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Diffusion Model as Stochastic Quantization in lattice QFT

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ML & RG (ECT*, Trento)

Want to **model** the observed data's underlying but unknown **distribution**, to further :

- Understand/Inference the data (inherent structure, properties, features...)
- Sample according to the distribution

Suppose observation dataset :

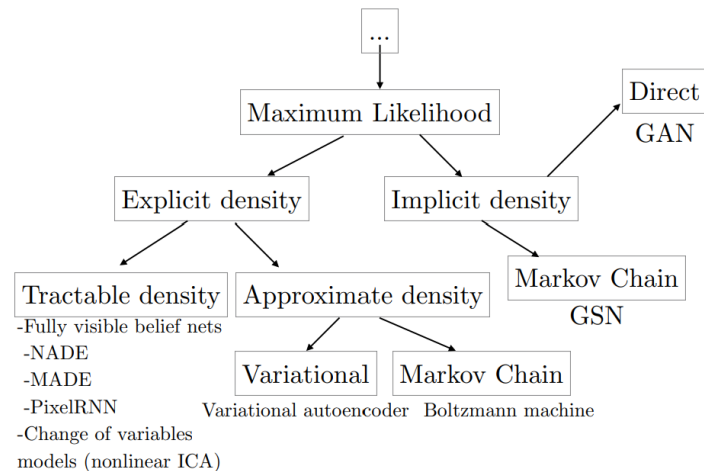
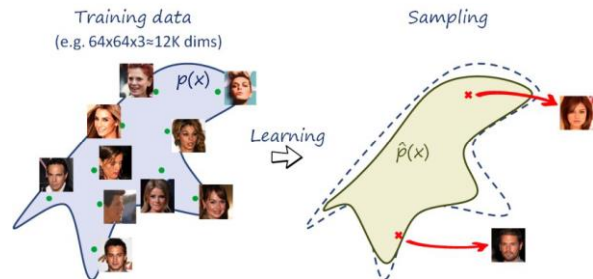
$$\mathbf{X} = \{x^{(1)}, x^{(2)}, \dots, x^{(N)}\} \stackrel{i.i.d}{\sim} p_{data}(x)$$

We use parametric model to approach the data distribution :

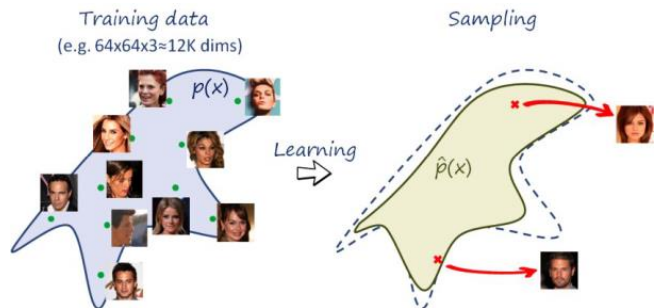
$$p_{\theta}(x) \rightarrow p_{data}(x)$$

- Maximize Likelihood Estimation :

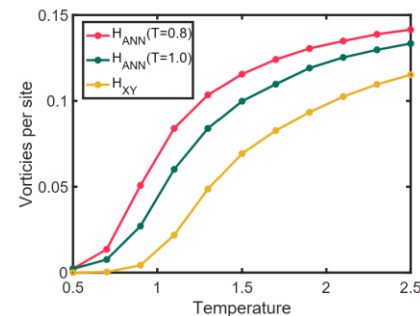
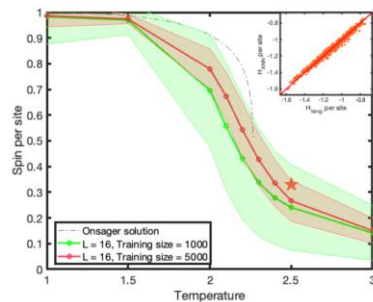
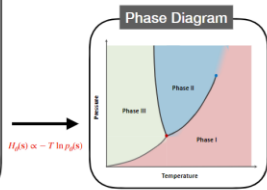
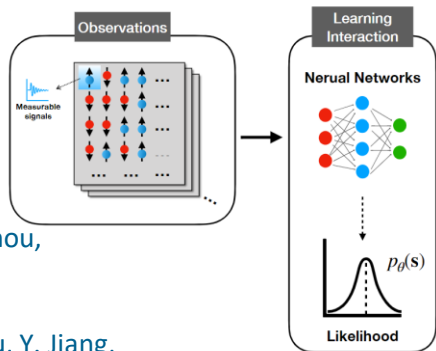
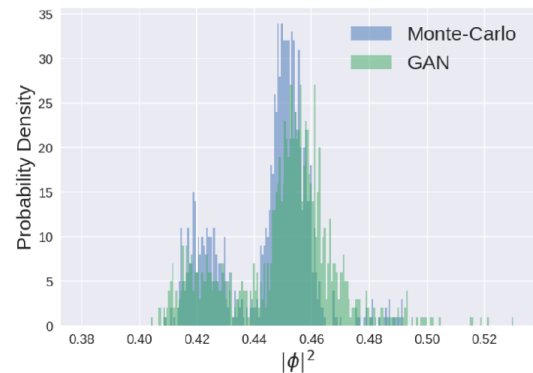
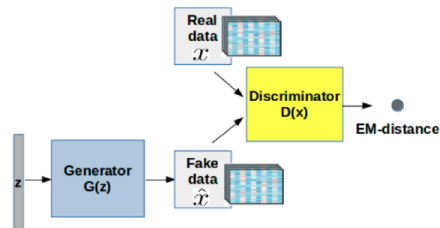
$$\theta^* = \arg \max_{\theta} \log p_{\theta}(\mathbf{X}) = \arg \max_{\theta} \frac{1}{N} \sum_{i=1}^N \log p_{\theta}(x^{(i)})$$



Given an ensemble of data from the target distribution



K. Zhou, G. Endrődi, L.-G. Pang, and H. Stöcker, *PRD* **100**, 011501 (2019)



L. Wang, L. He, Y. Jiang, K. Zhou,
[arXiv:2007.01037](https://arxiv.org/abs/2007.01037)

T. Xu, L. Wang, L. He, K. Zhou, Y. Jiang,
[:2405.10493](https://arxiv.org/abs/2405.10493)

See Lingxiao's talk on Friday !

Suppose knowing unnormalized probability distribution

- Reverse KL divergence

$$D_{\text{KL}}(q_{\theta} \parallel p) = \sum_{\mathbf{s}} q_{\theta}(\mathbf{s}) \ln \left(\frac{q_{\theta}(\mathbf{s})}{p(\mathbf{s})} \right) = \beta(F_q - F)$$

$$F_q = \frac{1}{\beta} \sum_{\mathbf{s}} q_{\theta}(\mathbf{s}) [\beta E(\mathbf{s}) + \ln q_{\theta}(\mathbf{s})]$$

