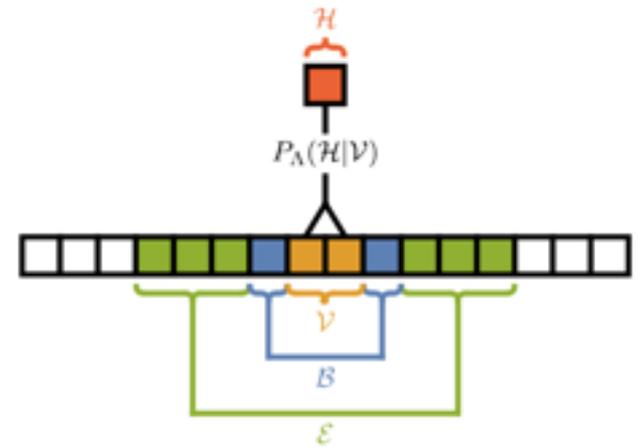
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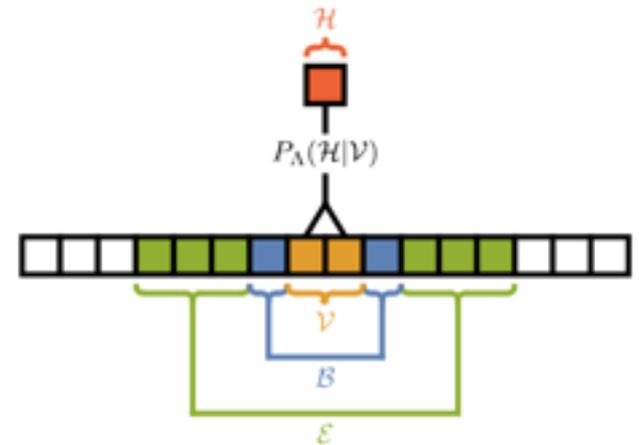
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The range of the Hamiltonian does not increase!



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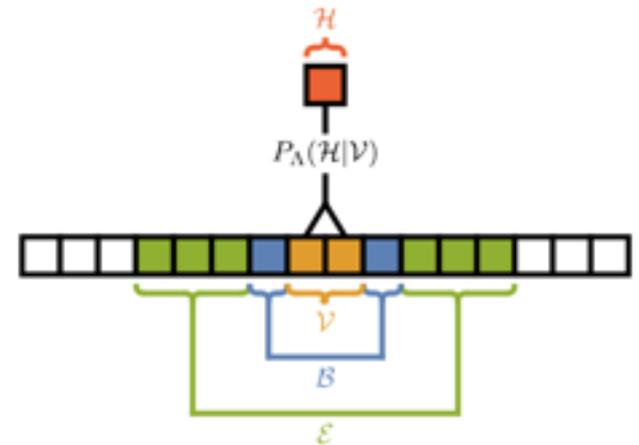
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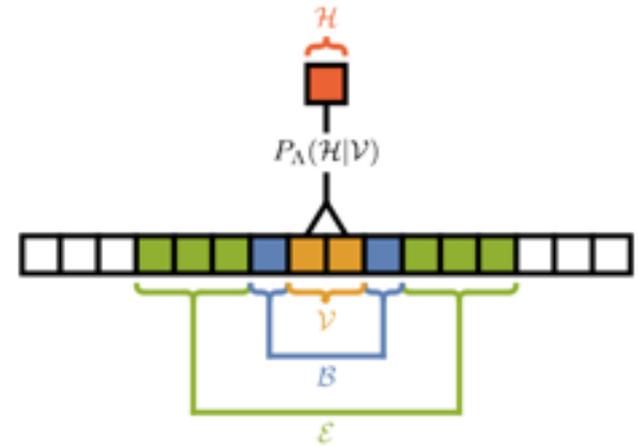


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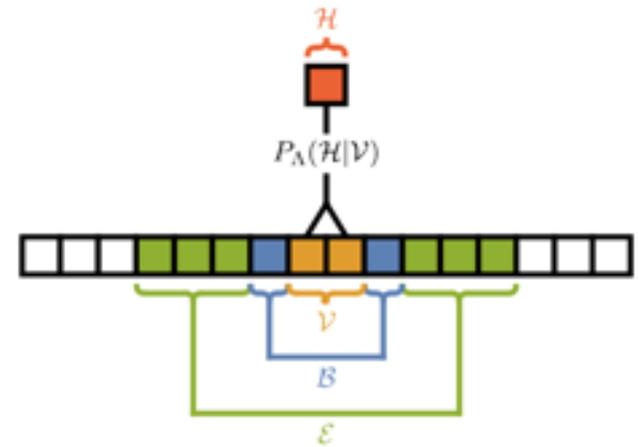
BUT: Realistically, this assumption is rarely true

# Optimality: 1D Ising model



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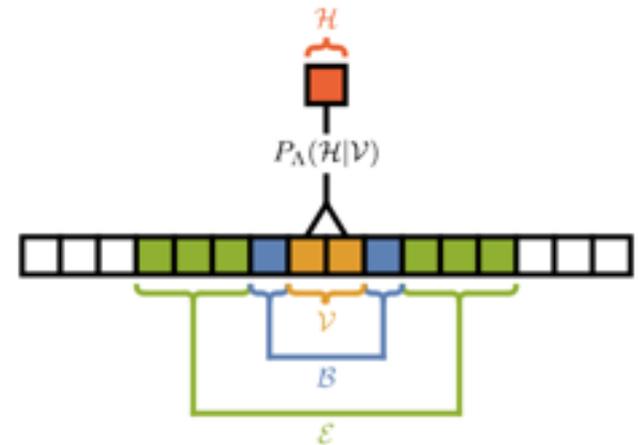
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# Optimality: 1D Ising model

