General Relativistic Hydrodynamics

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The metric in the 3+1 form

$$
ds^{2} = g_{\mu\nu}dx^{\mu}dx^{\nu} = -\alpha^{2}dt^{2} + \gamma_{ij}(dx^{i} + \beta^{i}dt)(dx^{j} + \beta^{j}dt)
$$

Equations

 $h \equiv 1 + \epsilon + P/\rho$

Eulerian Observer

- It moves with 4-velocity \bm{n}
- \cdot u^μ is the four-velocity of the fluid

•
$$
u^{\mu} \equiv \frac{dx^{\mu}}{d\tau}
$$
 and the velocity is $v^{i} = \frac{dx^{i}}{dt} = \frac{dx^{i}}{d\tau} \frac{d\tau}{dt} = \frac{u^{i}}{u^{t}}$

• In 3+1 GR, the Eulerian observer will measure the following velocity:

$$
v^{i} \equiv \frac{\gamma_{\mu}^{i} u^{\mu}}{W}
$$

where $W = \alpha u^{t}$ is the Lorentz factor, i.e., $W = \frac{1}{\sqrt{1 - v^{i} v_{i}}} = \frac{1}{\sqrt{1 - v^{2}}}$

Remember: for a normal observer $d\tau = \alpha dt$

Eulerian Observer

• Therefore,
$$
v^i = \frac{1}{W} (g^i_\mu + n^i n_\mu) u^\mu = \frac{1}{W} (u^i + \frac{\beta^i}{\alpha} \alpha u^t) = \frac{u^i}{W} + \frac{\beta^i}{\alpha}
$$

$$
v^i = \frac{u^i}{W} + \frac{\beta^i}{\alpha}
$$

$$
{\displaystyle \mathop{\nu}_{i} = \frac{\mathop{\boldsymbol{u}}\nolimits_{i}}{W}}
$$

Remember:
$$
n_{\mu} = (-\alpha, 0, 0, 0), n^{\mu} = \left(\frac{1}{\alpha}, -\frac{\beta^{i}}{\alpha}\right)
$$

Conservation of Rest Mass

$$
\nabla_{\mu}J^{\mu} = 0 \rightarrow \nabla_{\mu}(\rho u^{\mu}) = 0 \rightarrow
$$

$$
\frac{1}{\sqrt{-g}} \partial_{\mu} (\sqrt{-g} \rho u^{\mu}) = 0
$$
\n
$$
\frac{\partial_{t} (\alpha \sqrt{\gamma} \rho u^{t}) + \partial_{i} (\alpha \sqrt{\gamma} \rho u^{i}) = 0}{\partial_{t} D + \partial_{i} [\sqrt{\gamma} (\alpha v^{i} - \beta^{i}) W \rho]} = 0
$$
\n
$$
\frac{\partial_{t} (D) + \partial_{i} [\sqrt{\gamma} (\alpha v^{i} - \beta^{i}) W \rho]}{\partial_{t} (D) + \partial_{i} [D (\alpha v^{i} - \beta^{i})] = 0}
$$

Conservation of Energy and Momentum

$$
\nabla_{\mu}T^{\mu\nu}=0
$$

$$
g^{\nu\lambda}\left[\frac{1}{\sqrt{-g}}\partial_{\mu}\left(\sqrt{-g}T^{\mu}_{\lambda}\right)-\frac{1}{2}T^{\alpha\beta}\partial_{\lambda}g_{\alpha\beta}\right]=0
$$

$$
\frac{1}{\sqrt{-g}}\partial_{\mu}\left(\sqrt{-g}T^{\mu}_{\lambda}\right)=\frac{1}{2}T^{\alpha\beta}\partial_{\lambda}g_{\alpha\beta}
$$

$$
\partial_t(\sqrt{\gamma}\alpha T_\lambda^0)+\partial_i(\sqrt{\gamma}\alpha T_\lambda^i)=\frac{\sqrt{-g}}{2}T^{\alpha\beta}\partial_\lambda g_{\alpha\beta}
$$

GRHD Equations

The system of equations is now written in a flux-conservative form (**Valencia formulation**, Banyuls et al 1997, Anton et al 2006):

 $\partial_t \boldsymbol{U} + \partial_i \boldsymbol{F}^i = \boldsymbol{S}$

where \boldsymbol{U} is the vector of conserved variables, \boldsymbol{F}^i the fluxes, and \boldsymbol{S} the source terms.

