Machine Learning and the Renormalization Group

May 27–31, 2024 ECT*



Supporting institutions

STRUCTURES CLUSTER OF

Building Interactions with Deep Autoregressive Networks

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Collaborators: Lianyi He(THU), Yin Jiang and Tian Xu(Beihang Uni.), Kai Zhou(CUHK-Shenzhen/FIAS),...

ArXiv: 2007.01037, 2405.10493, 24xx.xxxx

May 31, 2024, "Machine Learning and Renormalization Group" Workshop, ECT*



理化学研究所 数理創造プログラム RIKEN Interdisciplinary Theoretical and Mathematical Sciences Program

ences Program

RIKEN-ITHENS

RIKEN iTHEMS Interdisciplinary Theoretical and

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https://ithems.riken.jp/

March 1, 2024



L. Wang

Theorists in mathematics, biology physics, chemistry, **comp/info sciences** under one-roof

since Nov.1, 2016





ithem.s



<u>About iTHEMS</u> / <u>Working Groups</u> / DEEP-IN Working Group

DEEP-IN Working Group

"DEEP learning for INverse problems (DEEP-IN) in Sciences" working group (April 1st, 2024 -)

DEEP-IN Working Group Website

Objectives

The essence of discovery in sciences has always been rooted in the reverse engineering of natural phenomena and observational data. This paradigm of deducing the underlying laws of nature from observable outcomes forms the cornerstone of our scientific inquiry. The DEEP-IN working group is established with the recognition that the elucidation of such complex phenomena demands a fusion of physics insights and advanced deep learning methodologies. Historically, the exploration of sceinces has relied heavily on intuition and empirical exploration, with methods like inference playing a significant role in our understanding.

Facilitators:

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- Neural Network as Universal Emulator
- Learn from Observations
 - Building Microscopic Interactions
 - Autoregressive Networks
- **Classical Systems** \bullet
 - Ferromagnetic Phase Transition
 - Topological Phase Transition
- Quantum Systems
- Outlooks

Outline





Machine Learning and Physics



Phys.Rev. Lett. 124, 010508 (2020)



Data, X

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Machine, $\{\theta\}$



An inverse problem in science is the process of inferring from a set of observations the causal factors that produced them.



Prediction

Estimation



Machine Learning and Inference









Neural Network as Universal Emulator



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Neural Network as Universal Emulator



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Neural Network as Universal Emulator



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•K. Zhou, L. Wang, L.-G. Pang, and S. Shi, Prog. Part. Nucl. Phys. 135, 104084 (2023).

•K. Cranmer, **G. Kanwar,** S. Racanière, D. J. Rezende, and P. E. Shanahan, Nat Rev Phys 1 (2023).

•G. Carleo, etc., Rev. Mod. Phys. 91, 045002 (2019).

•V. Dunjko and H. J. Briegel, Rep. Prog. Phys. 81, 074001 (2018).



Can We Learn Microscopic Interactions From Observations Directly?

Learn Microscopic Interactions



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Autoregressive Networks

$$p_{\theta}(s) = \prod_{i=1}^{N} p(s_i | s_1, \dots, s_{i-1})$$

• Example (L=3) for 1D spin model

$$p_{\theta}(s) = p(s_3 | s_2, s_1) p(s_2 | s_1) p(s_1)$$

• $p(s_i | s_{< i})$ can be any naive distribution

Bernoulli distribution for Ising model $p(s_i | s_{< i}) = q_i \delta_{s_i, +1} + (1 - q_i) \delta_{s_i, -1}$ $q_1 = f(s_1 = +1), q_2 = f(s_2 = +1 | s_1), q_3 = f(s_3 = +1 | s_2, s_1)$

discrete *d.o.f.*s

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<u> Chinese Phys. Lett. 39, 120502 (2022)</u> Beta distribution for continuous *d.o.f.*, $X \sim Beta(a, b)$ $p_{\theta}(s_i | s_1, \dots, s_{i-1}) = \frac{\Gamma(a_i + b_i)}{\Gamma(a_i)\Gamma(b_i)} s_i^{a_i - 1} (1 - s_i)^{b_i - 1}$ $\Gamma(a)$ is gamma function, $s_i = \theta_i/2\pi \in [0,1), (a_i, b_i) > 0$

continuous *d.o.f.*s



Autoregressive Networks

$$p_{\theta}(s) = \prod_{i=1}^{N} p(s_i | s_1, \dots, s_{i-1})$$

Network is parametrized by a triangular matrix L, which ensures that s_i is independent with s_j when $j \ge i$. This is named as autoregressive property in machine learning.

