

Apples to Apples in Jet Quenching

New jet quenching tools
ECT* - Trento

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In collaboration with
Guilherme Milhano

LIP - Lisboa
IST - ULisboa

February 16, 2024



ECT*
EUROPEAN CENTRE
FOR THEORETICAL STUDIES
IN NUCLEAR PHYSICS AND RELATED AREAS



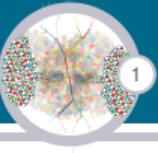
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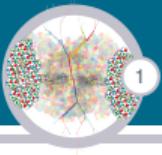
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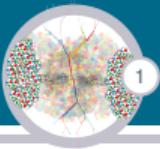
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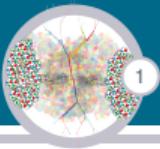
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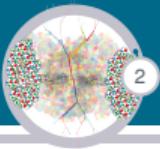
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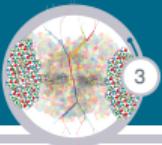
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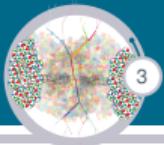
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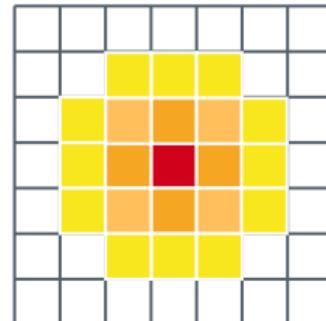
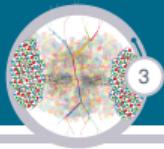
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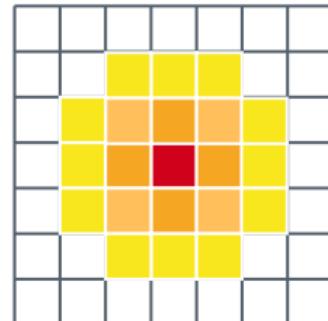
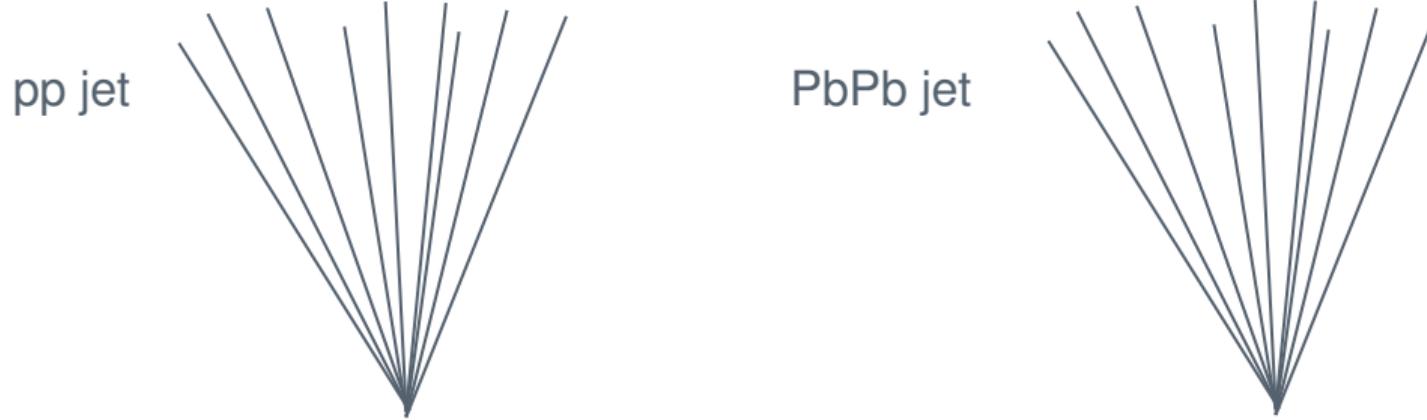
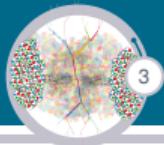
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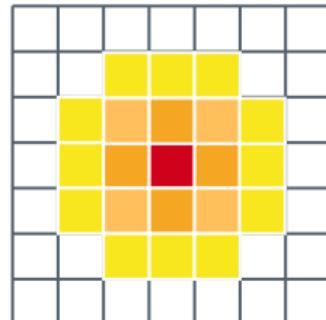
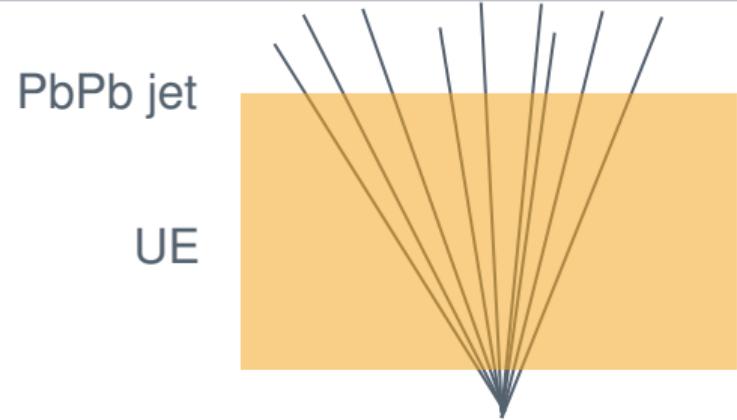
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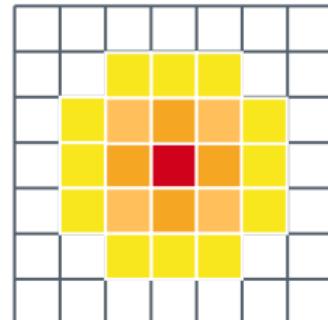
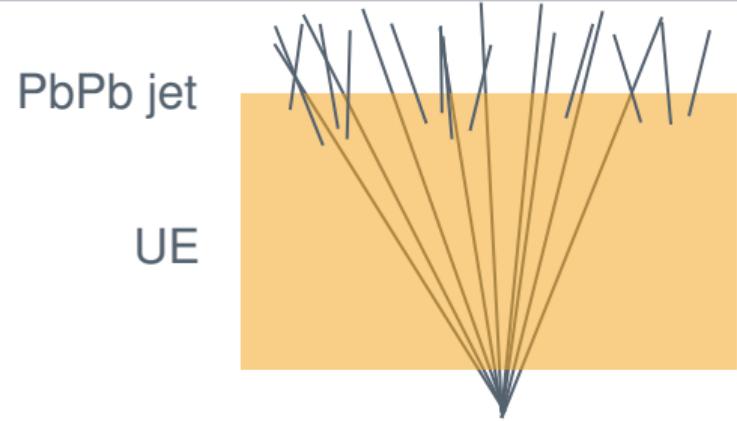
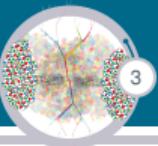
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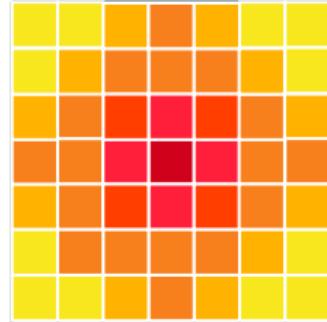
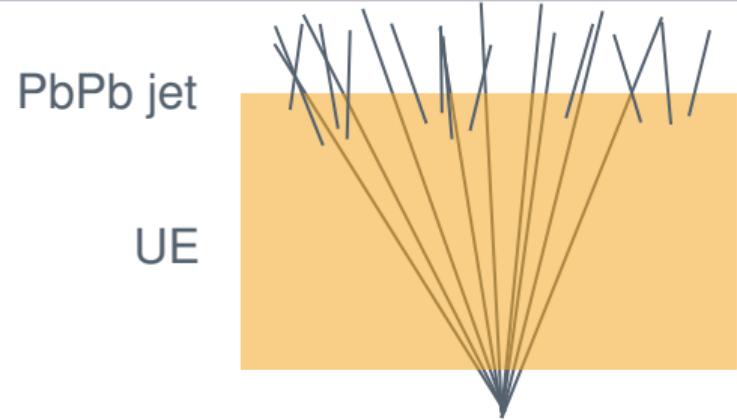
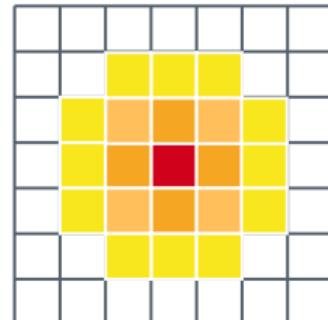
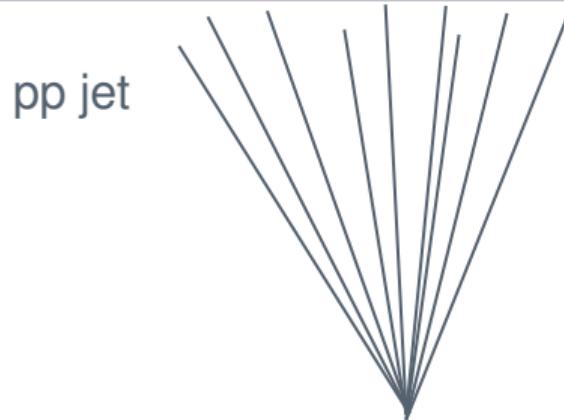
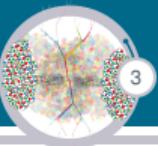
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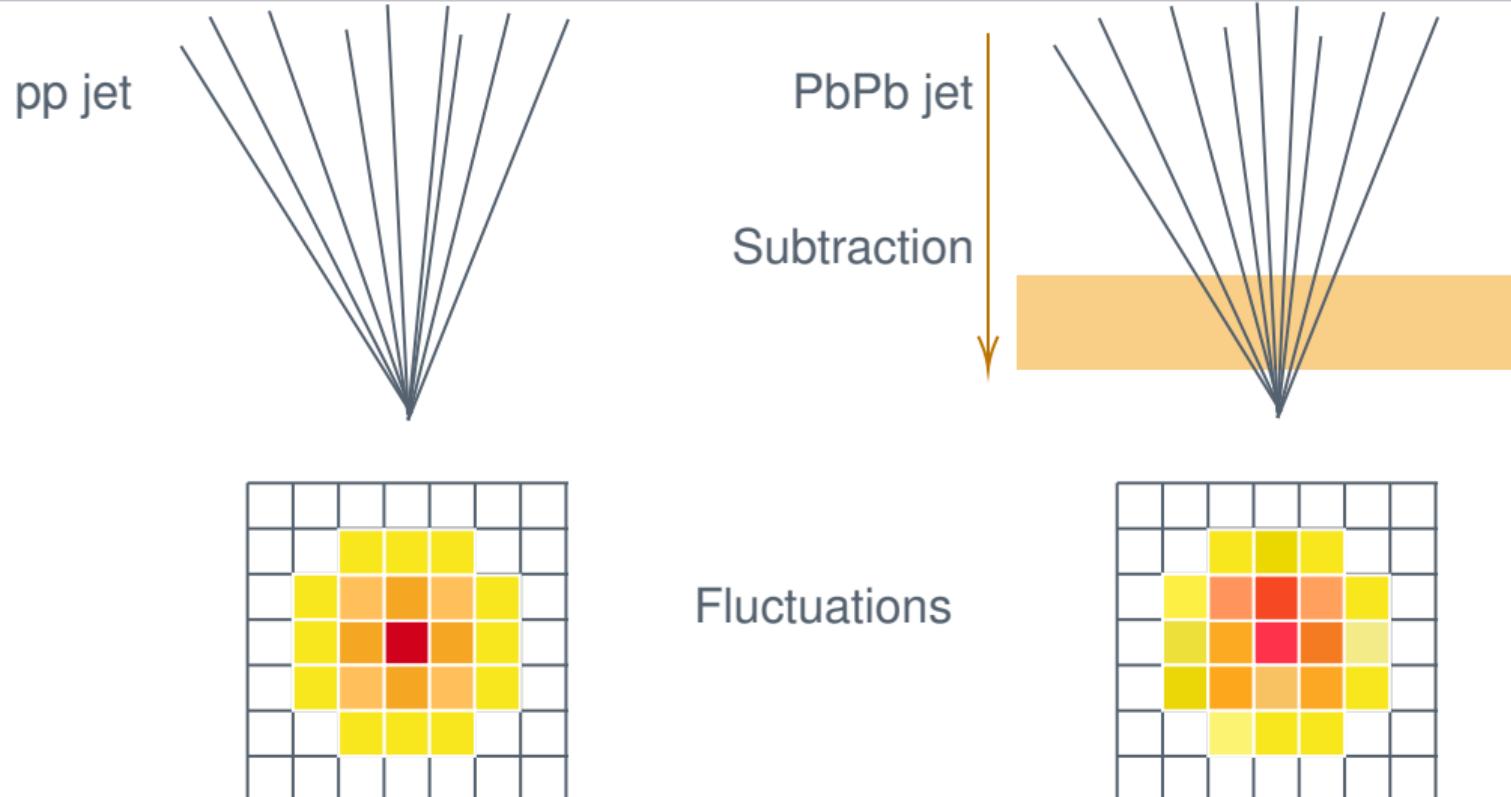
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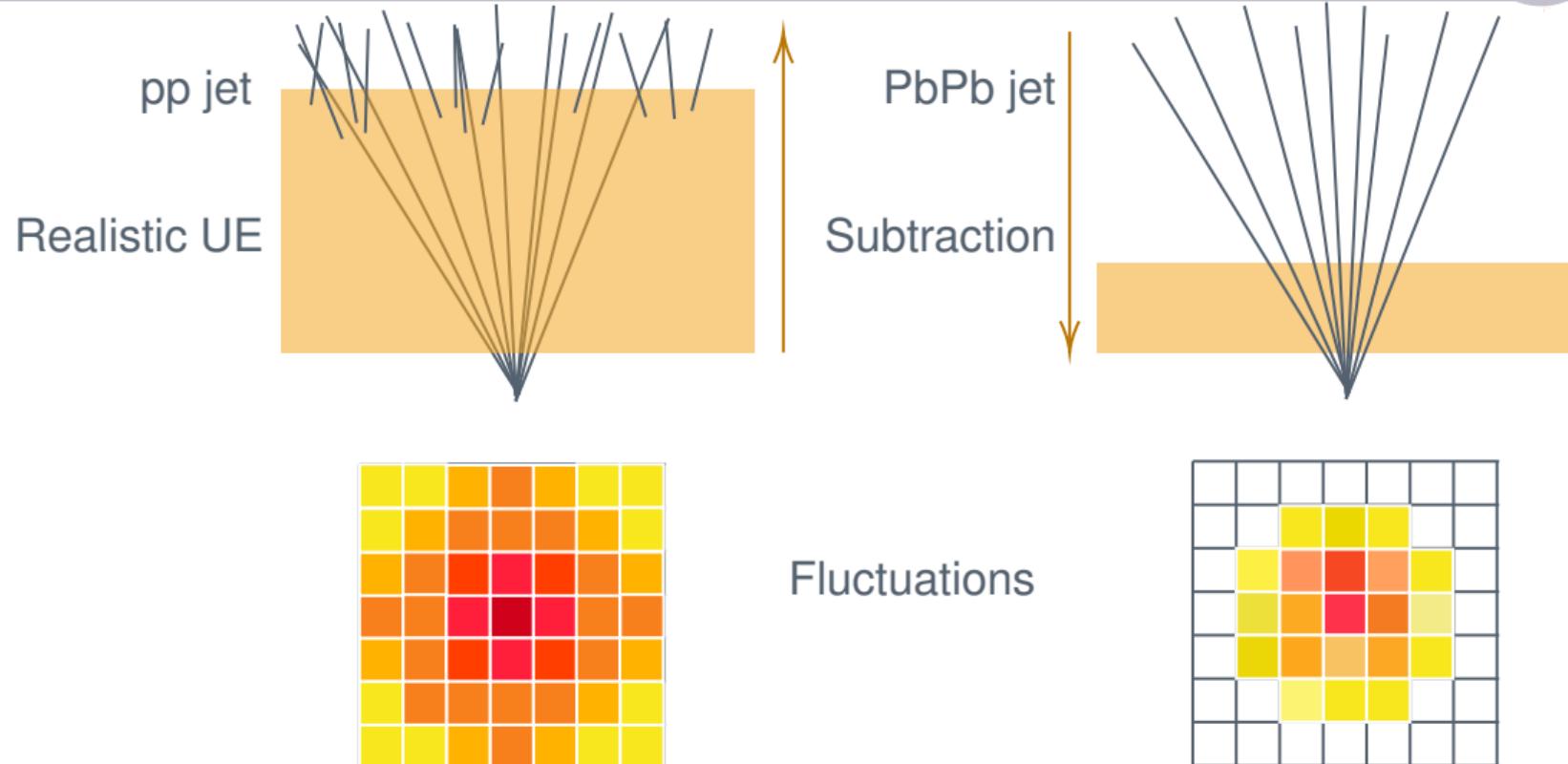
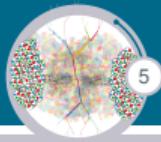
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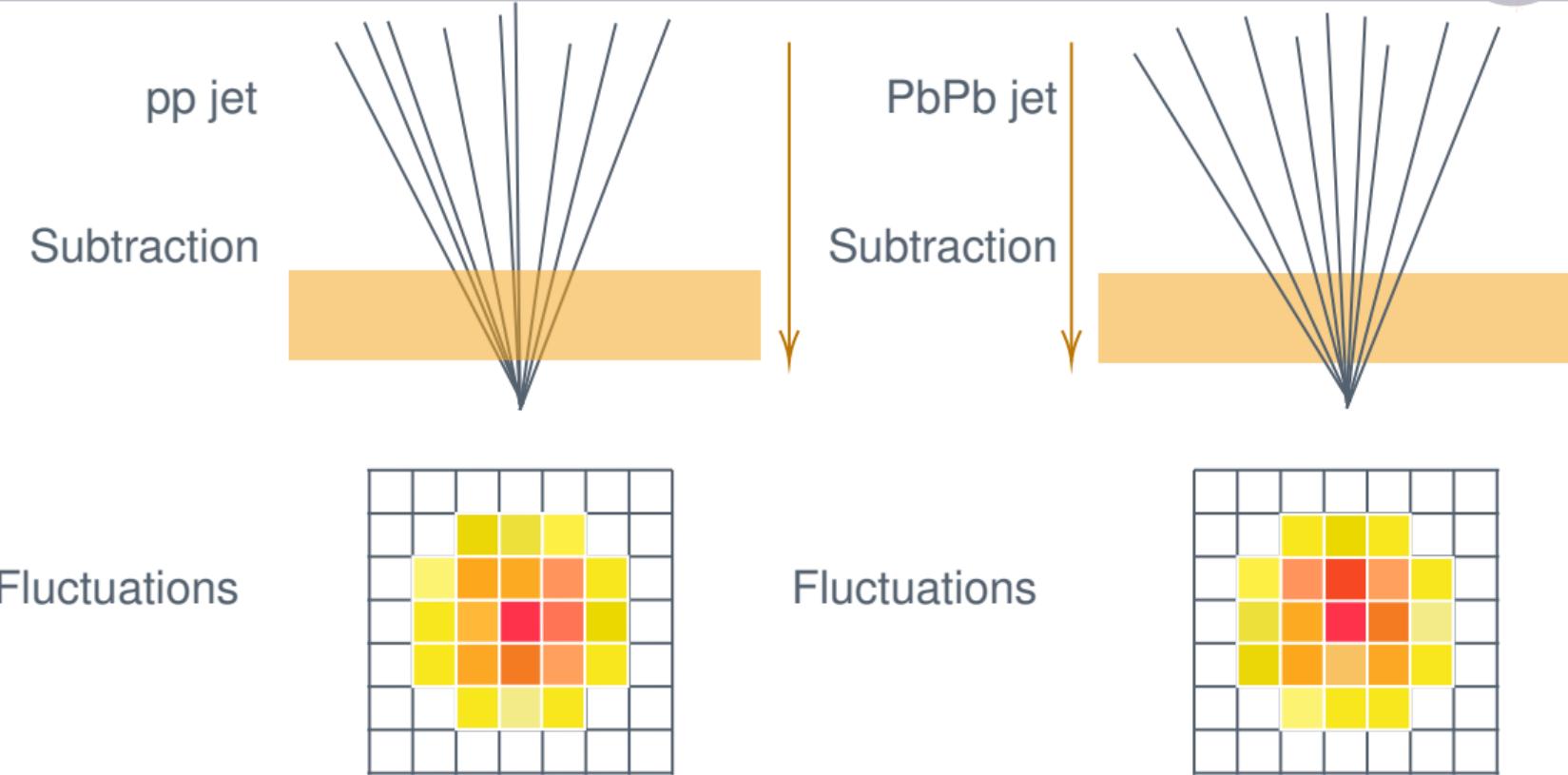
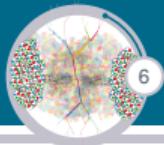
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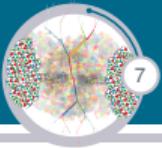


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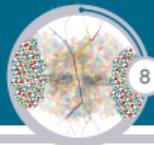
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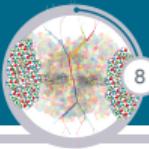
Generation and Reconstruction Details



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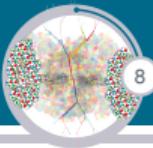


Generation Details

Process	dijets
Centrality	[0, 10]%
τ_i	= 0.4
T_i	= 590 MeV
$\sqrt{s_{NN}}$	= 5.02 TeV
\hat{p}_t	> 50 GeV
$ \eta $	< 4

Analysis Details

Generation and Reconstruction Details



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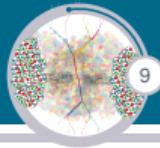
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Reconstruction Details

p_t^{part}	>	100 MeV
$ \eta^{part} $	<	4
Jets		0.4 anti_ kt
$ \eta^{jets} $	<	3
$\Delta\phi$	<	$5\pi/6$
p_t^{lead}	>	120 GeV
$p_t^{sublead}$	>	50 GeV

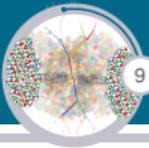
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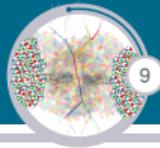


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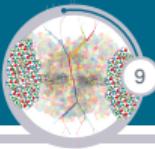
Experimentally motivated UE generation steps:



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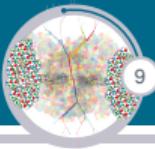
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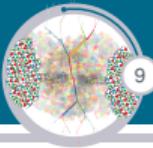
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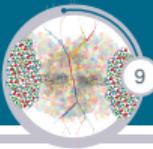


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4. Take the number of particles per UE to follow a Gaussian distribution of experimentally motivated average value and standard deviation.

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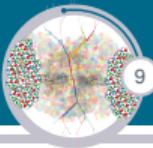


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5. For each particle to be generated, sample a value for p_T , η and ϕ from the considered distributions.

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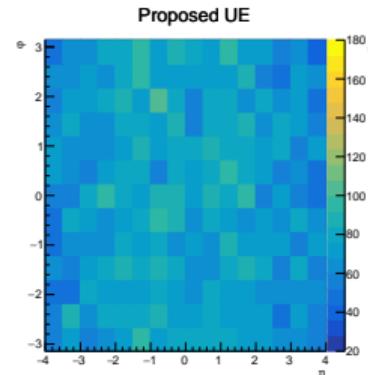
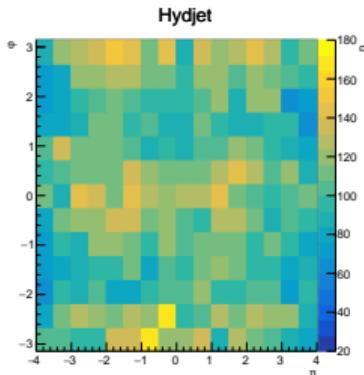
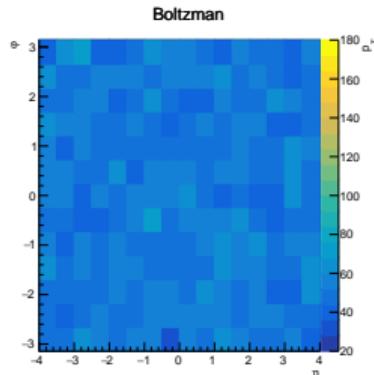
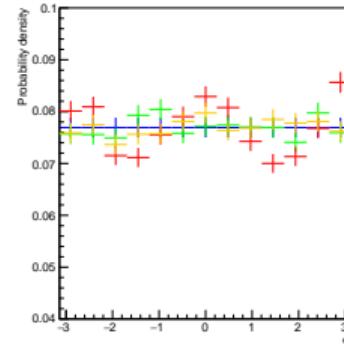
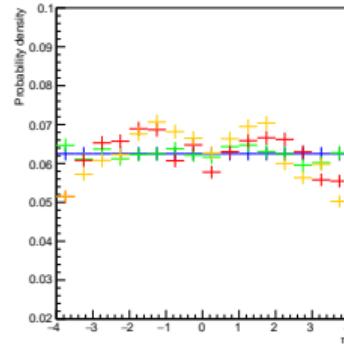
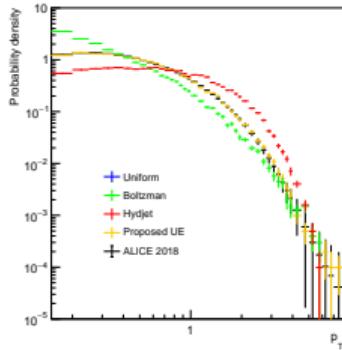
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4. Take the number of particles per UE to follow a Gaussian distribution of experimentally motivated average value and standard deviation.
5. For each particle to be generated, sample a value for p_T , η and ϕ from the considered distributions.
6. Considering only pions, sample randomly and uniformly one of the three species, and use its mass to complete the four-momentum of the particle.

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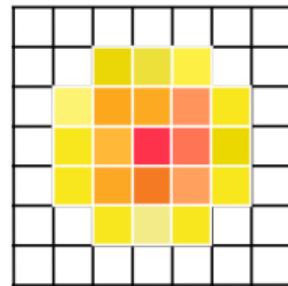
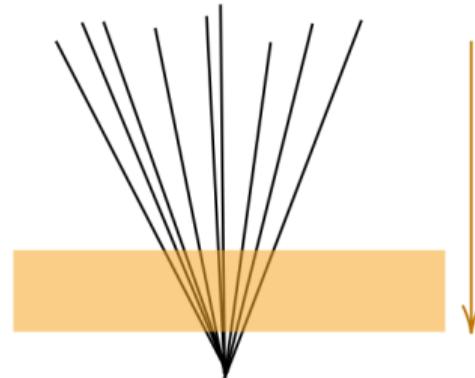
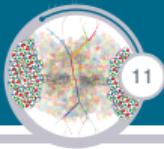
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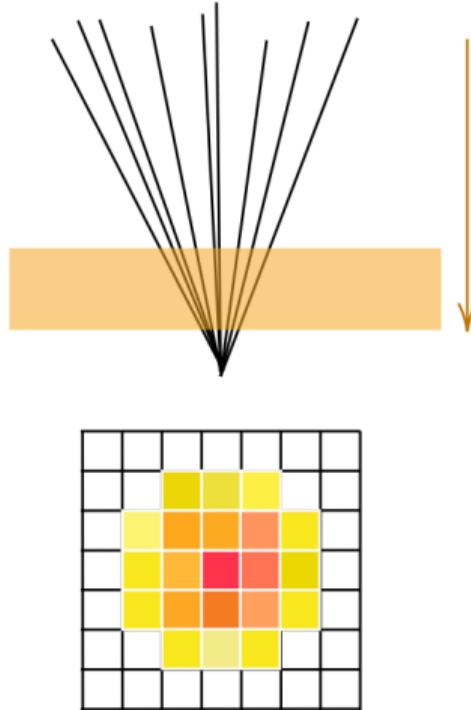
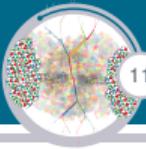
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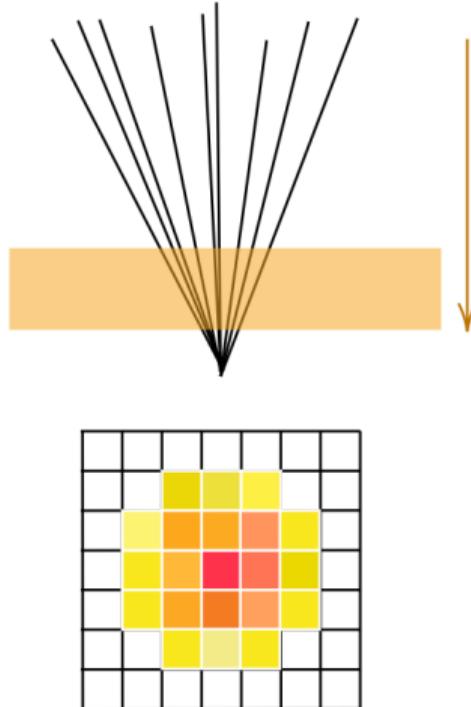
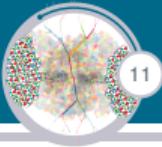
Subtraction Details



We have performed two different types of subtractions:

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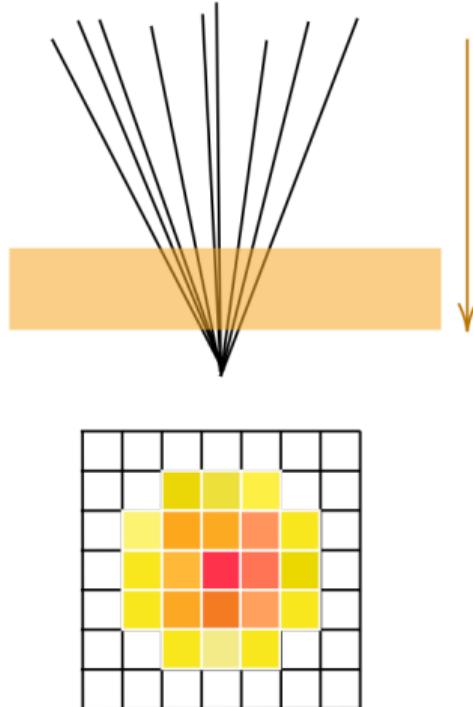
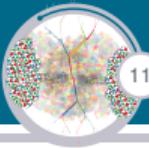
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1. JEWEL's internal background subtraction to give physical medium response (only for PbPb and this is always performed before embedding) [3]

[3] Eur.Phys.J.C 82 (2022) 11, 1010

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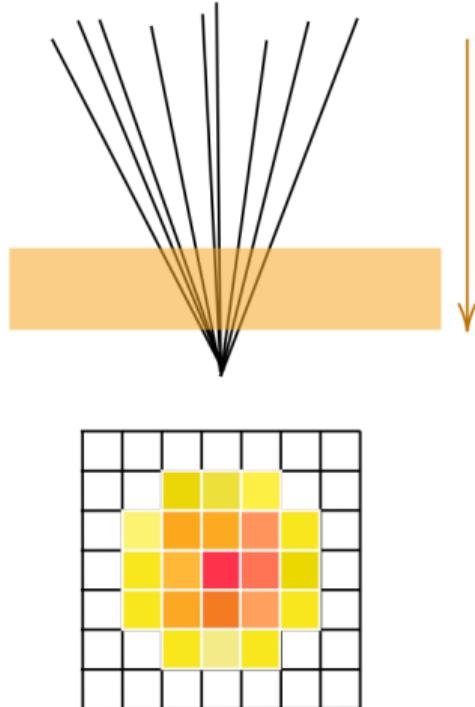
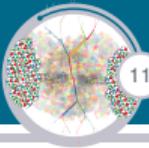
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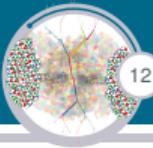
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We have used the parameters suggested in [4] for 0.4 anti- k_T jets.