For example, let's take the conservation of rest mass:

$$
\partial_t(D) + \partial_i [D(\alpha v^i - \beta^i)] = 0
$$

then $U = D = \sqrt{\gamma \rho} W$, $F^i = D(\alpha v^i - \beta^i) = \alpha D \tilde{v}^i$, $S = 0$.

GRHD Equations

 $\boldsymbol{U} = (D, S_j, \tau)$

$$
D = \sqrt{\gamma} \rho W
$$

\n
$$
S_j = \sqrt{\gamma} (\rho h W^2 v_j)
$$

\n
$$
\tau = \sqrt{\gamma} (\rho h W^2 - P) - D
$$

In the non-relativistic case, $D \to \rho$, $S_i \to \rho v_j$, $\tau \to \rho \epsilon$

GRHD Equations

$$
F^{i} = \alpha \times \begin{bmatrix} D\tilde{v}^{i} \\ S_{j}\tilde{v}^{i} + \sqrt{\gamma}P\delta_{j}^{i} \\ \tau\tilde{v}^{i} + \sqrt{\gamma}Pv^{i} \end{bmatrix}
$$

$$
S = \alpha \sqrt{\gamma} \times \left[T^{\mu\nu} \left(\frac{\partial g_{\nu j}}{\partial x^{\mu}} - \Gamma^{\lambda}_{\mu\nu} g_{\lambda j} \right) \right]
$$

$$
\alpha \left(T^{\mu 0} \frac{\partial \ln \alpha}{\partial x^{\mu}} - T^{\mu \nu} \Gamma^0_{\mu \nu} \right)
$$

The importance of flux-conservative Form

- **Lax-Wendroff Theorem** (1960): If a consistent numerical method written in a flux conservative form converges to a function u(x,t) for dx that goes to zero, then $u(x,t)$ is a solution of the conservation law*.
- **Hou-LeFlock Theorem** (1994): non-conservative schemes do not converge to the correct solution if a shock wave is present in the flow.

*note that the proper formulation of the Lax-Wendroff theorem is slightly different from what reported here (but for our purposes it is OK).

WHAT IS A FLUX-CONSERVATIVE FORM?

$$
\frac{\partial u}{\partial t} + \frac{\partial f(u)}{\partial x} = 0
$$

Let's solve it on a numerical grid

$$
x_j = j \times \Delta x, j = 0, \cdots, J - 1
$$

$$
t^n = n \times \Delta t, n = 0, \cdots, N - 1
$$

We now take the integral in t and x

$$
\int_{x_{j-1/2}}^{x_{j+1/2}} \int_{t^n}^{t^{n+1}} \frac{\partial u}{\partial t} dx dt + \int_{t^n}^{t^{n+1}} \int_{x_{j-1/2}}^{x_{j+1/2}} \frac{\partial f(u)}{\partial x} dx dt = 0
$$
\n
$$
\int_{x_{j-1/2}}^{x_{j+1/2}} \left[u(x, t^{n+1}) - u(x, t^n) \right] dx + \int_{t^n}^{t^{n+1}} \left[f\left(u(x_{j+1/2}, t) \right) - f\left(u(x_{j-1/2}, t) \right) \right] dt = 0
$$

We then divide by Δx

$$
\frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^{n+1}) dx = \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx \n- \frac{1}{\Delta x} \left[\int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^n}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right] = 0
$$

$$
\frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^{n+1}) dx = \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx \n- \frac{1}{\Delta x} \left[\int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^n}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right] = 0
$$