- Effective Hamiltonian:

$$\mathcal{K}'[\mathcal{X}'] = \log(Z_{\Lambda,0}[\mathcal{X}']) + \sum_{k=0}^{\infty} \frac{1}{k!} C_k[\mathcal{X}']$$

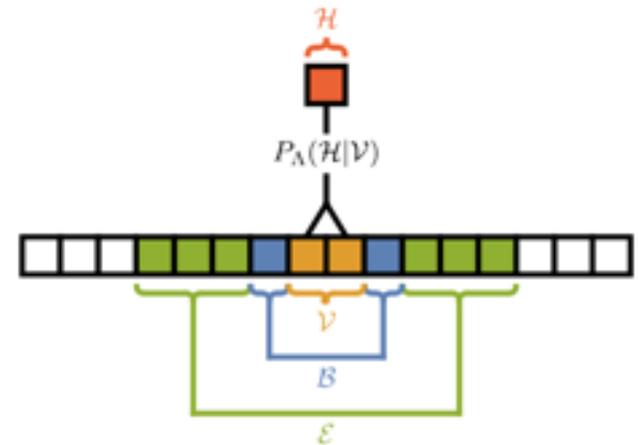


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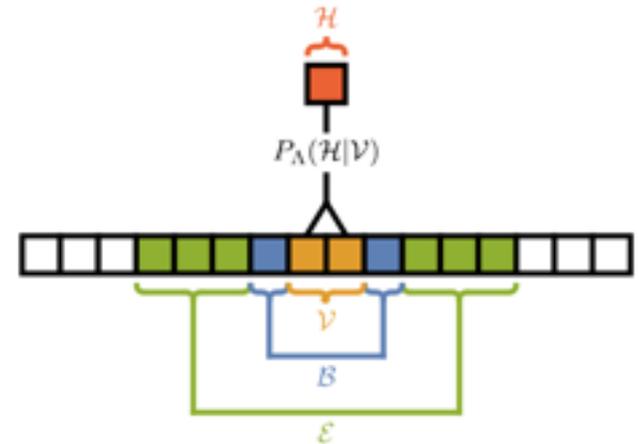
- The “rangeness” and “n-body-ness”