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[4] JHEP 08 (2019) 175

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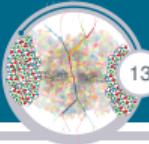
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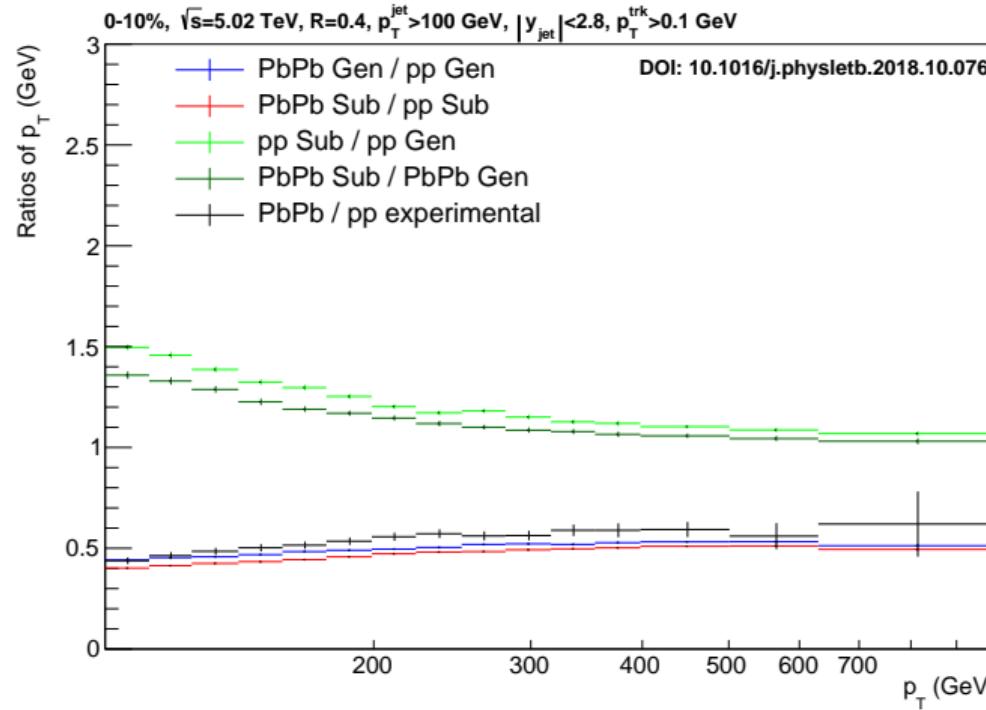
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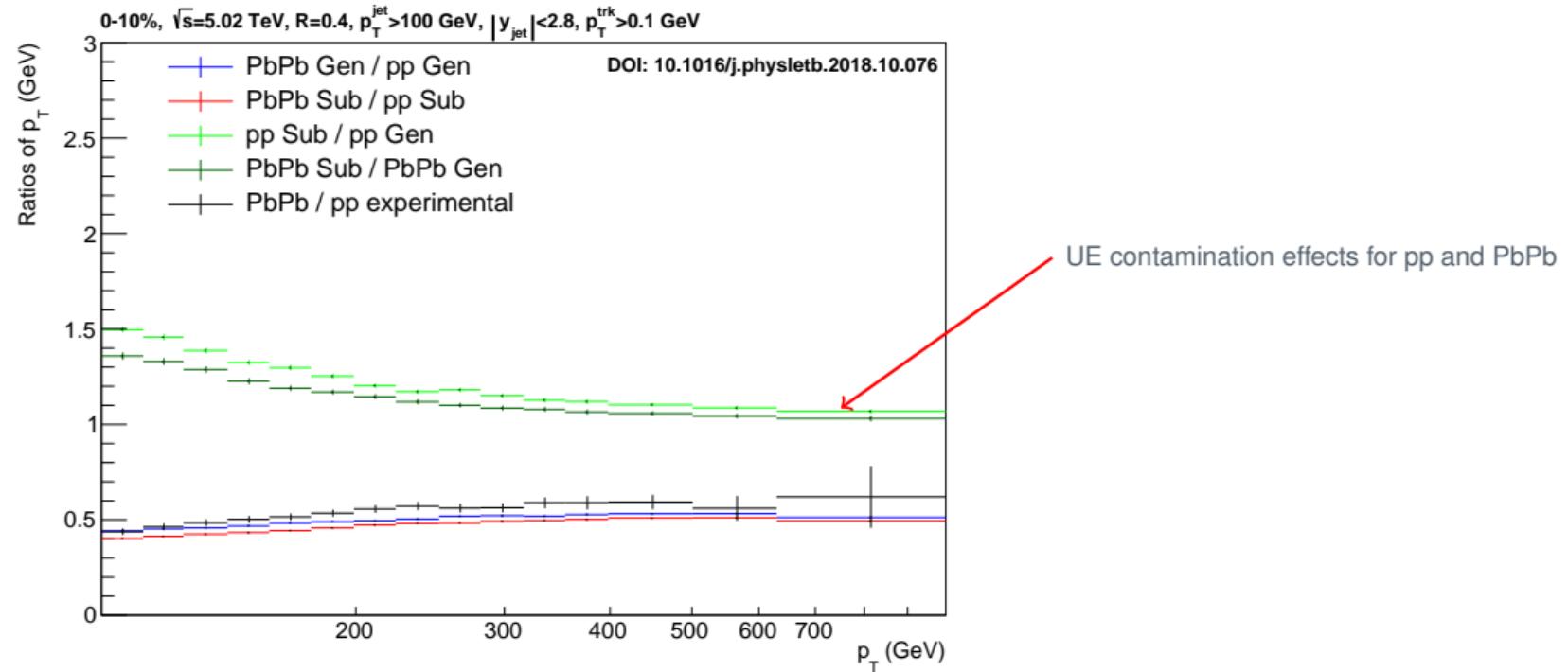
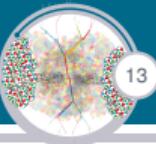
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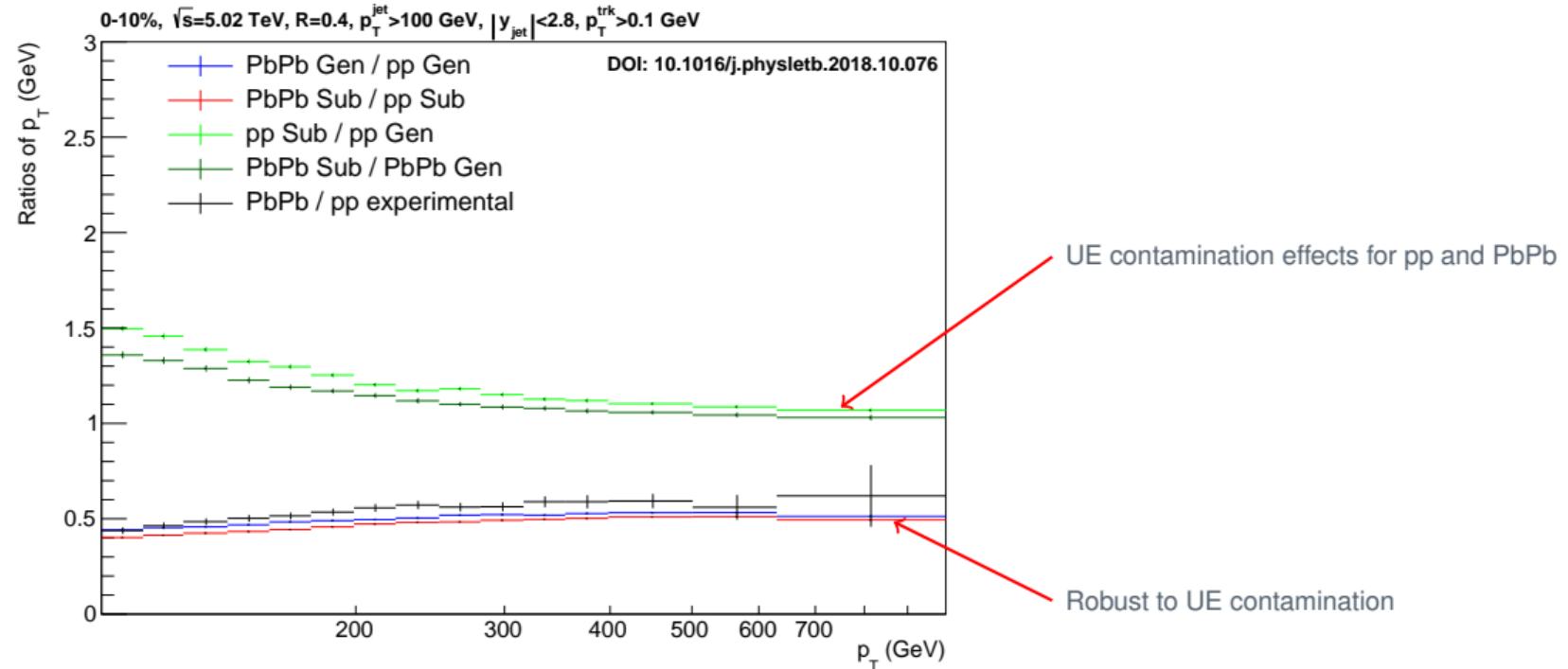
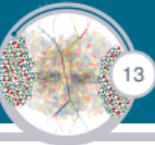
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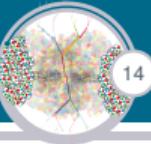
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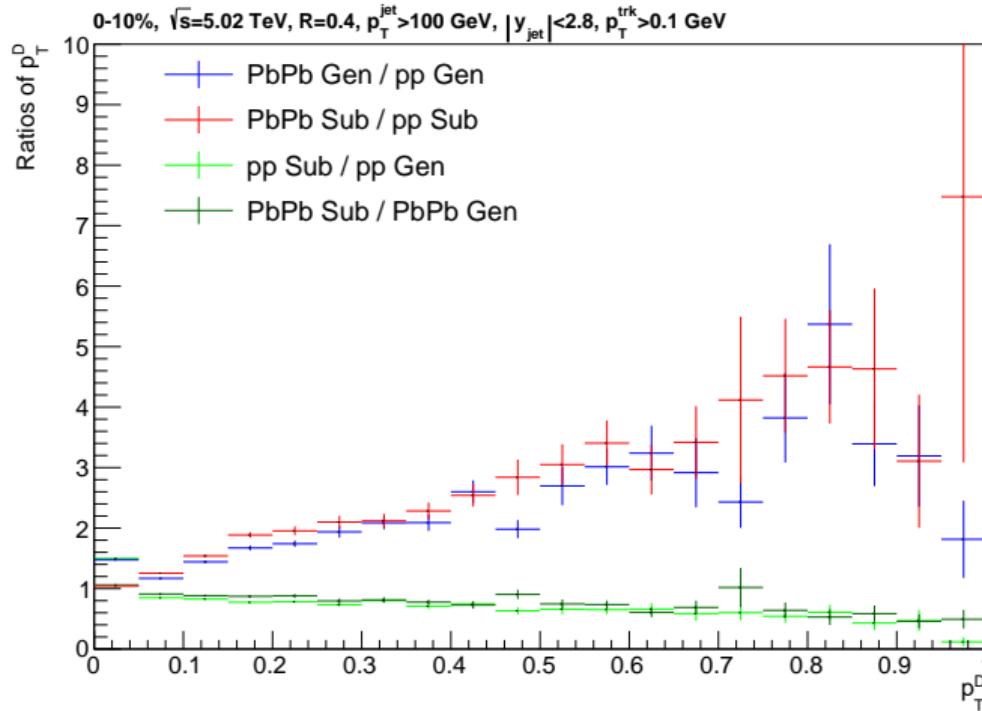
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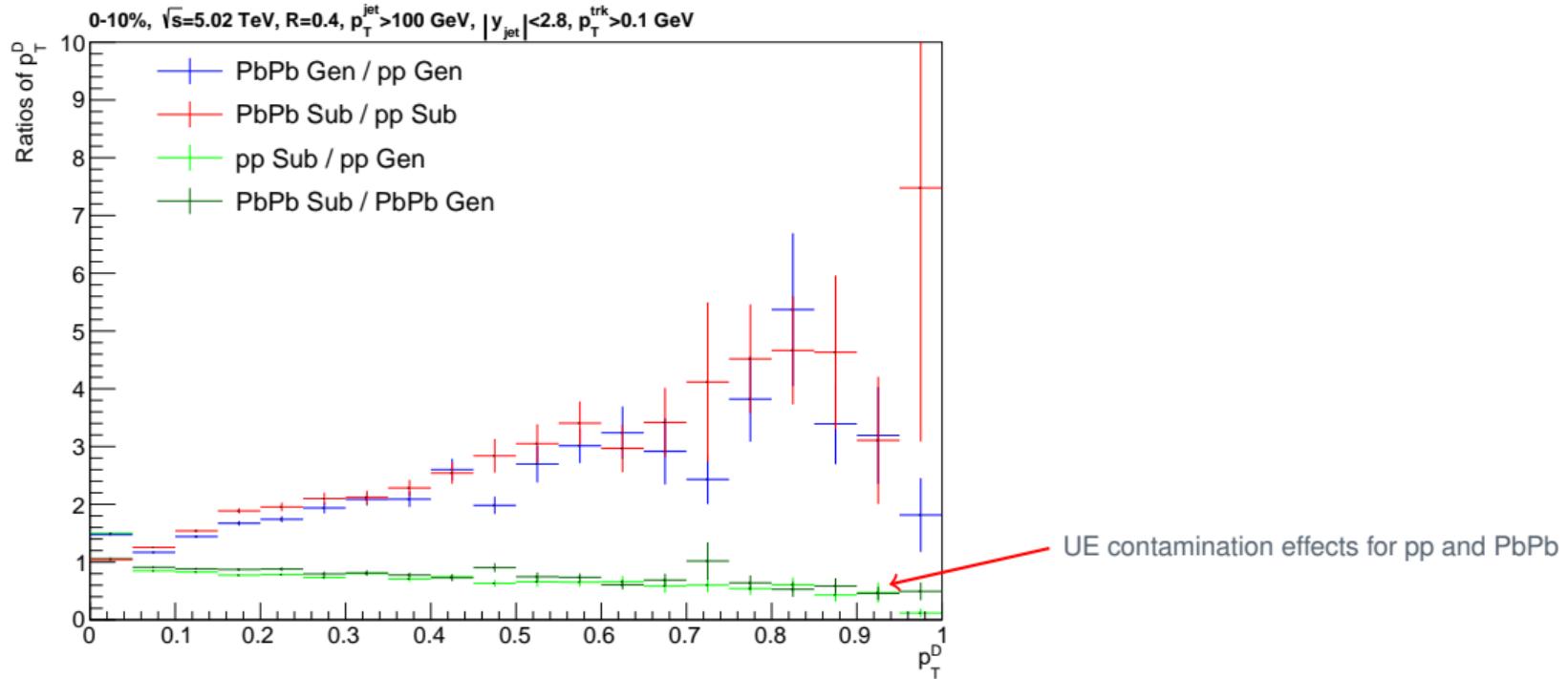


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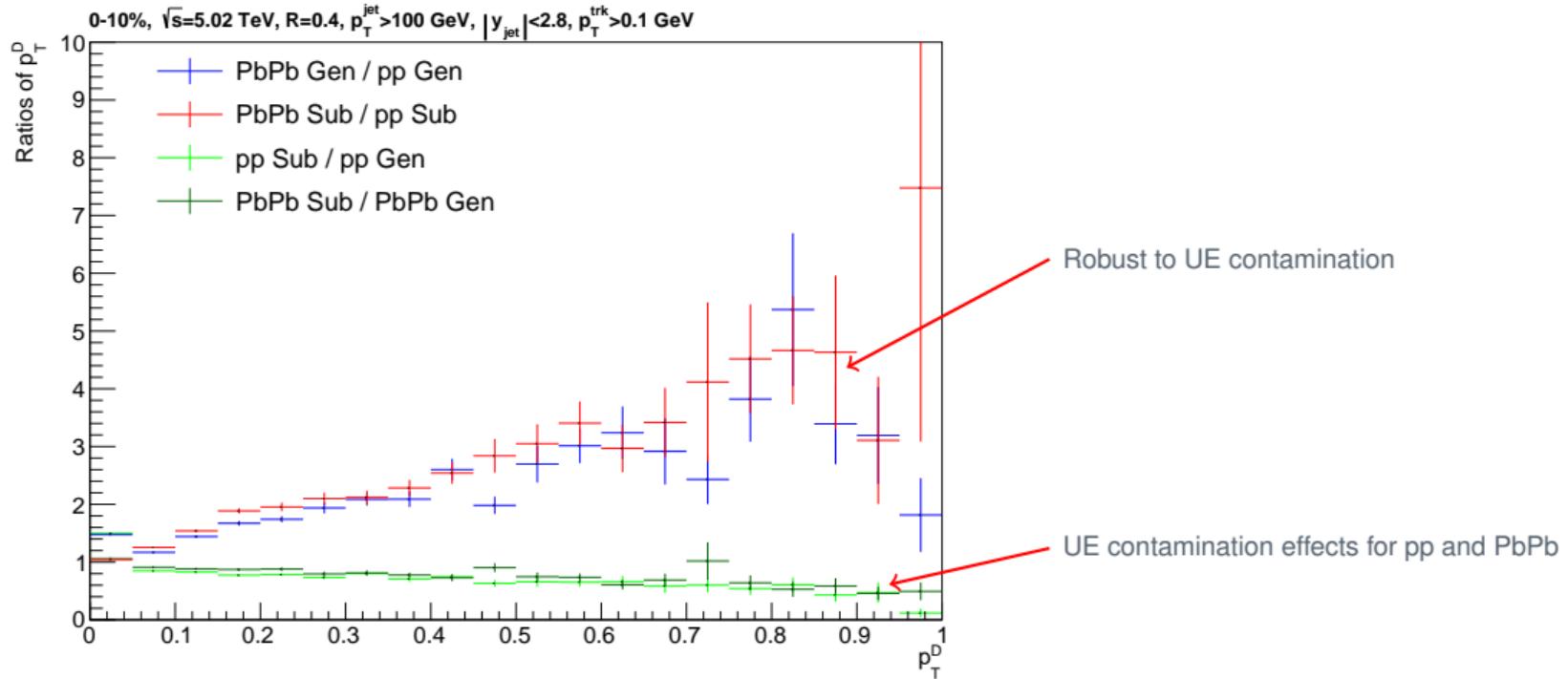


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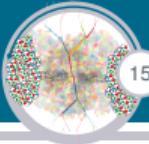
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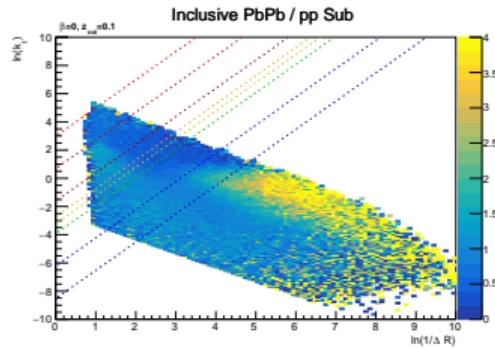
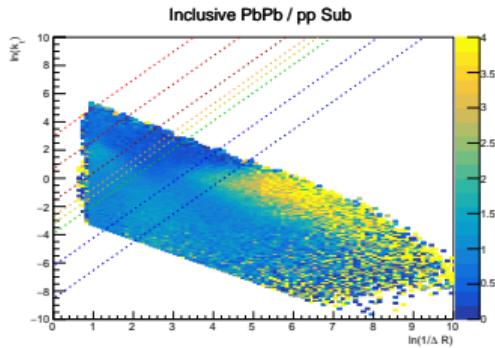
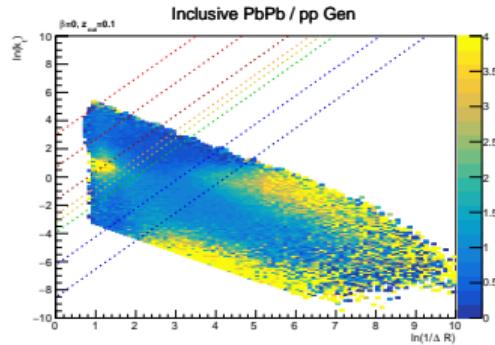
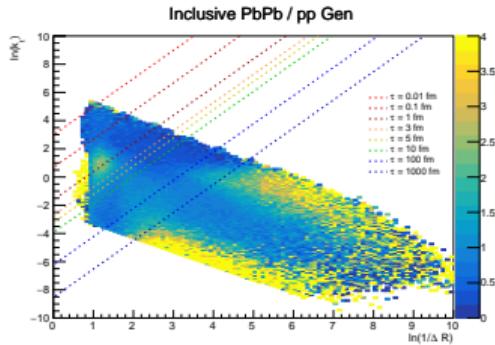


Results

Observable Robustness



15

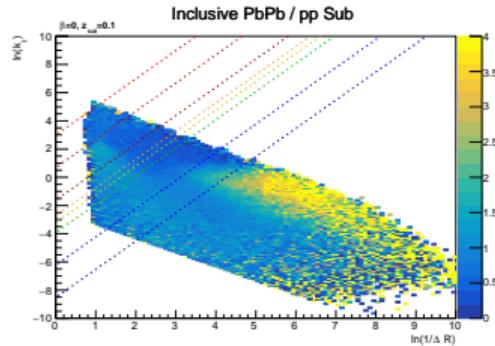
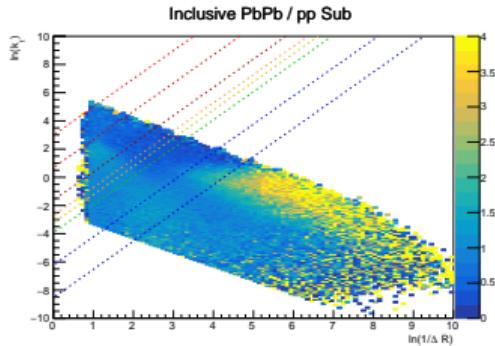
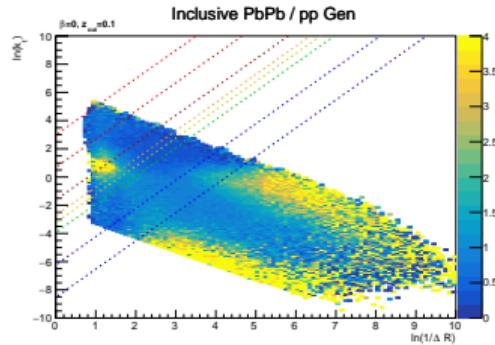
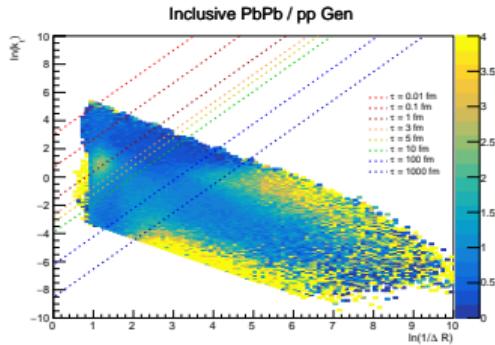


Results

Observable Robustness



SoftDrop Grooming



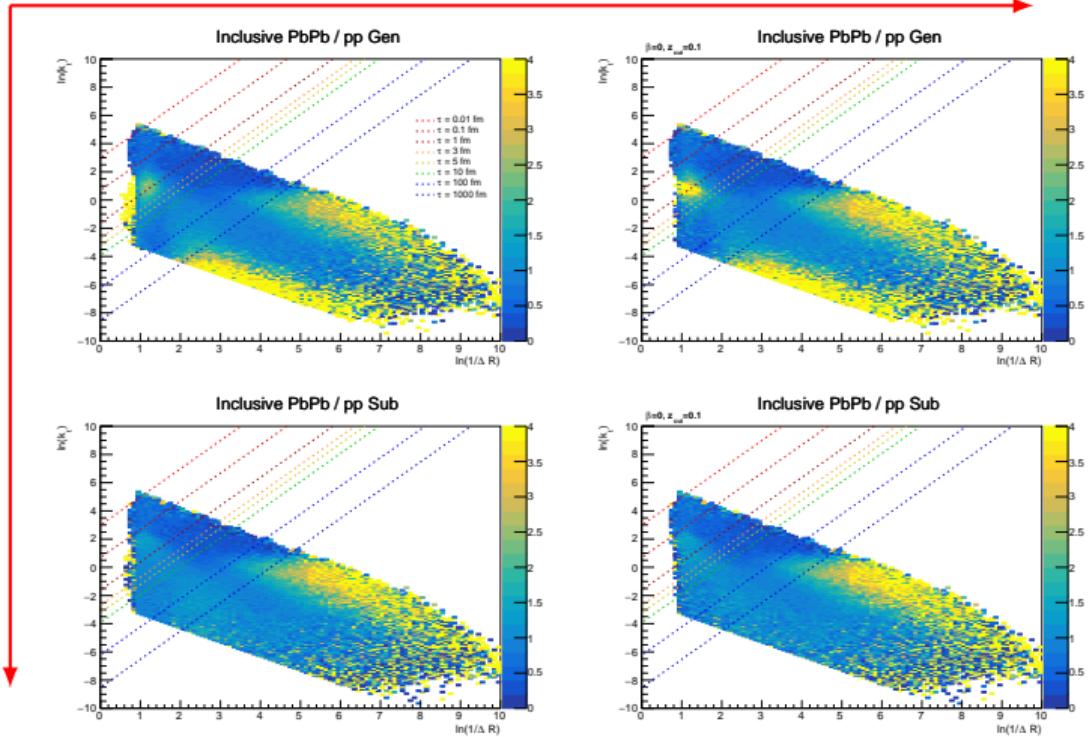
Results

Observable Robustness



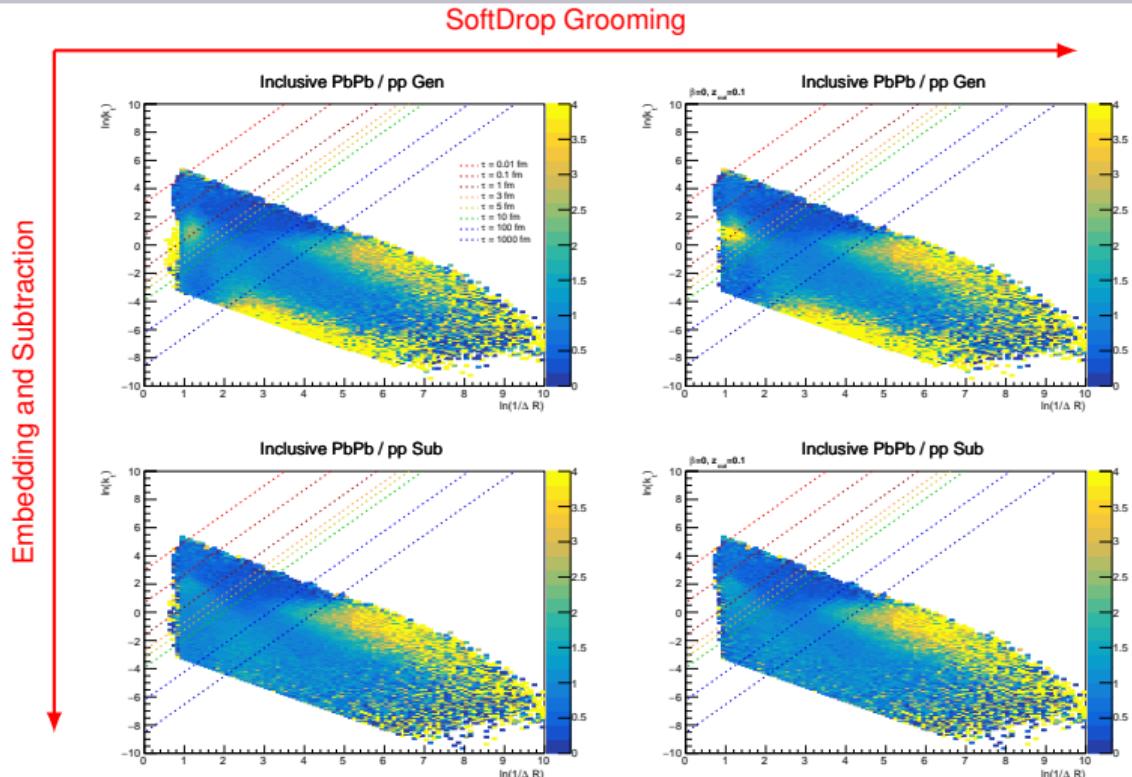
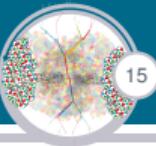
15

Embedding and Subtraction



Results

Observable Robustness



Grooming seems to increase the signal in the medium time window, but the subtraction always depletes the signal in this region.

Results

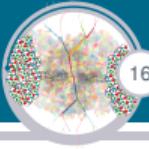
ML Robustness



16

Results

ML Robustness

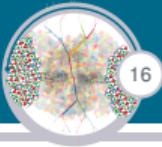


16

We now turn to the effects of UE contamination in a ML analysis.

Results

ML Robustness



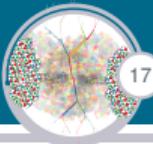
We now turn to the effects of UE contamination in a ML analysis.

We reproduced the results presented by Ankita on Monday for the PCA, AE and BDT analysis on the gen level, [5], and after UE embedding and subtraction (our work).

[5] 10.48550/arXiv.2304.07196

Results

ML Robustness



Results

ML Robustness



Observable	Type
y_{SD} ϕ_{SD} $\Delta p_{T,SD} = p_{T,jet} - p_{T,jet_{SD}}$ m_{SD} $n_{\text{const},SD}$	Jet Momenta and Constituent Multiplicity
$\bar{r}_{SD} = \frac{1}{n_{\text{const},SD}} \lambda_{1,SD}^0$ $\bar{r}_{SD}^2 = \frac{1}{n_{\text{const},SD}} \lambda_{2,SD}^0$ $r z_{SD} = \lambda_{1,SD}^1$ $r^2 z_{SD} = \lambda_{2,SD}^1$ $\bar{z}_{SD}^2 = \frac{1}{n_{\text{const},SD}} \lambda_{0,SD}^2$ $p_T D_{SD} = \sqrt{\sum_{i \in jet_{SD}} p_{T,i}^2} / p_{T,jet,SD}$	Angularities
$\tau_{2,SD}, \tau_{3,SD}$ $\tau_{1,2,SD}, \tau_{2,3,SD}$	N -subjettiness
$ Q_{SD}^{0.3} , Q_{SD}^{0.5} , Q_{SD}^{0.7} , Q_{SD}^{1.0} ,$	Jet-Charges
R_g, z_g, n_{SD}	SoftDrop Grooming Intrinsic
$R_{g,A}, z_{g,A}, \kappa_A$ with $A \in \{TD, ktD, zD\}$	Dynamical Grooming Intrinsic

Ankita's talk on Monday

[5] 10.48550/arXiv.2304.07196

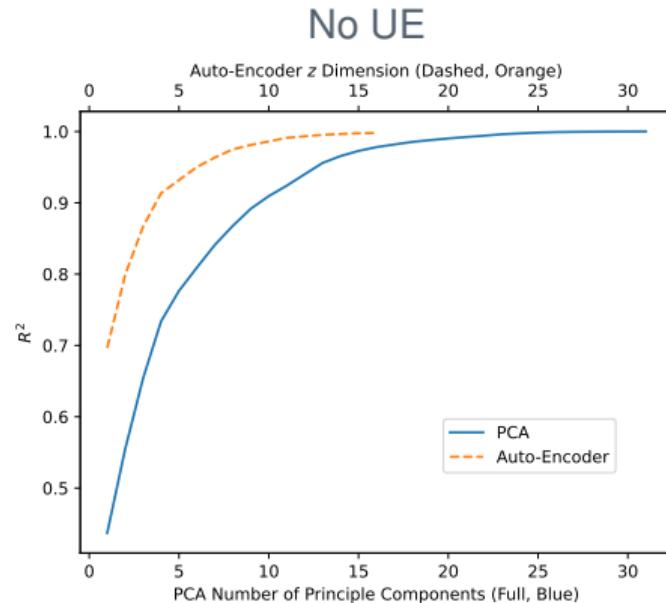
Results

ML Robustness



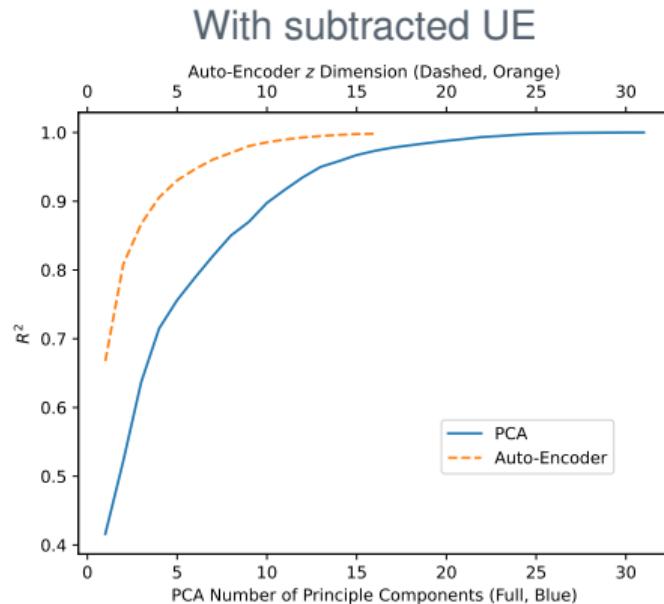
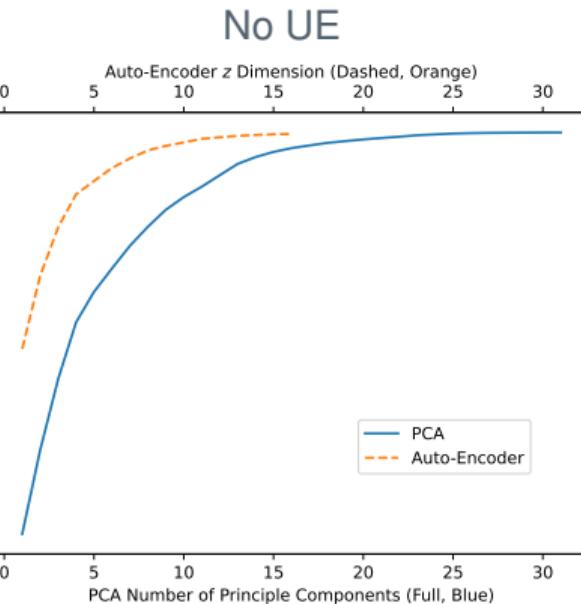
Results

ML Robustness



Results

ML Robustness



Results

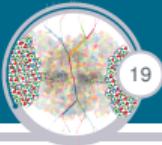
ML Robustness



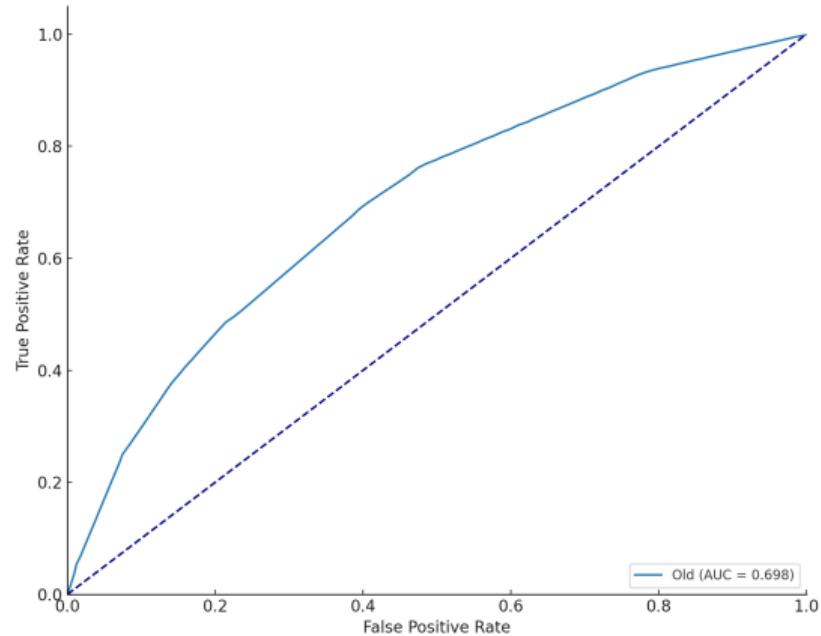
19

Results

ML Robustness

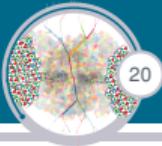


BDT using the same variables



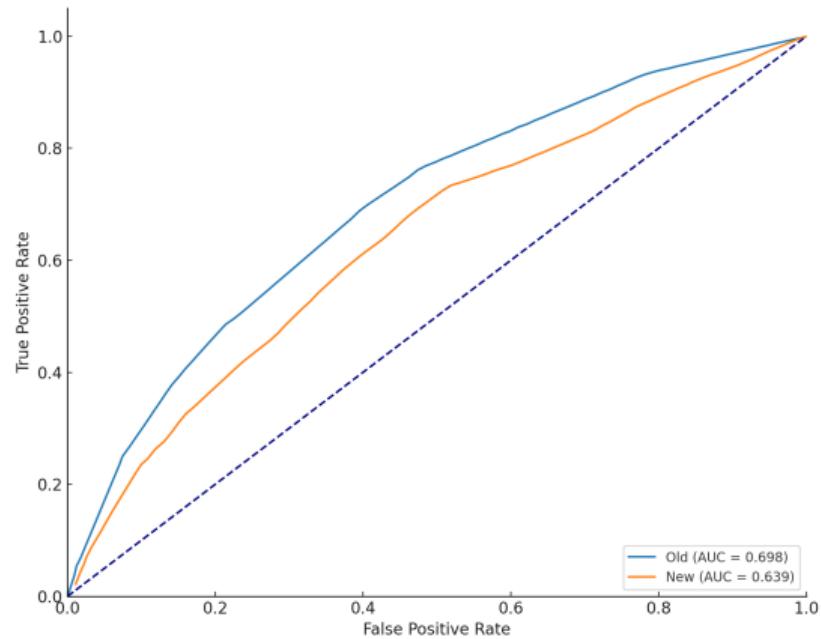
Results

ML Robustness



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BDT using the same variables

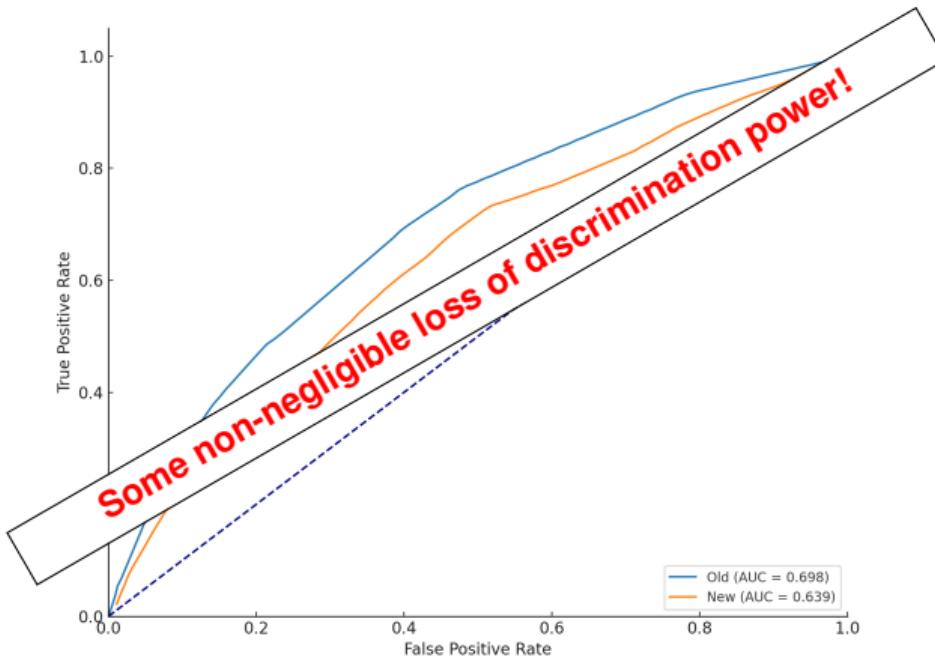


Results

ML Robustness

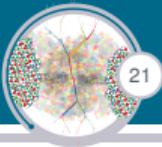


BDT using the same variables



Results

ML Robustness



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Results

ML Robustness

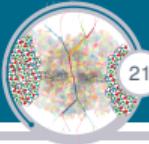


21

But...

Results

ML Robustness

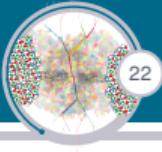


21

But... are there better choices of observables?

Results

A note on EFPs



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Results

A note on EFPs

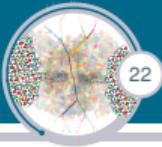


"These observables are multiparticle energy correlators with specific angular structures which directly result from IRC safety."

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



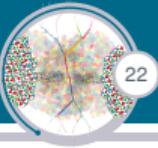
"These observables are multiparticle energy correlators with specific angular structures which directly result from IRC safety."

"EFPs can be viewed as a discrete set of C-correlators"

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



"These observables are multiparticle energy correlators with specific angular structures which directly result from IRC safety."

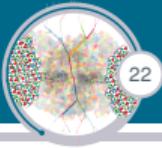
"EFPs can be viewed as a discrete set of C-correlators"

"EFPs form a linear basis of all IRC-safe observables, making them suitable for a wide variety of jet substructure contexts where linear methods are applicable"

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



"These observables are multiparticle energy correlators with specific angular structures which directly result from IRC safety."