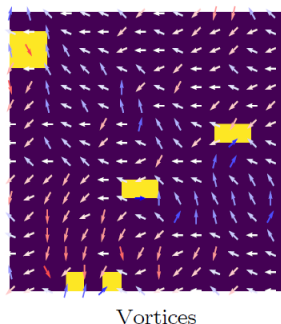
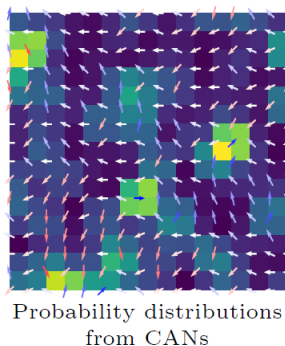
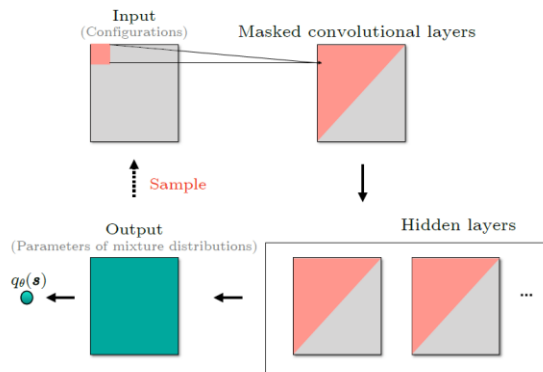
$$p(\mathbf{s}) = \frac{e^{-\beta E(\mathbf{s})}}{Z}$$

- Autoregressive $q_{\theta}(\mathbf{s}) = \prod_{i=1}^N q_{\theta}(s_i | s_1, \dots, s_{i-1})$

D. Wu, Lei Wang and P. Zhang, [PRL122,080602\(2019\)](#)

- Continuous Autoregressive for XY model

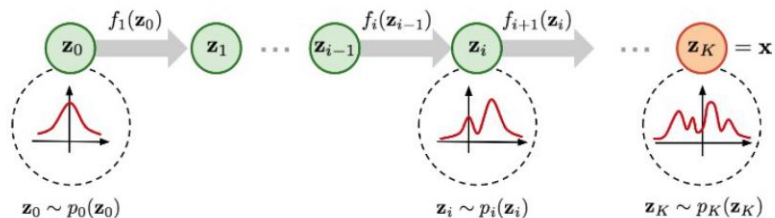
L. Wang, Y. Jiang, L. He, K. Zhou, [CPL39, 120502 \(2022\)](#)



Flow based generative model given unnormalized distribution

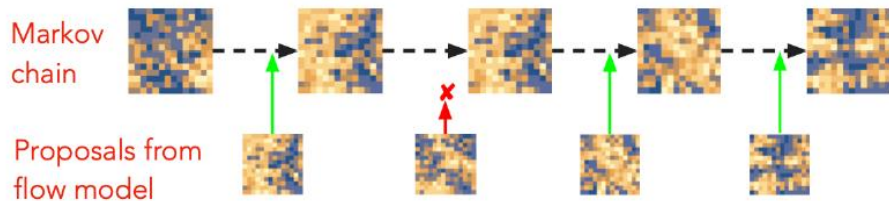
A series (**Flow**) of invertible/bijective transformations for $p(\mathbf{z})$

compose several invertible transformations to form the flow :



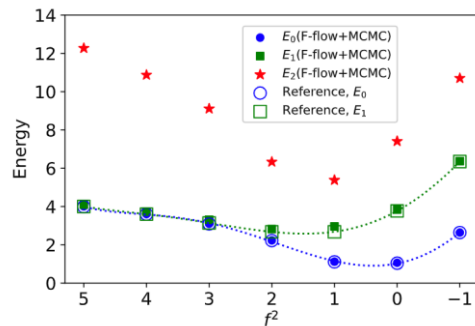
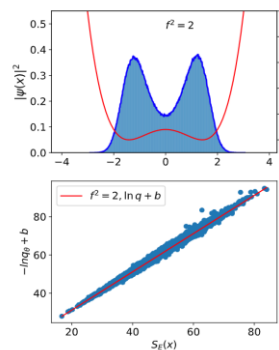
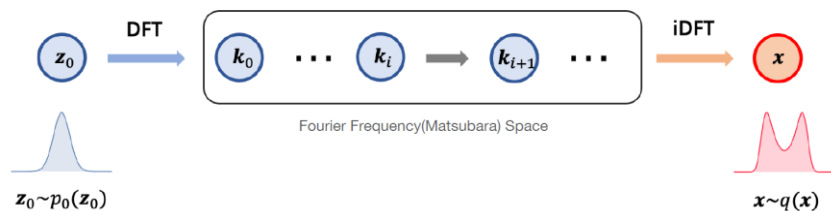
$$p_i(\mathbf{z}_i) = p_{i-1}(f_i^{-1}(\mathbf{z}_i)) |\det J_{f_i^{-1}}| = p_{i-1}(\mathbf{z}_{i-1}) |\det J_{f_i}|^{-1}$$

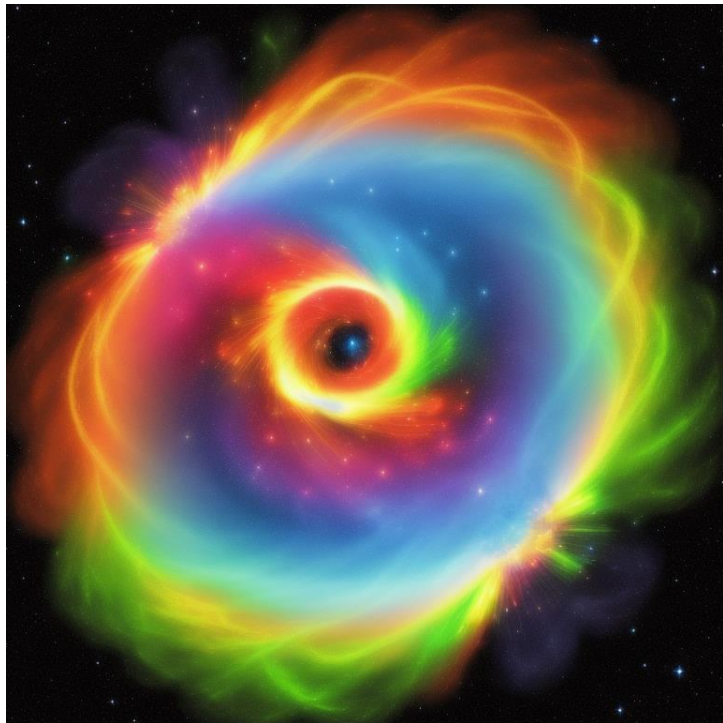
$$\rightarrow \log p(\mathbf{x}) = \log p_0(f^{-1}(\mathbf{x})) + \sum_{i=1}^K \log |\det J_{f_i^{-1}}| = \log p_0(\mathbf{z}_0) - \sum_{i=1}^K \log |\det J_{f_i}|$$



Fourier Flow Model

S.Chen, O. Savchuk, S. Zheng, B. Chen, H. Stoecker, L. Wang, K. Zhou, **PRD107, 056001(2023)**