We now define

$$
\tilde{u}_j^n \equiv \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx
$$

$$
\tilde{u}_j^{n+1} = \tilde{u}_j^n - \frac{1}{\Delta x} \left[\int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^n}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right]
$$

$$
\tilde{u}_j^{n+1} = \tilde{u}_j^n - \frac{1}{\Delta x} \left[\int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^n}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right]
$$

Let's also define

$$
f_{j+1/2}^n \equiv \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt
$$

And our equation reduces to:

$$
\tilde{u}_j^{n+1} = \tilde{u}_j^n - \frac{\Delta t}{\Delta x} \left(f_{j+1/2}^n - f_{j-1/2}^n \right)
$$

$$
\tilde{u}_j^n \equiv \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx
$$

$$
f_{j+1/2}^n \equiv \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t) \right) dt
$$

a numerical method written in this way is said to be in **flux conservative form**.

Methods written in this form conserve \tilde{u} , indeed by summing over j

$$
\Delta x \sum_{j=0}^{J-1} \tilde{u}_j^{n+1} = \Delta x \sum_{j=0}^{J-1} \tilde{u}_j^n - \Delta t \left(f_{J-1/2}^n - f_{-1/2}^n \right)
$$

so \tilde{u} is conserved except for fluxes at the boundaries of the numerical domain.

How do we compute the flux?

A very simple choice could be

$$
f_{j+1/2}^n = \frac{1}{2} \left[f(\tilde{u}_j^n) + f(\tilde{u}_{j+1}^n) \right]
$$

$$
\tilde{u}_{j}^{n+1} = \tilde{u}_{j}^{n} - \frac{\Delta t}{2\Delta x} \left[f(\tilde{u}_{j}^{n}) + f(\tilde{u}_{j+1}^{n}) - f(\tilde{u}_{j-1}^{n}) - f(\tilde{u}_{j}^{n}) \right]
$$
\n
$$
= \tilde{u}_{j}^{n} - \frac{\Delta t}{2\Delta x} \left[f(\tilde{u}_{j+1}^{n}) - f(\tilde{u}_{j-1}^{n}) \right]
$$

This method is known as FTCS and it is known to be unfortunately unstable…

Godunov Method

RIEMANN PROBLEM

25

RIEMANN PROBLEM

• By solving the Riemann problem one can compute

$$
f_{j+1/2}^n \equiv \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt
$$

- My open-source exact RMHD Riemann solver can be downloaded here: https://github.com/bgiacoma/Exact_Riemann_Solver
- More computationally convenient to use approximate Riemann solvers, e.g., HLLE

HIGH RESOLUTION SHOCK-CAPTURING METHODS

• To increase the order, instead of assuming a step function one could use a piecewise linear function:

$$
\tilde{u}(x, t^n) = \tilde{u}_j^n + \sigma_j^n (x - x_j) \quad \text{for} \quad x_{j-1/2} < x < x_{j+1/2}
$$
\n
$$
\sigma_j^n = \text{minmod} \left(\frac{\tilde{u}_j^n - \tilde{u}_{j-1}^n}{\Delta x}, \frac{\tilde{u}_{j+1}^n - \tilde{u}_j^n}{\Delta x} \right)
$$
\n
$$
\text{minmod}(a, b) \equiv \begin{cases}\n a \text{ if } |a| < |b| \text{ and } ab > 0 \\
b \text{ if } |b| < |a| \text{ and } ab > 0 \\
0 \text{ if } ab < 0\n\end{cases}
$$

or higher orders functions (e.g., PPM). 27

Maxwell Equations

It is useful to recap Maxwell Equations in a (special) Relativistic formulation (cgs units):

$$
\nabla_{\mathbf{v}} F^{\mu \nu} = I^{\mu} \rightarrow \nabla \cdot \vec{E} = 4\pi \rho_*, \qquad \frac{\partial \vec{E}}{\partial t} = \nabla \times \vec{B} - 4\pi \vec{I}
$$

$$
\nabla_v * F^{\mu\nu} = 0 \rightarrow \nabla \cdot \vec{B} = 0, \qquad \frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}
$$

$$
\nabla_{\nu} I^{\nu} = 0 \nightharpoonup \frac{\partial \rho_{*}}{\partial t} + \nabla \cdot \vec{I} = 0 \text{ (charge conservation)}
$$