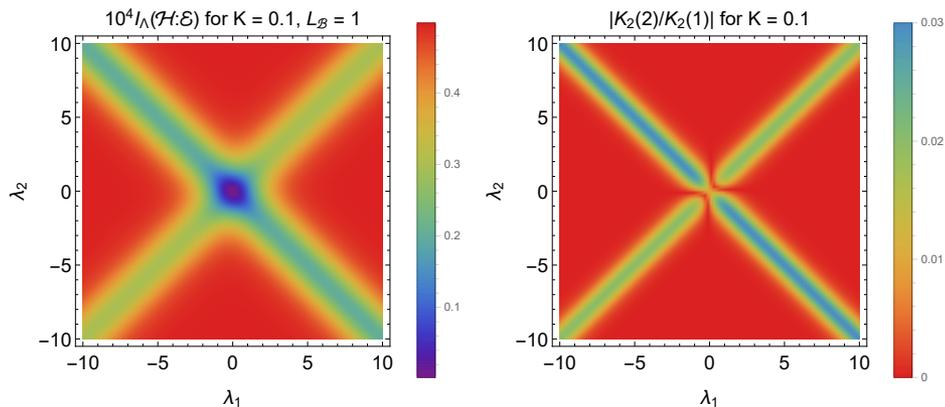
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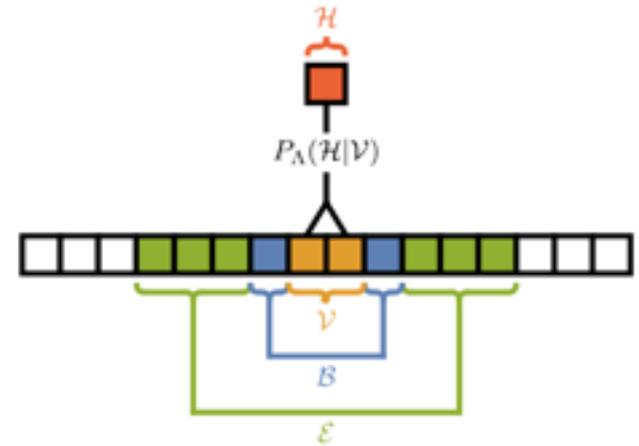
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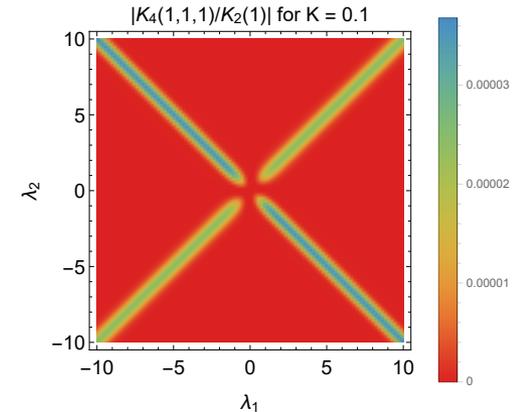
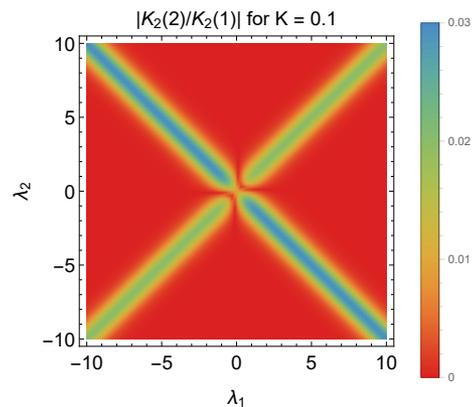
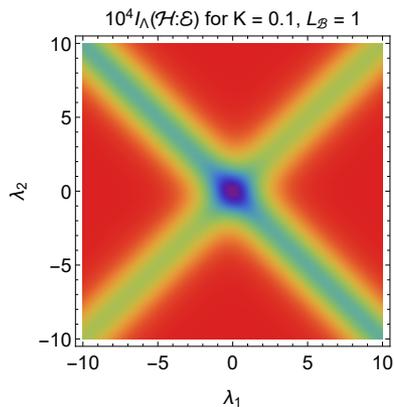
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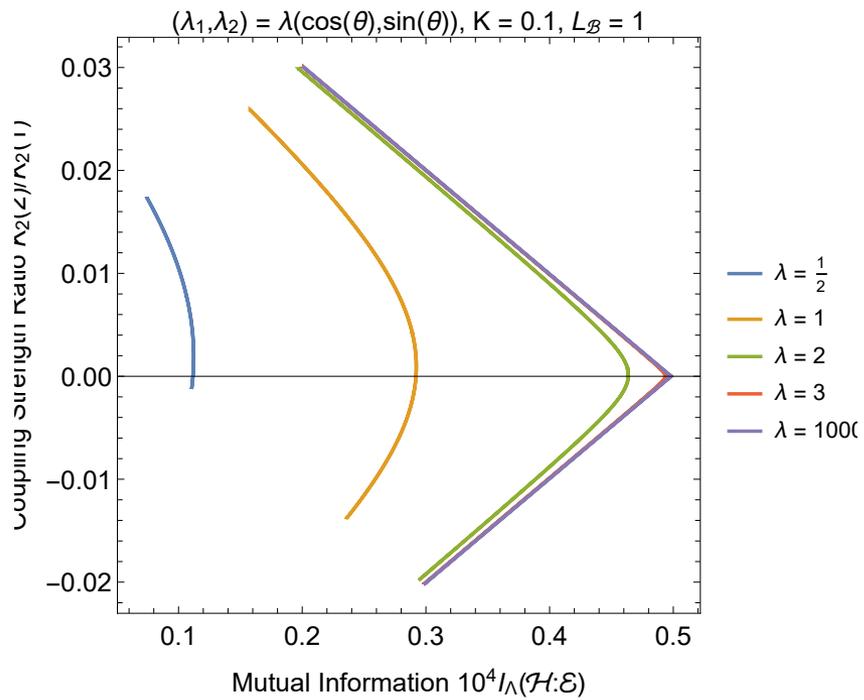
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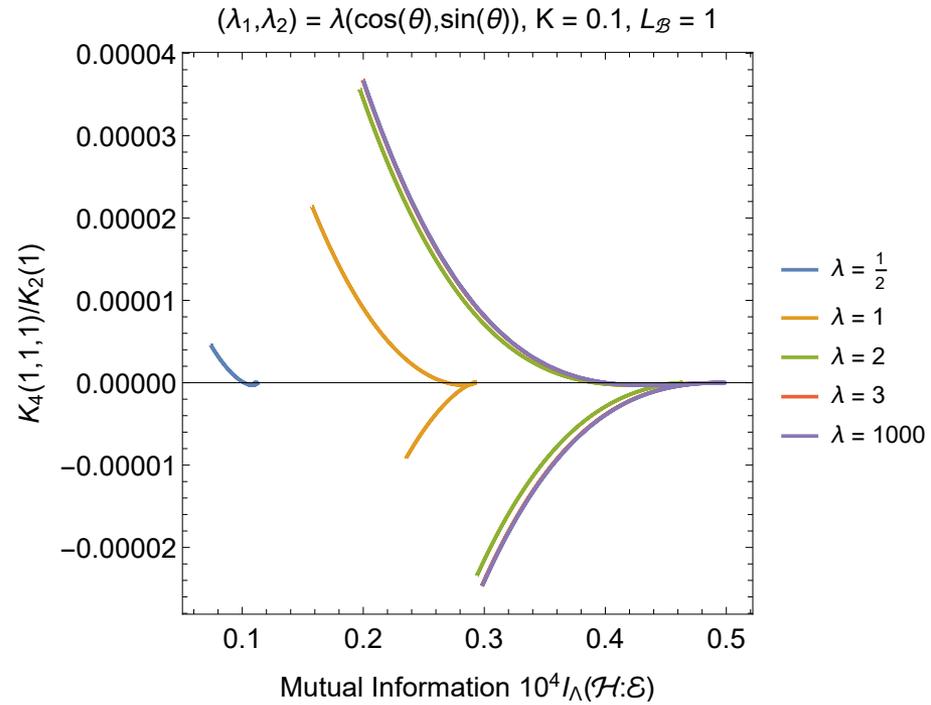
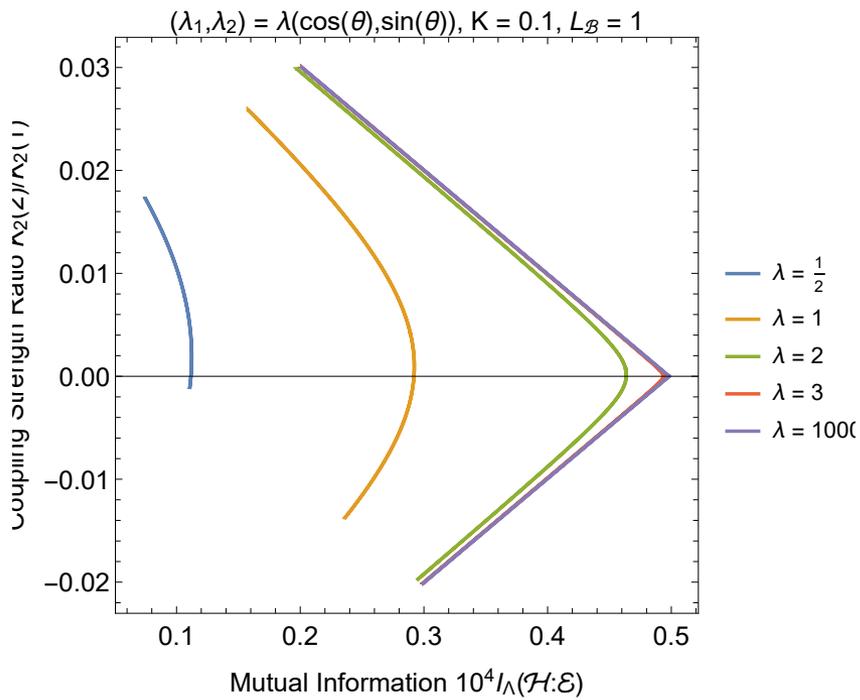