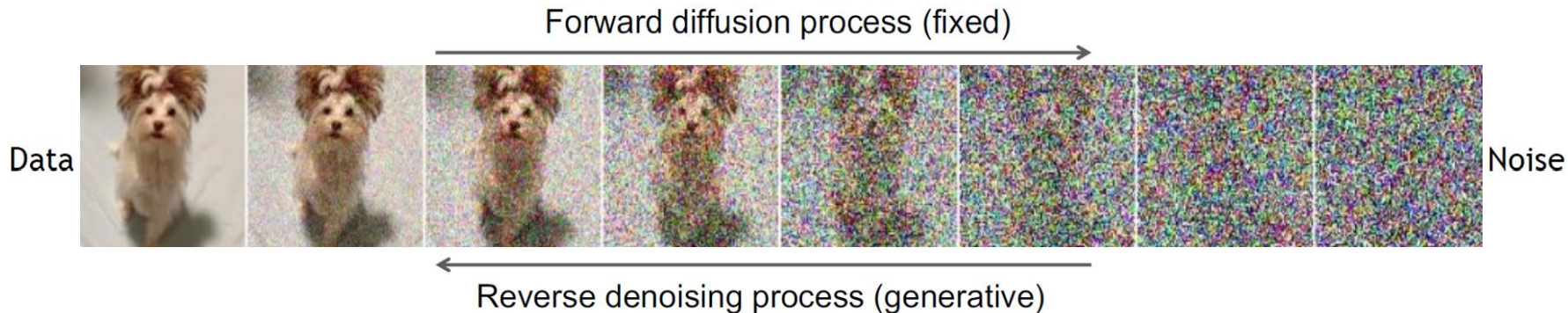




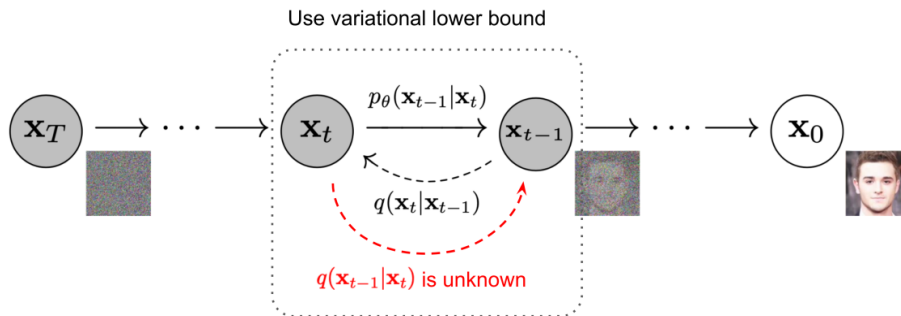
“A heavy quark move inside quark-gluon plasma”



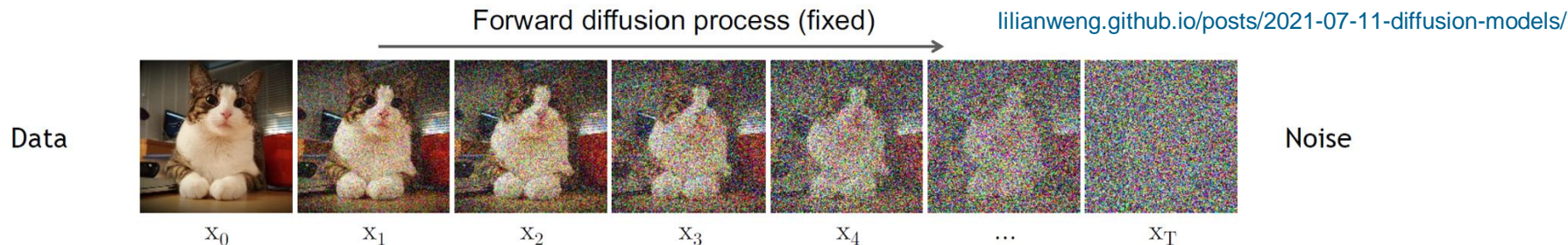
- Forward diffusion process (fixed): gradually introduce noise into data



- Reverse diffusion process (learned): gradually denoise to generate data



Forward Diffusion Process



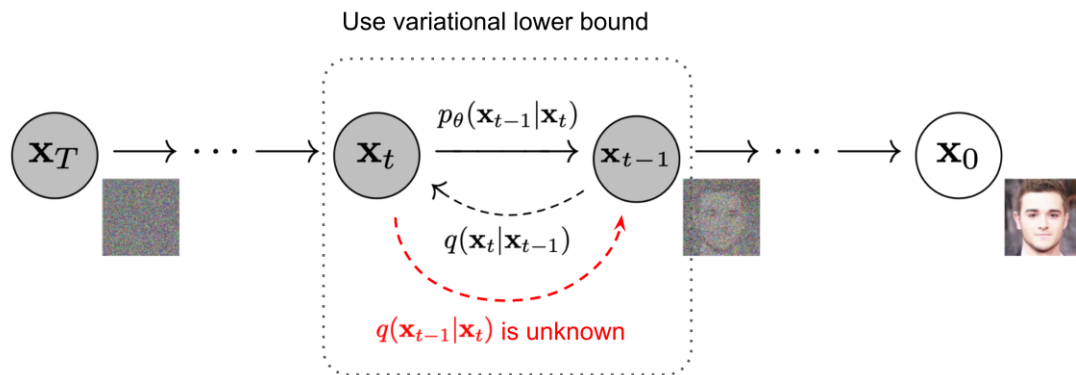
$$q(\mathbf{x}_t | \mathbf{x}_{t-1}) = \mathcal{N}(\mathbf{x}_t; \sqrt{1 - \beta_t} \mathbf{x}_{t-1}, \beta_t \mathbf{I}) \quad \rightarrow \quad q(\mathbf{x}_{1:T} | \mathbf{x}_0) = \prod_{t=1}^T q(\mathbf{x}_t | \mathbf{x}_{t-1}) \quad (\text{joint})$$

Let $\alpha_t = 1 - \beta_t$ and $\bar{\alpha}_t = \prod_{i=1}^t \alpha_i$ → $q(\mathbf{x}_t | \mathbf{x}_0) = \mathcal{N}(\mathbf{x}_t; \sqrt{\bar{\alpha}_t} \mathbf{x}_0, (1 - \bar{\alpha}_t) \mathbf{I})$

↓

$$\mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{(1 - \bar{\alpha}_t)} \epsilon \quad \text{where } \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

$\beta_1 < \beta_2 < \dots < \beta_T$ therefore $\bar{\alpha}_1 > \dots > \bar{\alpha}_T$ $\bar{\alpha}_T \rightarrow 0$ and $q(\mathbf{x}_T | \mathbf{x}_0) \approx \mathcal{N}(\mathbf{x}_T; \mathbf{0}, \mathbf{I})$



$$p_\theta(\mathbf{x}_{0:T}) = p(\mathbf{x}_T) \prod_{t=1}^T p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t) \quad p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t) = \mathcal{N}(\mathbf{x}_{t-1}; \boldsymbol{\mu}_\theta(\mathbf{x}_t, t), \boldsymbol{\Sigma}_\theta(\mathbf{x}_t, t))$$

$$\mathbb{E}_{q(\mathbf{x}_0)} [-\log p_\theta(\mathbf{x}_0)] \leq \mathbb{E}_{q(\mathbf{x}_0)q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \left[-\log \frac{p_\theta(\mathbf{x}_{0:T})}{q(\mathbf{x}_{1:T}|\mathbf{x}_0)} \right] = L = \mathbb{E}_q \left[\underbrace{D_{\text{KL}}(q(\mathbf{x}_T|\mathbf{x}_0)||p(\mathbf{x}_T))}_{L_T} + \sum_{t>1} \underbrace{D_{\text{KL}}(q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)||p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t))}_{L_{t-1}} \underbrace{-\log p_\theta(\mathbf{x}_0|\mathbf{x}_1)}_{L_0} \right]$$