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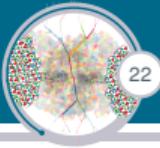
"EFPs form a linear basis of all IRC-safe observables, making them suitable for a wide variety of jet substructure contexts where linear methods are applicable"

"There is a one-to-one correspondence between EFPs and loopless multigraphs, which helps to visualize and calculate the EFPs"

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



"These observables are multiparticle energy correlators with specific angular structures which directly result from IRC safety."

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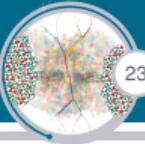
"There is a one-to-one correspondence between EFPs and loopless multigraphs, which helps to visualize and calculate the EFPs"

"(...) we usually truncate by restricting to the set of all multigraphs with at most d edges (...) this truncation results in a finite number of EFPs at each order of truncation, which is not true for truncation by the number of vertices."

[6] doi.org/10.1007/JHEP04(2018)013

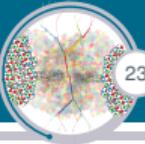
Results

A note on EFPs



Results

A note on EFPs



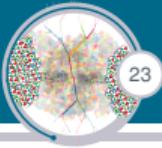
23

$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



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$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell} \quad \bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

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Results

A note on EFPs



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$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j} \quad k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$

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Results

A note on EFPs



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$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

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Results

A note on EFPs



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$$= \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2$$

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



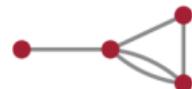
$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

$$k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$



$$= \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2$$



$$= \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_2 i_4}^2 \theta_{i_3 i_4}$$

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

$$k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$

$$\begin{array}{c} \text{Diagram of a graph with 5 nodes and 4 edges} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2 \end{array}$$

$$\begin{array}{c} \text{Diagram of a graph with 4 nodes and 3 edges} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_2 i_4}^2 \theta_{i_3 i_4} \end{array}$$

$$\frac{m_J^2}{p_{TJ}^2} = \sum_{i_1=1}^M \sum_{i_2=1}^M z_{i_1} z_{i_2} (\cosh(\Delta y_{i_1 i_2}) - \cos(\Delta \phi_{i_1 i_2})) = \frac{1}{2} \times \begin{array}{c} \text{Diagram of a graph with 2 nodes and 1 edge} \\ + \dots \end{array}$$

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



23

$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

$$k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$

$$\begin{array}{c} \text{Diagram of a graph with 5 nodes and 6 edges, including a self-loop on one node.} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2 \end{array}$$

$$\begin{array}{c} \text{Diagram of a graph with 4 nodes and 5 edges, including a self-loop on one node.} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_2 i_4}^2 \theta_{i_3 i_4} \end{array}$$

$$\frac{m_J^2}{p_{TJ}^2} = \sum_{i_1=1}^M \sum_{i_2=1}^M z_{i_1} z_{i_2} (\cosh(\Delta y_{i_1 i_2}) - \cos(\Delta \phi_{i_1 i_2})) = \frac{1}{2} \times$$

$$\begin{array}{c} \text{Diagram of a graph with 2 nodes and 1 edge, forming a simple loop.} \\ + \dots \end{array}$$

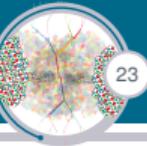
$$\lambda^{(2)} = \frac{1}{2} \sum_{i \in J} \sum_{j \in J} z_i z_j \theta_{ij}^2 = \frac{1}{2} \times$$

$$\begin{array}{c} \text{Diagram of a graph with 1 node and 1 self-loop edge.} \end{array}$$

[6] doi.org/10.1007/JHEP04(2018)013

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A note on EFPs



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$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

$$k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$

$$\begin{array}{c} \text{Diagram of a graph with 5 nodes and 6 edges} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2 \end{array}$$

$$\begin{array}{c} \text{Diagram of a graph with 4 nodes and 5 edges} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_2 i_4}^2 \theta_{i_3 i_4} \end{array}$$

$$\frac{m_J^2}{p_{TJ}^2} = \sum_{i_1=1}^M \sum_{i_2=1}^M z_{i_1} z_{i_2} (\cosh(\Delta y_{i_1 i_2}) - \cos(\Delta \phi_{i_1 i_2})) = \frac{1}{2} \times$$

$$\begin{array}{c} \text{Diagram of a graph with 2 nodes and 1 edge} \\ + \dots \end{array}$$

$$\lambda^{(2)} = \frac{1}{2} \sum_{i \in J} \sum_{j \in J} z_i z_j \theta_{ij}^2 = \frac{1}{2} \times$$

$$\begin{array}{c} \text{Diagram of a graph with 1 node and 1 self-loop edge} \\ \dots \end{array}$$

$$\lambda^{(4)} = \begin{array}{c} \text{Diagram of a graph with 4 nodes and 6 edges} \\ - \frac{3}{4} \times \begin{array}{c} \text{Diagram of a graph with 2 nodes and 2 self-loop edges} \end{array} \end{array}$$

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



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$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

$$k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$

$$\begin{array}{c} \text{Diagram of a graph with 5 nodes and 6 edges} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2 \end{array}$$

$$\begin{array}{c} \text{Diagram of a graph with 4 nodes and 5 edges} \\ = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_2 i_4}^2 \theta_{i_3 i_4} \end{array}$$

$$\frac{m_J^2}{p_{TJ}^2} = \sum_{i_1=1}^M \sum_{i_2=1}^M z_{i_1} z_{i_2} (\cosh(\Delta y_{i_1 i_2}) - \cos(\Delta \phi_{i_1 i_2})) = \frac{1}{2} \times$$

$$\begin{array}{c} \text{Diagram of a graph with 2 nodes and 1 edge} \\ + \dots \end{array}$$

$$\lambda^{(2)} = \frac{1}{2} \sum_{i \in J} \sum_{j \in J} z_i z_j \theta_{ij}^2 = \frac{1}{2} \times$$

$$\begin{array}{c} \text{Diagram of a graph with 1 node and 1 self-loop} \\ \dots \end{array}$$

$$\lambda^{(4)} = \begin{array}{c} \text{Diagram of a graph with 4 nodes and 6 edges} \\ - \frac{3}{4} \times \begin{array}{c} \text{Diagram of a graph with 2 nodes and 2 edges} \end{array} \end{array}$$

$$\lambda^{(6)} = \begin{array}{c} \text{Diagram of a graph with 6 nodes and 12 edges} \\ - \frac{3}{2} \times \begin{array}{c} \text{Diagram of a graph with 4 nodes and 10 edges} \\ + \frac{5}{8} \times \begin{array}{c} \text{Diagram of a graph with 6 nodes and 12 edges} \end{array} \end{array} \end{array}$$

[6] doi.org/10.1007/JHEP04(2018)013

Results

A note on EFPs



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$$\text{EFP}_G = \sum_{i_1=1}^M \cdots \sum_{i_N=1}^M z_{i_1} \cdots z_{i_N} \prod_{(k,\ell) \in G} \theta_{i_k i_\ell}$$

$$\bullet_j \iff \sum_{i_j=1}^M z_{i_j}$$

$$k \xrightarrow{\hspace{1cm}} \ell \iff \theta_{i_k i_\ell}$$

$$\begin{array}{c} \text{Diagram: } \\ \text{Three nodes connected by two edges between the first and second nodes, and one edge from the second to the third.} \end{array} = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M \sum_{i_5=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_1 i_3} \theta_{i_1 i_4} \theta_{i_1 i_5} \theta_{i_4 i_5}^2$$

$$\begin{array}{c} \text{Diagram: } \\ \text{Three nodes connected by three edges: one from the first to the second, one from the second to the third, and one from the first to the third.} \end{array} = \sum_{i_1=1}^M \sum_{i_2=1}^M \sum_{i_3=1}^M \sum_{i_4=1}^M z_{i_1} z_{i_2} z_{i_3} z_{i_4} \theta_{i_1 i_2} \theta_{i_2 i_3} \theta_{i_2 i_4}^2 \theta_{i_3 i_4}$$

$$\frac{m_J^2}{p_{TJ}^2} = \sum_{i_1=1}^M \sum_{i_2=1}^M z_{i_1} z_{i_2} (\cosh(\Delta y_{i_1 i_2}) - \cos(\Delta \phi_{i_1 i_2})) = \frac{1}{2} \times$$

$$\text{Diagram: } \text{A single vertical loop with a red dot at the top.}$$

$$\lambda^{(2)} = \frac{1}{2} \sum_{i \in J} \sum_{j \in J} z_i z_j \theta_{ij}^2 = \frac{1}{2} \times$$

$$\text{Diagram: } \text{A single vertical loop with a red dot at the top.}$$

$$\lambda^{(4)} = \text{Diagram: } \text{Two loops connected by a horizontal line.} - \frac{3}{4} \times \text{Diagram: } \text{Two separate vertical loops.}$$

$$\lambda^{(6)} = \text{Diagram: } \text{Three nodes connected by five edges forming a triangle with a central node.} - \frac{3}{2} \times \text{Diagram: } \text{Three nodes connected by four edges forming a triangle with a central node.} + \frac{5}{8} \times \text{Diagram: } \text{Four separate vertical loops.}$$

Take home: EFPs are interesting.

[6] doi.org/10.1007/JHEP04(2018)013

Results

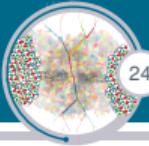
A note on EFPs



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Results

A note on EFPs

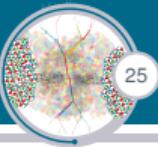


24

On the next analysis we focus on Linear Discriminant Analysis (LDA) with these observables and medium response.

Results

ML Robustness



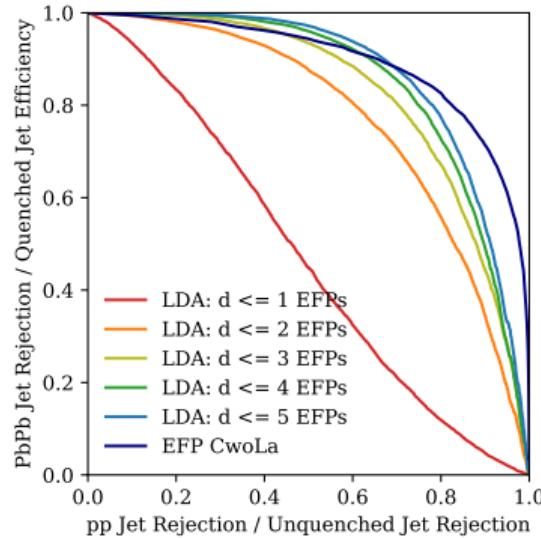
Results

ML Robustness



25

No UE



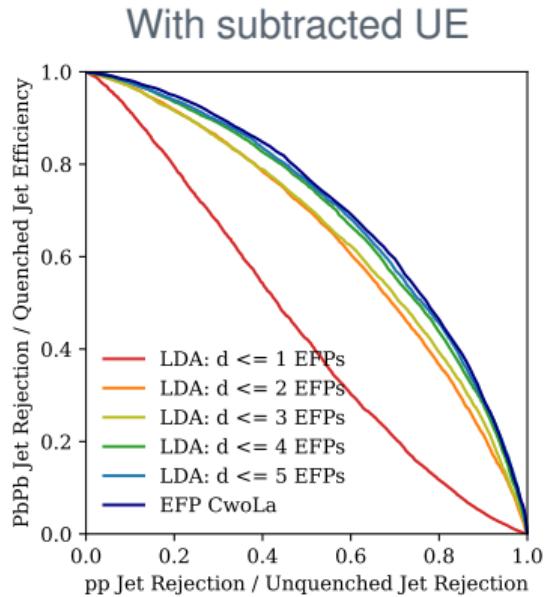
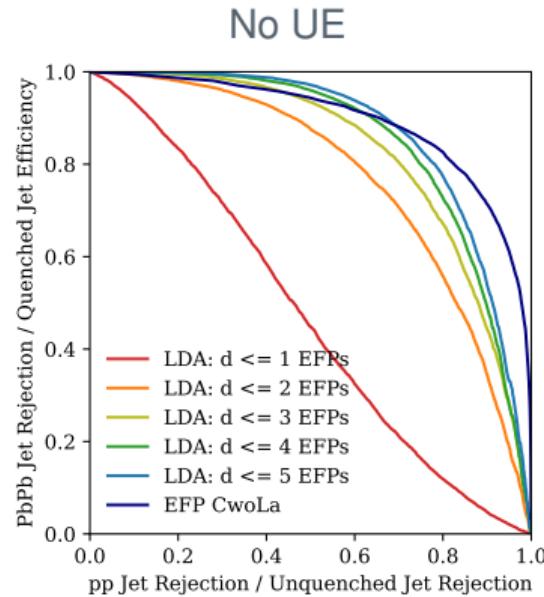
[6] doi.org/10.1007/JHEP04(2018)013

Results

ML Robustness

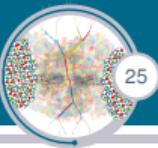


25



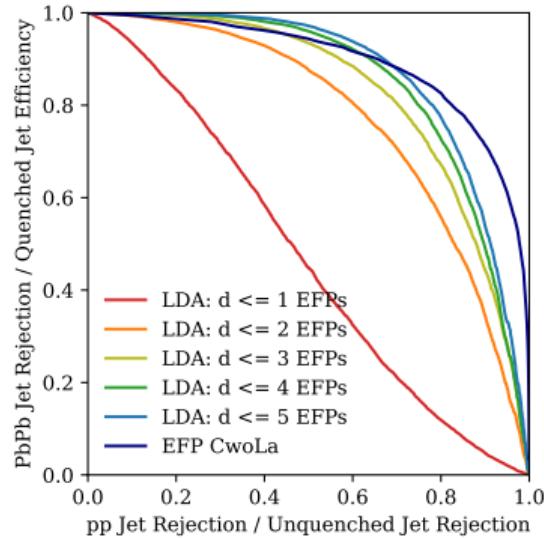
Results

ML Robustness

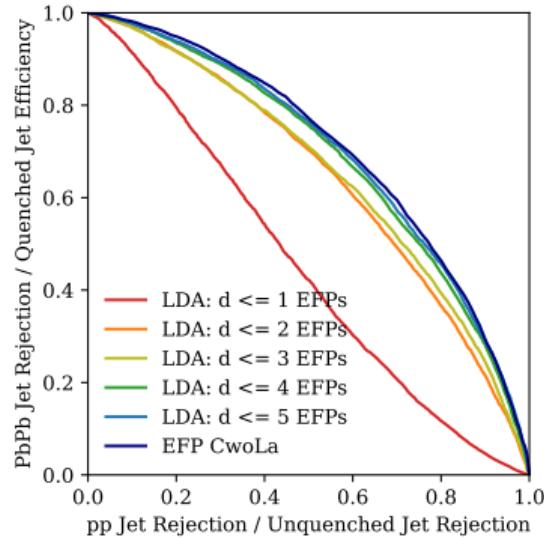


25

No UE



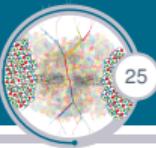
With subtracted UE



Classification on gen level, picks up on the medium response and the model performs very well.

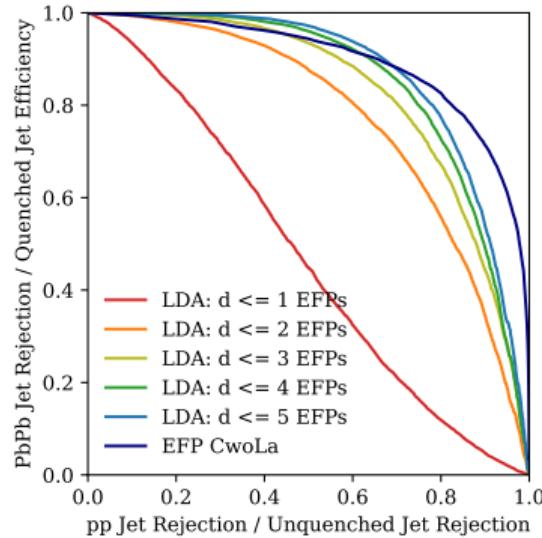
Results

ML Robustness

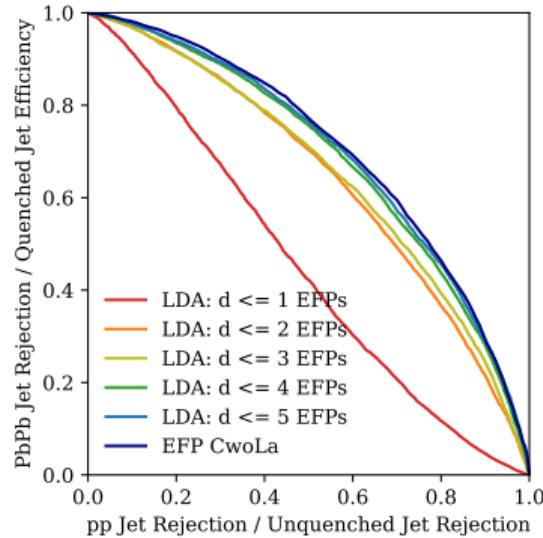


25

No UE



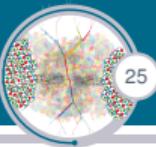
With subtracted UE



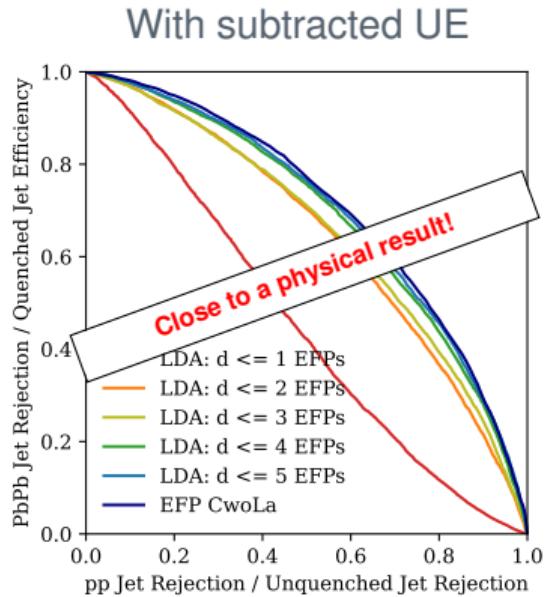
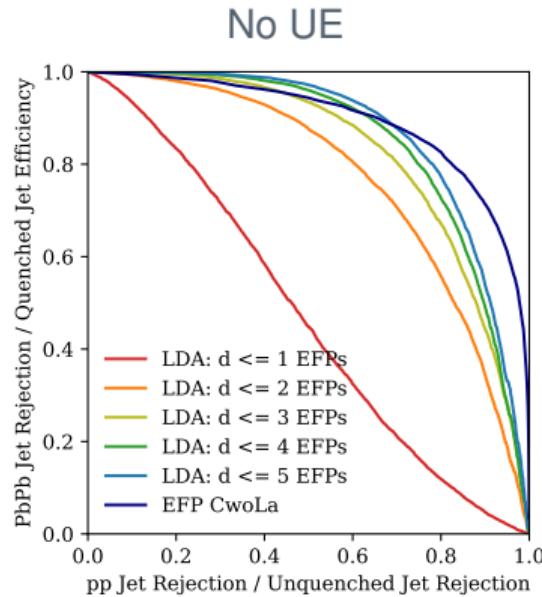
Classification on gen level, picks up on the medium response and the model performs very well.
Applying the procedure greatly reduces the discrimination power (AUC from .85 to .7).

Results

ML Robustness



25



Classification on gen level, picks up on the medium response and the model performs very well.
Applying the procedure greatly reduces the discrimination power (AUC from .85 to .7).

[6] doi.org/10.1007/JHEP04(2018)013

Results

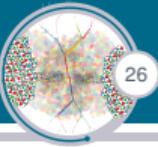
A note on EFPs



But..

Results

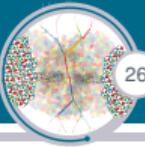
A note on EFPs



But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle
weights)

Results

A note on EFPs



But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle
weights)

(We have plotted the ROC curves and model outputs with the weights)

Results

A note on EFPs



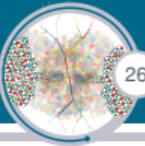
But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle weights)

(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

Results

A note on EFPs



26

But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle
weights)

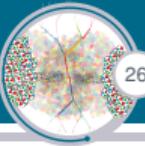
(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

Is it stable?

Results

A note on EFPs



26

But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle weights)

(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

Is it stable? Can we train on weighted (MC), test on unweighted (Data)?

Results

A note on EFPs



26

But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle
weights)

(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

Is it stable? Can we train on weighted (MC), test on unweighted (Data)?

Should we use the weights in training?

Results

A note on EFPs



But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle weights)

(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

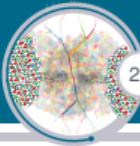
Is it stable? Can we train on weighted (MC), test on unweighted (Data)?

Should we use the weights in training?

Do we want to capture the true p_T distribution in training (use the weights)

Results

A note on EFPs



But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle
weights)

(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

Is it stable? Can we train on weighted (MC), test on unweighted (Data)?

Should we use the weights in training?

Do we want to capture the true p_T distribution in training (use the weights)
or prefer that the network learns uniformly across p_T bins (no weights)?

Results

A note on EFPs



But.. We have trained on a weighted sample but without the weights
(sklearn's **Linear** Discriminant Analysis (LDA) model, does not handle weights)

(We have plotted the ROC curves and model outputs with the weights)

Can we do this though?

Is it stable? Can we train on weighted (MC), test on unweighted (Data)?

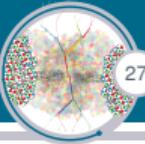
Should we use the weights in training?

Do we want to capture the true p_T distribution in training (use the weights)
or prefer that the network learns uniformly across p_T bins (no weights)?

Is the model robust to this?

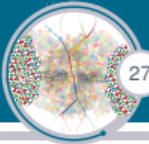
Results

A note on EFPs



Results

A note on EFPs

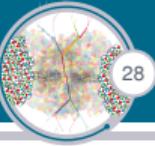


27

We are going to perform a test now without medium response.

Results

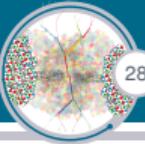
A note on EFPs



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Results

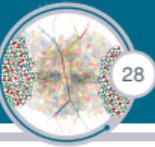
A note on EFPs



Tested on	Weighted	Unweighted
Trained on	Weighted	Unweighted
Weighted		
Unweighted		

Results

A note on EFPs



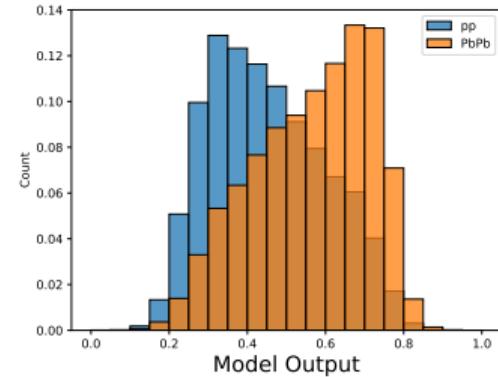
Tested on

Weighted

Unweighted

Trained on

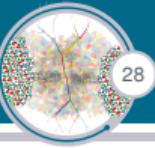
Weighted



Unweighted

Results

A note on EFPs



Tested on

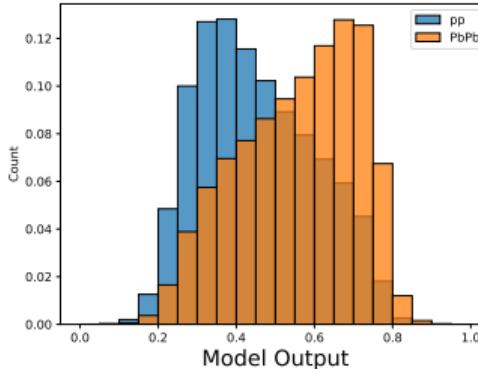
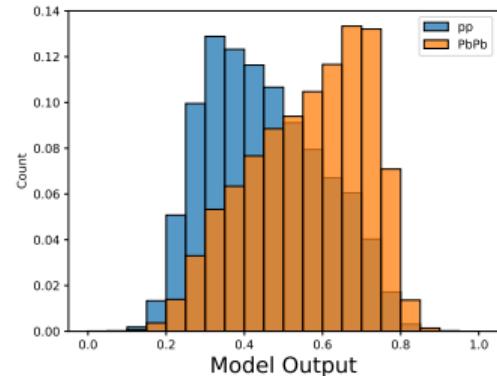
Trained on

Unweighted

Weighted

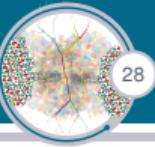
Weighted

Unweighted



Results

A note on EFPs



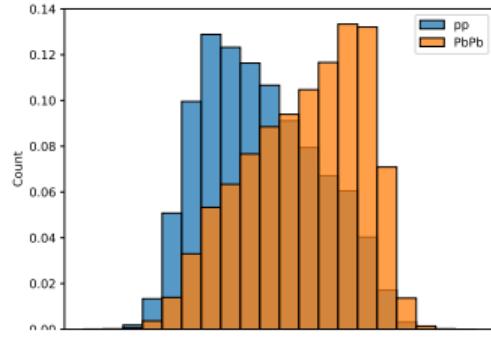
Tested on

Trained on

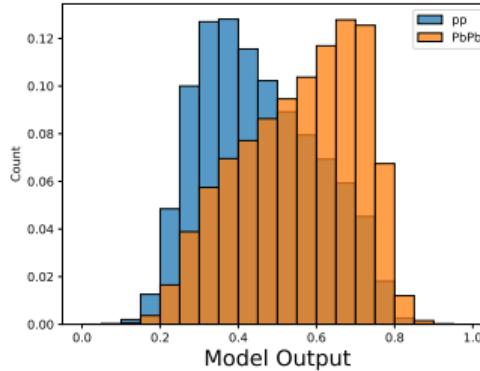
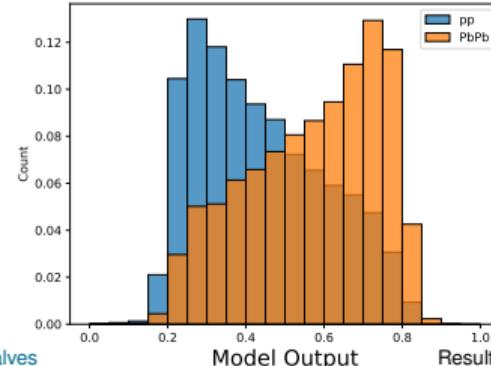
Weighted

Unweighted

Weighted

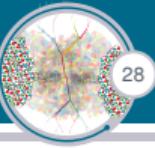


Unweighted



Results

A note on EFPs



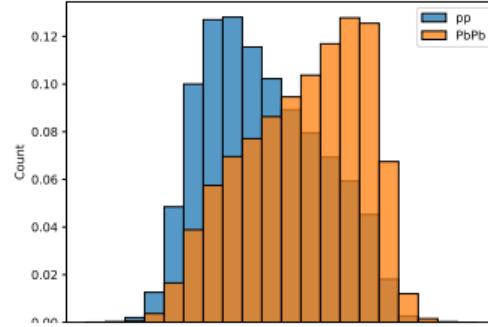
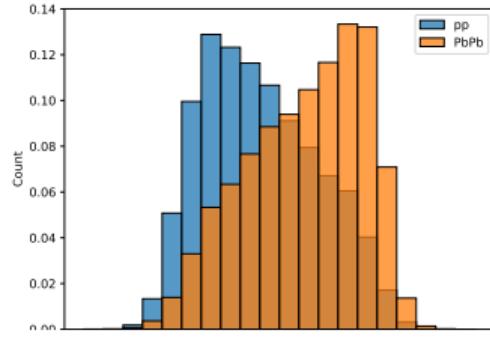
Tested on

Trained on

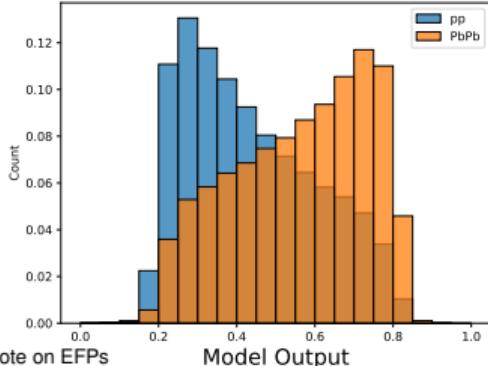
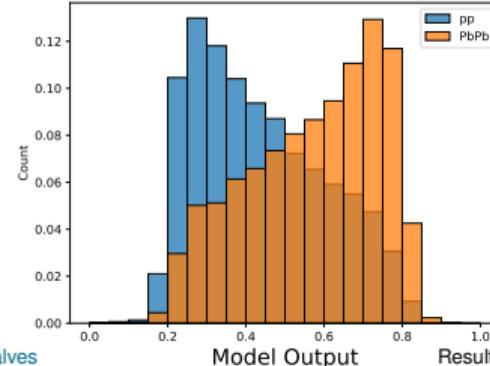
Weighted

Unweighted

Weighted

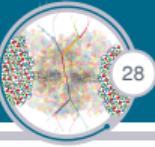


Unweighted



Results

A note on EFPs



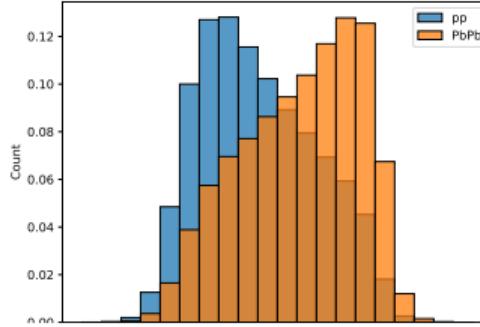
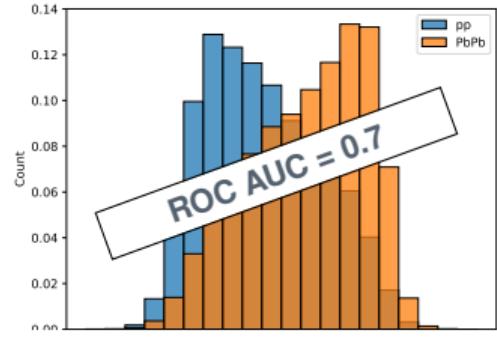
Tested on

Trained on

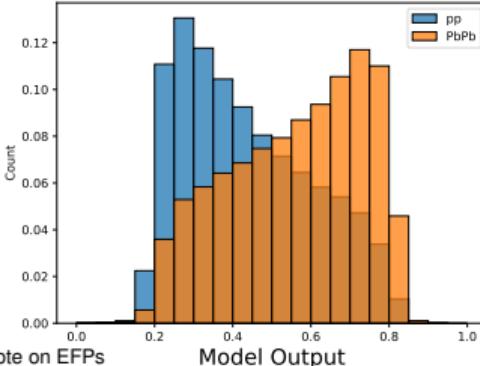
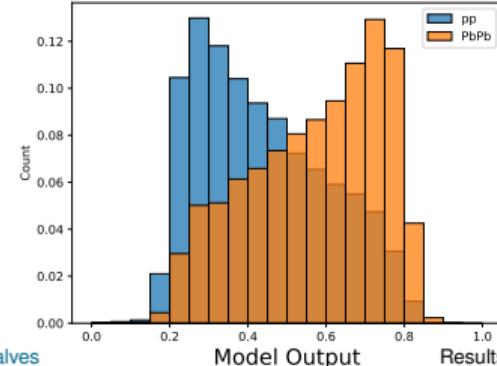
Weighted

Unweighted

Weighted

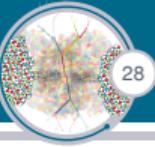


Unweighted



Results

A note on EFPs



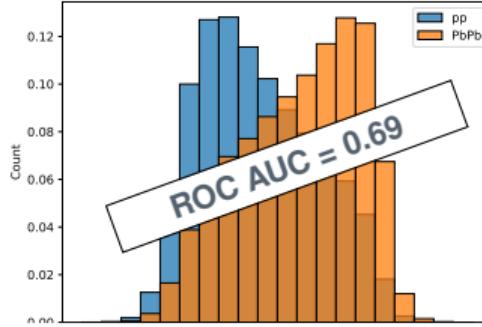
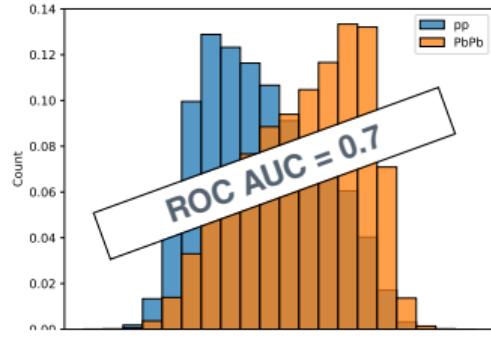
Tested on

Trained on

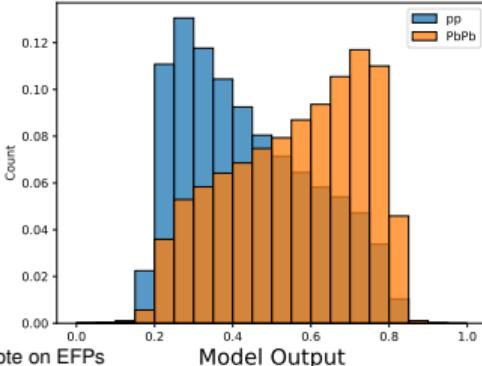
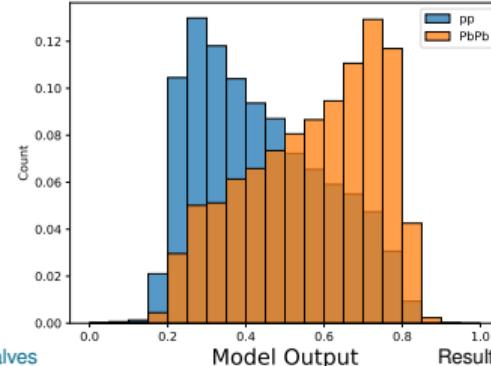
Weighted

Unweighted

Weighted

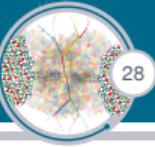


Unweighted



Results

A note on EFPs



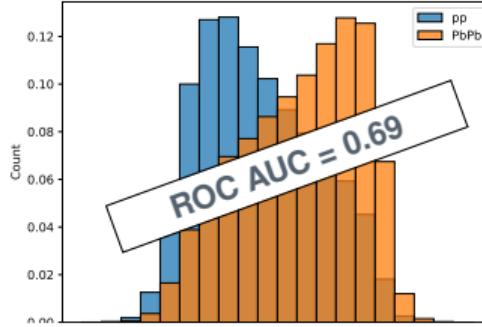
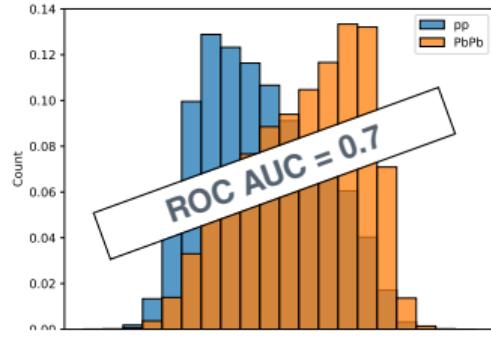
Tested on

Trained on

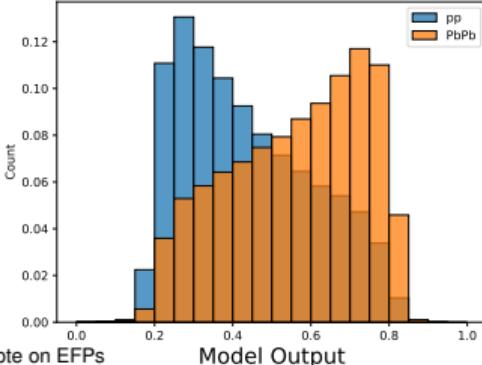
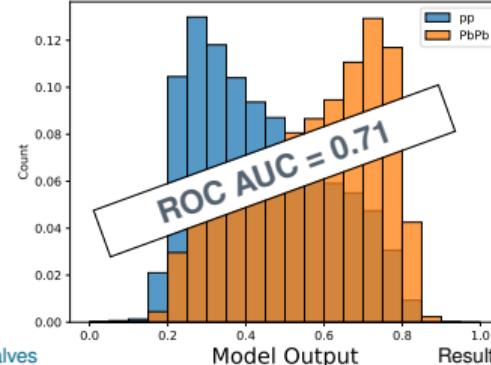
Weighted

Unweighted

Weighted

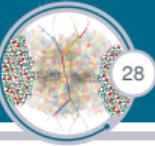


Unweighted



Results

A note on EFPs



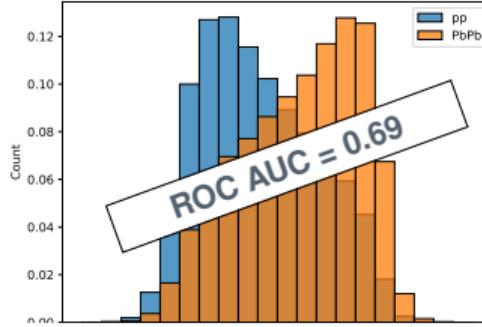
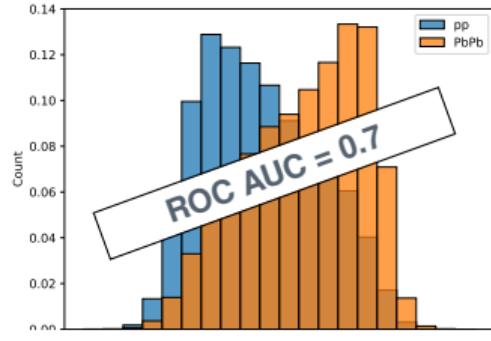
Tested on

Trained on

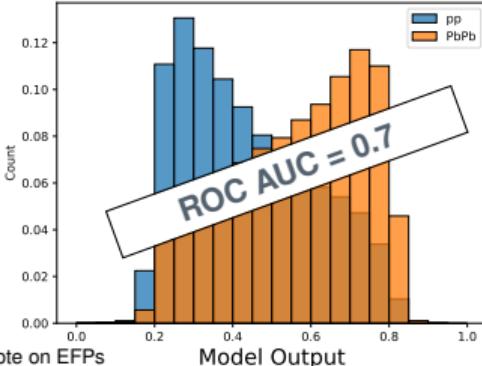
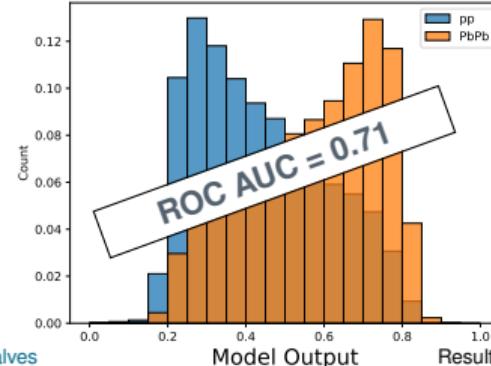
Weighted

Unweighted

Weighted

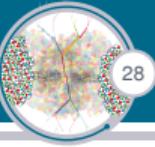


Unweighted



Results

A note on EFPs



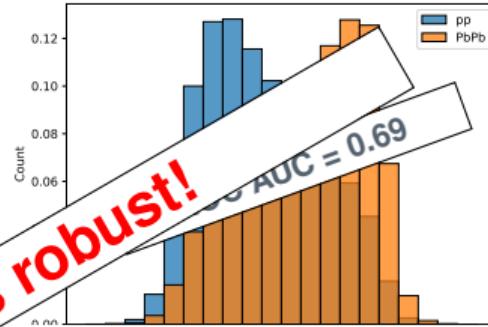
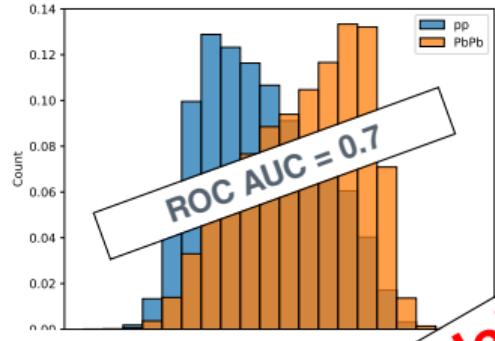
Tested on

Trained on

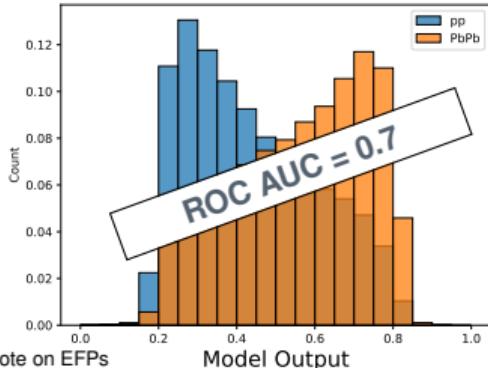
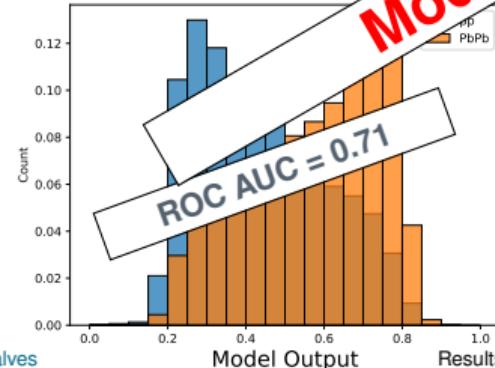
Weighted

Unweighted

Weighted

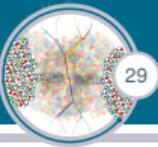


Unweighted



Model is robust!