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# Disordered systems

## Disordered systems

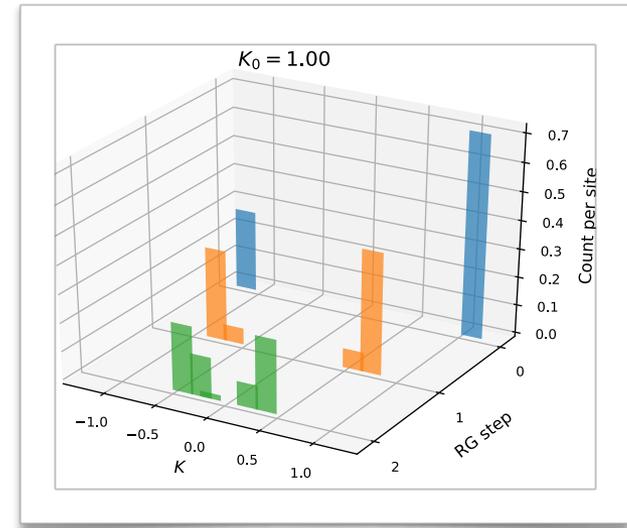
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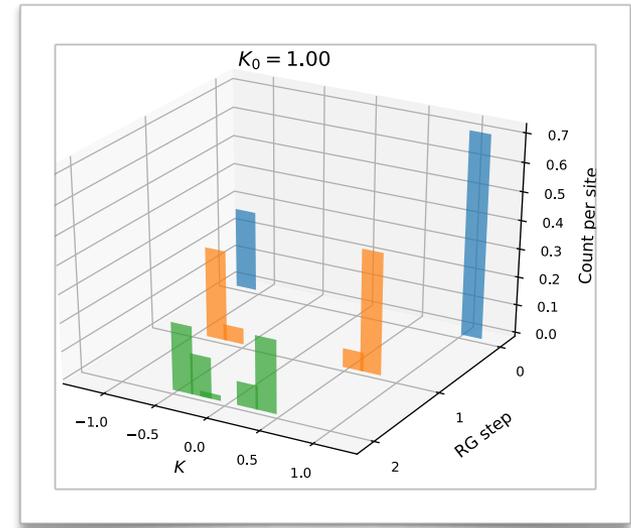
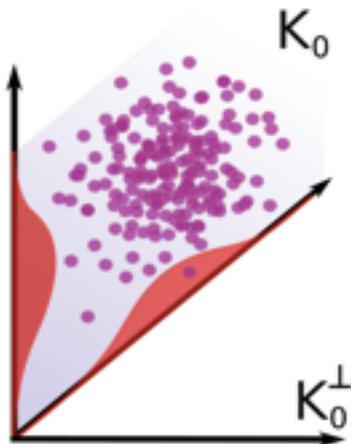
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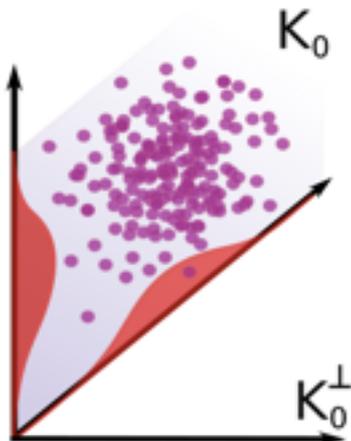
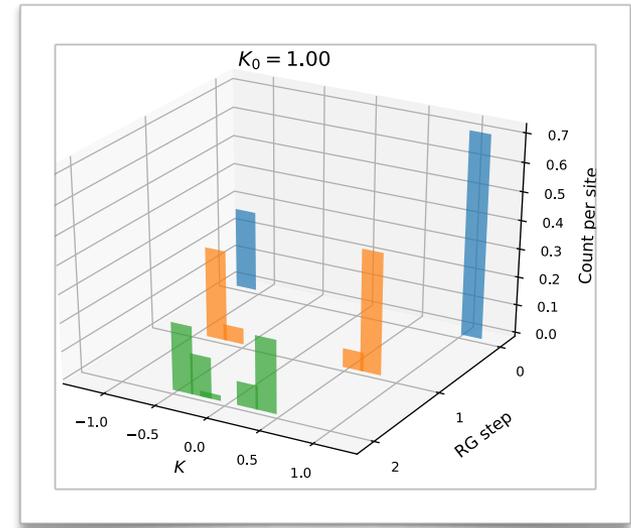
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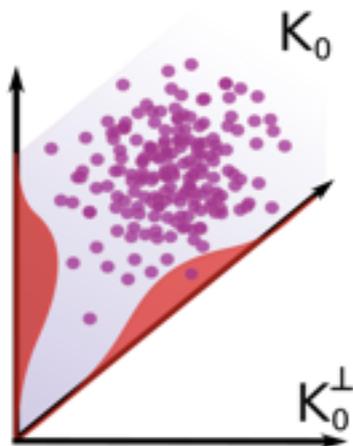
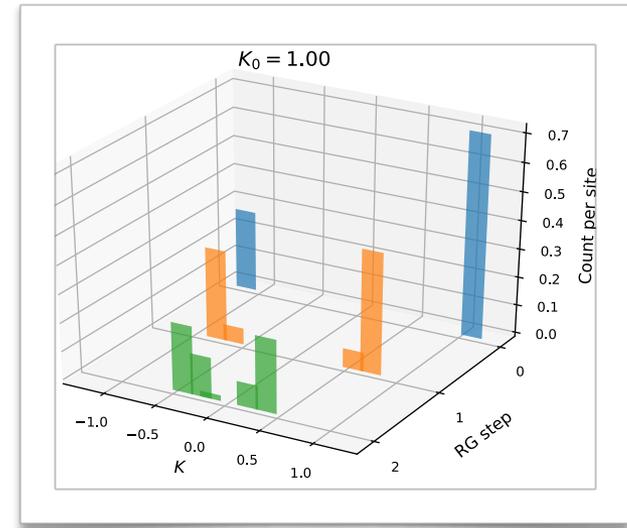