$$\begin{aligned} L_t &= \mathbb{E}_{\mathbf{x}_0, \epsilon} \left[\frac{1}{2\|\Sigma_\theta(\mathbf{x}_t, t)\|_2^2} \|\tilde{\mu}_t(\mathbf{x}_t, \mathbf{x}_0) - \mu_\theta(\mathbf{x}_t, t)\|^2 \right] \\ &= \mathbb{E}_{\mathbf{x}_0, \epsilon} \left[\frac{1}{2\|\Sigma_\theta\|_2^2} \left\| \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\bar{\alpha}_t}} \epsilon_t \right) - \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\bar{\alpha}_t}} \epsilon_\theta(\mathbf{x}_t, t) \right) \right\|^2 \right] \\ &= \mathbb{E}_{\mathbf{x}_0, \epsilon} \left[\frac{(1-\alpha_t)^2}{2\alpha_t(1-\bar{\alpha}_t)\|\Sigma_\theta\|_2^2} \|\epsilon_t - \epsilon_\theta(\mathbf{x}_t, t)\|^2 \right] \\ &= \mathbb{E}_{\mathbf{x}_0, \epsilon} \left[\frac{(1-\alpha_t)^2}{2\alpha_t(1-\bar{\alpha}_t)\|\Sigma_\theta\|_2^2} \|\epsilon_t - \epsilon_\theta(\sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1-\bar{\alpha}_t}\epsilon_t, t)\|^2 \right] \end{aligned}$$

Algorithm 1 Training

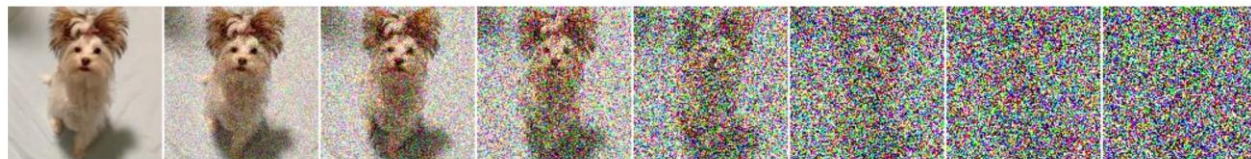
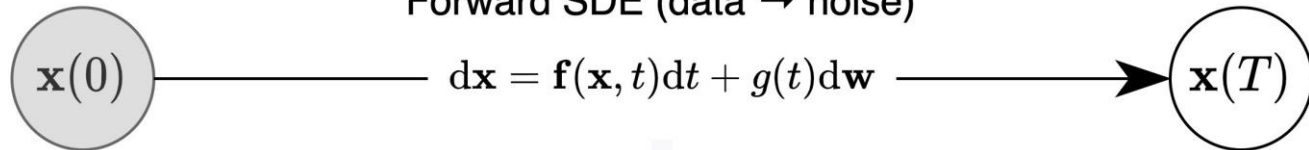
- 1: **repeat**
- 2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$
- 3: $t \sim \text{Uniform}(\{1, \dots, T\})$
- 4: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 5: Take gradient descent step on $\nabla_\theta \|\epsilon - \epsilon_\theta(\sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1-\bar{\alpha}_t}\epsilon, t)\|^2$
- 6: **until** converged

Algorithm 2 Sampling

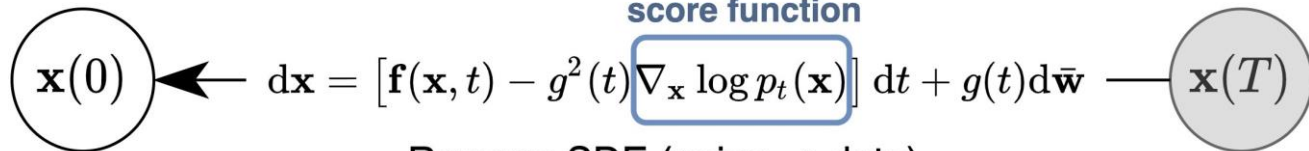
- 1: $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 2: **for** $t = T, \dots, 1$ **do**
- 3: $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 4: $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\bar{\alpha}_t}} \epsilon_\theta(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$
- 5: **end for**
- 6: **return** \mathbf{x}_0

$$d\mathbf{x}_t = -\frac{1}{2}\beta(t)\mathbf{x}_t dt + \sqrt{\beta(t)} d\omega_t$$

Forward SDE (data \rightarrow noise)



score function



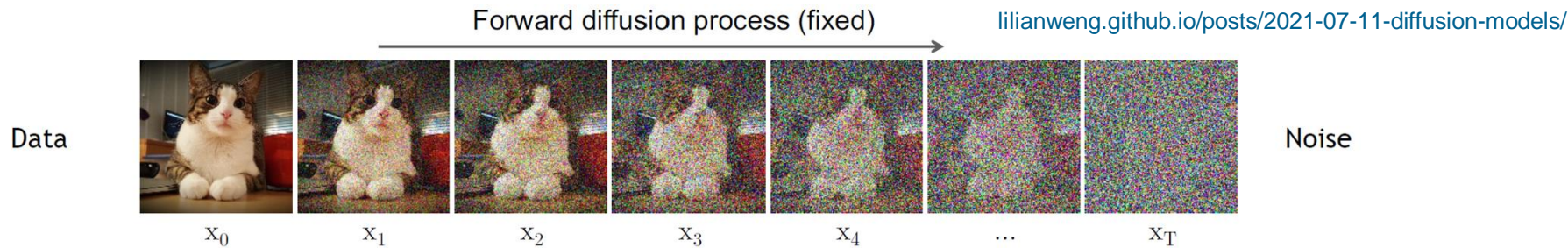
Reverse SDE (noise \rightarrow data)

Song et al., Score-Based Generative Modeling through Stochastic Differential Equations, ICLR 2021

- Fisher Divergence
Via score matching

$$\mathbb{E}_{p(\mathbf{x})} [\|\nabla_{\mathbf{x}} \log p(\mathbf{x}) - \mathbf{s}_{\theta}(\mathbf{x})\|_2^2]$$

Forward Diffusion Process



$$q(\mathbf{x}_t | \mathbf{x}_{t-1}) = \mathcal{N}(\mathbf{x}_t; \sqrt{1 - \beta_t} \mathbf{x}_{t-1}, \beta_t \mathbf{I}) \quad \rightarrow \quad q(\mathbf{x}_{1:T} | \mathbf{x}_0) = \prod_{t=1}^T q(\mathbf{x}_t | \mathbf{x}_{t-1}) \quad (\text{joint})$$