Outline



Introduction

- Apples to Oranges
- Apples to Apples

Analysis Details

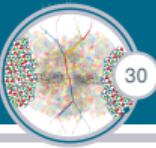
- Generation and Reconstruction Details
- Underlying Event Generation Details
- Subtraction Details

Results

- Observable Robustness
- ML Robustness
- A note on EFPs

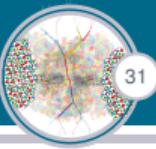
Conclusions and Future Work

Conclusions



1. In order to compare apples to apples, such that our algorithms hunt the physics not procedural fluctuations, one needs to embed the pp jets in a "as similar as possible" UE, uncorrelated with the hard scattering, and perform the same procedure as in PbPb jets.
2. The way we model this "fake" UE is crucial for our final results, but more crucial even for the possibility of a fair usable jet-by-jet quenching tagger in experiment, theory and phenomenology.
3. Modelling this UE directly through data seems to be our best option.
4. The modifications and discriminant information left after the procedure is the only one we can access in experiment and so is the only one we can take as physical.
5. Only the effects present after a similar procedure, can be taken as true PbPb modifications against a pp baseline.

Future Work



1. We intend to take this work further and study the impact of this procedure on different Neural Networks architectures, through supervised, unsupervised and semi-supervised learning. (many already done)
2. The inclusion of some data-driven modelling for ϕ would make the comparison between pp and PbPb jets fairer.
3. The inclusion of other particle species other than pions according to their measured abundance in experiment, would make the comparison even fairer.

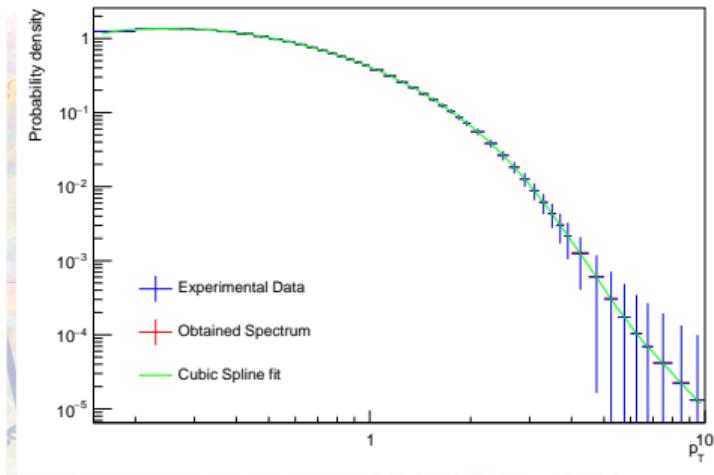
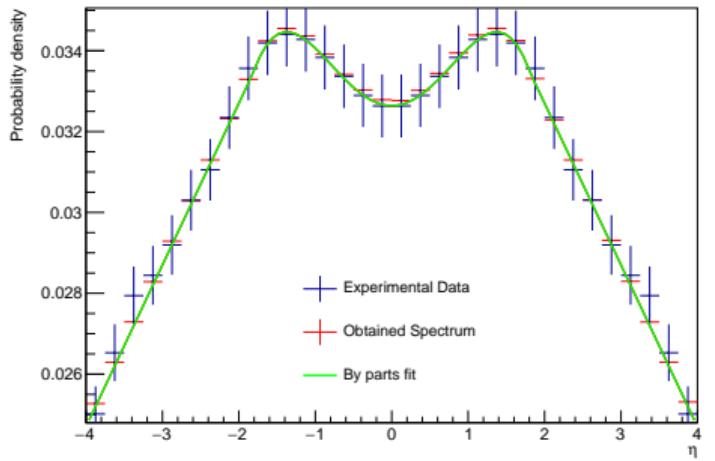


Thank you for your attention!

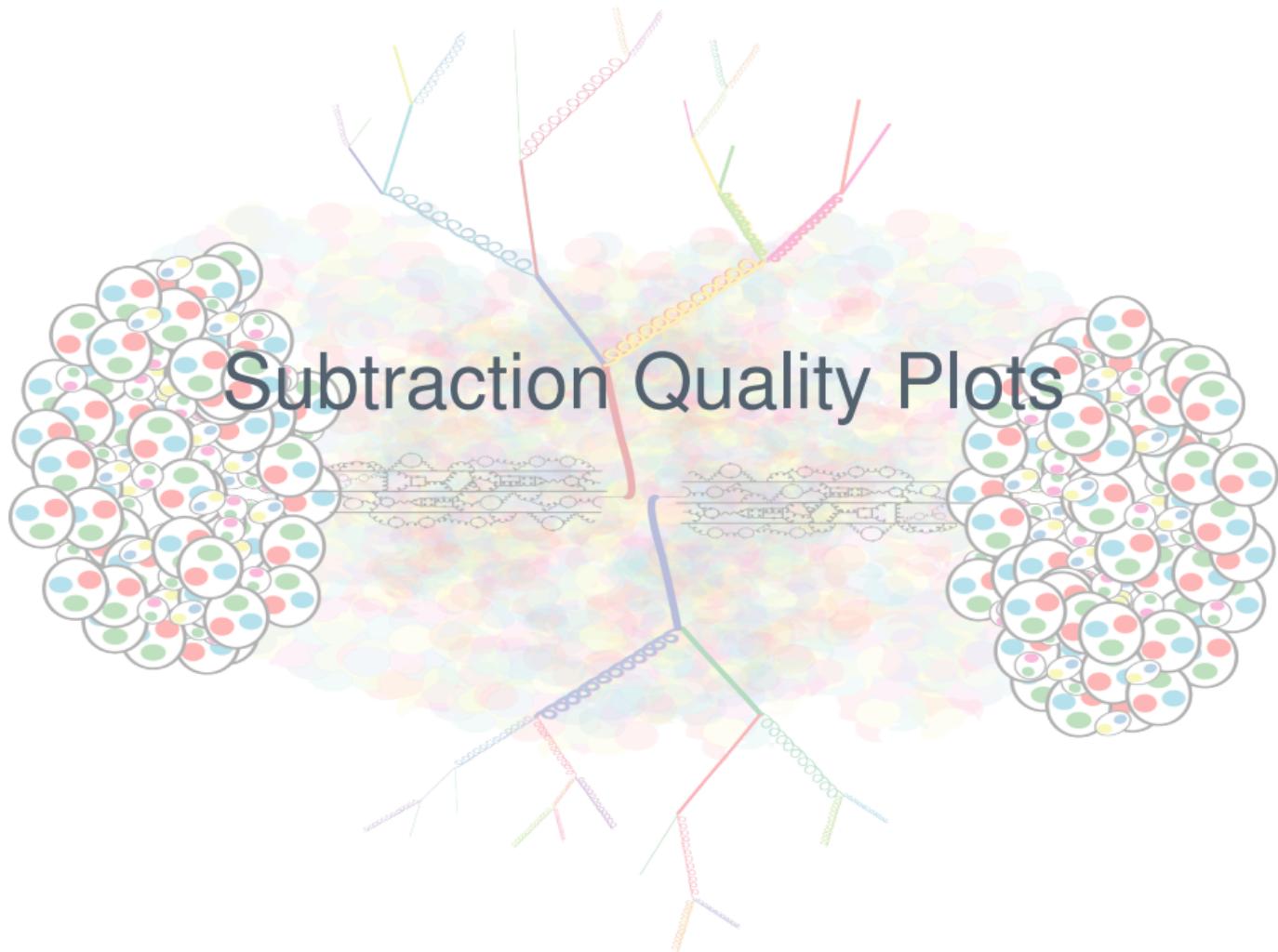
Backup

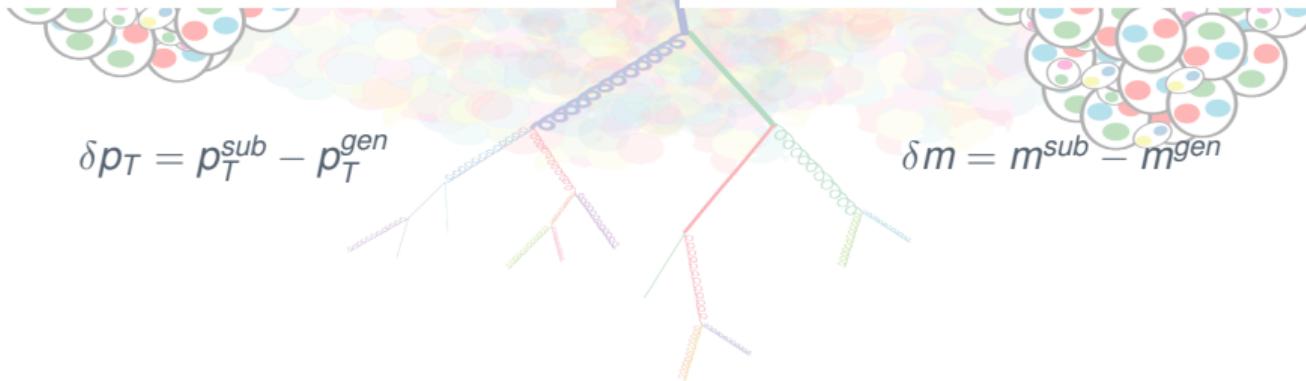
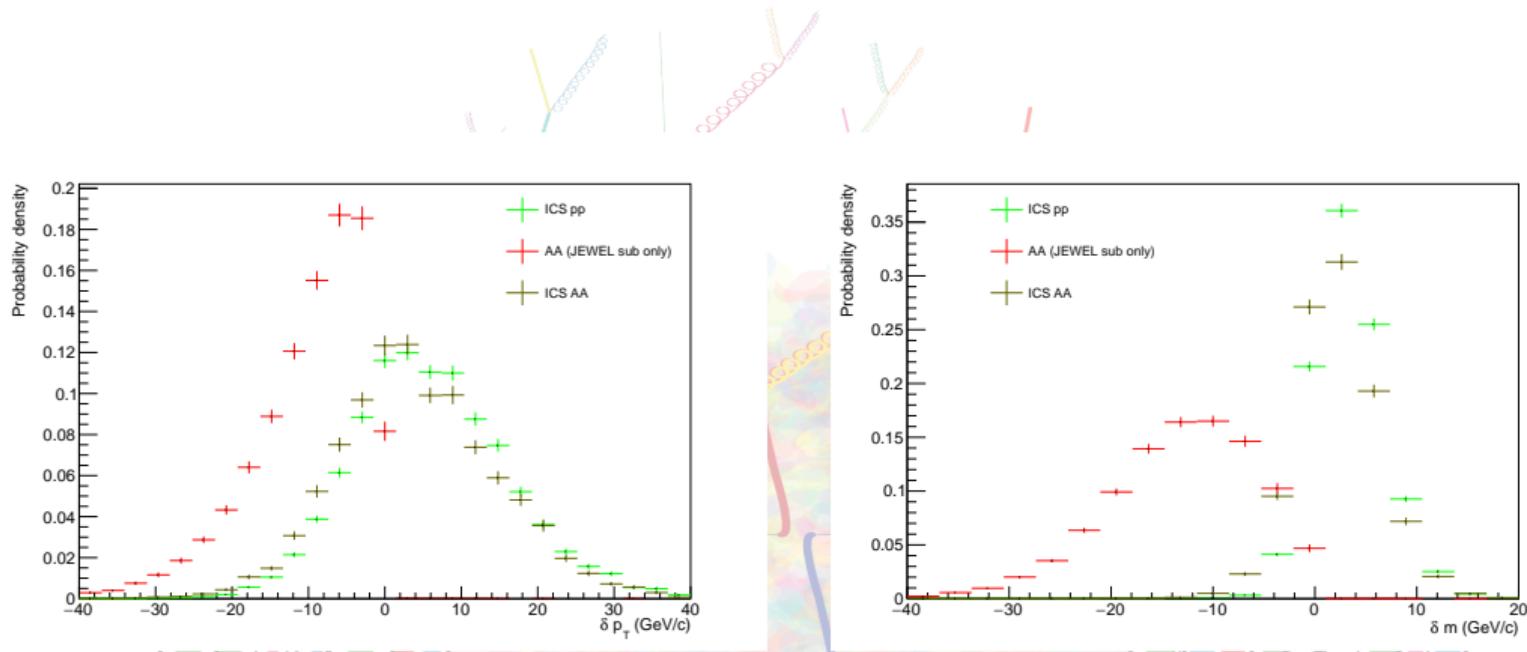
Underlying Event Fits

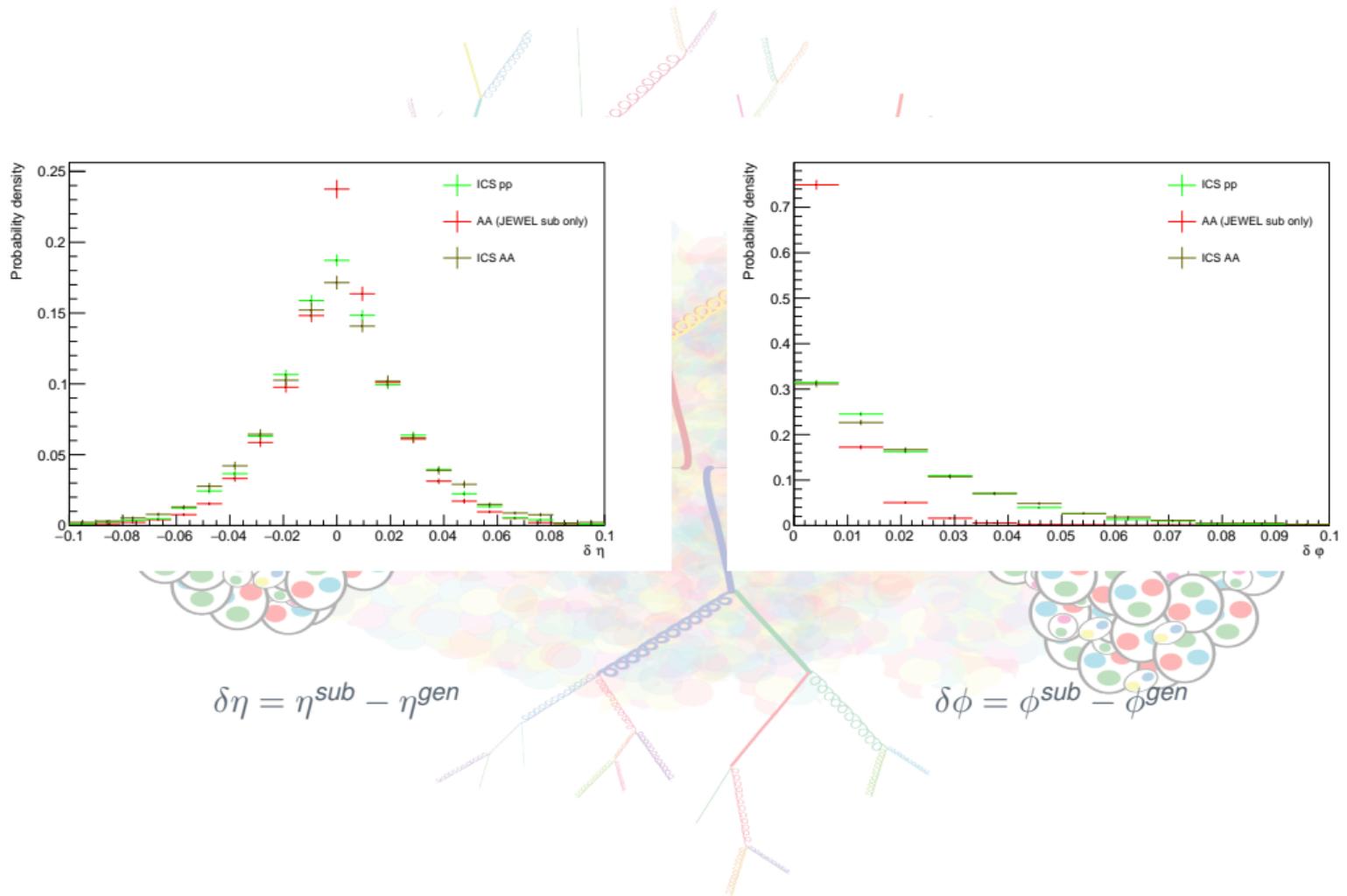




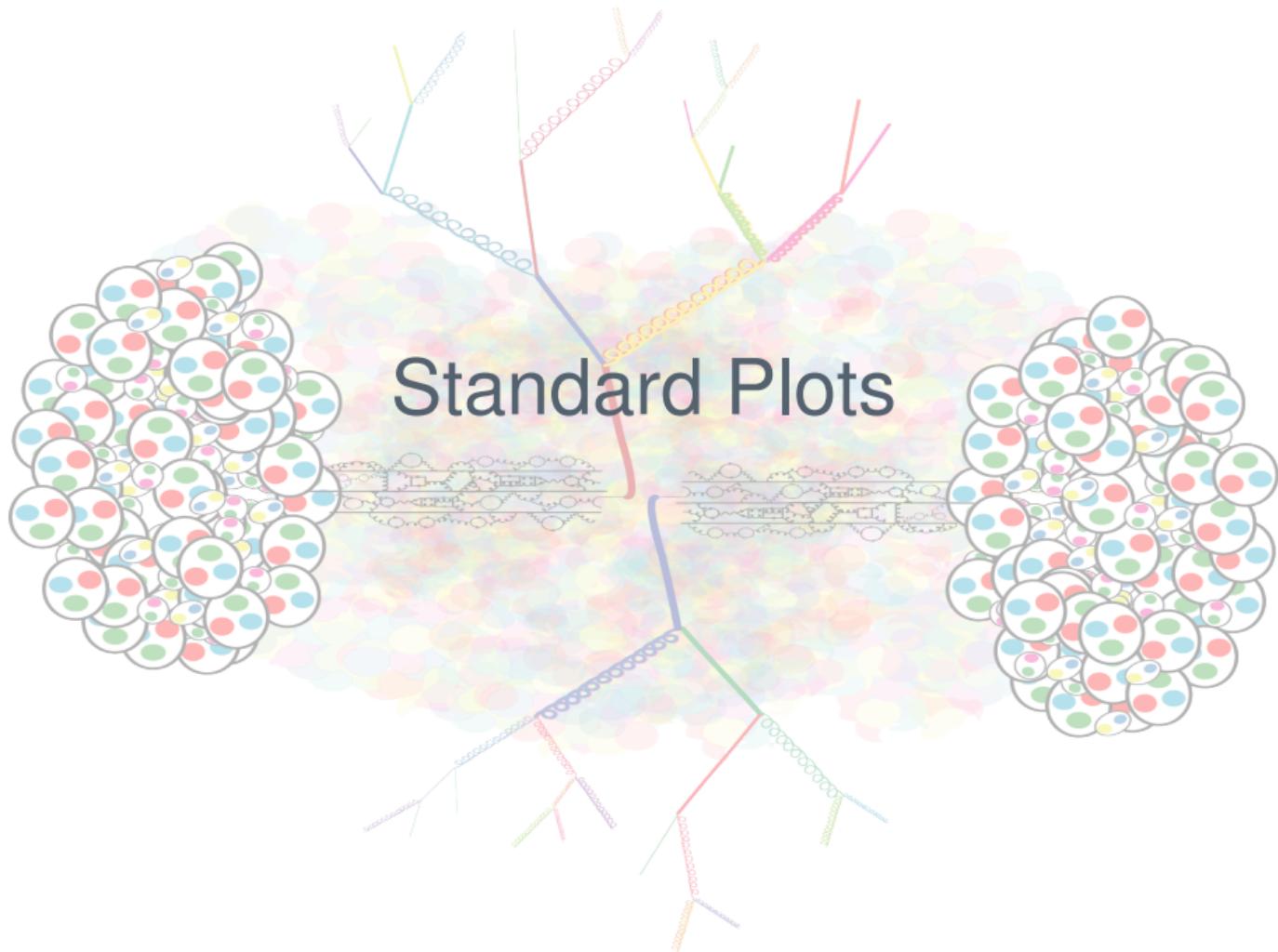
Subtraction Quality Plots

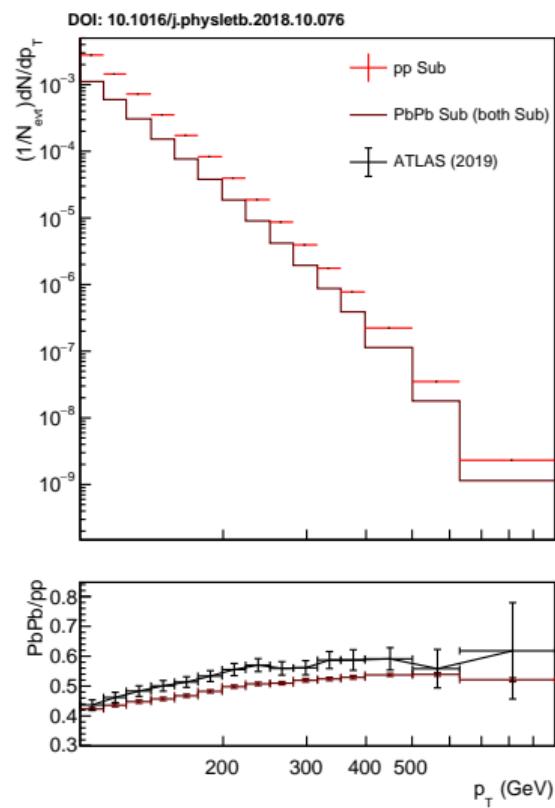
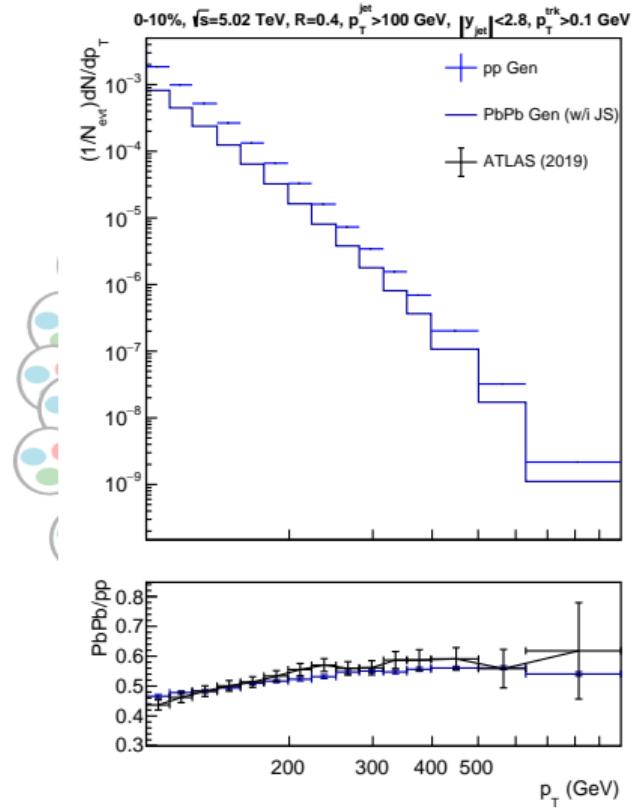


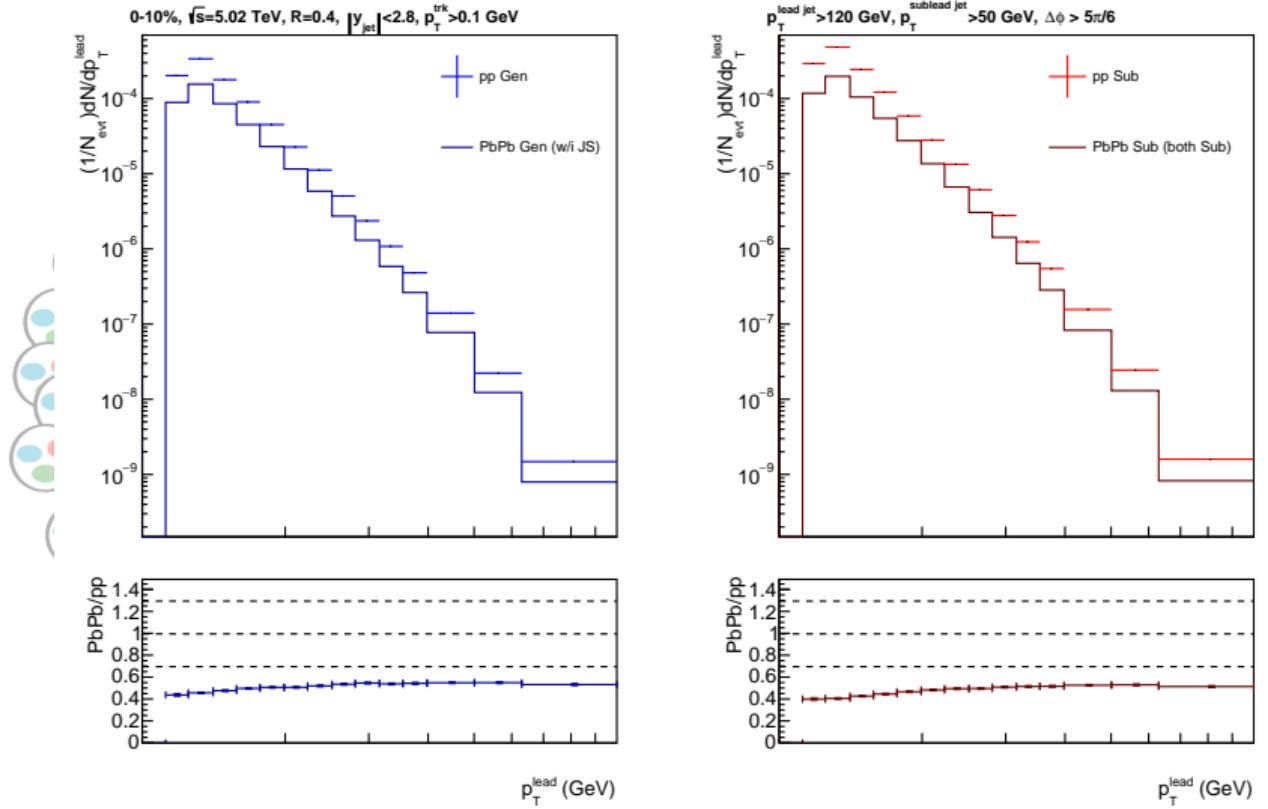


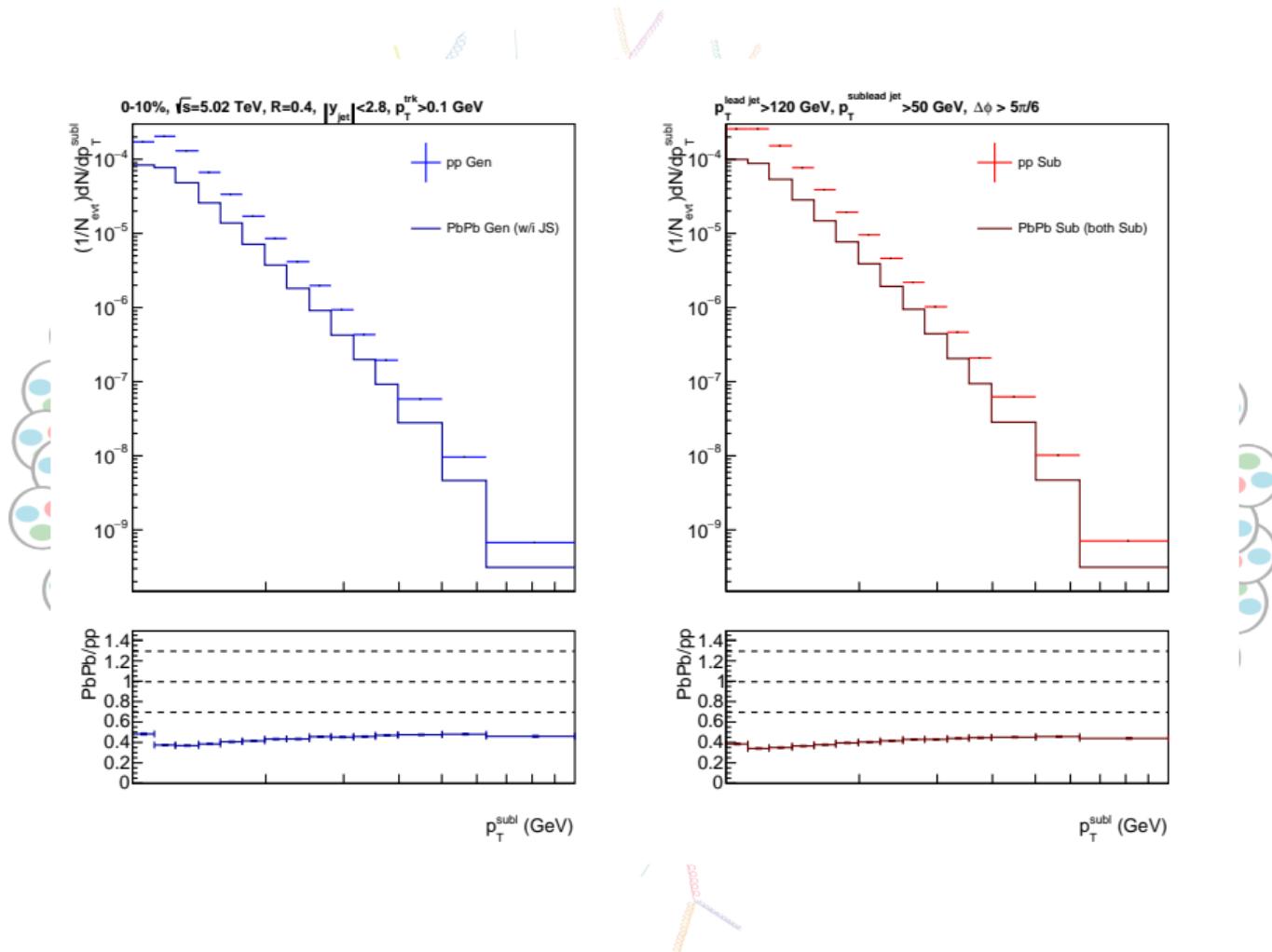


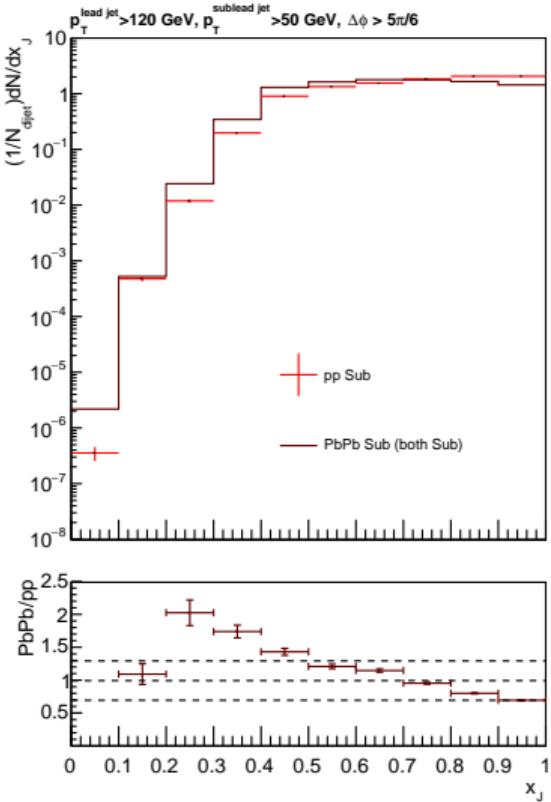
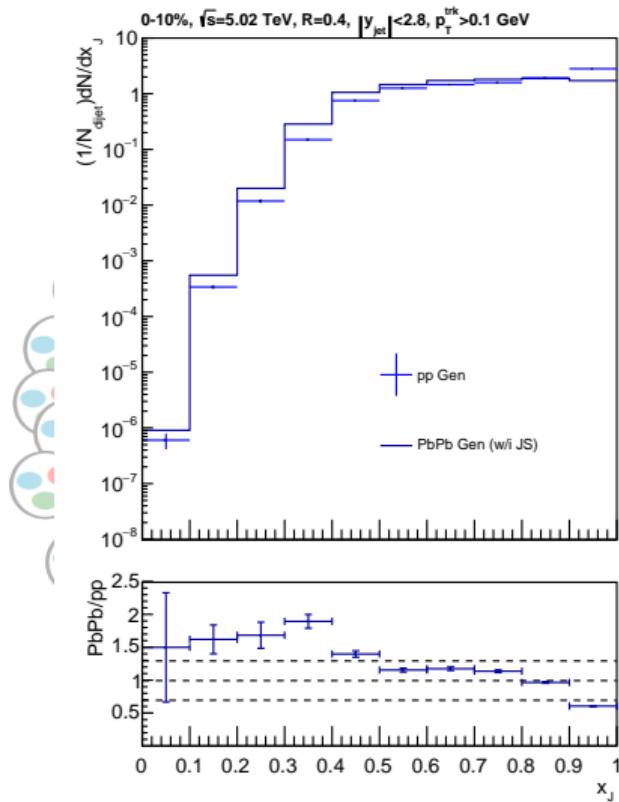
Standard Plots



