

Stabilizing Solitonic Dynamics of Ultracold Gases in the BCS-BEC crossover

Departamento de Física Cuántica y Fotónica, LSCSC-LANMAC, Instituto de Física, UNAM (México)





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Santiago F. Caballero-Benitez with César Terán







Motivation

- Typical soliton problem
- Effective theory for time ev (inspired in LPDA)
- Some preliminary results
- Conclusions

• Effective theory for time evolution in the BCS-BEC crossover

Motivation

- are interesting novel conditions to seed dynamical protocols.

- We have some preliminary tests we want to share :)

• As it has been shown along the conference it is possible to seed and manipulate defects in ultracold fermionic systems by optical means and one can print density and phase patterns with micro-mirror devices (MMDS) and spatial light modulators (SLM). These

• Besides from manipulating vortices in 2D and other topological objects, a simple test setup can be a solitonic solution in an elongated system. There are well know solutions to this problem and has been extensive explored over the past decades. This gives an ideal candidate to explore possible effective theories for effective simulation, as methods like BdG and self consistent density methods can be computationally very expensive to use.

• Recent developments with equilibrium theory (LPDA and related extensions) motivates the exploration of these ideas in a time dependent extension in the non-equilibrium setup.





$$i\hbar\partial_t \psi = -\frac{1}{2}\partial_x^2 \psi + q |\psi|^2 \psi$$

Supports the dark soliton solution:

 $\psi = \exp(-iqt/\hbar) \tanh\left(\sqrt{qx}\right)$

With trapping potential is not necessary stable...

Dark soliton solution of the GPE (No potential)

 $\forall, \quad q > 0$



Theoretical basis (LPDA)

Based on the works of Strinati, Pieri, Simonucci, Pisani and Piselli in the BCS BEC crossover. PRB 89, 054511 (2014) we take as basis.

$$-\frac{m}{4\pi a_F} \Delta(\mathbf{r}) = \mathcal{I}_0(\mathbf{r}) \Delta(\mathbf{r}) + \mathcal{I}_1(\mathbf{r}) \frac{\nabla^2}{4m} \Delta(\mathbf{r})$$
$$-\mathcal{I}_1(\mathbf{r}) i \frac{\mathbf{A}(\mathbf{r})}{m} \cdot \nabla \Delta(\mathbf{r})$$

$$\xi(\mathbf{k}|\mathbf{r}) = \frac{\mathbf{k}^2}{2m} - \bar{\mu}(\mathbf{r}) \ E_+^{\mathbf{A}}(\mathbf{k}|\mathbf{r}) = E(\mathbf{k}|\mathbf{r}) - E(\mathbf{k}|\mathbf{r}) = \sqrt{\xi(\mathbf{k}|\mathbf{r})^2 + |\Delta(\mathbf{r})|^2}$$

This gives the correct limits in Ginzburg-Landau, BEC and BCS limits as shown in 2014 and subsequent works.

 $\mathbf{k} \cdot \mathbf{A}(\mathbf{r})$

In the ground state following the BCS-BEC formalism with coarse graining one can write:

$$\mathcal{I}_0(\mathbf{r}) = \int \frac{d\mathbf{k}}{(2\pi)^3} \begin{cases} \frac{1 - 2f_F(E_+^{\mathbf{A}}(\mathbf{k}|\mathbf{r}))}{2 E(\mathbf{k}|\mathbf{r})} - \frac{m}{\mathbf{k}^2} \end{cases}$$

$$\begin{aligned} \mathcal{I}_{1}(\mathbf{r}) &= \frac{1}{2} \int \frac{d\mathbf{k}}{(2\pi)^{3}} \left\{ \frac{\xi(\mathbf{k}|\mathbf{r})}{2 E(\mathbf{k}|\mathbf{r})^{3}} \left[1 - 2f_{F}(E_{+}^{\mathbf{A}}(\mathbf{k}|\mathbf{r})) + \frac{\xi(\mathbf{k}|\mathbf{r})}{E(\mathbf{k}|\mathbf{r})^{2}} \frac{\partial f_{F}(E_{+}^{\mathbf{A}}(\mathbf{k}|\mathbf{r}))}{\partial E_{+}^{\mathbf{A}}(\mathbf{k}|\mathbf{r})} - \frac{\mathbf{k} \cdot \mathbf{A}(\mathbf{r})}{\mathbf{A}(\mathbf{r})^{2}} \frac{1}{E(\mathbf{k}|\mathbf{r})} \frac{\partial f_{F}(E_{+}^{\mathbf{A}}(\mathbf{k}|\mathbf{r}))}{\partial E_{+}^{\mathbf{A}}(\mathbf{k}|\mathbf{r})} \right\} \end{aligned}$$



·))]



Effective dynamical equation

After some algebra and some redefinitions it is convenient to re-write (A = 0):

$$-\frac{1}{2}\nabla^2\Delta + 2V\Delta + \left(\tilde{I}_2 \left|\Delta\right| - 2\pi\eta\tilde{I}_3\sqrt{\left|\Delta\right|} + 2\eta^2\right)\Delta = \mu_B\Delta$$

It follows, we propose the time dependent extension:

$$-\frac{1}{2}\nabla^2\Delta + 2V\Delta + \left(\tilde{I}_2 |\Delta| - 2\pi\eta\tilde{I}_3\sqrt{|\Delta|} + 2\eta^2\right)\Delta = i\hbar\partial_t\Delta$$

with $\eta = 1/k_F a$ and

$$\tilde{I}_{2} = \frac{2\left(\mu - V - \frac{|\nabla \phi|^{2}}{4}\right)}{\Delta}$$

$$\frac{2\mathscr{I}_0}{\mathscr{I}_1}, \quad \tilde{I}_3 = \frac{\pi}{4\mathscr{I}_1}$$

For $T = 0, \tilde{I}_{2,3}$ are some non-linear monotonic functions



BEC Simulations

Dark Soliton



 $\omega_y = \alpha$

t = 10.0

$$\omega_z \quad \omega_x = \frac{\omega_y}{10}$$





 $\omega_y = \omega_z$

Grey Soliton (finite v)

t = 1.0

$$\omega_z \quad \omega_x = \frac{\omega_y}{10} \quad v \neq 0$$



Snake instability





$$= \omega_z = \omega_x$$

BCS-BEC Simulations (in 3D)



t=1000

BEC Unitary BCS











Current students

Ulises Ramírez

Humberto E. Hernández

PhD.

MSc.

Brahyam Ríos

Ronaldo Navarro

Computational simulation and algorithm development for quantum systems

Quantum optical lattices Light-matter interaction

Analog Quantum Simulation Novel states of quantum matter

Conclusions

- crossover scenario at T = 0.
- corrections.
- methods.
- The effective theory has been implemented in GPU's and runs smoothly.

•We have a potentially useful method to explore dynamics of Fermi systems in the BCS-BEC

• The method is amenable to further refine to consider finite T and possibly additional beyond MFT

• The method allows to have some qualitative simulations to compare with other more sophisticated

Recent articles:

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