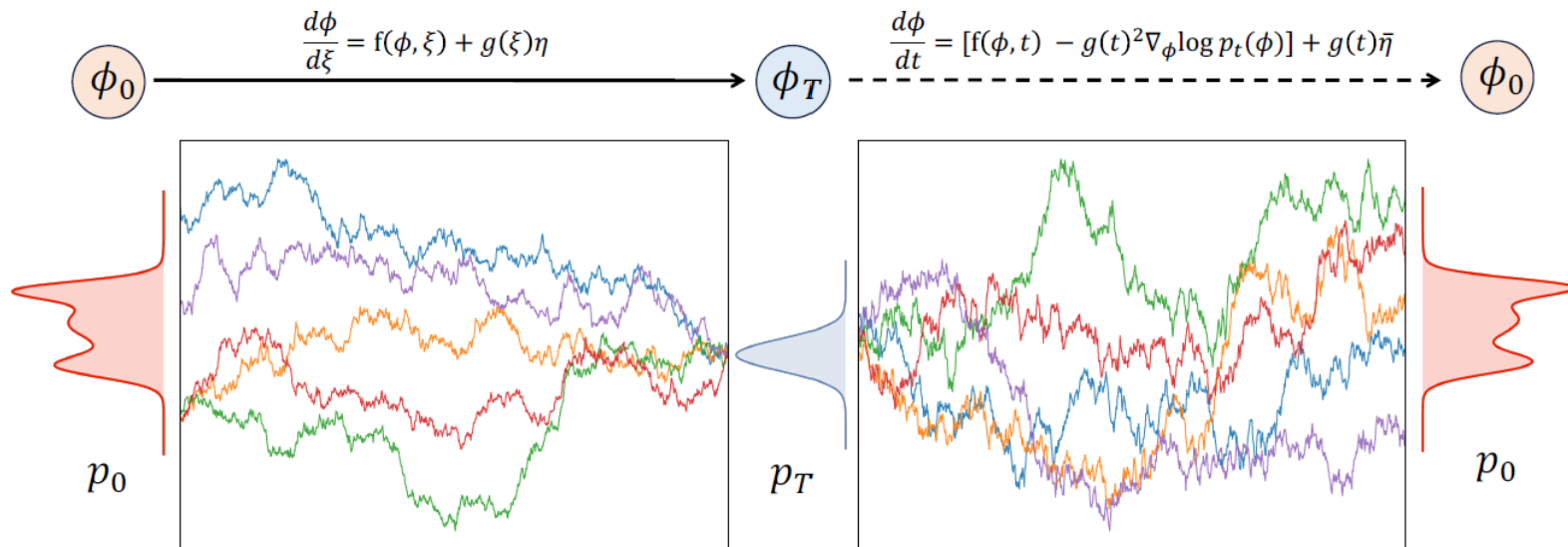
Let $\alpha_t = 1 - \beta_t$ and $\bar{\alpha}_t = \prod_{i=1}^t \alpha_i$ → $q(\mathbf{x}_t | \mathbf{x}_0) = \mathcal{N}(\mathbf{x}_t; \sqrt{\bar{\alpha}_t} \mathbf{x}_0, (1 - \bar{\alpha}_t) \mathbf{I})$

↓

$$\mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{(1 - \bar{\alpha}_t)} \epsilon \quad \text{where } \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

$\beta_1 < \beta_2 < \dots < \beta_T$ therefore $\bar{\alpha}_1 > \dots > \bar{\alpha}_T$ $\bar{\alpha}_T \rightarrow 0$ and $q(\mathbf{x}_T | \mathbf{x}_0) \approx \mathcal{N}(\mathbf{x}_T; \mathbf{0}, \mathbf{I})$

Apply DM on lattice QFT configurations



L. Wang, G. Arts, K. Zhou, JHEP 05 (2024) 060

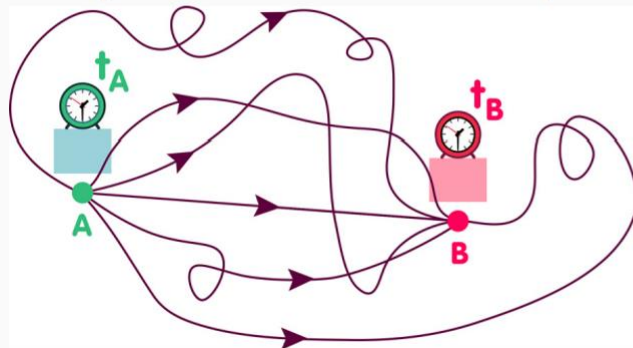
L. Wang, G. Arts, K. Zhou, arXiv:2311.03578 (NeurIPS 2023 workshop "ML&Physical Sciences")

- Stochastic vibration

$$i\hbar \frac{\partial}{\partial t} \Psi = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2}$$

$$\frac{\partial \phi(x,t)}{\partial t} = D \frac{\partial^2 \phi(x,t)}{\partial x^2}$$

In Feynman's formulation of quantum mechanics in Euclidean space:



$$\mathcal{Z} = \int \mathcal{D}x e^{-S_E[x]/\hbar}$$

$$\langle 0 | \hat{x}^N | 0 \rangle = \frac{1}{\mathcal{Z}} \int \mathcal{D}x x^N e^{-S_E[x]/\hbar}$$

One can construct stochastic process to reproduce the quantum path
Integral with its equilibrium:

$$e^{-S_E[x]/\hbar} \rightarrow \frac{\partial x}{\partial \tau} = -\frac{\delta S_E[x]}{\delta x} + \eta \begin{cases} \langle \eta(t, \tau) \rangle_\eta = 0 \\ \langle \eta(t, \tau) \eta(t', \tau') \rangle_\eta = 2\hbar \delta(t - t') \delta(\tau - \tau') \end{cases}$$

- **Stochastic quantization** $Z = \int D\phi e^{-S_E}$ $p(\phi) = \frac{e^{-S_E(\phi)}}{Z}$

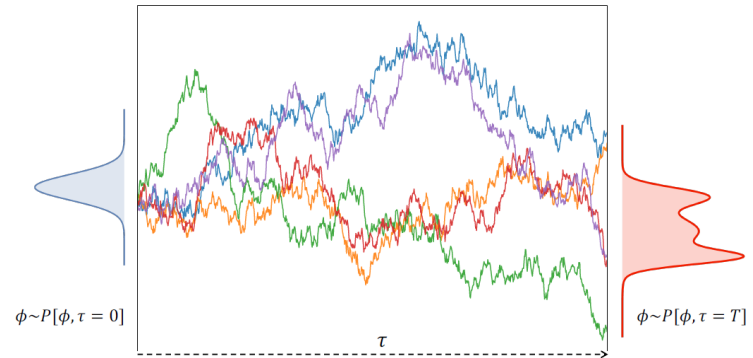
$$\frac{\partial \phi(x, \tau)}{\partial \tau} = -\frac{\delta S_E[\phi]}{\delta \phi(x, \tau)} + \eta(x, \tau) \quad \langle \eta(x, \tau) \rangle = 0, \quad \langle \eta(x, \tau) \eta(x', \tau') \rangle = 2\alpha \delta(x - x') \delta(\tau - \tau')$$

- **Fokker-Planck equation** $\frac{\partial P[\phi, \tau]}{\partial \tau} = \int d^n x \left\{ \frac{\delta}{\delta \phi} \left(\alpha \frac{\delta}{\delta \phi} + \frac{\delta S_E}{\delta \phi} \right) \right\} P[\phi, \tau]$

long time equilibrium limit $P_{\text{eq}}[\phi] \propto e^{-\frac{1}{\alpha} S_E[\phi]}$

- **Observables** $\langle \mathcal{O}[\phi] \rangle_\tau = \int D\phi \mathcal{O}[\phi] P[\phi, \tau]$

$$\langle \mathcal{O}[\phi] \rangle_{\tau \rightarrow \infty} = \frac{\int D\phi \mathcal{O}(\phi) e^{-\frac{1}{\hbar} S_E(\phi)}}{\int D\phi e^{-\frac{1}{\hbar} S_E(\phi)}} = \langle \mathcal{O}[\phi] \rangle_{\text{quantum}}$$



- Forward diffusion SDE

$$\frac{d\phi}{d\xi} = f(\phi, \xi) + g(\xi)\eta(\xi) \quad \langle \eta(\xi)\eta(\xi') \rangle = 2\alpha\delta(\xi - \xi')$$