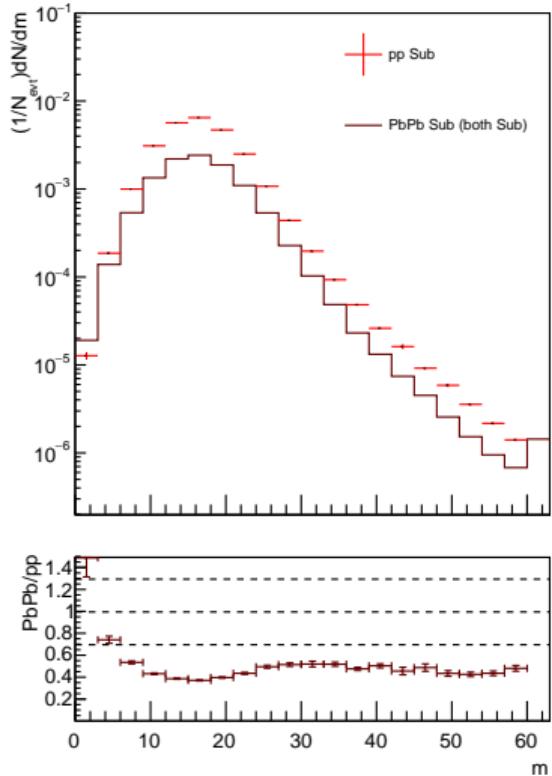
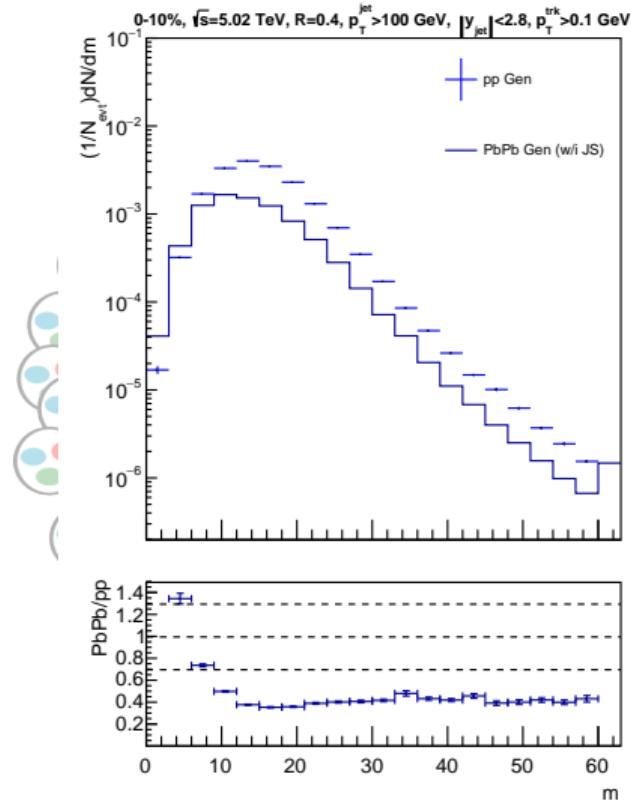


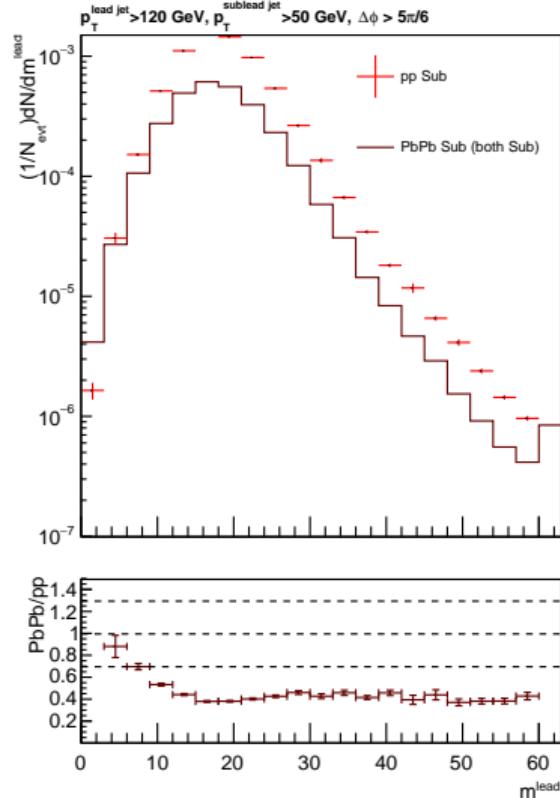
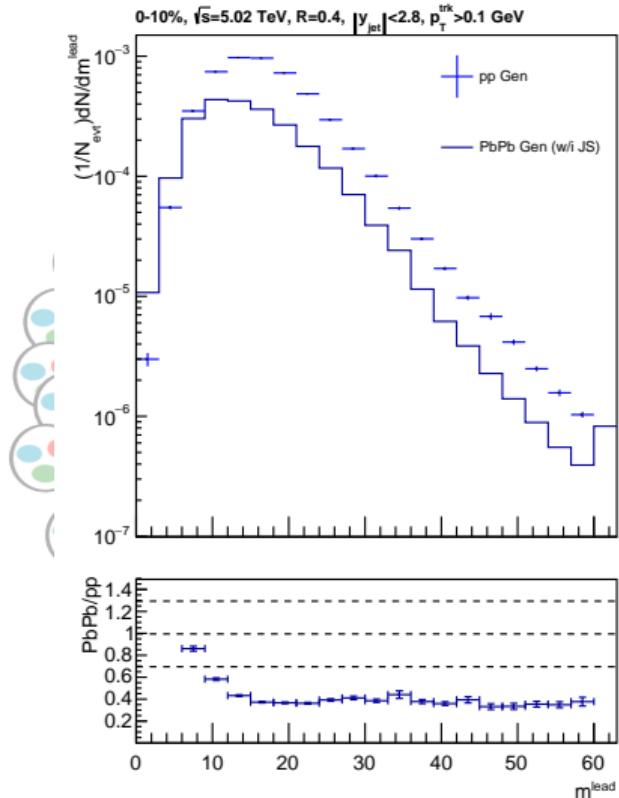




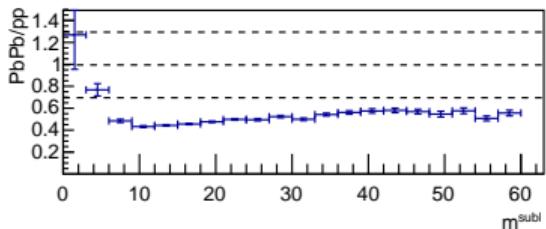
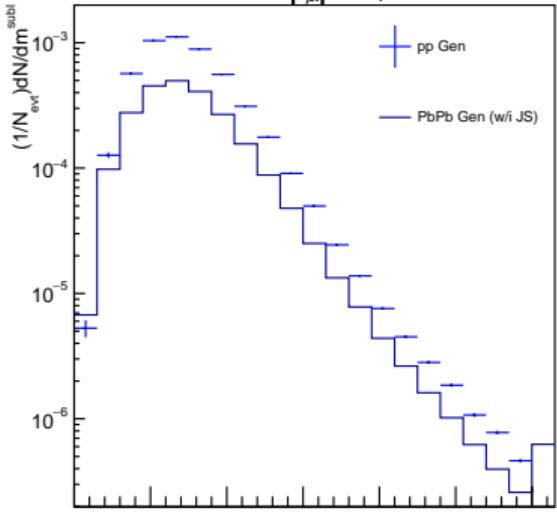


$$x_j = p_T^{\text{sublead}} / p_T^{\text{lead}}$$

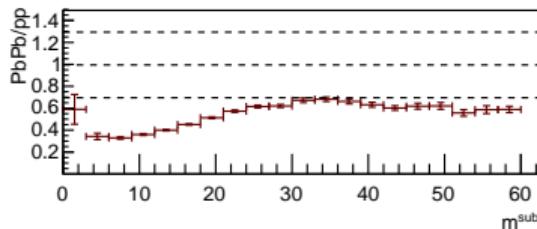
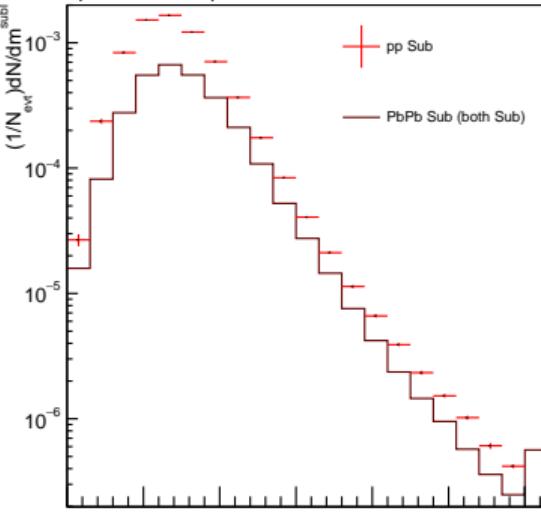




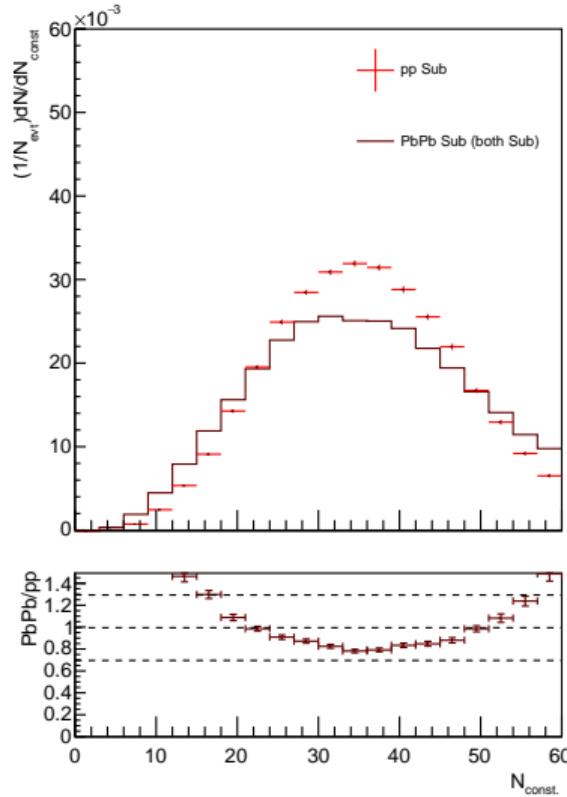
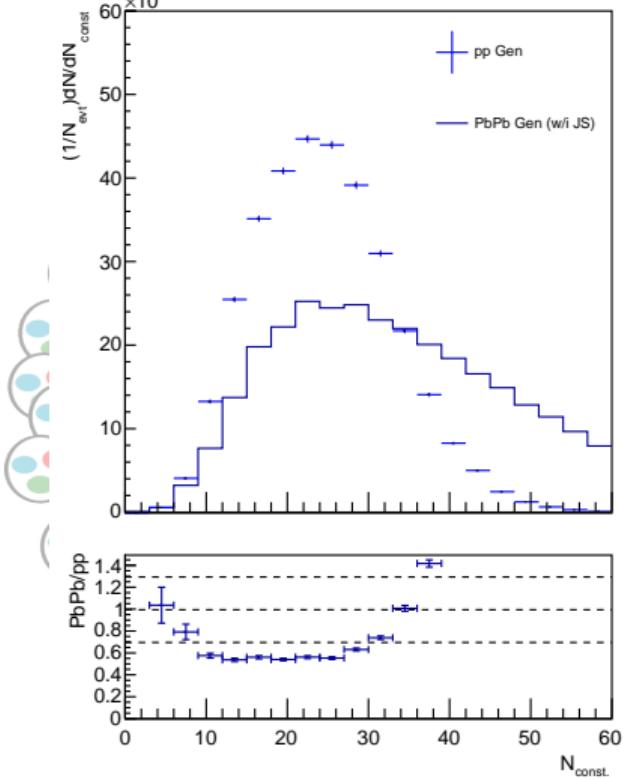
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|y_{\text{jet}}|<2.8$, $p_T^{\text{trk}}>0.1$ GeV



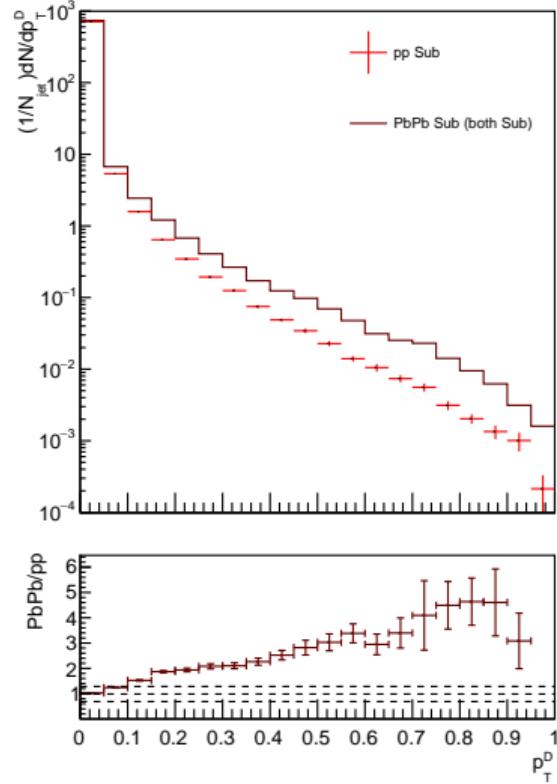
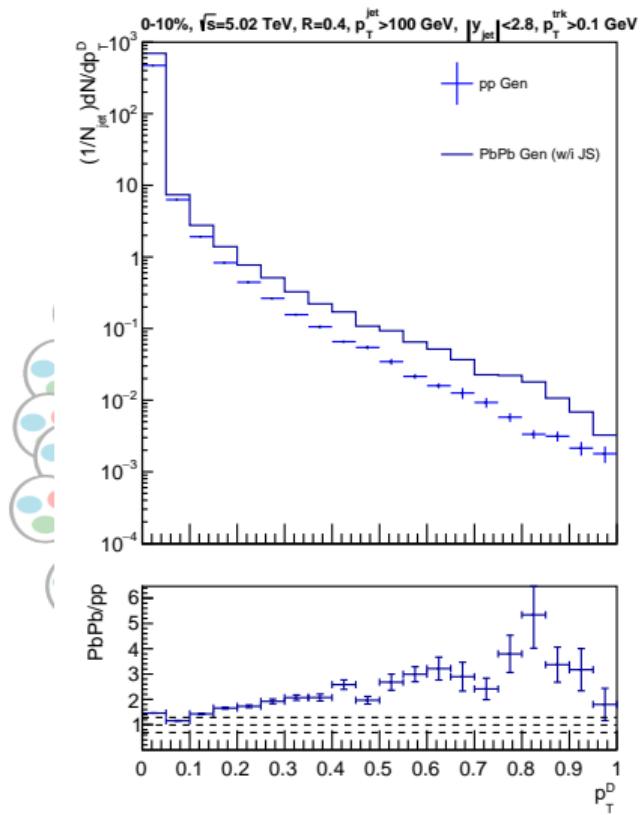
$p_T^{\text{lead jet}}>120$ GeV, $p_T^{\text{sublead jet}}>50$ GeV, $\Delta\phi>5\pi/6$



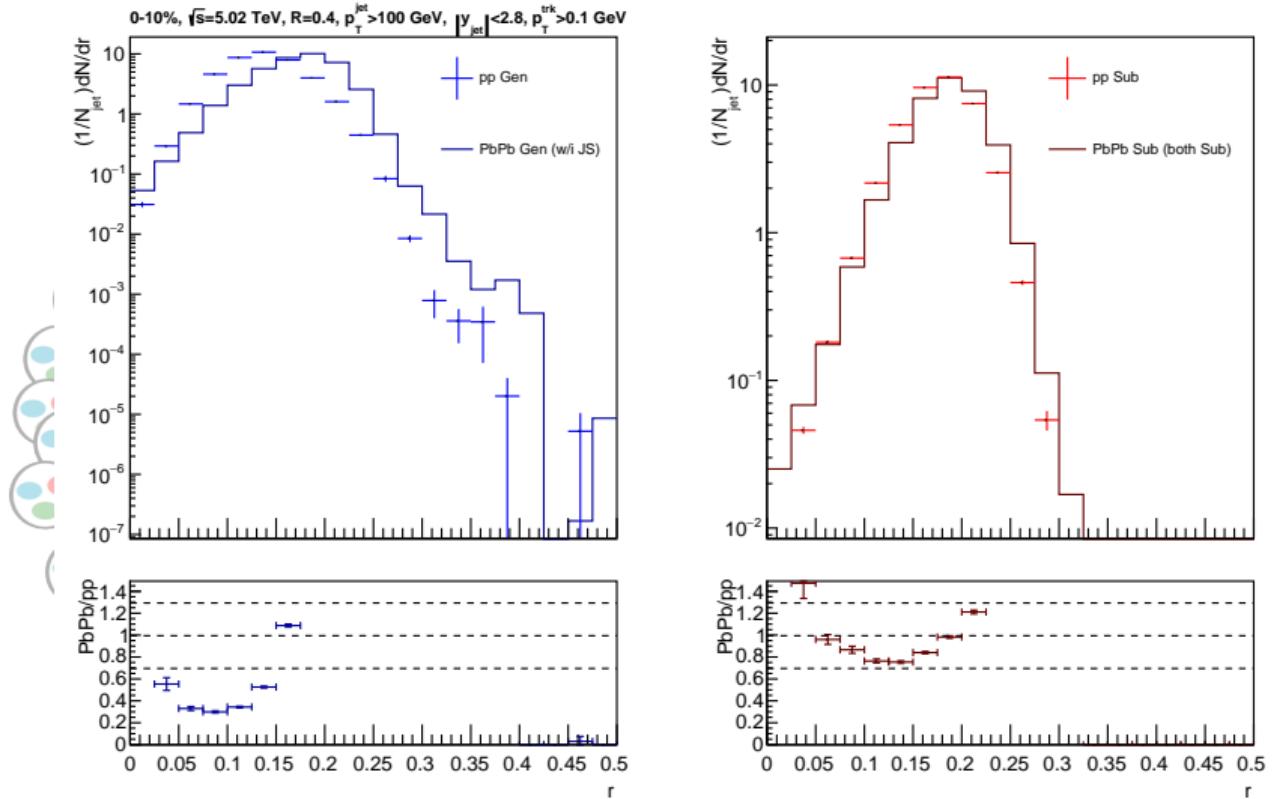
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $p_T^{jet} > 100$ GeV, $|y_{jet}| < 2.8$, $p_T^{trk} > 0.1$ GeV



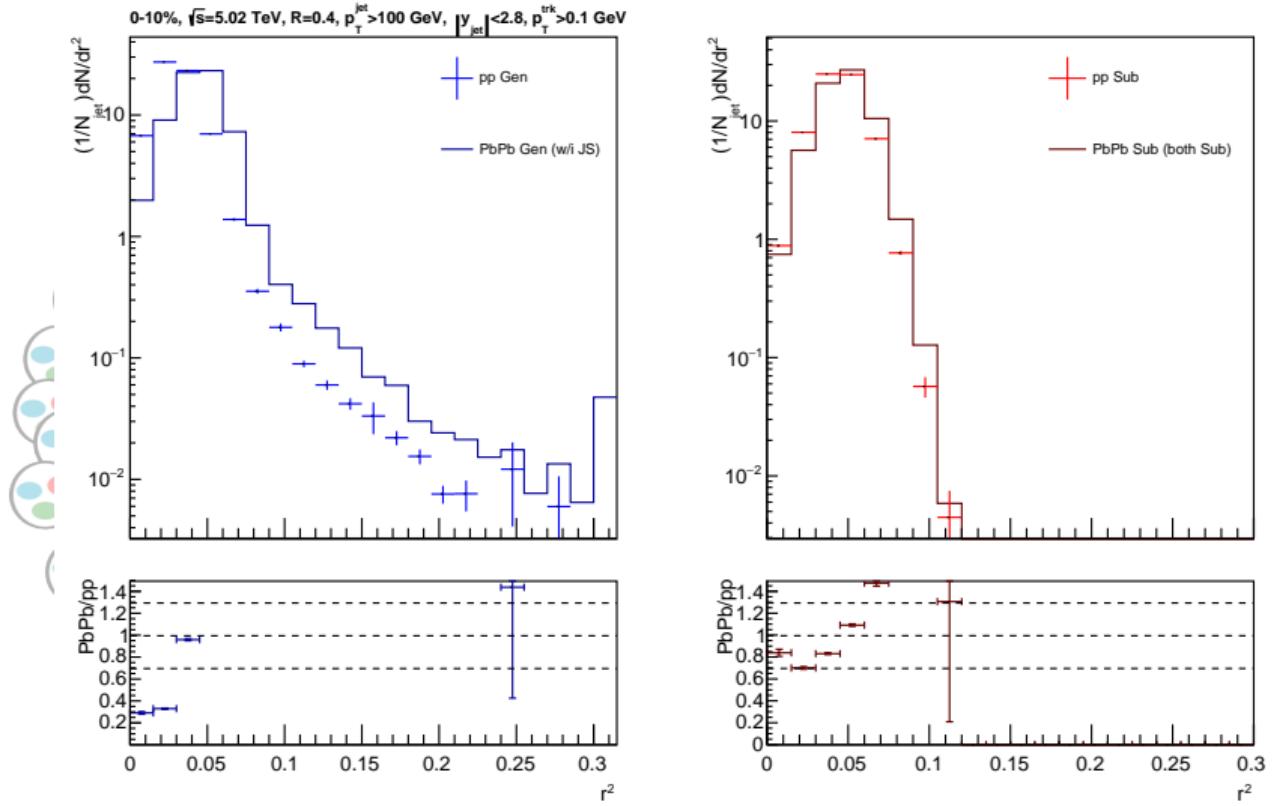
$$N_{cts} = \sum_{\text{consts}} 1$$



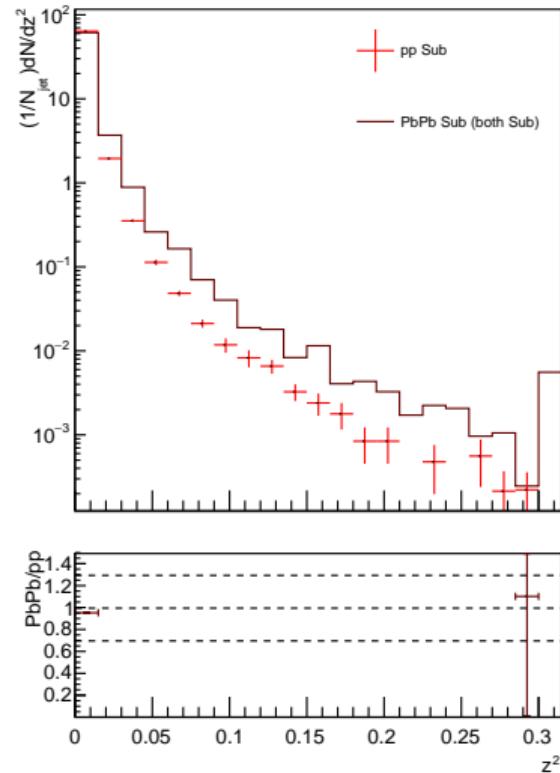
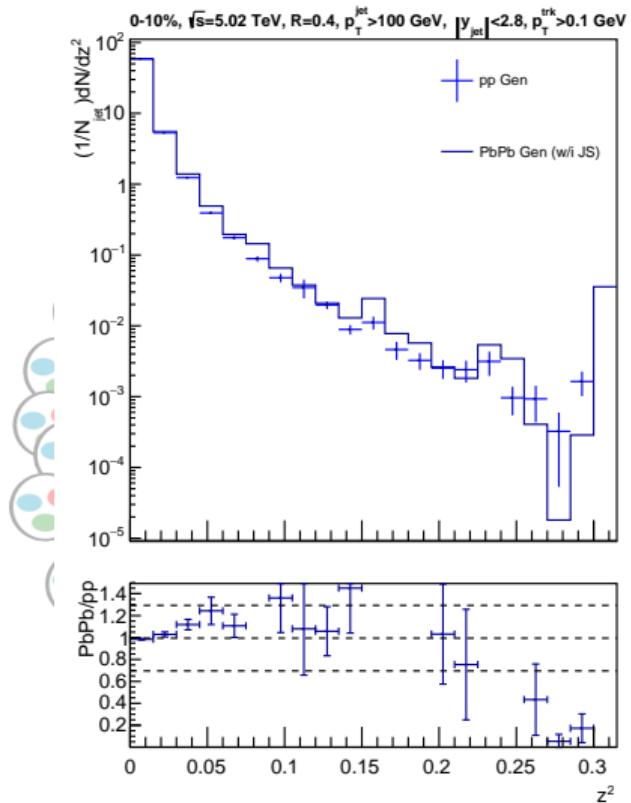
$$p_T^D = \left(\frac{p_T^j}{p_T^{jet}} \right)^2 \cos^2(r); r = \sqrt{(\phi_i - \phi_{jet})^2 + (\eta_i - \eta_{jet})^2}$$



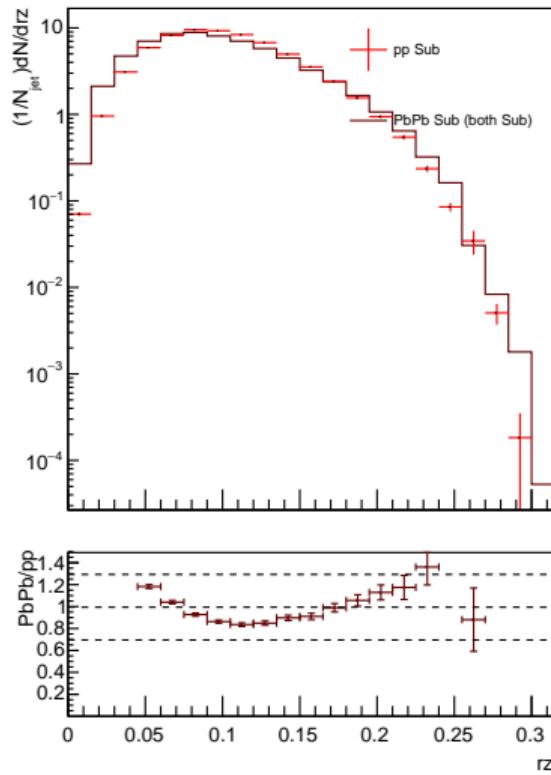
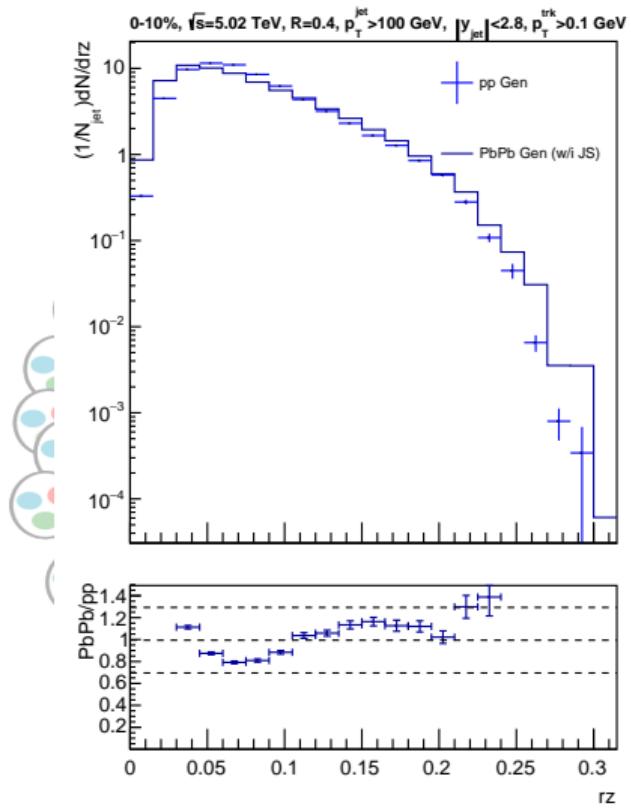
$$r = \sum_{\text{consts}} \frac{1}{N_{\text{consts}}} \sqrt{(\phi_i - \phi_{\text{jet}})^2 + (\eta_i - \eta_{\text{jet}})^2}$$



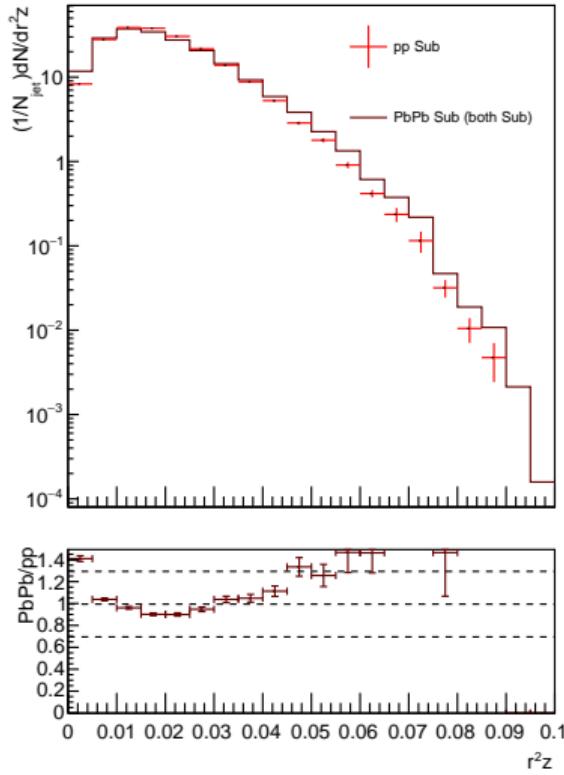
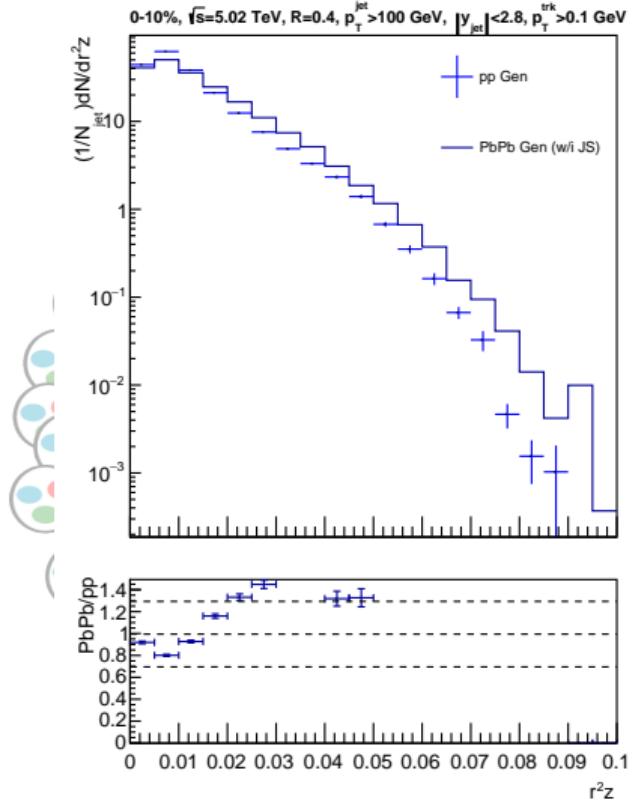
$$r^2 = \sum_{\text{consts}} \frac{1}{N_{\text{consts}}} |(\phi_i - \phi_{\text{jet}})^2 + (\eta_i - \eta_{\text{jet}})^2|$$



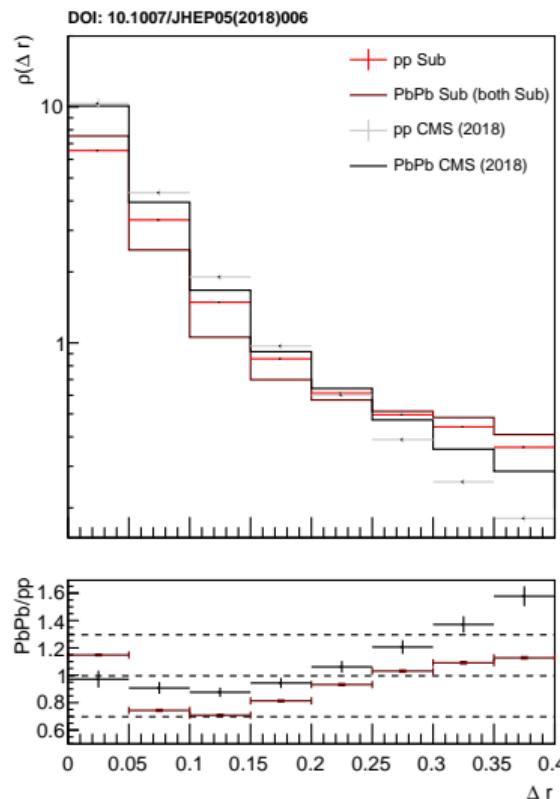
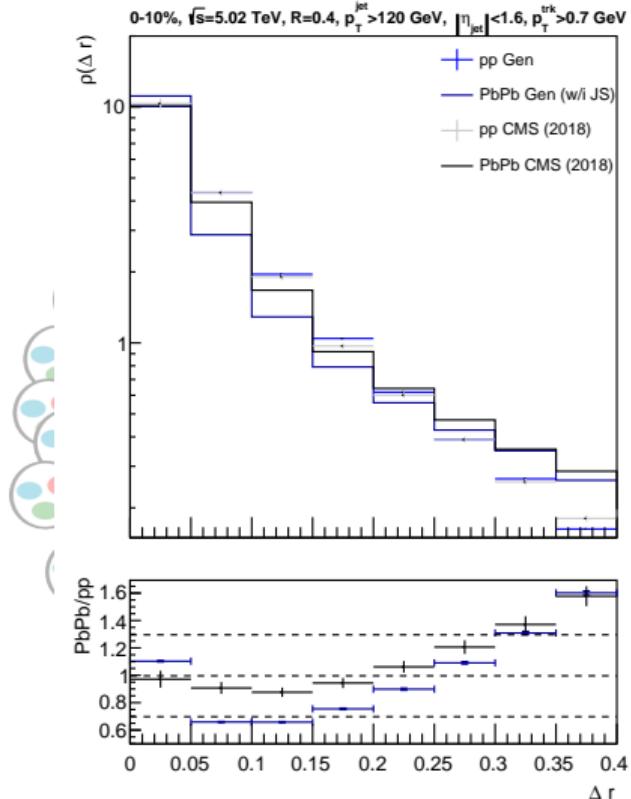
$$z^2 = \sum_{\text{consts}} \frac{1}{N_{\text{consts}}} \left(\frac{p_T^i}{p_T^{\text{jet}}} \right)^2$$