Gaussian scalar field RBM



• induced distribution on visible layer

$$p(\phi) = \int Dh \, p(\phi, h) = \frac{1}{Z} \exp\left(-\frac{1}{2} \sum_{i,j} \phi_i K_{ij} \phi_j + \sum_i J_i \phi_i\right)$$

 \circ scalar field with kinetic (all-to-all) term $K_{ij} = \mu_i^2 \delta_{ij} - \sigma^2 \sum_i w_{ia} w_{aj}^T$

and source $J_i = \sum_a w_{ia} \eta_a$

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• unusual Gaussian LFT: what is the weight matrix W and bias η ?

Gert's slides@XQCD2023

arXiv:2007.01037



$$WW^T = rac{1}{\sigma^2} \left(\mu^2 \mathbb{1} - K^\phi \right) \equiv \mathcal{K}$$

Exact results for $N_h = N_\nu$

(infinitely) many solutions for weight matrix: \mathcal{K} is symmetric and positive-definite

- 1. Cholesky decomposition $\mathcal{K} = LL^T$: W = L triangular
- 2. diagonalisation $\mathcal{K} = ODO^T = O\sqrt{D}O^TO\sqrt{D}O^T$: $W = W^T = O\sqrt{D}O^T$
- 3. non-uniqueness: internal symmetry $W \to WO_R \rightarrow \phi^T W h \to \phi^T W O_R h = \phi^T W h'$

in practice

- o all equally valid, realisation depends on initialisation
- non-observable degeneracy due to internal symmetry on hidden layer





Autoregressive Networks

$$p_{\theta}(s) = \prod_{i=1}^{N} p(s_i | s_1, \dots, s_{i-1})$$

• Example (L=3) for 1D spin model

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$$p_{\theta}(s) = p(s_3 | s_2, s_1) p(s_2 | s_1) p(s_1)$$

• $p(s_i | s_{< i})$ can be any naive distribution

G. Aarts, B. Lucini, and C. Park, Scalar Field Restricted Boltzmann Machine as an Ultraviolet Regulator, Phys. Rev. D 109, 034521 (2024).

arXiv:2007.01037



Autoregressive networks are variants of RBM with $N_h = N_v$ and triangular weight matrix!

no "UV cut-off"





Learning Interactions

$$\max_{\theta} \prod_{i=1}^{N} p_{\theta}(\mathbf{s}_i)$$

- 1. Prepare data-set from observations
 - $\mathbf{s} \sim q$ data
- 2. Put them into the deep autoregressive network(DAN)

$$p_{\theta}(\mathbf{s}) = \prod_{i=1}^{N} p(s_i | s_1, \dots, s_{i-1}, \theta)$$

3. Minimize the negative log-liklihood(NLL)

$$\mathcal{L} = -\sum_{\mathbf{s} \sim q_{data}} \sum_{d=1}^{N} \log(p(s_d | \mathbf{s}_{< d}, \theta))$$

4. Get your DAN represented Hamiltonian

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$$H_{\theta}(\mathbf{s}, T) = -T \ln p_{\theta}(\mathbf{s})$$





on specific degrees of freedom(*d.o.f.s*)







What Can We Do With Neural Network Interactions?