- Backward diffusion SDE

$$\frac{d\phi}{dt} = [f(\phi, t) - g^2(t)\nabla_{\phi} \log p_t(\phi)] + g(t)\bar{\eta}(t) \quad t \equiv T - \xi$$

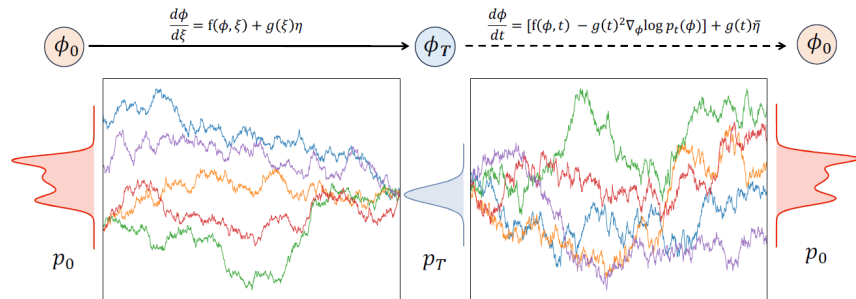
- Score match training

$$\mathcal{L}_{\theta} = \sum_{i=1}^N \sigma_i^2 \mathbb{E}_{p_0(\phi_0)} \mathbb{E}_{p_i(\phi_i|\phi_0)} \left[\|s_{\theta}(\phi_i, \xi) - \nabla_{\phi_i} \log p_i(\phi_i|\phi_0)\|_2^2 \right]$$

$$p_{\xi}(\phi_{\xi}|\phi_0) = \mathcal{N}\left(\phi_{\xi}; \phi_0, \frac{1}{2 \log \sigma} (\sigma^{2\xi} - 1) \mathbf{I}\right)$$

- Sample generation SDE

$$\frac{d\phi}{dt} = [f(\phi, t) - g^2(t)s_{\hat{\theta}}(\phi, t)] + g(t)\bar{\eta}(t).$$



- Backward diffusion SDE in **variance expanding** scheme (i.e., vanishing drift in Forward)

$$\frac{d\phi}{dt} = -g(t)^2 \nabla_{\phi} \log p_t(\phi) + g(t) \bar{\eta}(t)$$

- Redefine time $\tau \equiv T - t$ and denoting $g_{\tau} = g(T - \tau)$, $q_{\tau}(\phi) = p_{T-\tau}(\phi)$

$$\frac{d\phi}{d\tau} = g_{\tau}^2 \nabla_{\phi} \log q_{\tau}(\phi) + g_{\tau} \bar{\eta}(\tau) \quad \phi(\tau_{n+1}) = \phi(\tau_n) + g_{\tau_n}^2 \nabla_{\phi} \log q_{\tau_n}[\phi(\tau_n)] \Delta\tau + g_{\tau_n} \sqrt{\Delta\tau} \bar{\eta}(\tau_n)$$

- The corresponding Fokker-Planck equation and equilibrium

$$\frac{\partial p_{\tau}(\phi)}{\partial \tau} = \int d^n x \left\{ g_{\tau}^2 \frac{\delta}{\delta \phi} \left(\bar{\alpha} \frac{\delta}{\delta \phi} + \nabla_{\phi} S_{\text{DM}} \right) \right\} p_{\tau}(\phi), \quad \nabla_{\phi} S_{\text{DM}} \equiv -\nabla_{\phi} \log q_{\tau}(\phi) \quad p_{\text{eq}}(\phi) \propto e^{-S_{\text{DM}}/\bar{\alpha}}$$

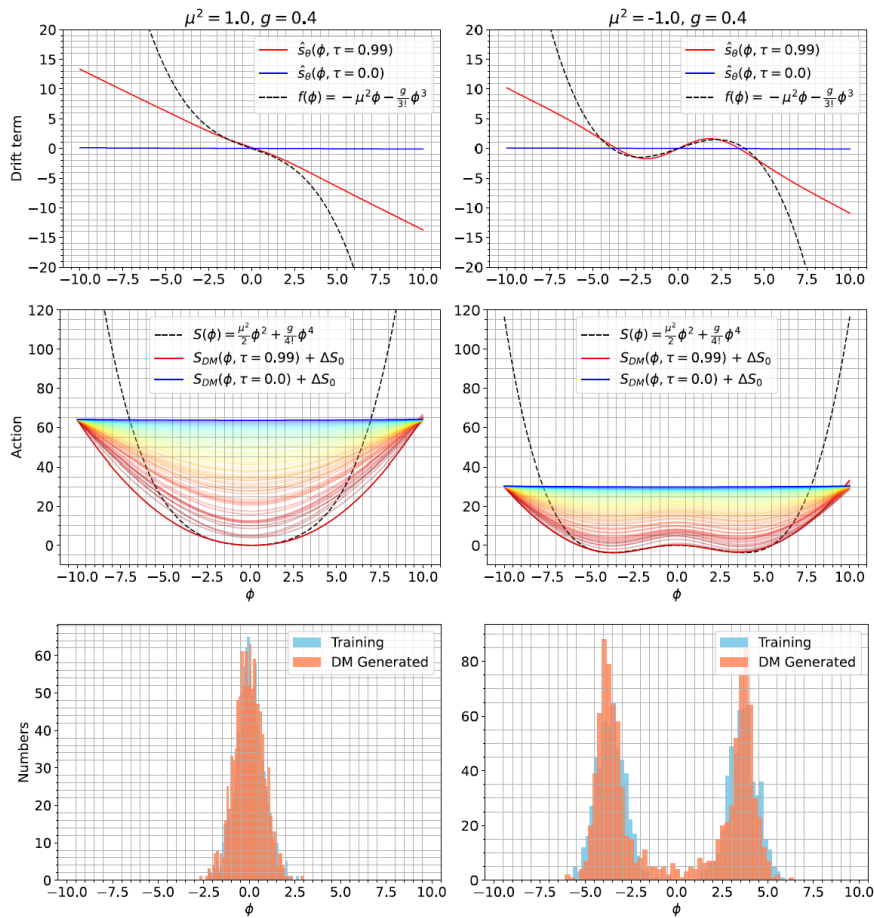
- A flow of effective action will be learned in DMs

$$p_{\tau=T}(\phi) \rightarrow P[\phi, T]$$

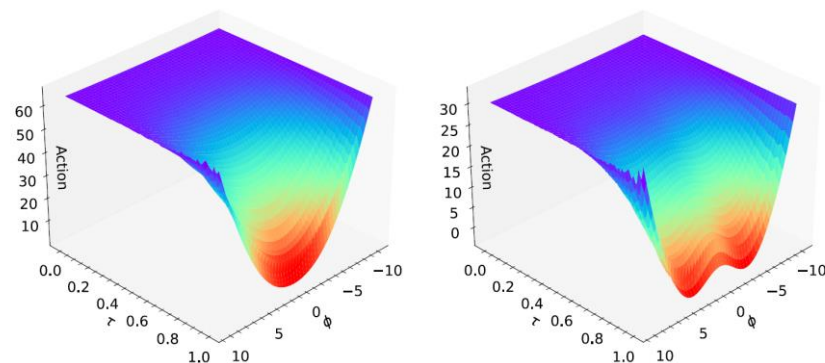
sampling from a DM is equivalent to optimizing a stochastic trajectory to approach the “equilibrium state”

$$O(\bar{\alpha}) \sim O(\hbar)$$

Effective Action on toy model



● Flow of an effective action



- Consider a real scalar field with action:

$$S = \int d^d x dt \mathcal{L} = \int d^d x dt \left(\frac{1}{2} (\partial^2 \phi_0^2 - m^2 \phi_0^2) - \frac{\lambda_0}{4!} \phi_0^4 \right),$$