$$\mathcal{P}(\mathbf{K}) \rightarrow \mathcal{P}'(\mathbf{K})$$

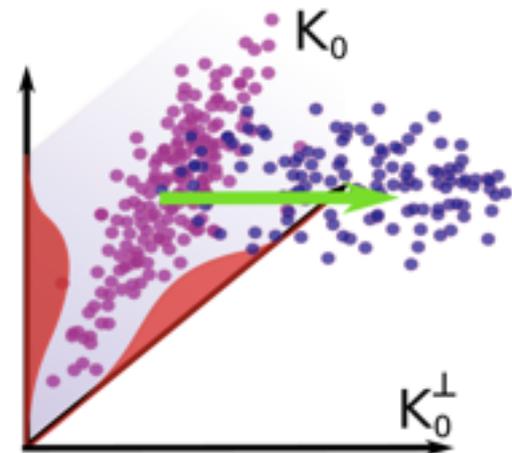


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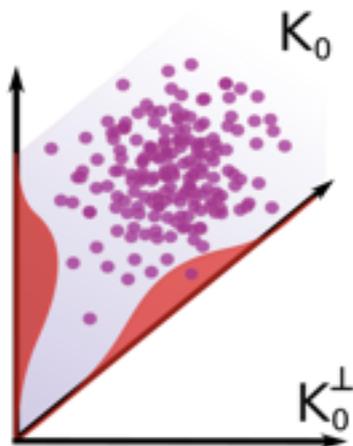
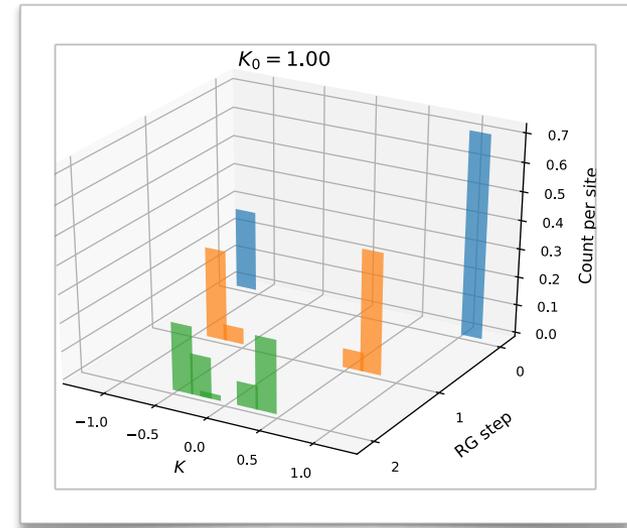


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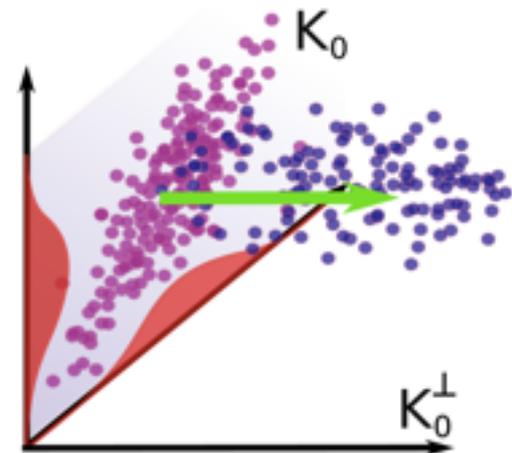


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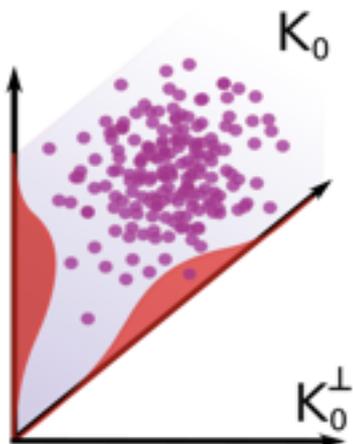
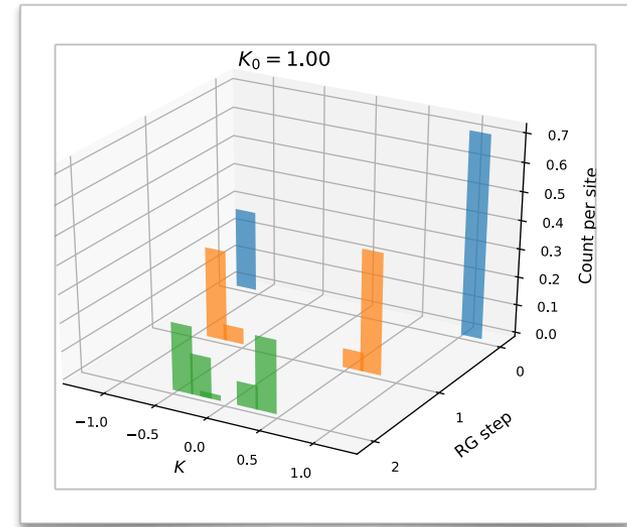