Ideal MHD

- (special) Relativistic Ohm Law: $\vec{I}=\sigma W \big[\vec{E}+\vec{\nu}\times\vec{B}-(\vec{E}\cdot\vec{\nu}\big)\vec{\nu}\big] + \rho_*\vec{\nu}$
- In many astrophysical scenarios $\sigma \rightarrow \infty$ and this implies $\vec{E} = -\vec{v} \times \vec{B}$
- This is called the ideal MHD limit
- In this case we do not need the evolve the electric field explicitly
- Maxwell equations reduce to $\nabla_{\nu}^*{}^*F^{\mu\nu}=0$

Equations

The system of equations is written in a conservative form (Valencia formulation, Anton et al 2006):

$$
\nabla_{\mu}(\rho u^{\mu}) = 0 \quad \Rightarrow \quad \frac{1}{\sqrt{-g}} \left(\frac{\partial \sqrt{\gamma} \mathbf{U}}{\partial t} + \frac{\partial \sqrt{-g} \mathbf{F}^i}{\partial x^i} \right) = \mathbf{S}
$$

where **U** is the vector of conserved variables, **F i** the fluxes, and **S** the source terms. They can then be solved using HRSC methods using approximate Riemann solvers.

To these one has to add the equations for the evolution of the magnetic field:

$$
\frac{\partial}{\partial t} \left(\sqrt{\gamma} \vec{B} \right) = \nabla \times \left[\left(\alpha \vec{v} - \vec{\beta} \right) \times \left(\sqrt{\gamma} \vec{B} \right) \right]
$$

$$
\nabla \cdot \left(\sqrt{\gamma} \vec{B} \right) = 0
$$

$$
\mathbf{U}\equiv\left[D,S_{j},\tau,B^{k}\right]
$$

$$
D \equiv \rho W,
$$

\n
$$
S_j \equiv (\rho h + b^2) W^2 v_j - \alpha b^0 b_j,
$$

\n
$$
\tau \equiv (\rho h + b^2) W^2 - \left(p + \frac{b^2}{2} \right) - \alpha^2 (b^0)^2 - D,
$$

$$
\tilde{v}^{i} \equiv \alpha v^{i} - \beta^{i} \qquad \qquad \mathbf{F}^{i} = \begin{pmatrix} D\tilde{v}^{i}/\alpha \\ S_{j}\tilde{v}^{i}/\alpha + (p + b^{2}/2)\delta_{j}^{i} - b_{j}B^{i}/W \\ \tau\tilde{v}^{i}/\alpha + (p + b^{2}/2)v^{i} - \alpha b^{0}B^{i}/W \\ B^{k}\tilde{v}^{i}/\alpha - B^{i}\tilde{v}^{k}/\alpha \end{pmatrix},
$$

$$
\mathbf{S} = \begin{pmatrix} 0 \\ T^{\mu\nu} (\partial_{\mu} g_{\nu j} - \Gamma^{\delta}_{\nu\mu} g_{\delta j}) \\ \alpha (T^{\mu 0} \partial_{\mu} \ln \alpha - T^{\mu \nu} \Gamma^{0}_{\nu \mu}) \\ 0^{k} \end{pmatrix}
$$

THE DIV(B)=0 PROBLEM

Several numerical techniques available to keep the magnetic field divergence-less:

- 1. Constrained Transport (Yee 1966, Evans & Hawley 1988, Balsara & Spicer 1999)
- 2. Hyperbolic Divergence Cleaning (Dedner et al 2002)
- 3. Vector Potential Evolution with Modified Lorenz Gauge (Etienne et al 2012, Farris et al 2012)

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