- In Euclidean space, the discretized action with dimension less form:

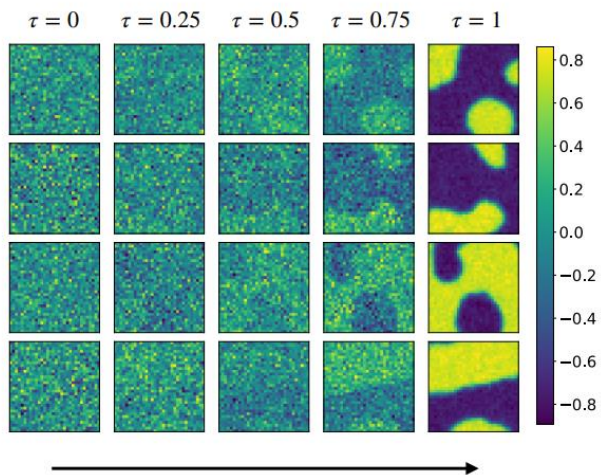
$$S_E = \sum_x \left[-2\kappa \sum_{\mu=1}^d \phi(x) \phi(x + \hat{\mu}) + (1 - 2\lambda) \phi(x)^2 + \lambda \phi(x)^4 \right].$$

$$a^{\frac{d-2}{2}} \phi_0 = (2\kappa)^{1/2} \phi, (am_0)^2 = \frac{1 - 2\lambda}{\kappa} - 2d, a^{-d+4} \lambda_0 = \frac{6\lambda}{\kappa^2},$$

- Broken phase and symmetric phase

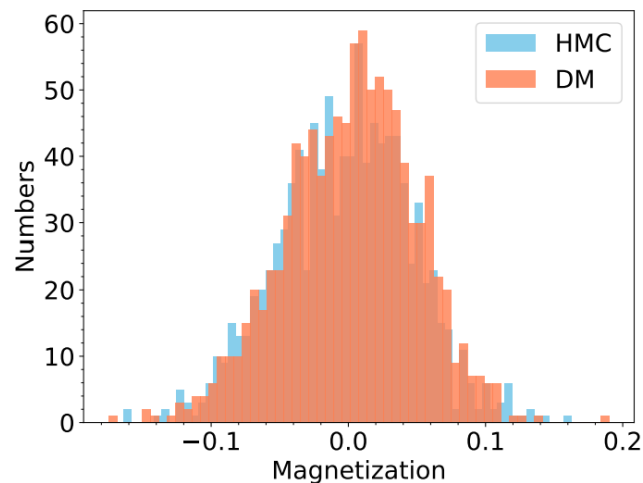
$$\kappa_c(\lambda) = \frac{1 - 2\lambda}{2d}.$$

- 2d 32x32 lattice size, HMC generated 5120 configurations for training
- Broken phase :



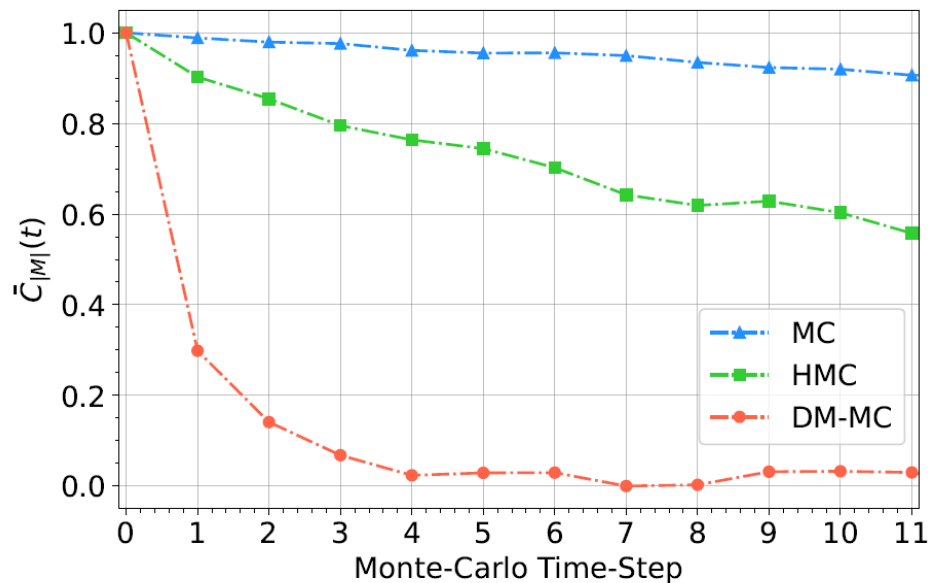
numerous “bulk” patterns emerge

symmetric phase :

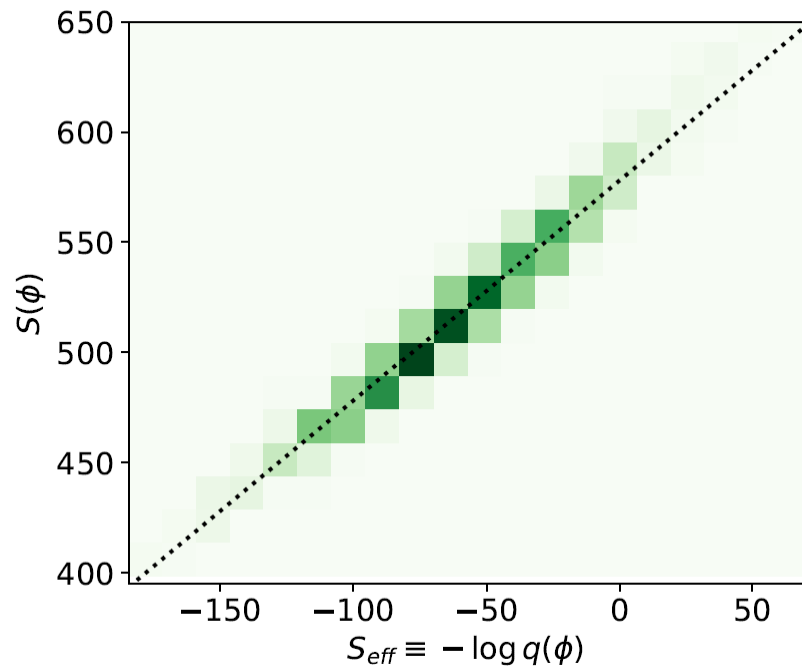


data-set	$\langle M \rangle$	χ_2	U_L
Training (HMC)	0.0012 ± 0.0007	2.5160 ± 0.0457	0.1042 ± 0.0367
Testing (HMC)	0.0018 ± 0.0015	2.4463 ± 0.1099	-0.0198 ± 0.1035
Generated (DM)	0.0017 ± 0.0015	2.4227 ± 0.1035	0.0484 ± 0.0959

Results: Autocorrelation time and final captured eff action



validation R2 ~0.96



- Forward diffusion kernel: gaussian smoothing

$$p_{\xi}(\phi_{\xi}|\phi_0) = \mathcal{N}\left(\phi_{\xi}; \phi_0, \frac{1}{2 \log \sigma}(\sigma^{2\xi} - 1)\mathbf{I}\right)$$

$$\phi_{\tau}(\mathbf{x}) = \phi_0(\mathbf{x}) + \sqrt{\frac{\sigma^{2\tau} - 1}{2 \log \sigma}} \epsilon(\mathbf{x}) \text{ with } \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