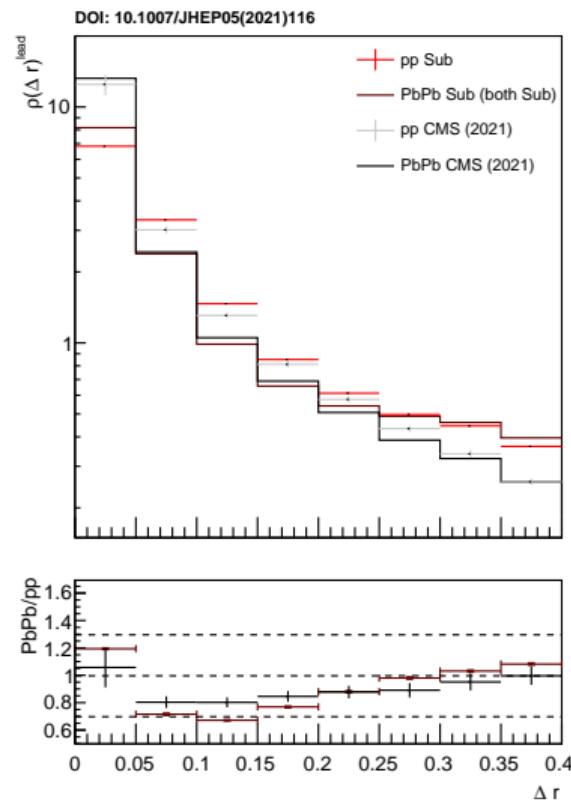
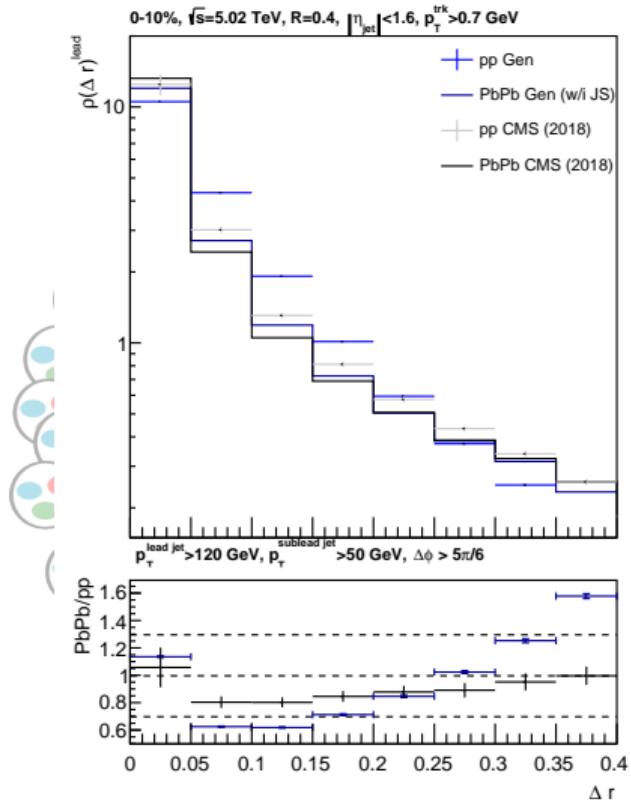
$$rz = \sum_{consts} \frac{1}{N_{consts}} \left(\frac{p_T^i}{p_T^{jet}} \right) \sqrt{(\phi_i - \phi_{jet})^2 + (\eta_i - \eta_{jet})^2}$$



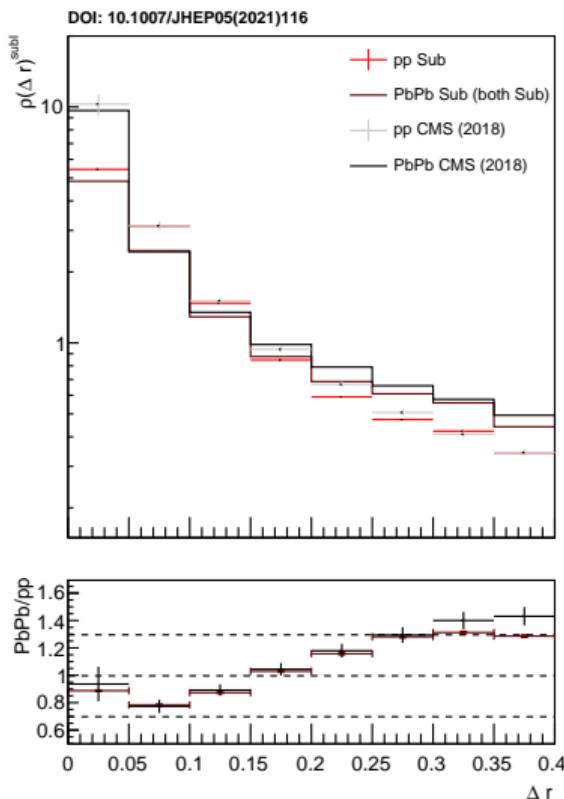
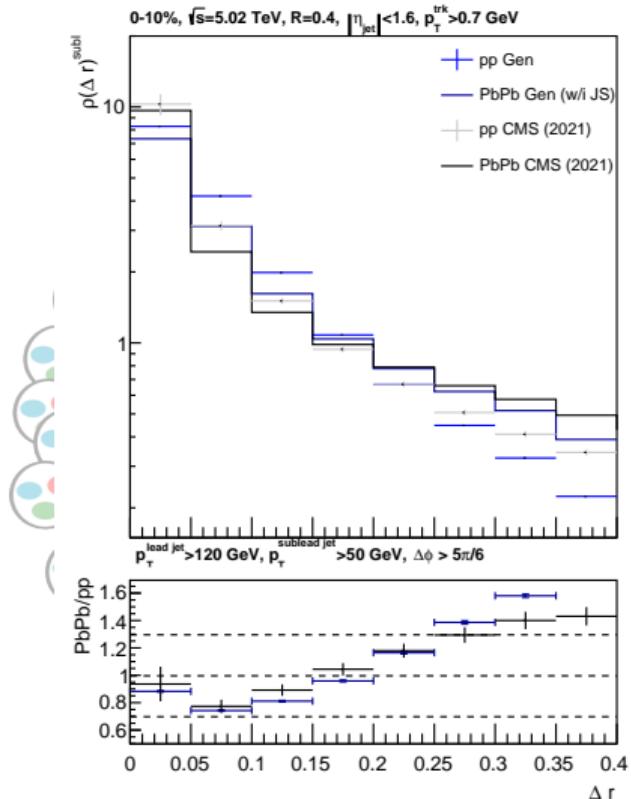
$$r^2 z = \sum_{\text{consts}} \frac{1}{N_{\text{consts}}} \left(\frac{p_T^i}{p_T^{\text{jet}}} \right) |(\phi_i - \phi_{\text{jet}})^2 + (\eta_i - \eta_{\text{jet}})^2|$$



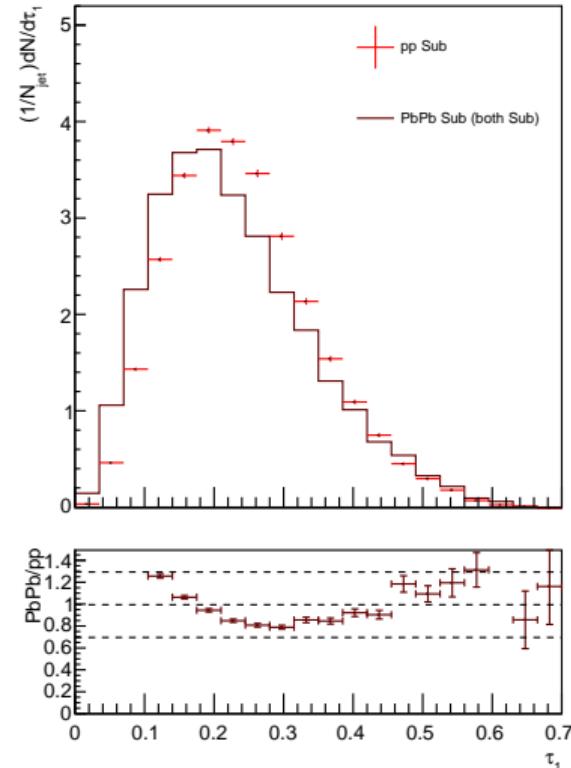
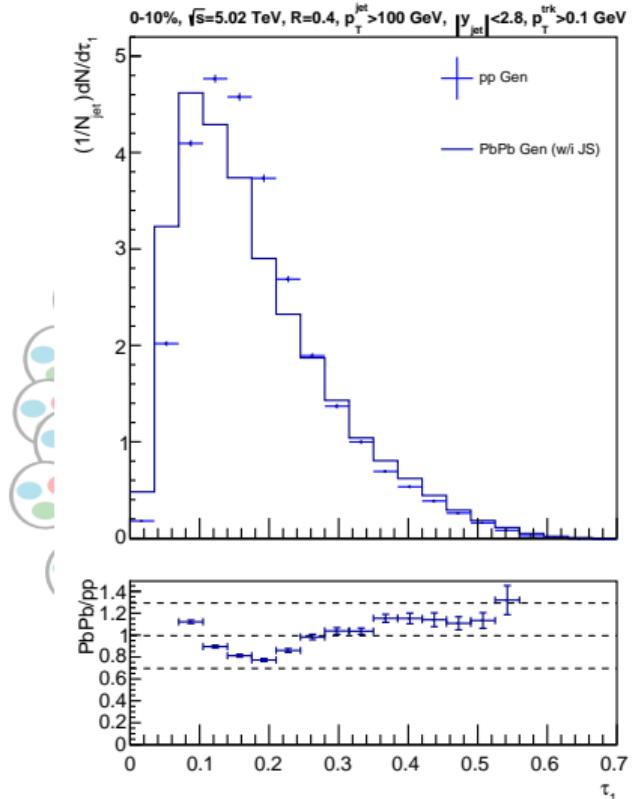
$$\rho(\Delta r) = \frac{1}{\delta r} \frac{1}{N_{\text{jets}}} \sum_{\text{const} \in \Delta r} p_T^{\text{const}}$$



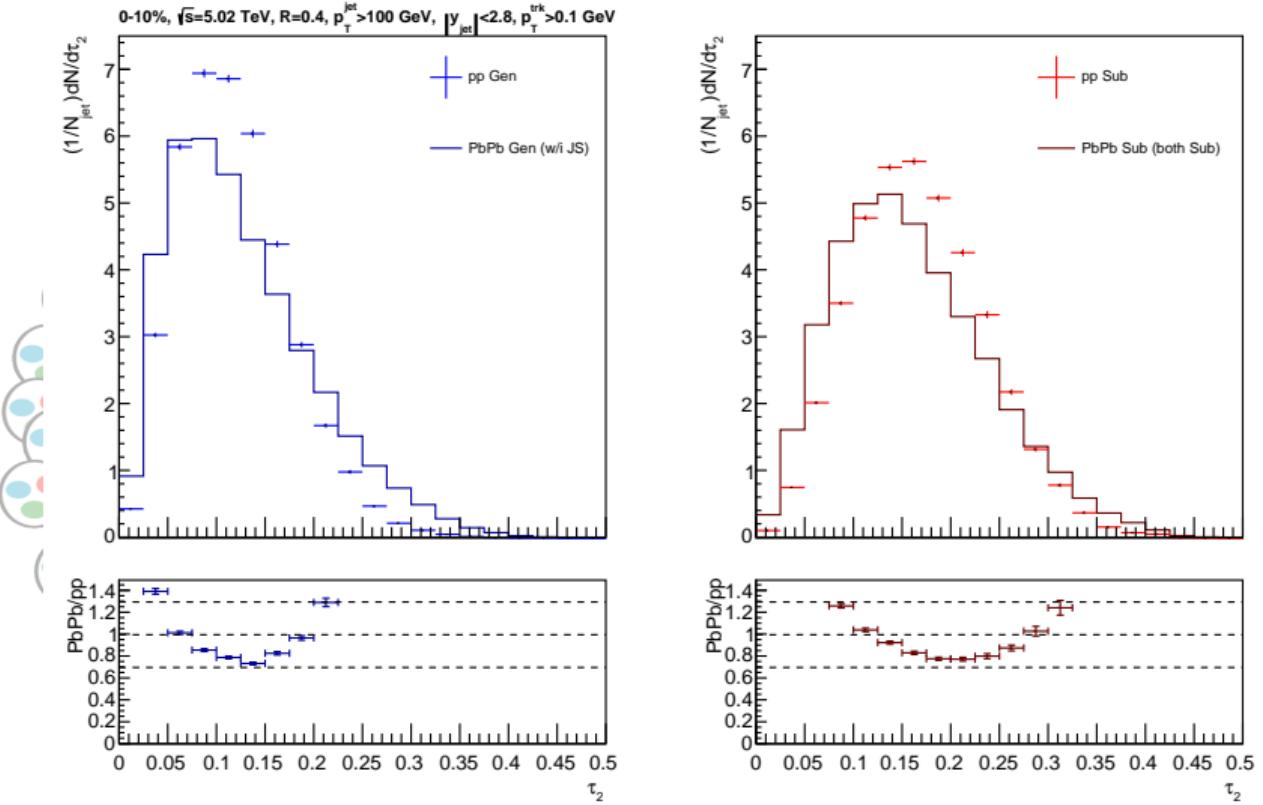
$$\rho(\Delta r) = \frac{1}{\delta r} \frac{1}{N_{\text{jets}}} \sum_{\text{const} \in \Delta r} p_T^{\text{const}}$$



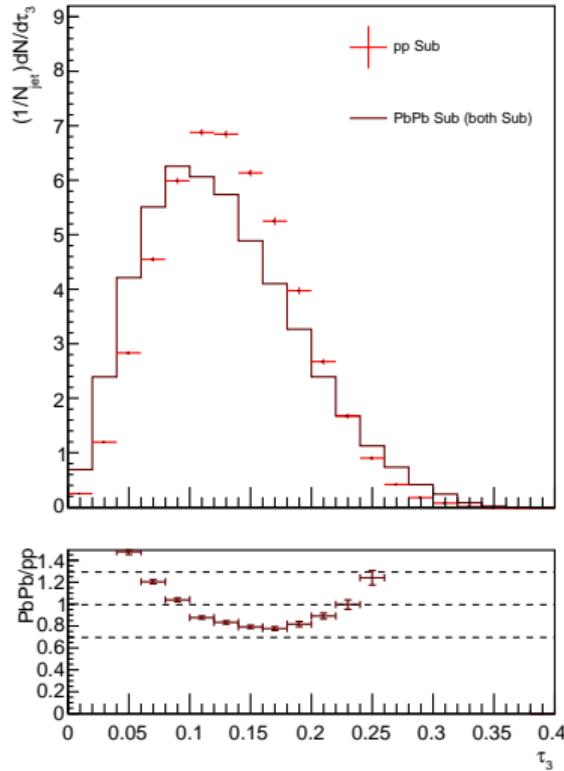
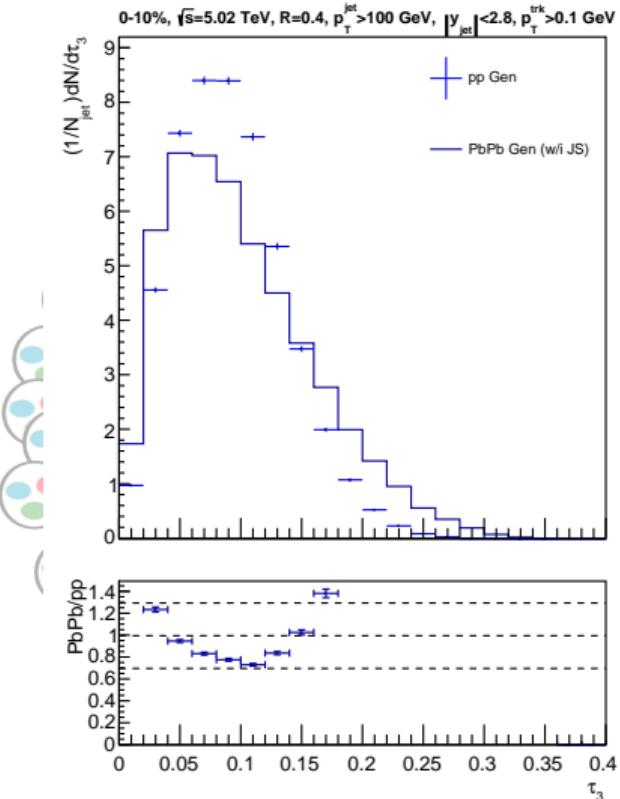
$$\rho(\Delta r) = \frac{1}{\delta r} \frac{1}{N_{\text{jets}}} \sum_{\text{const} \in \Delta r} p_T^{\text{const}}$$



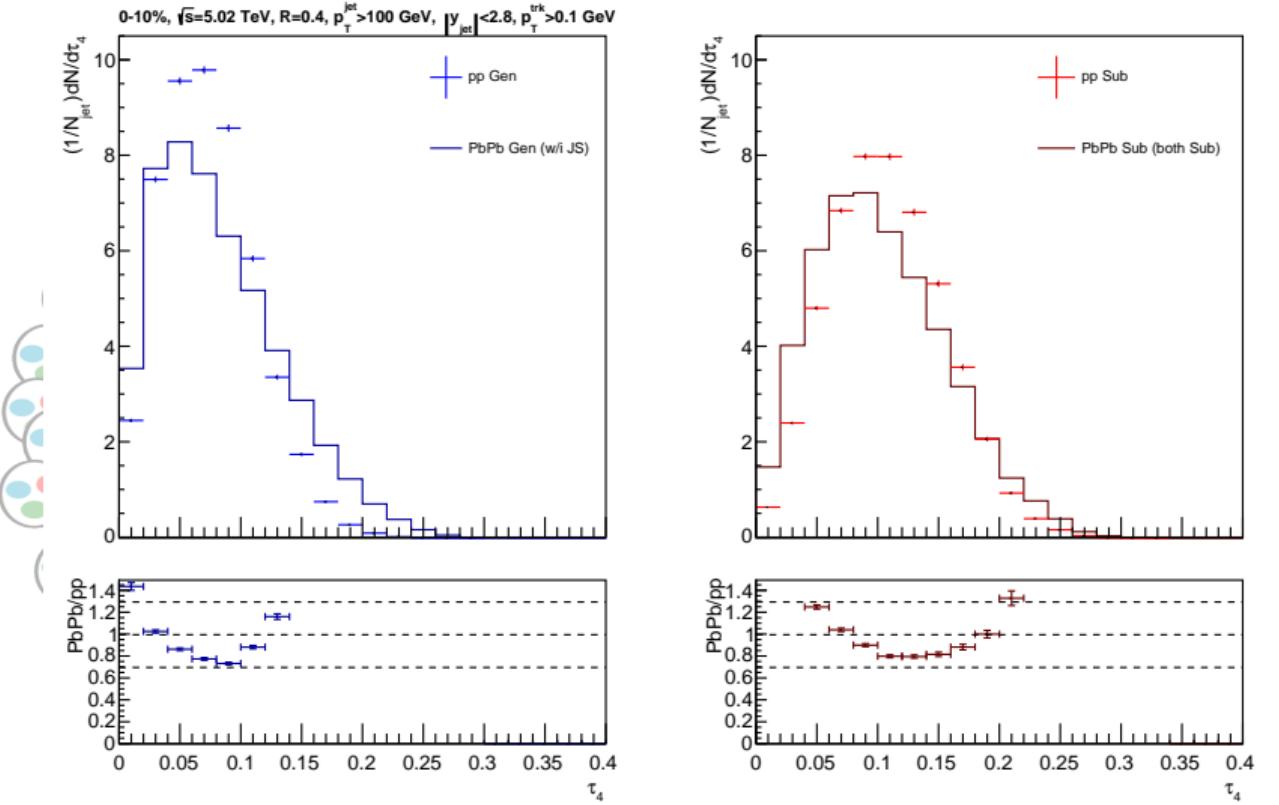
$$\tau_1 = \sum_{\text{consts}} p_T^{\text{const}} / \Delta R_{\text{subjet1, const}}$$



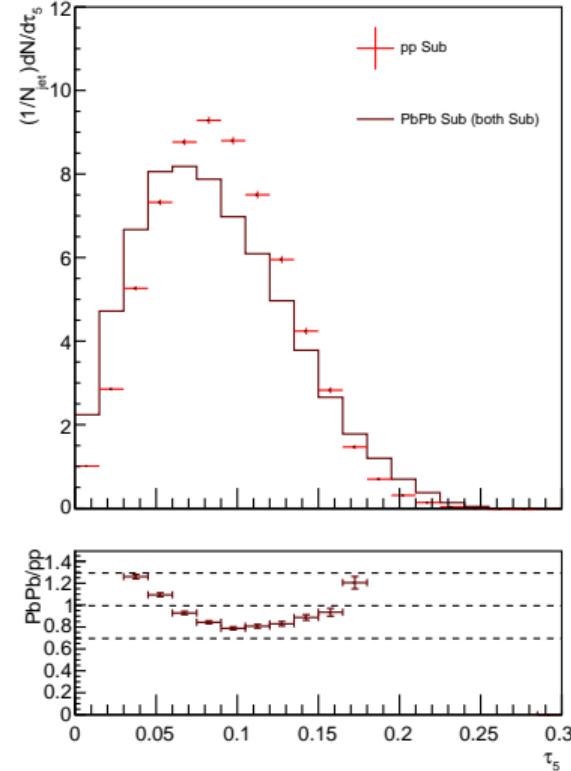
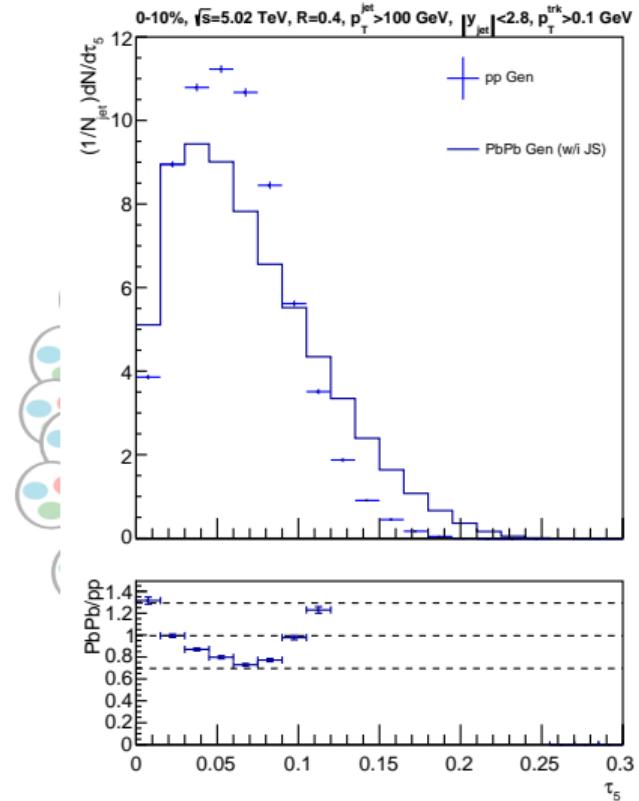
$$\tau_2 = \sum_{consts} p_T^{const} \min(\Delta R_{subj1,const}, \Delta R_{subj2,const})$$



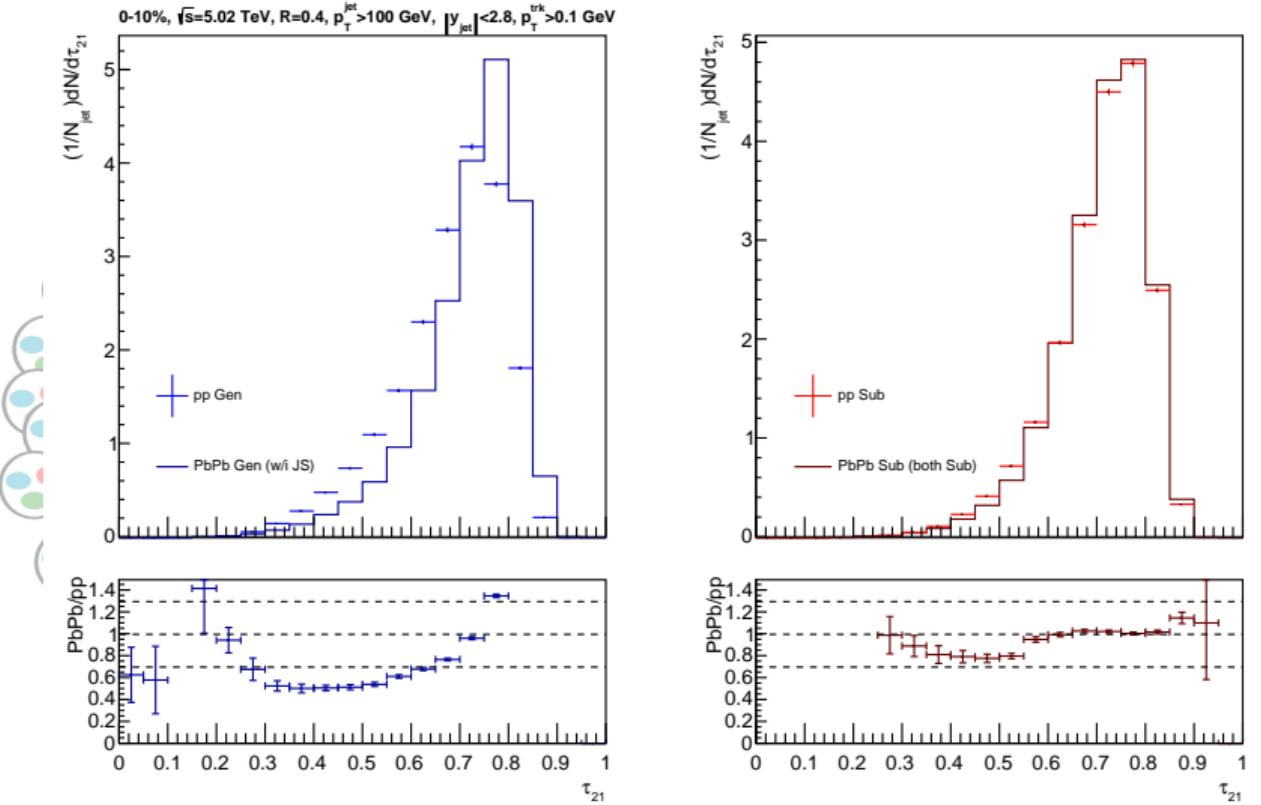
$$\tau_3 = \sum_{\text{consts}} p_T^{\text{const}} \min(\Delta R_{\text{subj}1,\text{const}}, \Delta R_{\text{subj}2,\text{const}}, \Delta R_{\text{subj}3,\text{const}})$$



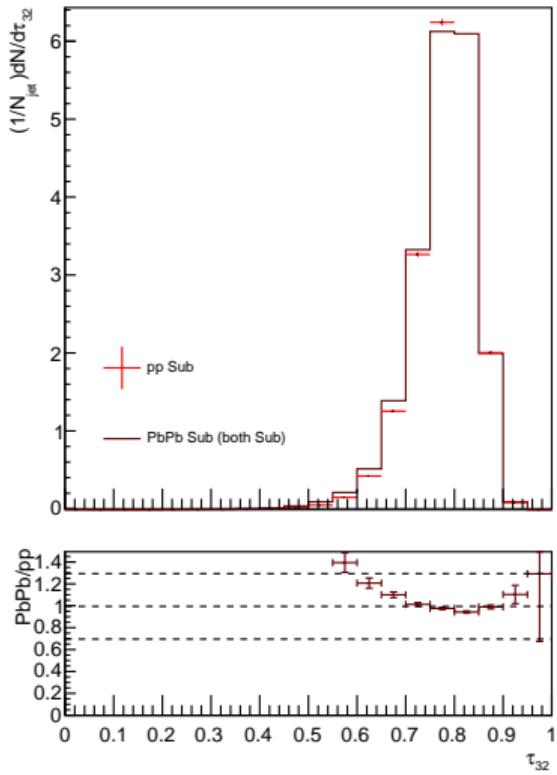
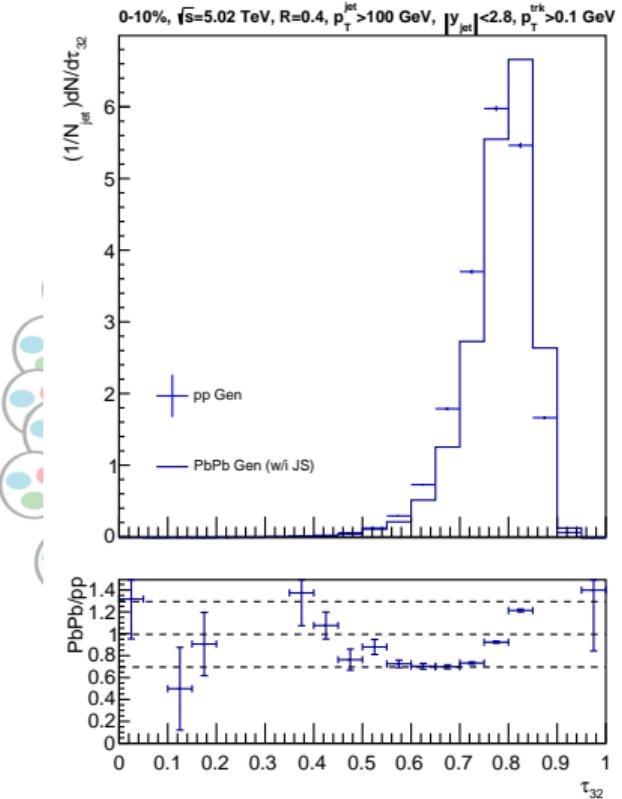
$$\tau_4 = \sum_{\text{consts}} p_T^{\text{const}} \min(\Delta R_{\text{subj}1,\text{const}}, \Delta R_{\text{subj}2,\text{const}}, \Delta R_{\text{subj}3,\text{const}}, \Delta R_{\text{subj}4,\text{const}})$$



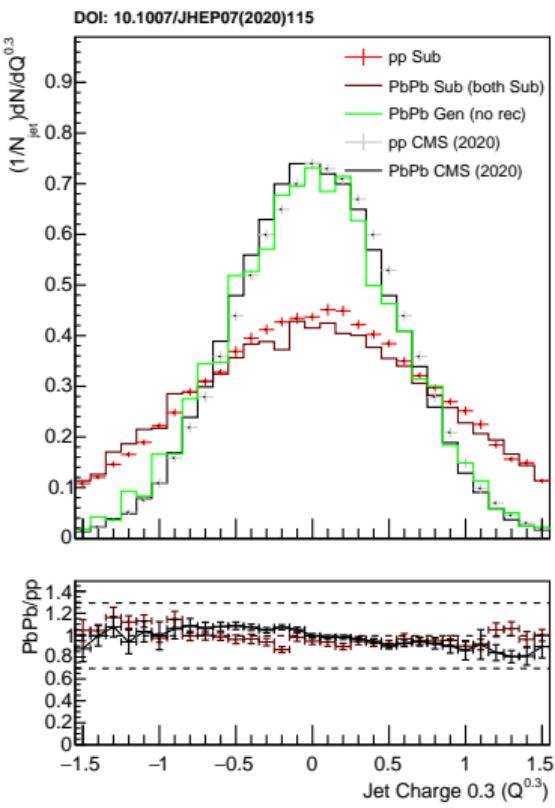
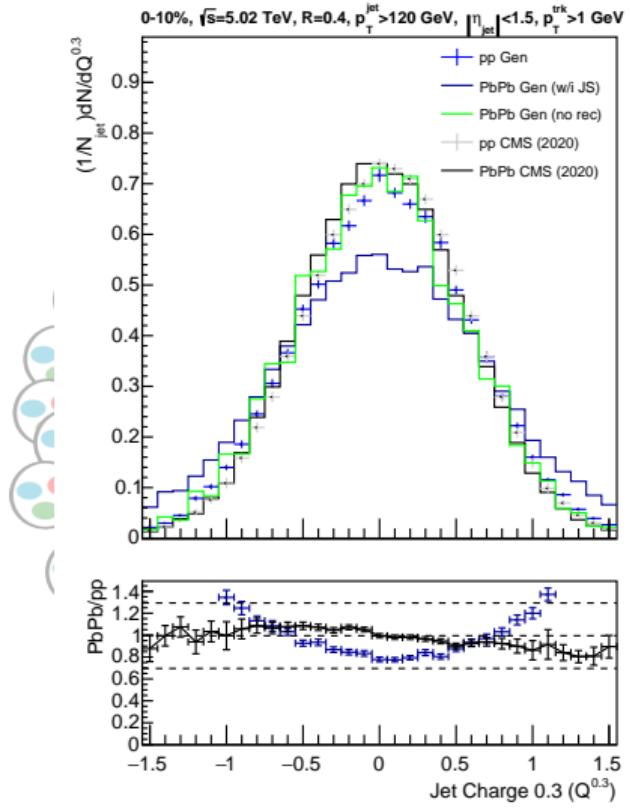
$$\tau_5 = \sum_{\text{consts}} p_T^{\text{const}} \min(\Delta R_{\text{subj}1,\text{const}}, \Delta R_{\text{subj}2,\text{const}}, \Delta R_{\text{subj}3,\text{const}}, \dots, \Delta R_{\text{subj}5,\text{const}})$$



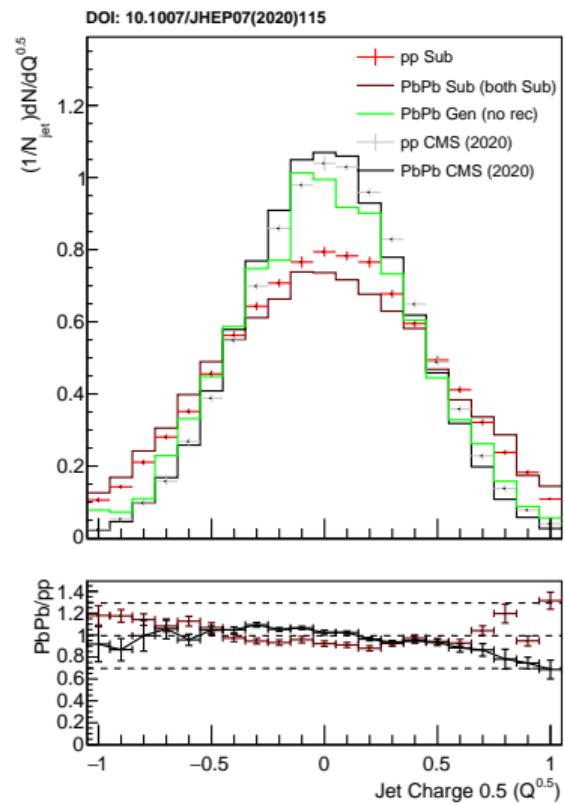
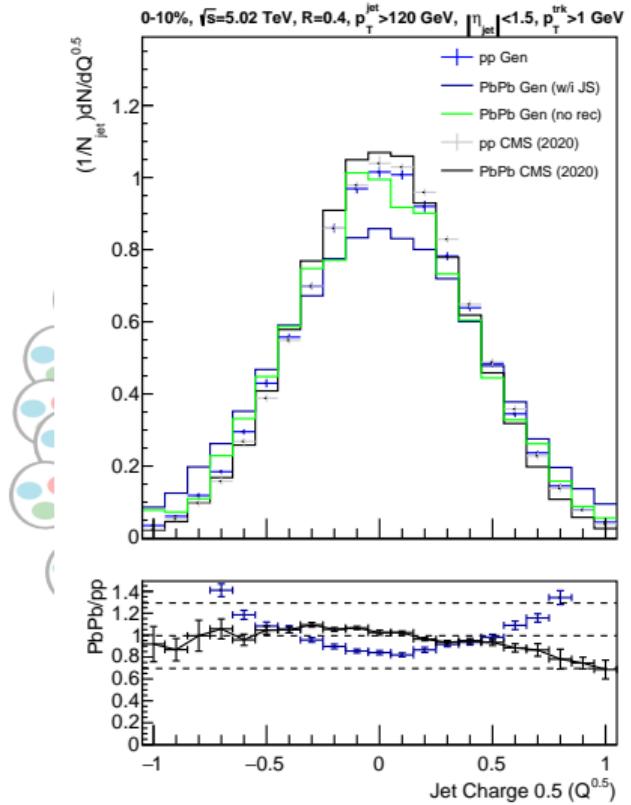
$$\tau_{21} = \frac{\tau_2}{\tau_1}$$