Detect Phase Transitions



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Experiments









1.2D Ising Model



Masked Autoencoder for Distribution Estimation (MADE)

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$$H(\mathbf{s}) = -\sum_{\langle i,j \rangle} s_i s_j$$





1.2D Ising Model



<u>arXiv:2007.01037</u>



Stride = 1

Stride = 2

 2×2 spin-block





2. Ferromagnetic Materials



3000 images

Resolution: 0.5 µm



PhysRevLett.125.027206

with Le Zhao and Wan-Jun Jiang

Magneto-optic Kerr effect (MOKE) microscope to capture images for the magnetic domains appearing inside a Ta/CoFeB/TaO_x thin film at room temperature T = 296 K

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2. Ferromagnetic Materials



with Le Zhao and Wan-Jun Jiang

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2. Ferromagnetic Materials





PhysRevLett.125.027206

3000 images

$\overline{T [\mathrm{K}]}$	50	100	150	200	250	300
$\overline{M_{\rm s} [{\rm emu/cc}]}$	961.16	925.25	877.73	818.17	753.31	673.427

$$M_s(T) = M_s(0)(1 - T/T_C)^{1/3}$$

$$T_C = 427.4 \pm 2.9 \text{ K}$$

In preparation





Topological Phase Transitions

3. 2D XY Model



9000 training configurations with L = 16

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In preparation





Topological Phase Transitions

3. 2D XY Model



9000 training configurations with L = 16

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from CANs

$$\delta q_{[i,j]} \equiv \sum_{[i,j]} q_{\theta}(s_{ij})$$

 $v = (1/2\pi) \oint_C \nabla \phi(\boldsymbol{r}) \cdot d\boldsymbol{r}$

 $q_{\theta}(s_{ii})$ conditional probability differences in the same given direction





Can It Still Work for Quantum Systems?

Finite-Temperature Fields

$$Z = \int D\Phi \exp(-S[\Phi])$$

$$S[\Phi] = \sum \Delta \tau (\Delta x)^3 [(\frac{\Delta \Phi}{\Delta \tau})^2 + (\nabla \Phi)^2 + V(\Phi)]$$
$$= \sum (\Delta x)^3 \left[\frac{(\Delta \Phi)^2}{\Delta \tau} + \Delta \tau ((\nabla \Phi)^2 + V(\Phi)) \right]$$
$$= \beta^{-1} K + \beta V$$

$$\Delta \tau = \beta / N_{\tau}$$

$$K \equiv N_{\tau} \sum (\Delta x)^{3} (\Delta \Phi)^{2}$$
$$V \equiv N_{\tau}^{-1} \sum (\Delta x)^{3} [(\nabla \Phi)^{2} + V(\Phi)]$$

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$$S_1[\Phi] = \beta_1^{-1} K[\Phi] + \beta_1 V[\Phi] + C_1$$
$$S_2[\Phi] = \beta_2^{-1} K[\Phi] + \beta_2 V[\Phi] + C_2,$$

$$S_{3}[\Phi] = \frac{\beta_{1}(\beta_{3}^{2} - \beta_{2}^{2})}{\beta_{3}(\beta_{1}^{2} - \beta_{2}^{2})}S_{1} + \frac{\beta_{2}(\beta_{1}^{2} - \beta_{3}^{2})}{\beta_{3}(\beta_{1}^{2} - \beta_{2}^{2})}S_{2} + C_{3}$$

$$C_3 = \frac{\beta_1(\beta_2^2 - \beta_3^2)}{\beta_3(\beta_1^2 - \beta_2^2)}C_1 + \frac{\beta_2(\beta_3^2 - \beta_1^2)}{\beta_3(\beta_1^2 - \beta_2^2)}C_2$$





Action Estimation

4.0+1 D Quantum Field

$$\mathscr{L} = \frac{1}{2} \left(\frac{dx}{d\tau}\right)^2 + V_k(x) \qquad \qquad V_k(x) = \frac{\lambda_k}{4} \left(x^2 - \frac{\mu_k^2}{2k}\right)^2$$

$$Z = \int_{x(\beta)=x(0)} Dx \ e^{-S_E[x(\tau)]}$$
$$= \int_{j=-N+1}^{N+1} \frac{dx_j}{\sqrt{2\pi a}} \times \exp\left\{-\sum_{i=-N+1}^{N+1} \left[\frac{(x_{i+1}-x_i)^2}{2a} + aV_k(x_i)\right]\right\}$$

$$S_E[x(\tau)] = \int_0^\beta d\tau \ \mathscr{L}_E[x(\tau)] = \int_0^\beta d\tau \ \left[\frac{1}{2}\left(\frac{dx}{d\tau}\right)^2 + V_k(x)\right]$$