## Disordered systems

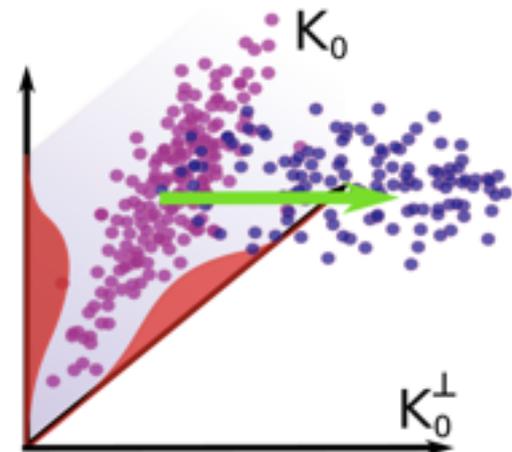
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The factorization is stable to local disorder changes



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## **Example 3: disordered 1d Ising model**

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$$\mathcal{P}'(\mathbf{K}') = \int \delta(\mathbf{K}' - \mathbf{K}'(\mathbf{K})) d\mathcal{P}(\mathbf{K})$$

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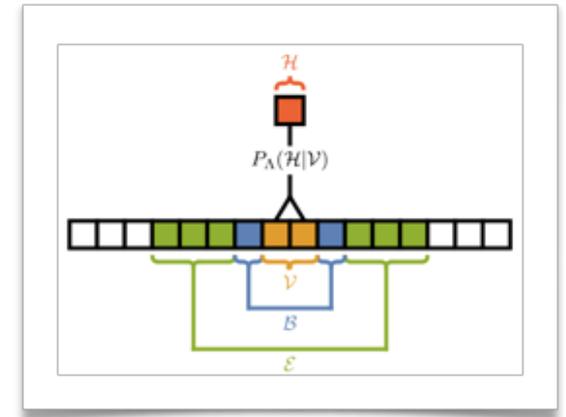
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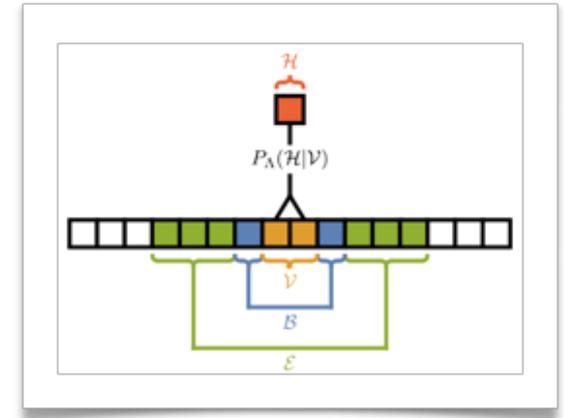
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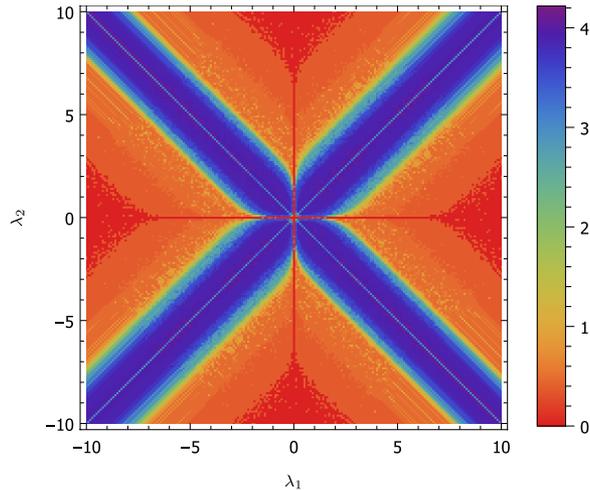
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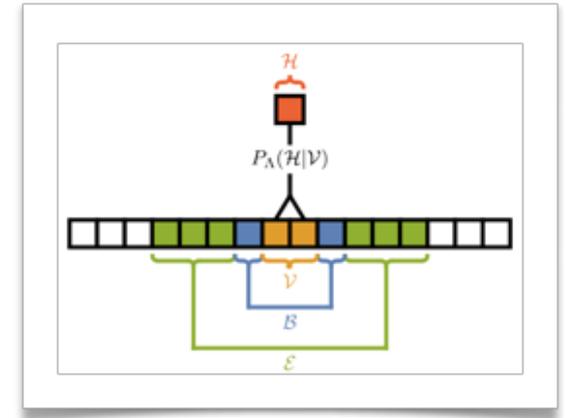
### KL-divergence