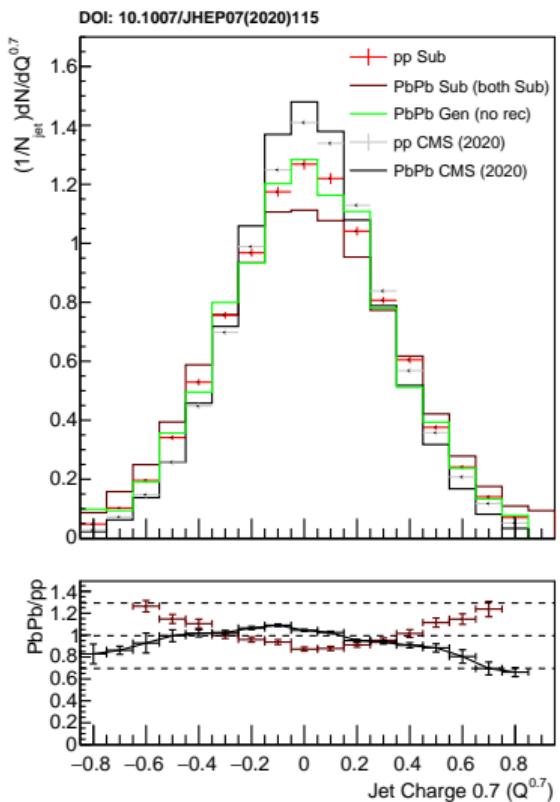
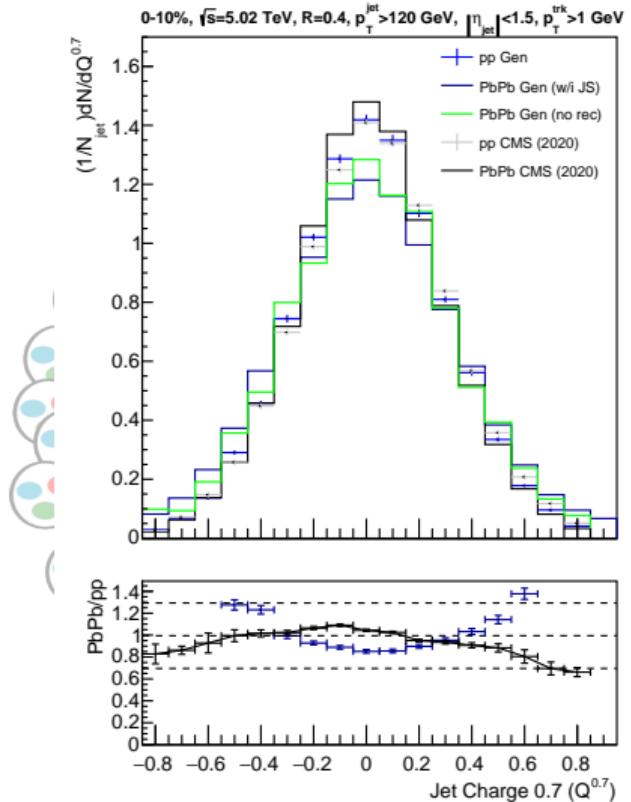
$$\tau_{21} = \frac{\tau_3}{\tau_2}$$



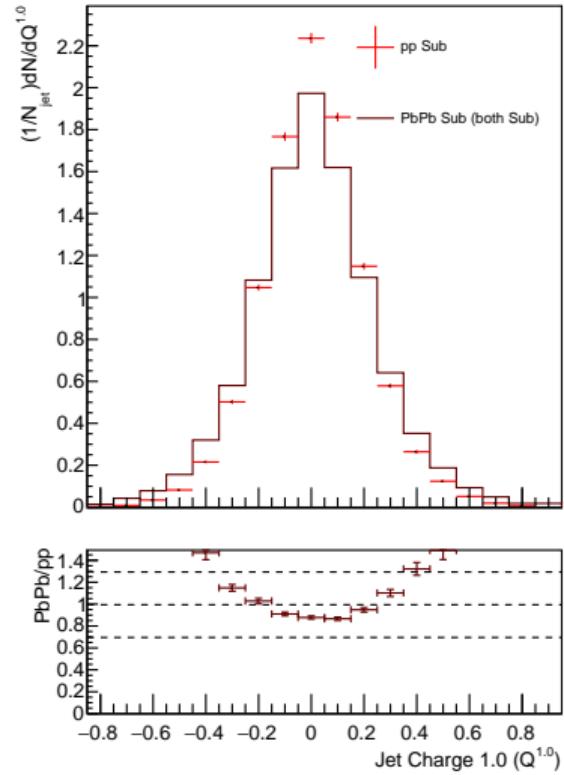
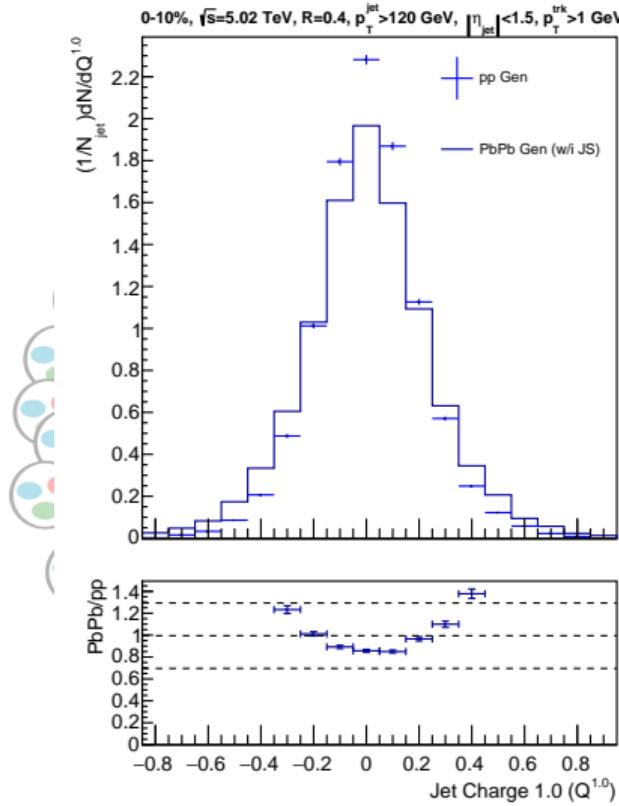
$$Q^{0.3} = \frac{1}{(p_T^{\text{jet}})^{0.3}} \sum_{\text{consts}} q^{\text{const}} (p_T^{\text{const}})^{0.3}$$



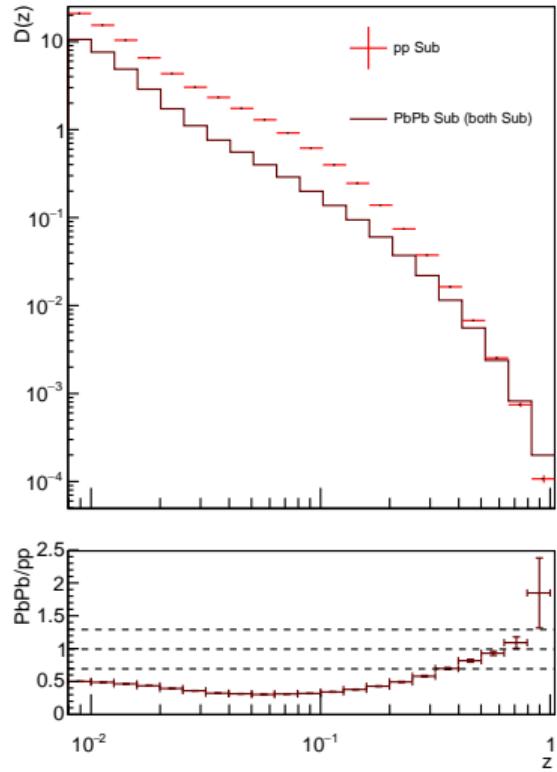
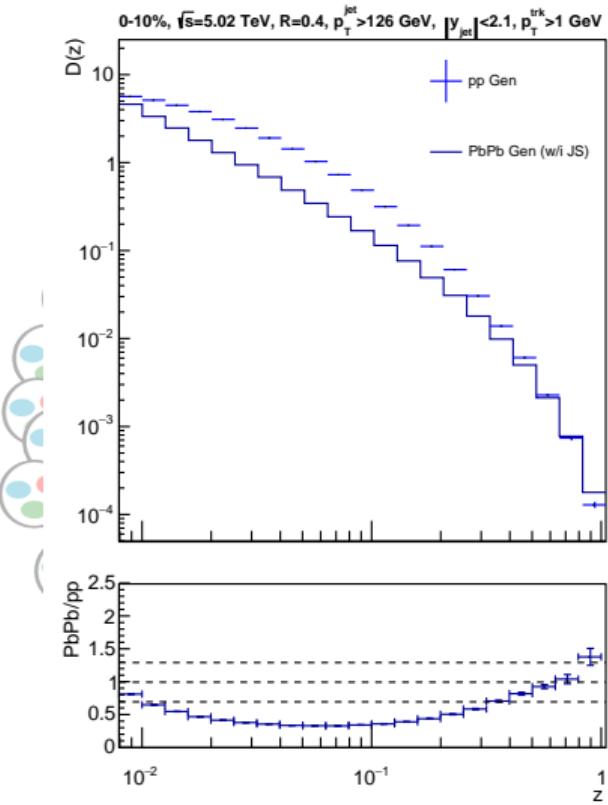
$$Q^{0.5} = \frac{1}{(p_T^{\text{jet}})^{0.5}} \sum_{\text{consts}} q^{\text{const}} (p_T^{\text{const}})^{0.5}$$



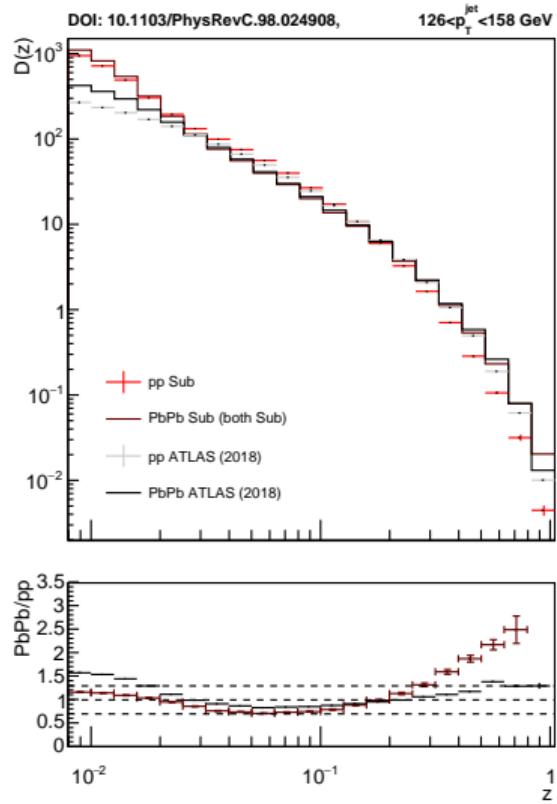
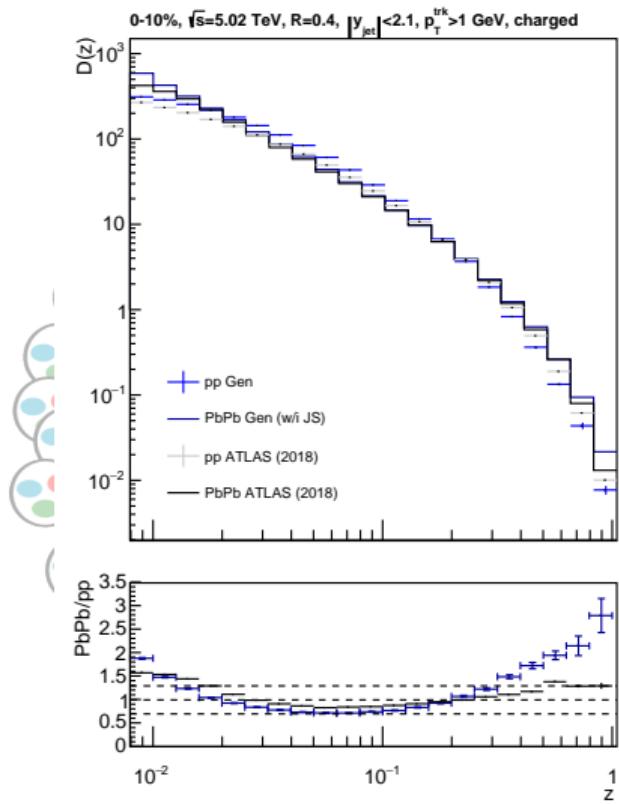
$$Q^{0.7} = \frac{1}{(p_T^{\text{jet}})^{0.7}} \sum_{\text{consts}} q^{\text{const}} (p_T^{\text{const}})^{0.7}$$



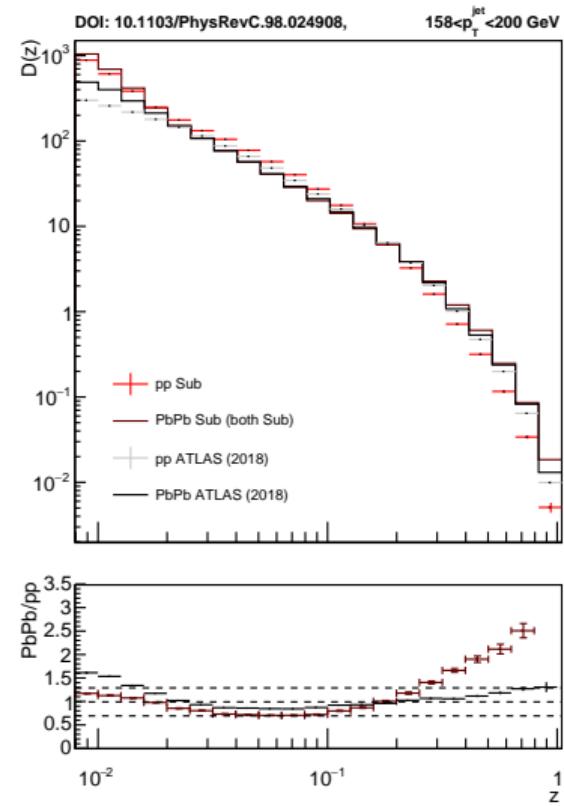
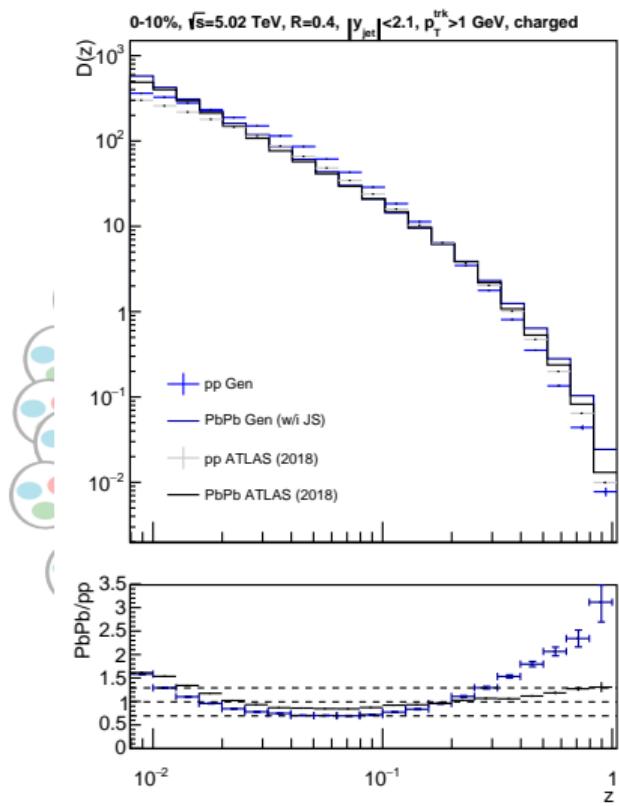
$$Q^1 = \frac{1}{p_T^{\text{jet}}} \sum_{\text{consts}} q^{\text{const}} p_T^{\text{const}}$$



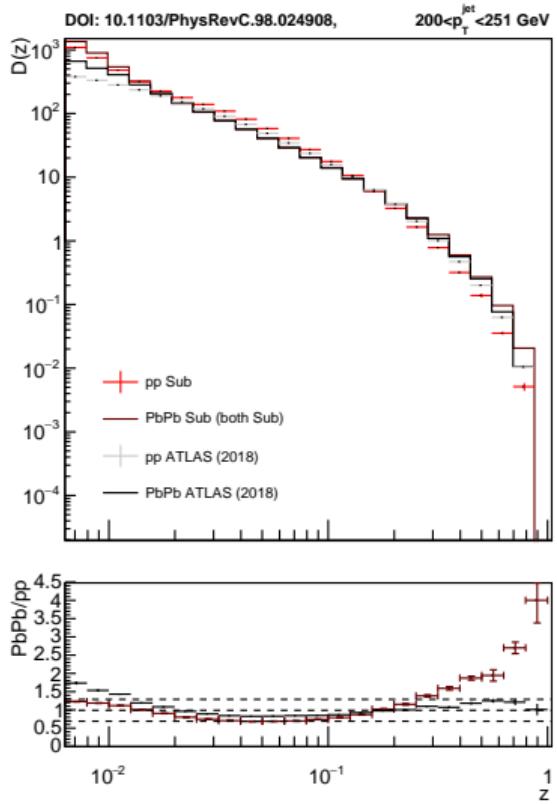
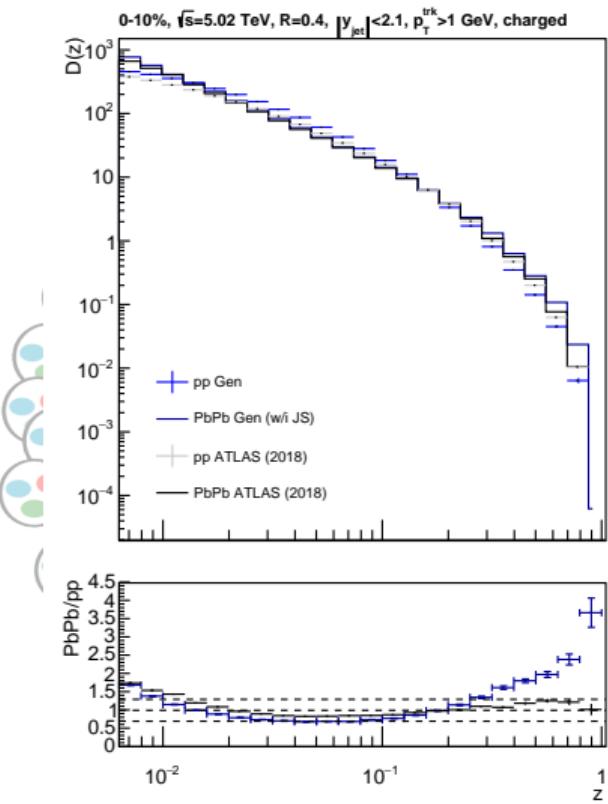
$$D(z) = \frac{1}{N_{jet}} \frac{dN_{chg}}{dz}, Z = \frac{p_T^{const} \cos(\Delta R)}{p_T^{jet}}$$



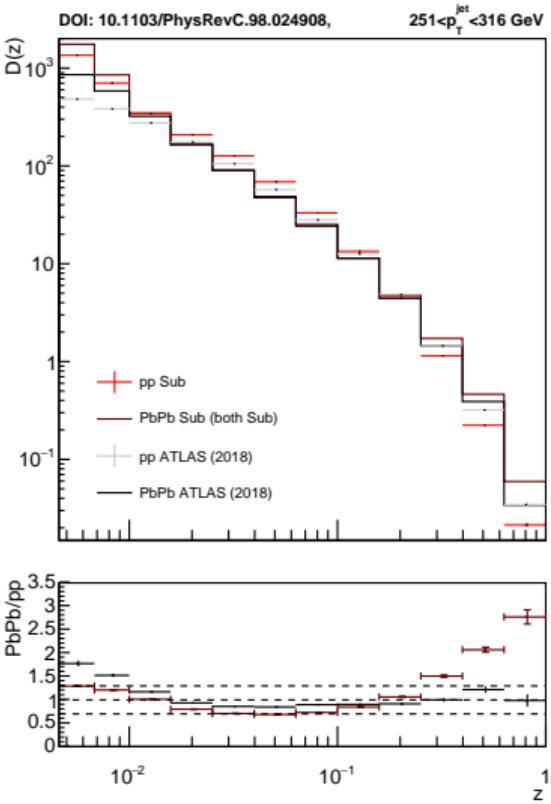
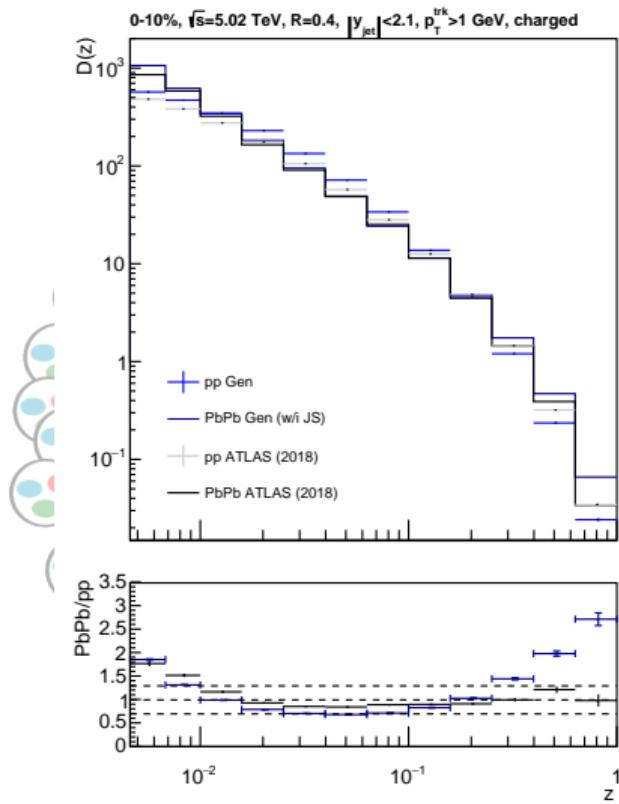
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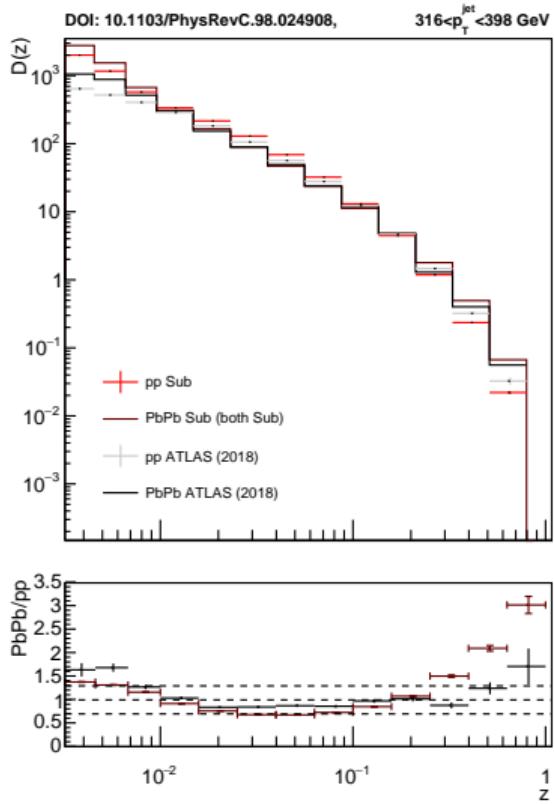
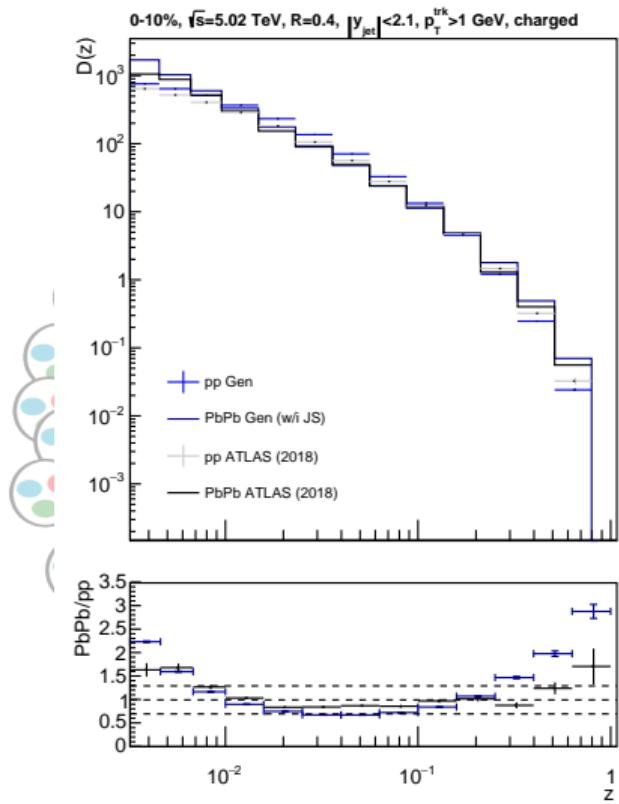
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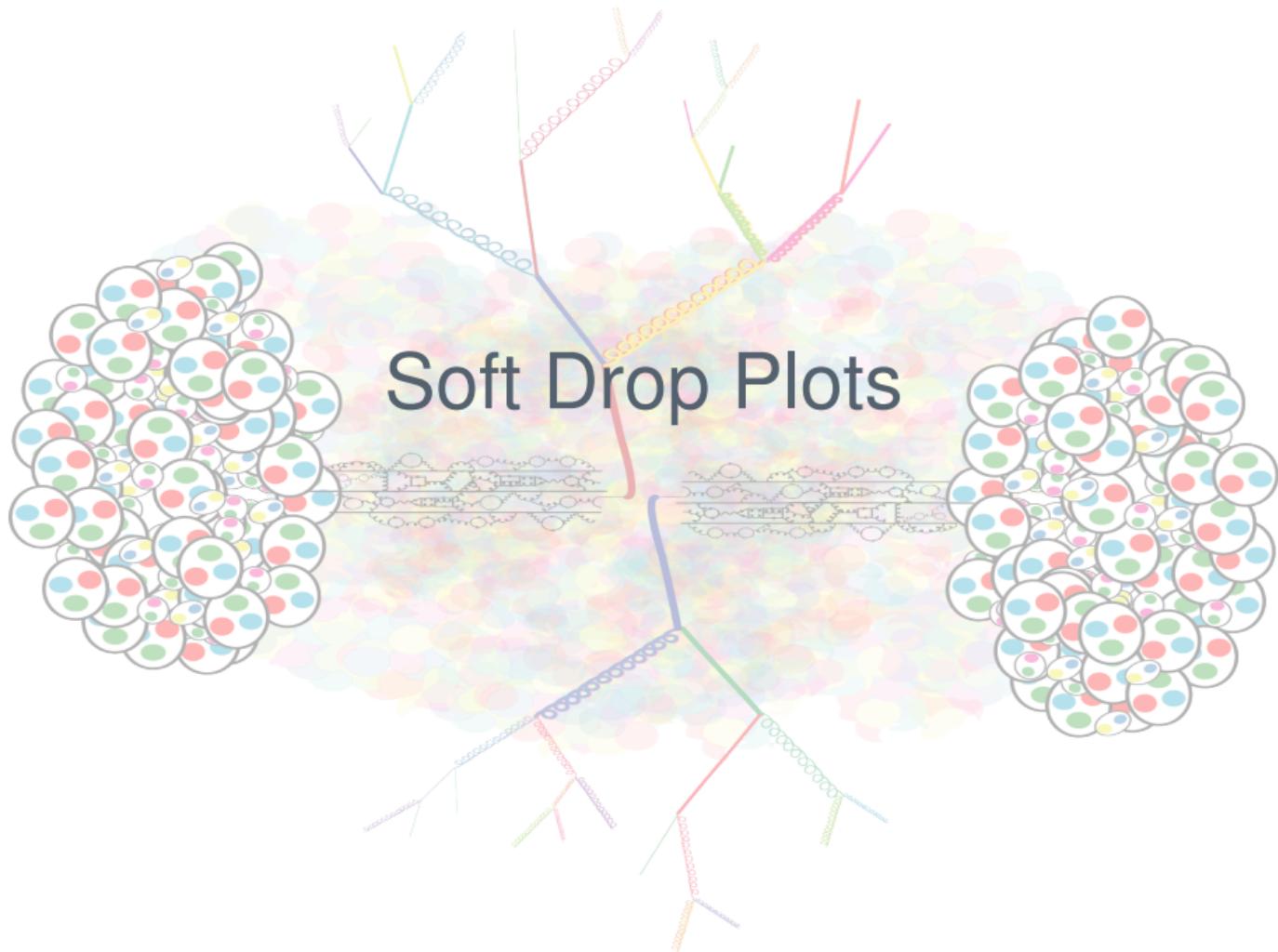


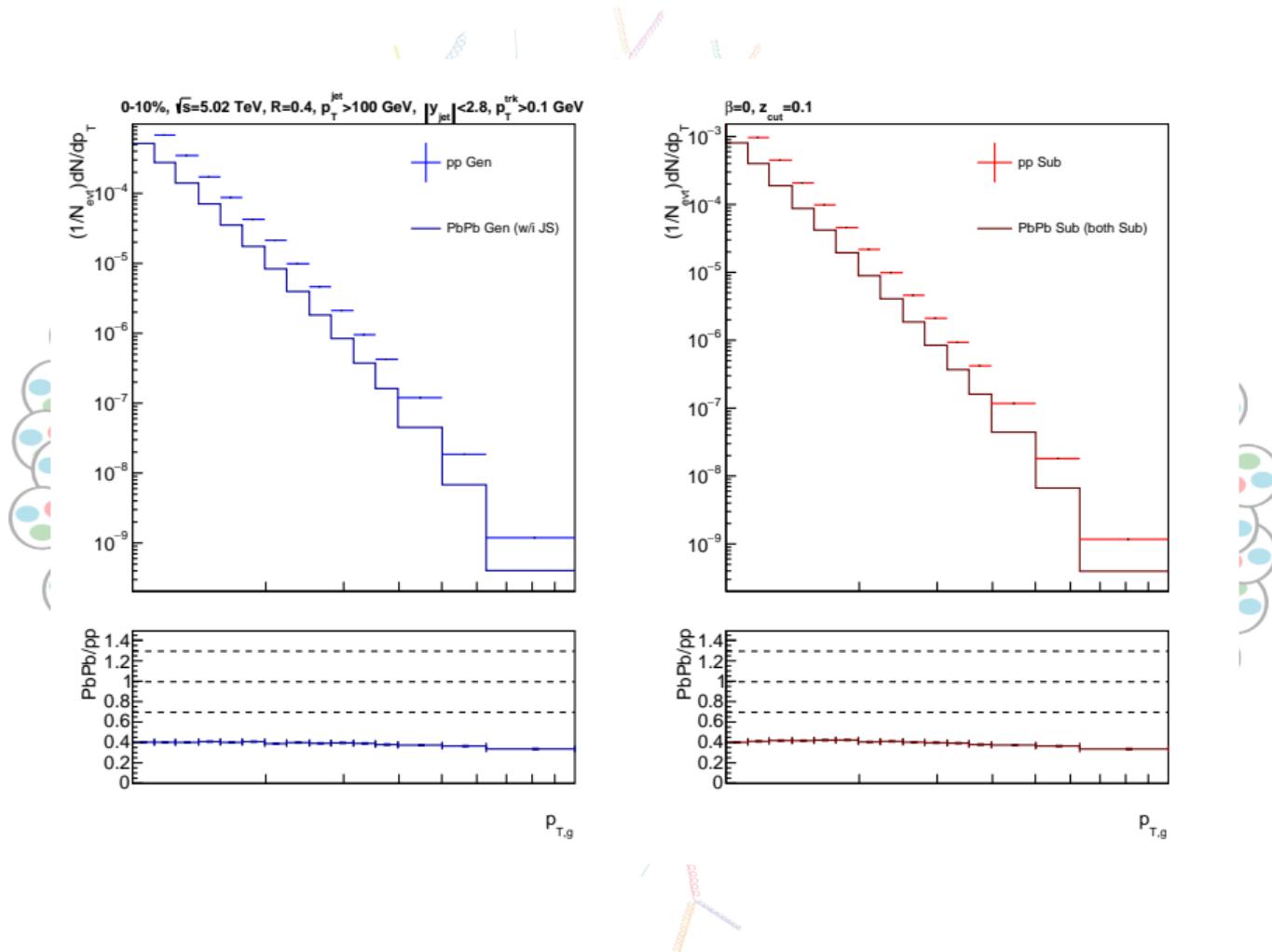
$$D(z) = \frac{1}{N_{jet}} \frac{dN_{chg}}{dz}, Z = \frac{p_T^{const} \cos(\Delta R)}{p_T^{jet}}$$

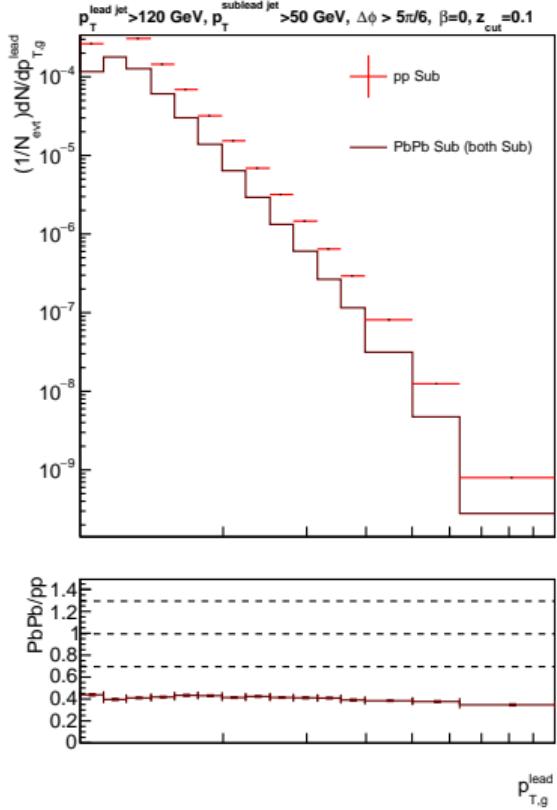
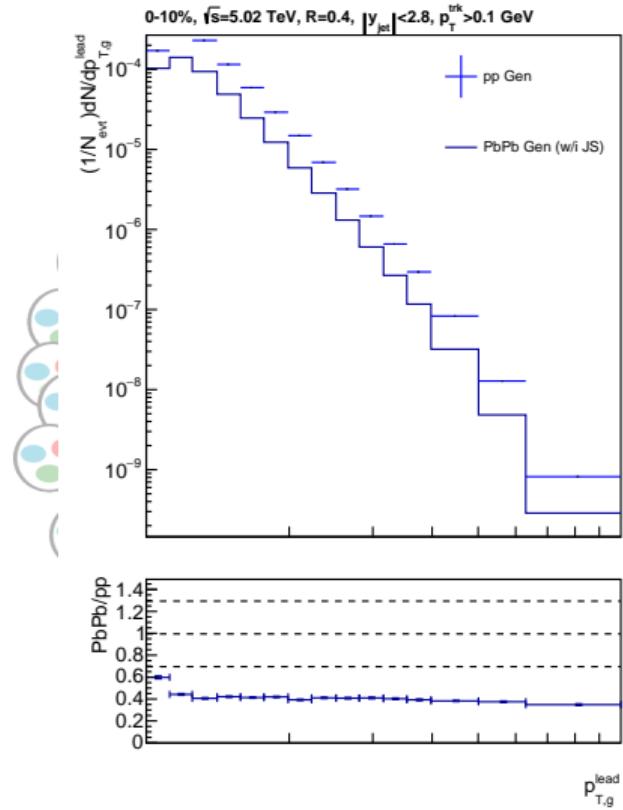


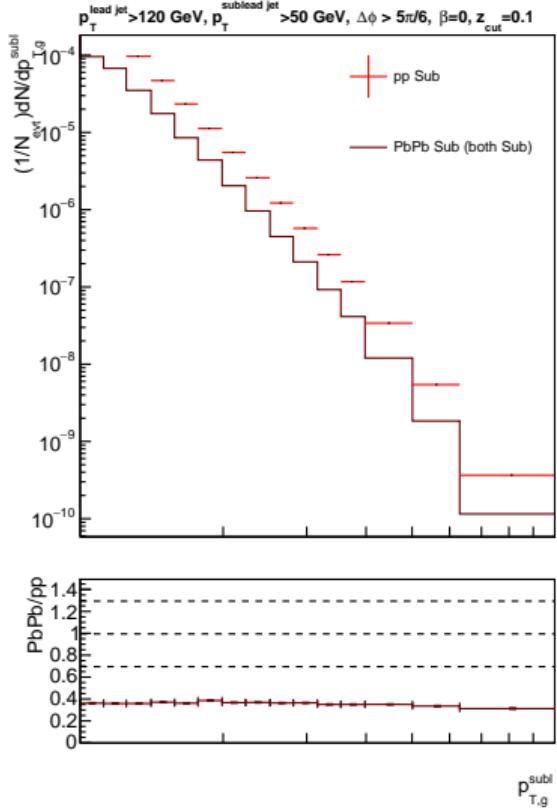
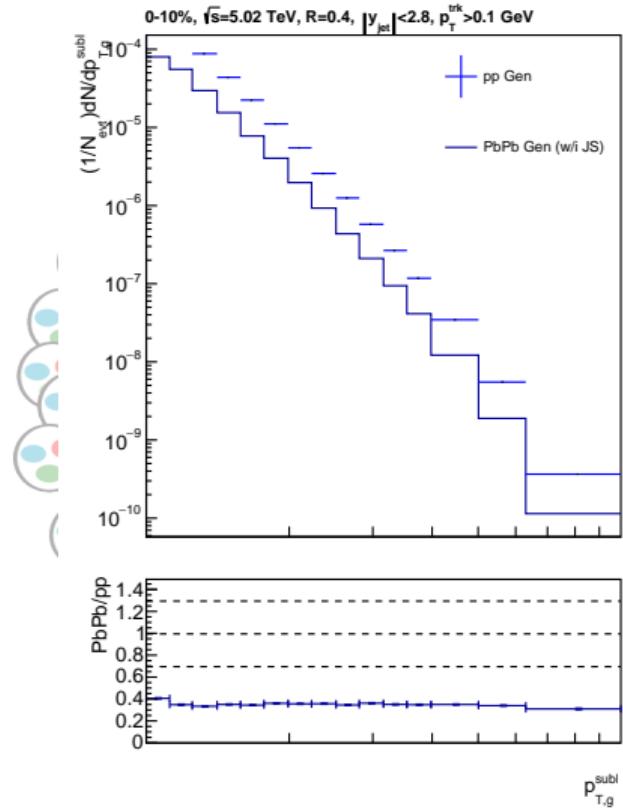
$$D(z) = \frac{1}{N_{jet}} \frac{dN_{chg}}{dz}, Z = \frac{p_T^{const} \cos(\Delta R)}{p_T^{jet}}$$