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arXiv:2405.10493

$$x(\tau) = \pm \frac{\mu_k}{\sqrt{\lambda_k}} \tanh \left[\frac{\mu_k}{\sqrt{2}} (\tau - \tau_0) \right]$$

Kink/Anti-Kink solutions reach $\pm \mu_k / \sqrt{\lambda_k}$ at $\tau = \pm \infty$

Numerical Simulations

$$\lambda_k = 4$$
 $\mu_k / \sqrt{\lambda_k} = 1.4$

 $\beta = T^{-1} = 80,40,20$ $N_{MC} = 5 \times 10^6$



Action Estimation



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Action Prediction



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ML and RG, **ECT*** 2024

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Action Prediction



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Action Prediction



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Summary

- **Building Interactions with DNNs** \bullet
 - Boltzmann Factor as Prior \bullet
 - Density Estimation \bullet
 - Autoregressive Networks
- Applications
 - **Detecting Phase Transitions** \bullet
 - Ferromagnetic PT
 - Topological PT
 - Estimating and Predicting Actions
 - 0+1 dimensional FTQT
- **Future works** \bullet
 - Finite-density quantum fields
 - Building effective interactions from macroscopic observations -> Renormalization Group ?!







Thank You !

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Samuel Velasco @Quanta Mag

Detecting Symmetries

Z2 flip for 2D Ising model

$H_{ANN}(\hat{O}\mathbf{S}) \stackrel{?}{=} H_{ANN}(\mathbf{S})$

$\overline{\theta}$	$[2\pi]$	0	0.2	0.4	0.6	0.8	1
\overline{H}	$\overline{f}_{\mathrm{ANN}}(heta \mathbf{s})$	-1.2397	-1.2394	-1.2406	-1.2413	-1.2417	-1.2397

O(2) rotation for 2D XY model

Virtual operations on observations to test learned neural network interactions

Backups - Ising Models

$$H(\mathbf{s}) = -\sum_{\langle i,j \rangle} s_i s_j$$
$$S_{I,J} = s_{i,j} + s_{i+1,j} + s_{i,j+1} + s_{i+1,j+1}$$
$$i = 1 + d(I-1), j = 1 + d(J-1)$$

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Backups - Important Sampling

9000 training configurations with L = 16

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Chinese Phys. Lett. 39, 120502 (2022)

$$\langle O \rangle = \int O(\mathbf{s})(p(\mathbf{s})/q_{\theta}(\mathbf{s}))q_{\theta}(\mathbf{s})d\mathbf{s}$$

$$\langle O \rangle \simeq \sum_{\mathbf{s} \sim q_{\theta}(\mathbf{s})} O(\mathbf{s}) w(\mathbf{s})$$

$$w(\mathbf{s}) = (p(\mathbf{s})/q_{\theta}(\mathbf{s}))/A$$

$$A = \sum_{\mathbf{s} \sim q_{\theta}(\mathbf{s})} p(\mathbf{s}) / q_{\theta}(\mathbf{s})$$

Continious Spin Configurations

Autoregressive Networks model Likelihood $q_{\theta}(s)$ explicitly

Optimization

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Minimizing loss function

Variational free energy

$$F_q = \sum_{s} q_{\theta}(s)(E(s) + (\ln q_{\theta}(s))/\beta)$$

Kullback-Leibler (KL) divergence

$$D_{KL}(q_{\theta} | | p) = \sum_{s} q_{\theta}(s) ln(\frac{q_{\theta}(s)}{p(s)}) = \beta(F_q - F) \ge 0$$

Chinese Phys. Lett. 39, 120502 (2022)