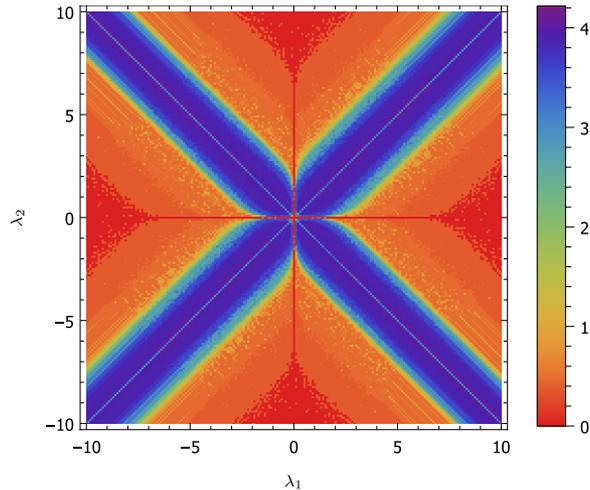
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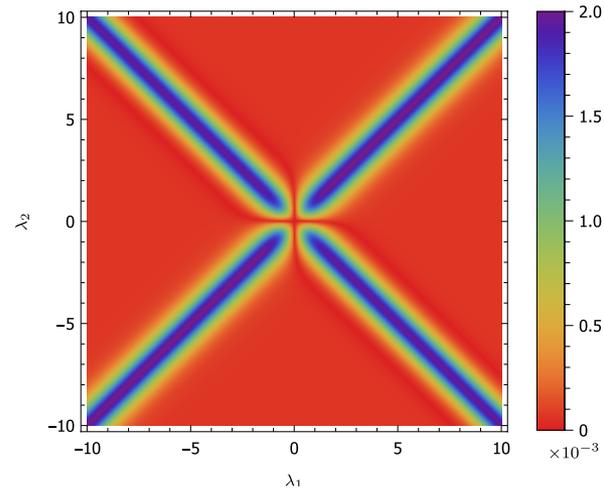
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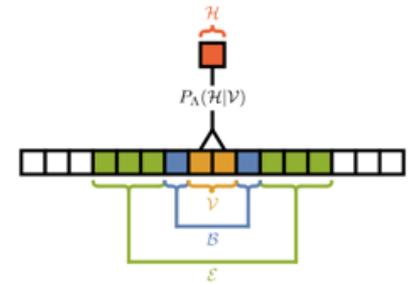
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### dCOM

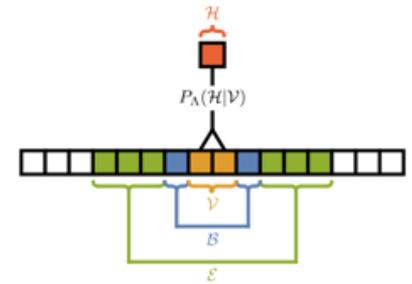


# The “shape” of coarse-grained variables



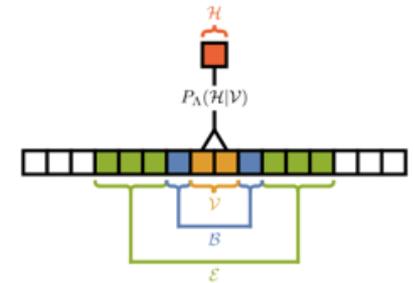
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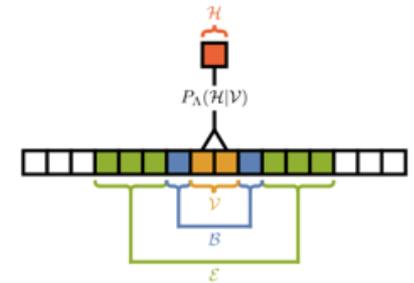
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$$\mathcal{V}_{\Lambda_i} = \frac{1}{\|\Lambda_i\|} \sum_j \lambda_{ij} v_j$$



## The “shape” of coarse-grained variables

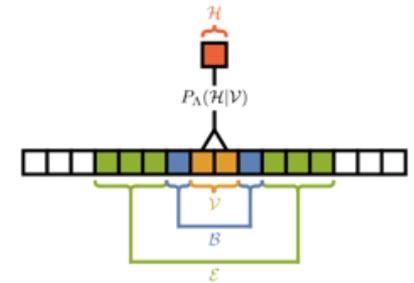
- The hidden couples to:  $\mathcal{V}_{\Lambda_i} = \frac{1}{\|\Lambda_i\|} \sum_j \lambda_{ij} v_j$

$$I_{\Lambda}(\mathcal{H} : \mathcal{E}) \leq I(\mathcal{V}_{\Lambda} : \mathcal{E}) \leq I(\mathcal{V} : \mathcal{E})$$