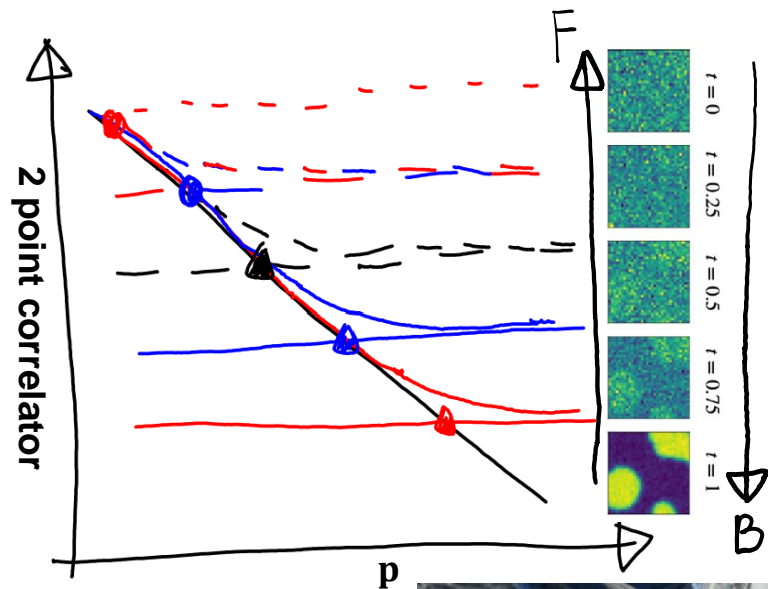
- In Fourier space:

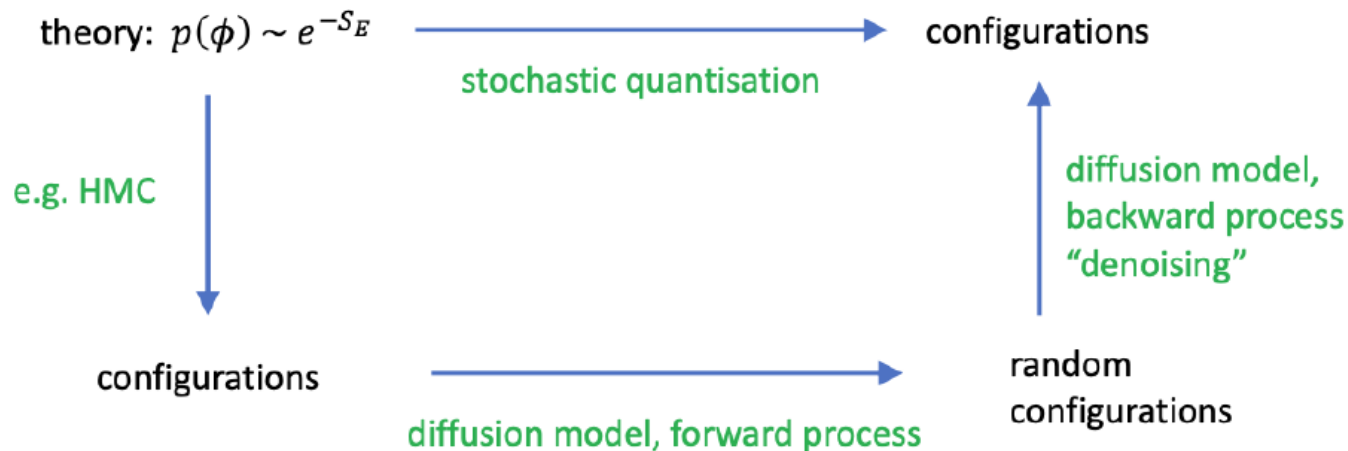
$$\phi_{\tau}(p) = \phi_0(p) + \sqrt{\frac{\sigma^{2\tau} - 1}{2 \log \sigma}} \epsilon(p).$$

- ! the above evolution will perturb (smear) higher momentum modes faster because of the gradually increasing noise level

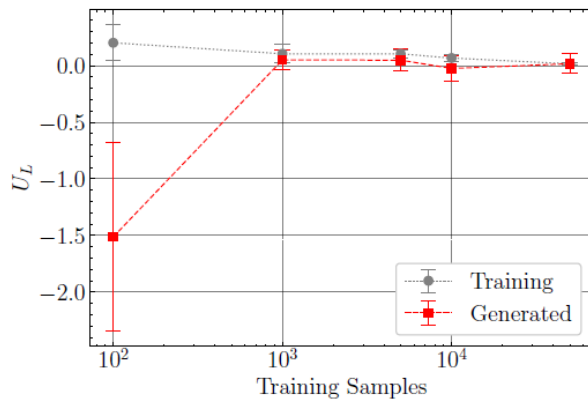
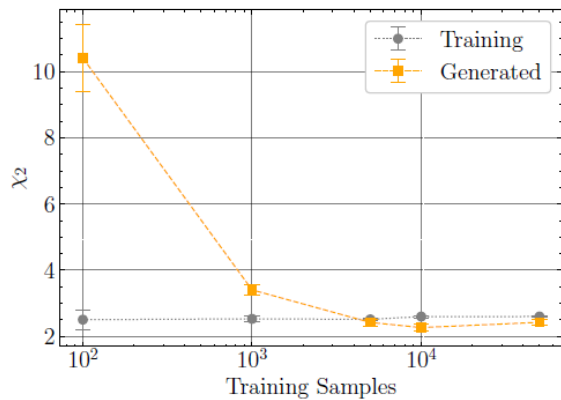
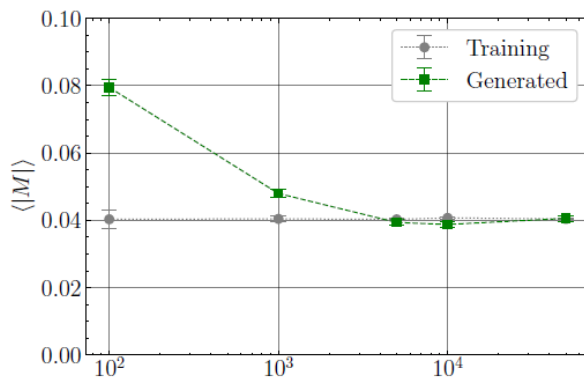
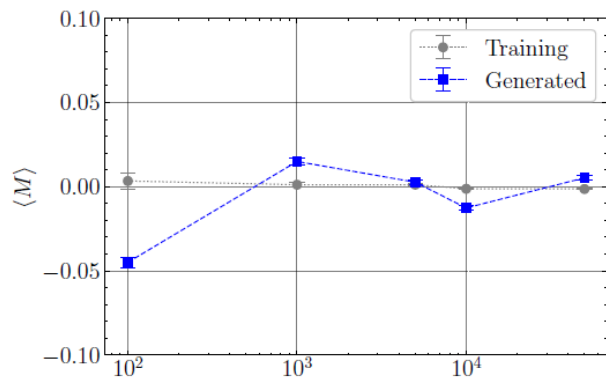


In **FRG**, the high frequency (short-distance) degrees of freedom is progressively integrated out !
See Semon's and Mathis's talk!





Training efficiency



Acceptance rate