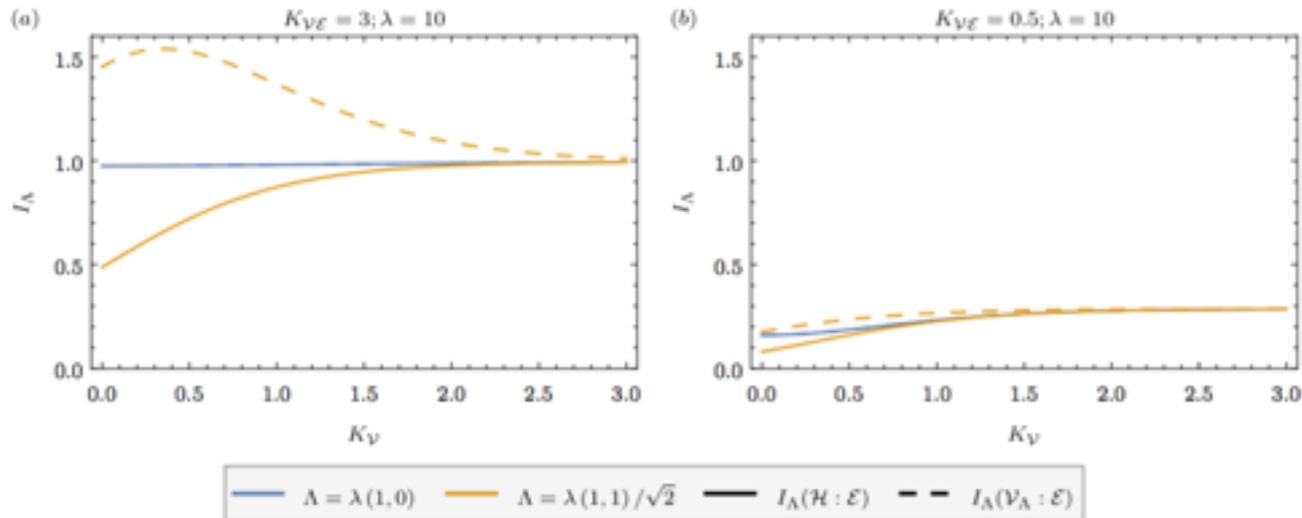


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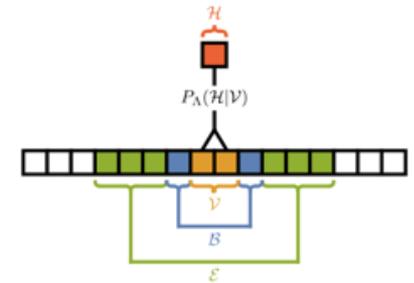


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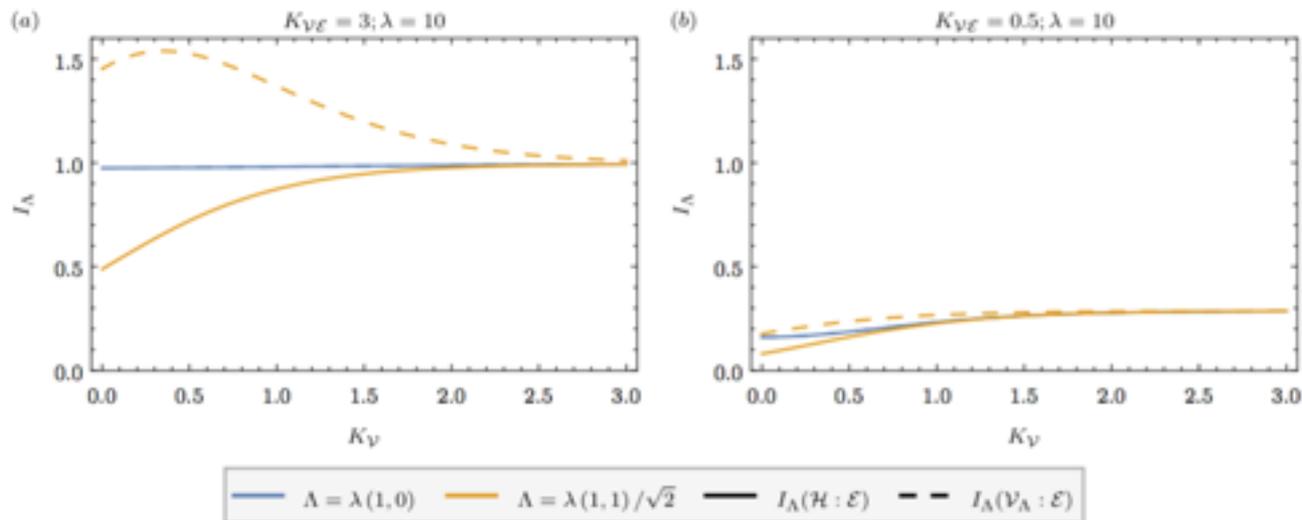


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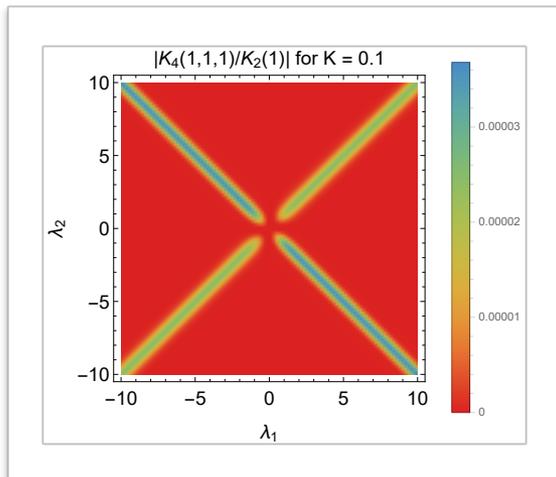
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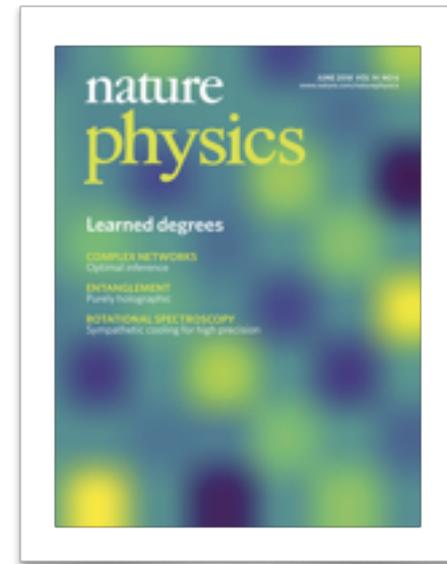
$$I_\Lambda(\mathcal{H} : \mathcal{E}) = I(\mathcal{V}_\Lambda : \mathcal{E}) - I(\mathcal{V}_\Lambda : \mathcal{E}|\mathcal{H})$$

# Conclusions & Outlook

- Information-theoretic view of real-space RG
- Applications to correlated disorder, soft matter
- New numerical techniques GRISE, MINE, ....



Lenggenhager, Ringel, Huber, MKJ,  
*arXiv:1809.09632*



MKJ and Z. Ringel  
*Nature Physics* **14**, 578-582 (2018)

# Thank you!