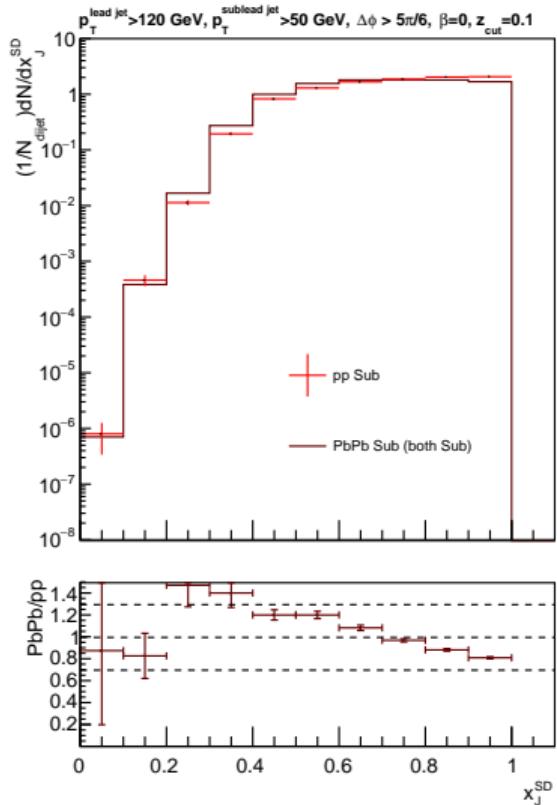
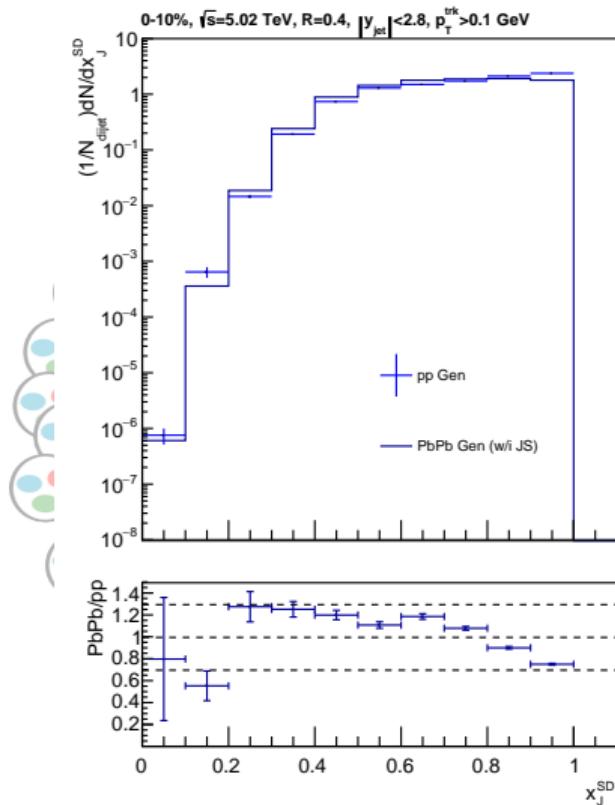
Soft Drop Plots

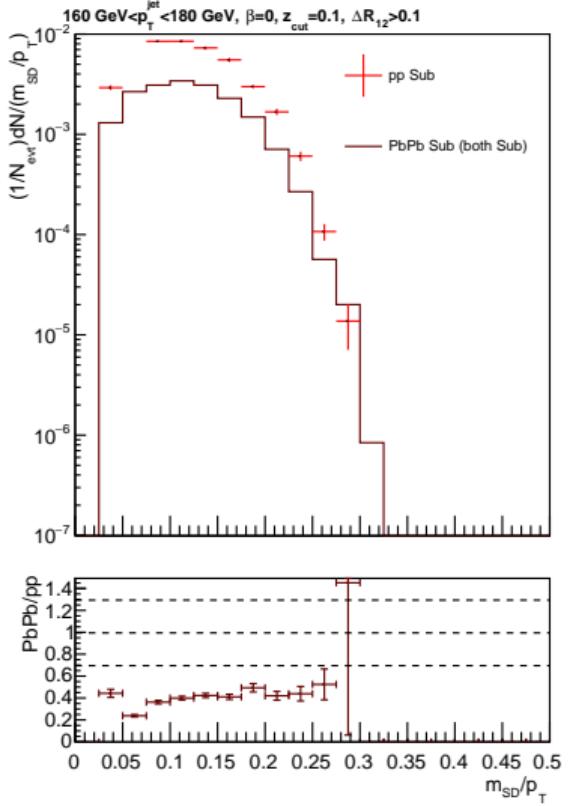
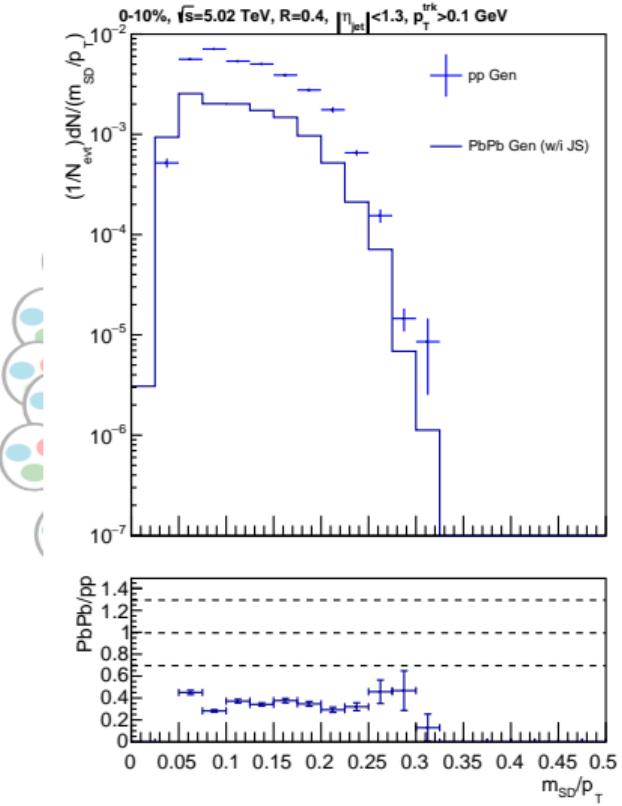


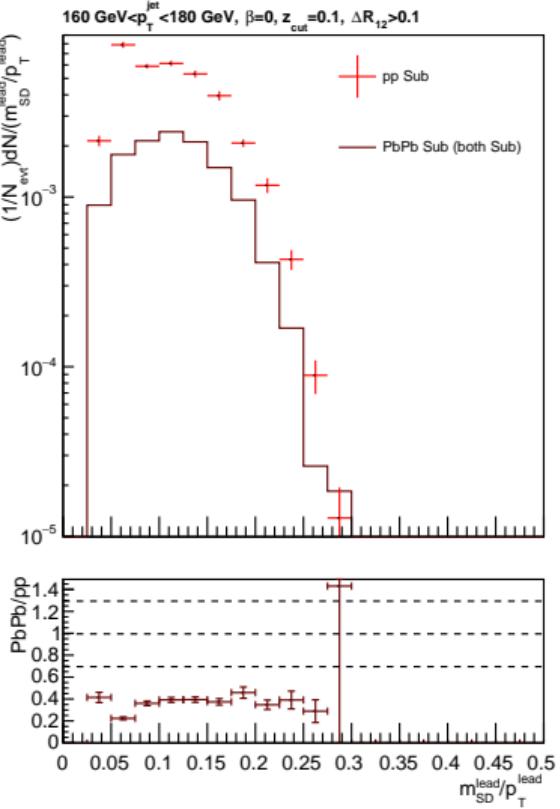
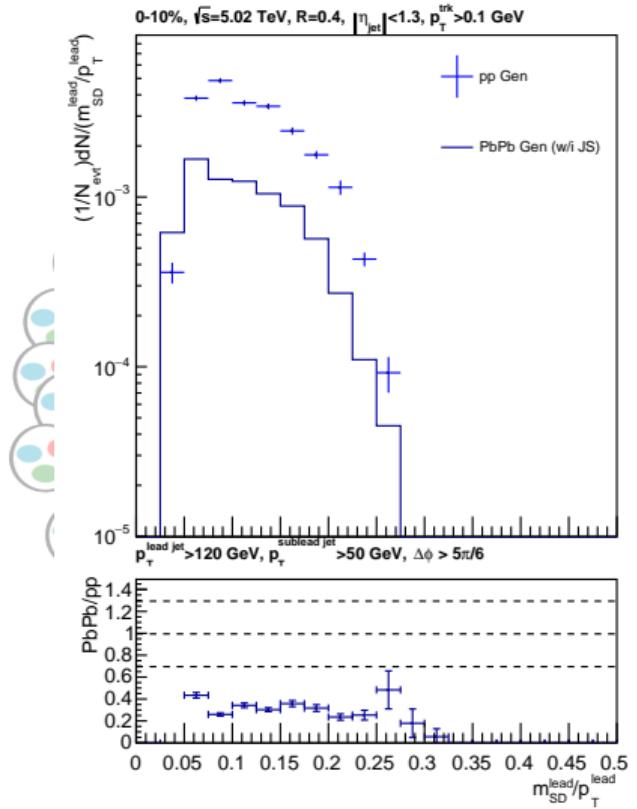




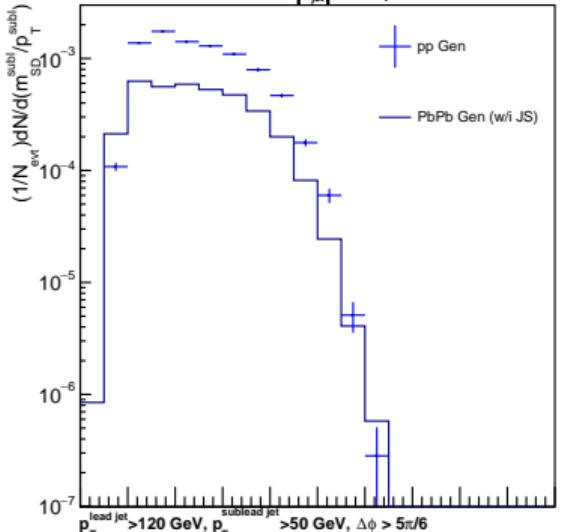




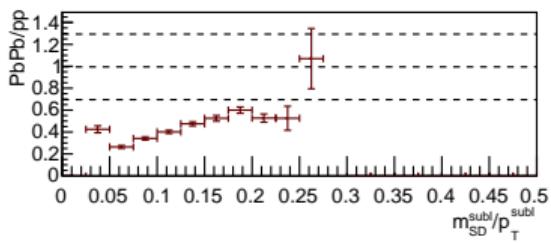
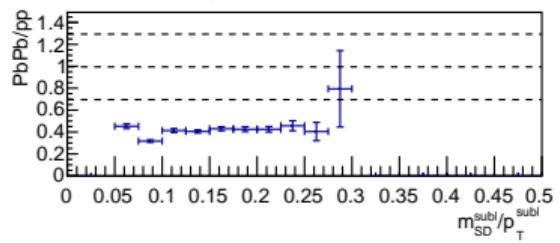
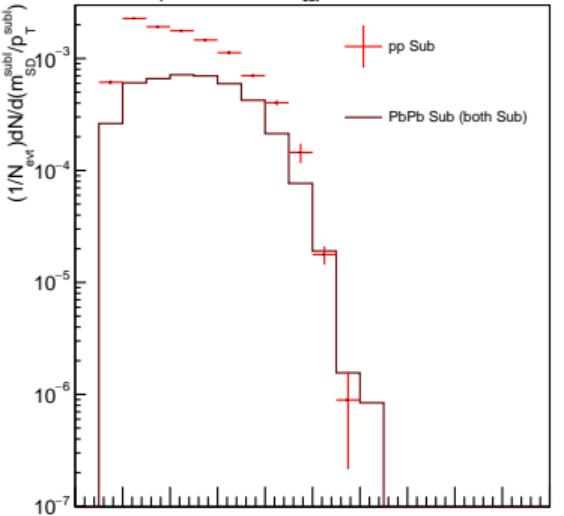




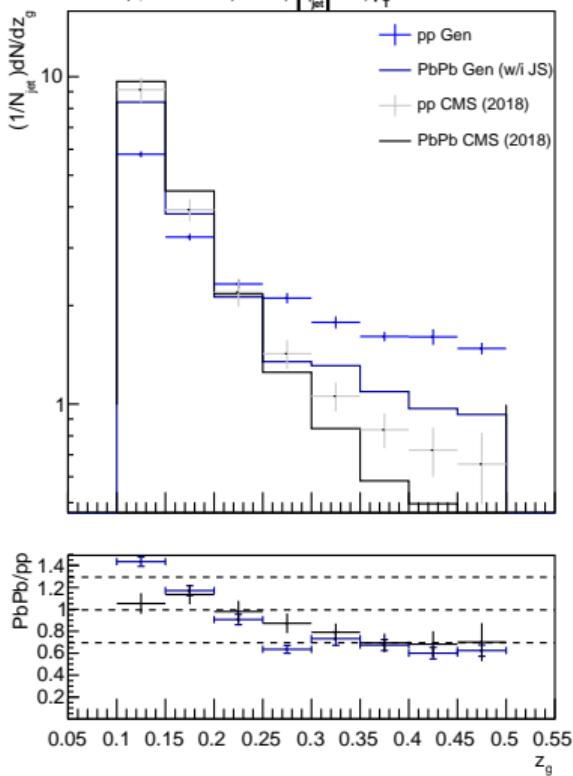
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $||\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV



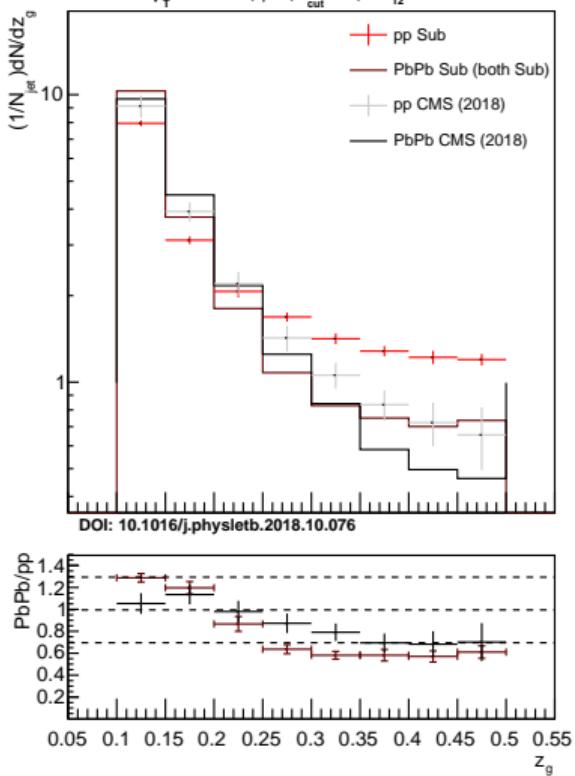
160 GeV $< p_T^{\text{jet}} < 180$ GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$



0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV

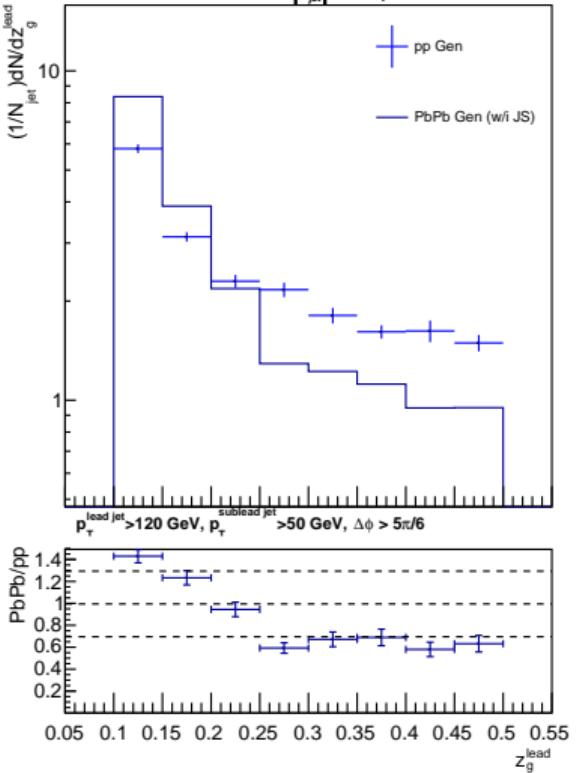


160 GeV $< p_T^{\text{jet}} < 180$ GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$

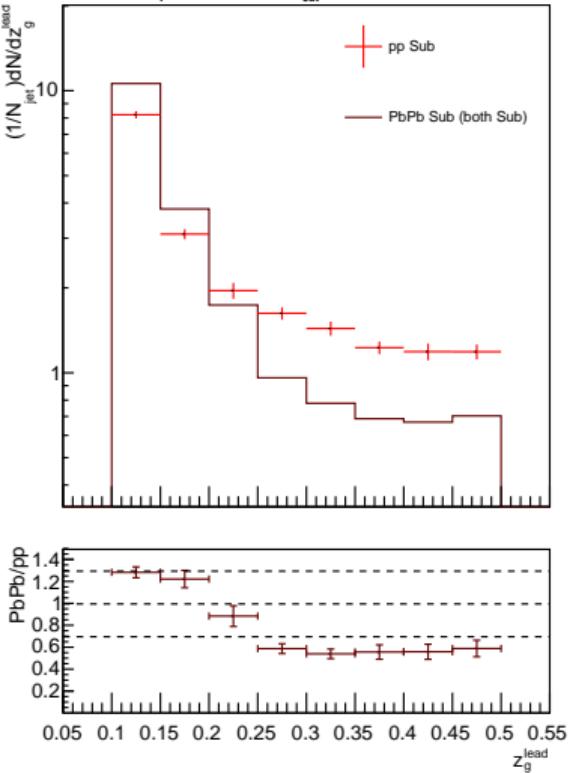


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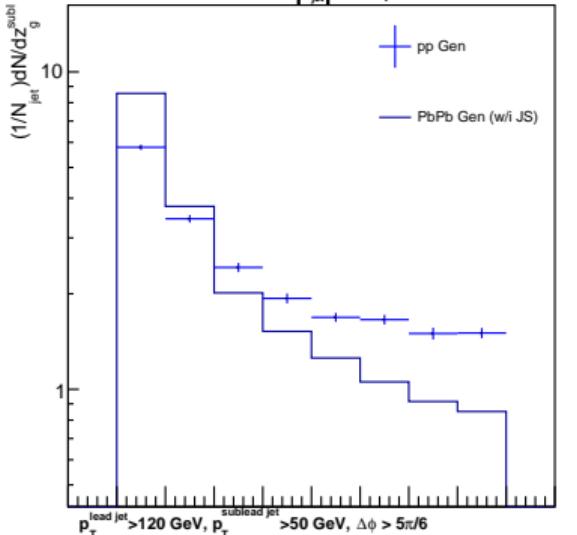
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV



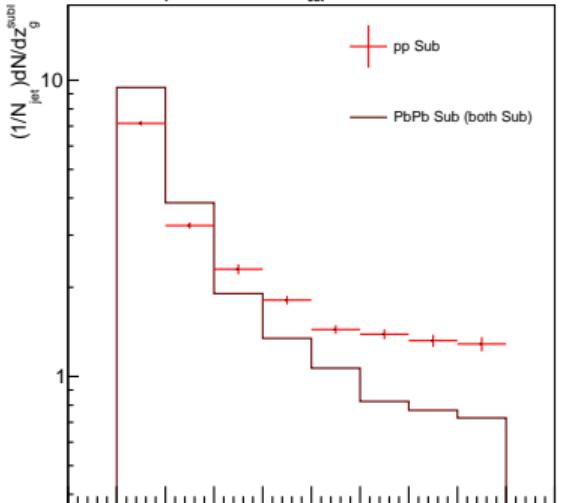
160 GeV $< p_T^{\text{jet}} < 180$ GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$

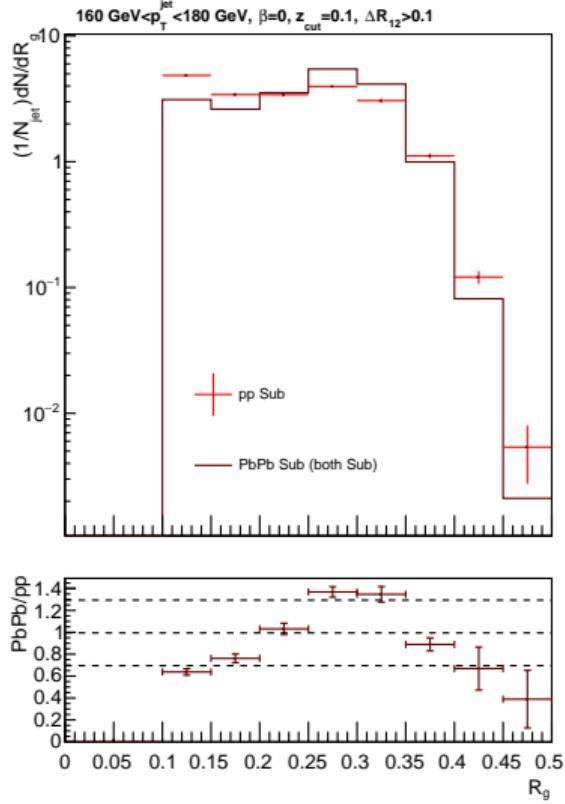
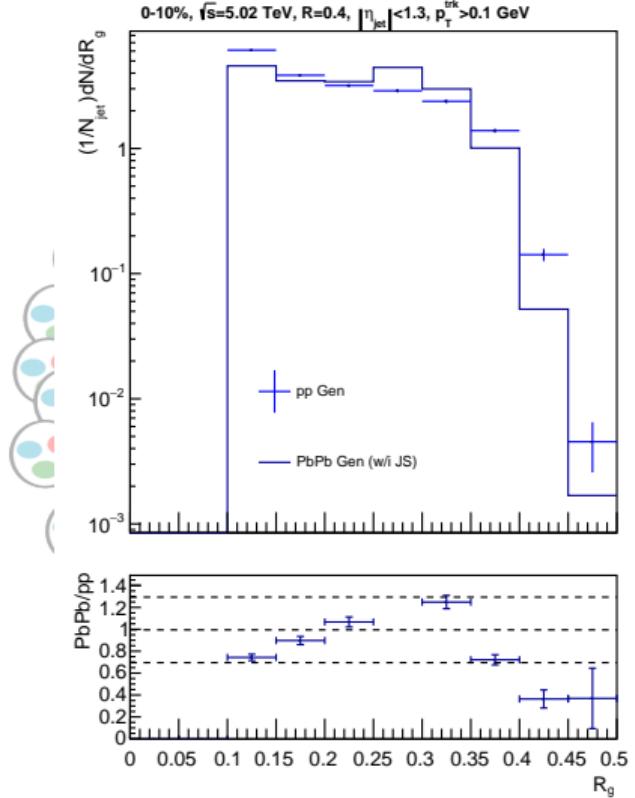


0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV

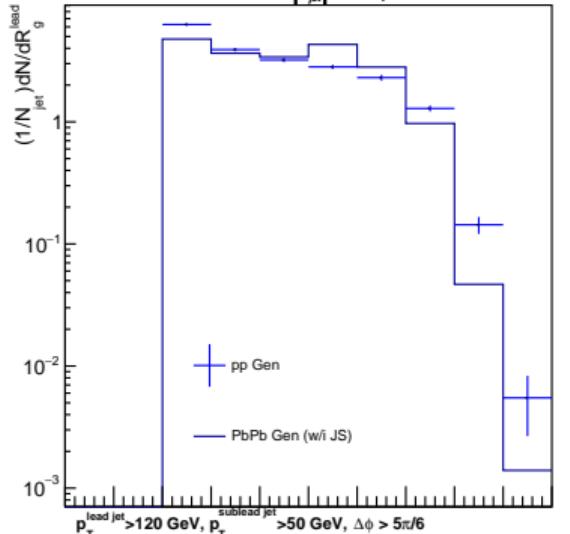


160 GeV $< p_T^{\text{jet}} < 180$ GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$

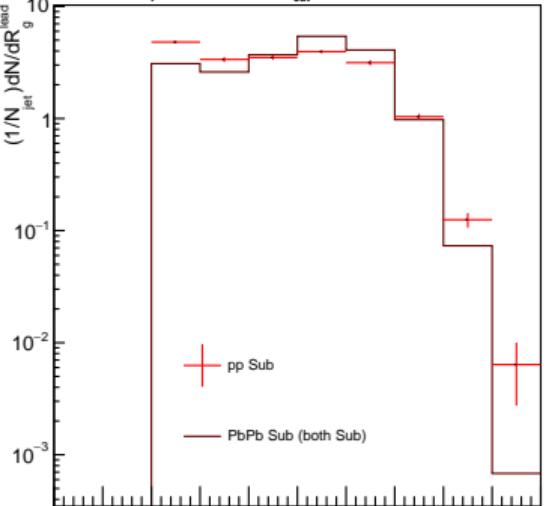




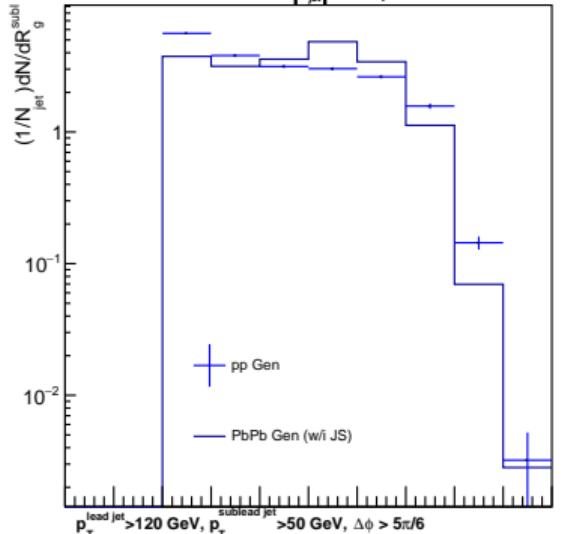
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV



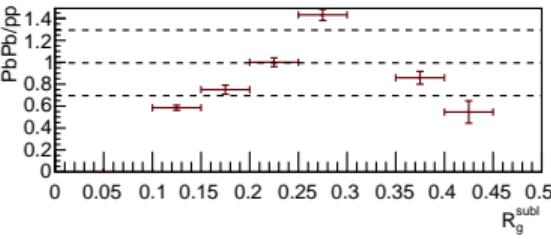
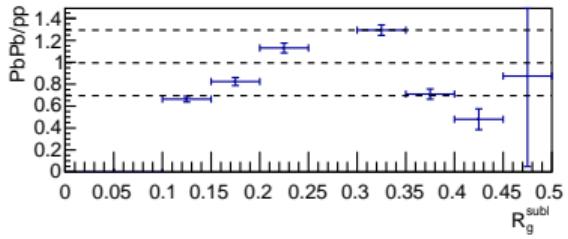
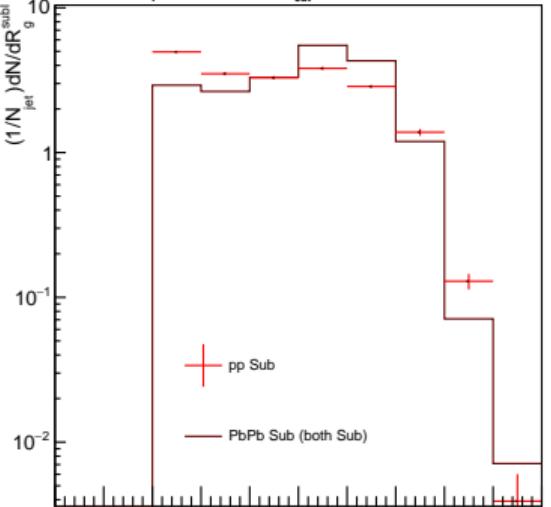
160 GeV < p_T^{jet} < 180 GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$



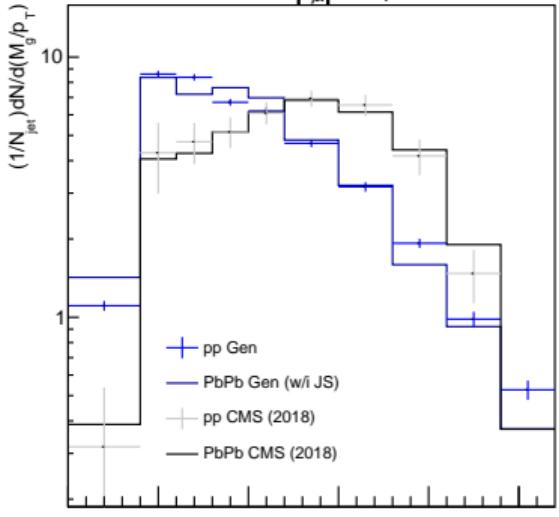
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV



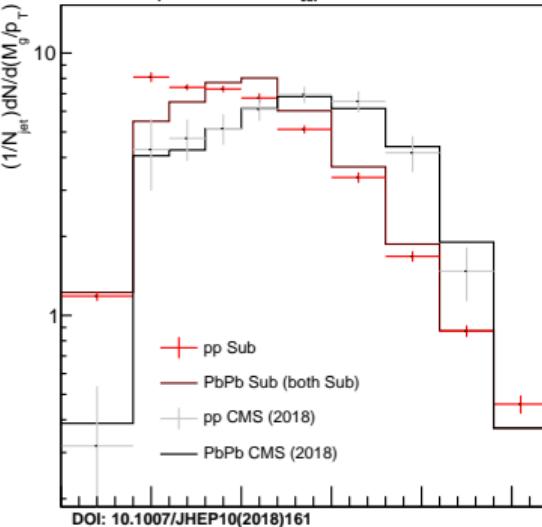
160 GeV < p_T^{jet} <180 GeV, $\beta=0$, $z_c=0.1$, $\Delta R_{12}>0.1$



0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV

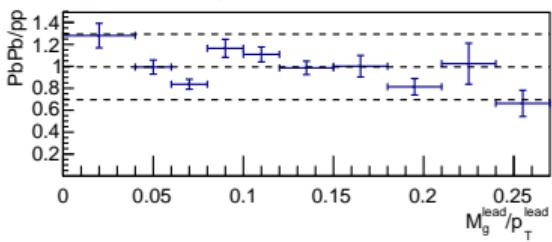
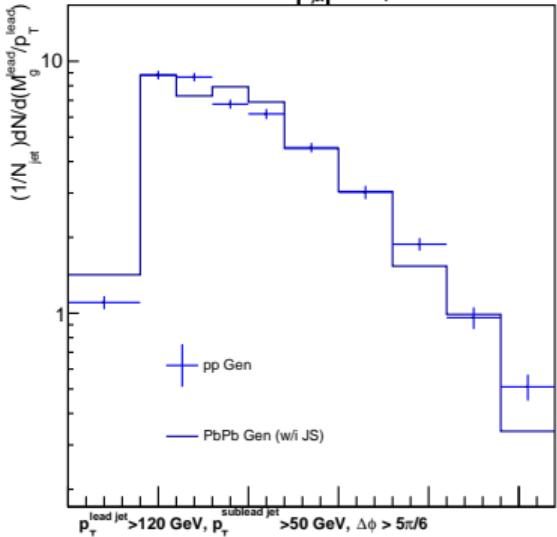


160 GeV $< p_T^{\text{jet}} < 180$ GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$

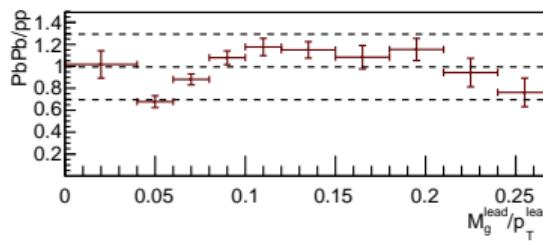
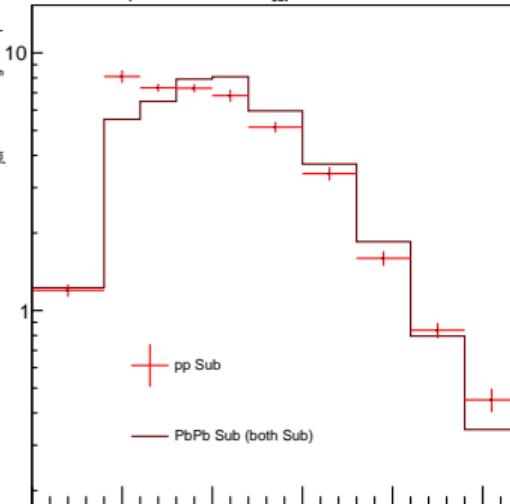


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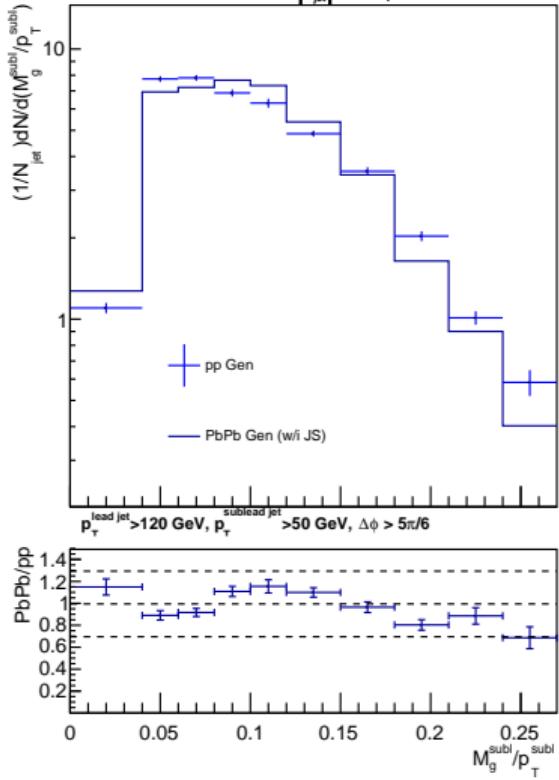
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $||\eta_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV



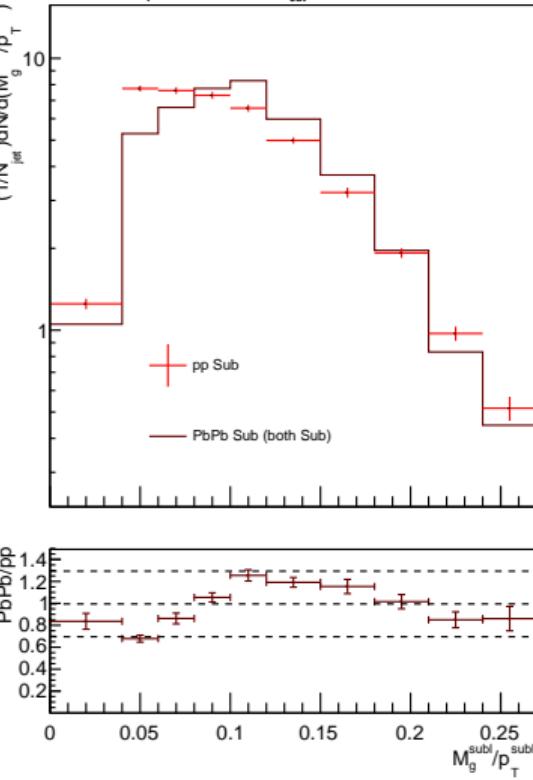
160 GeV < p_T^{jet} < 180 GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$



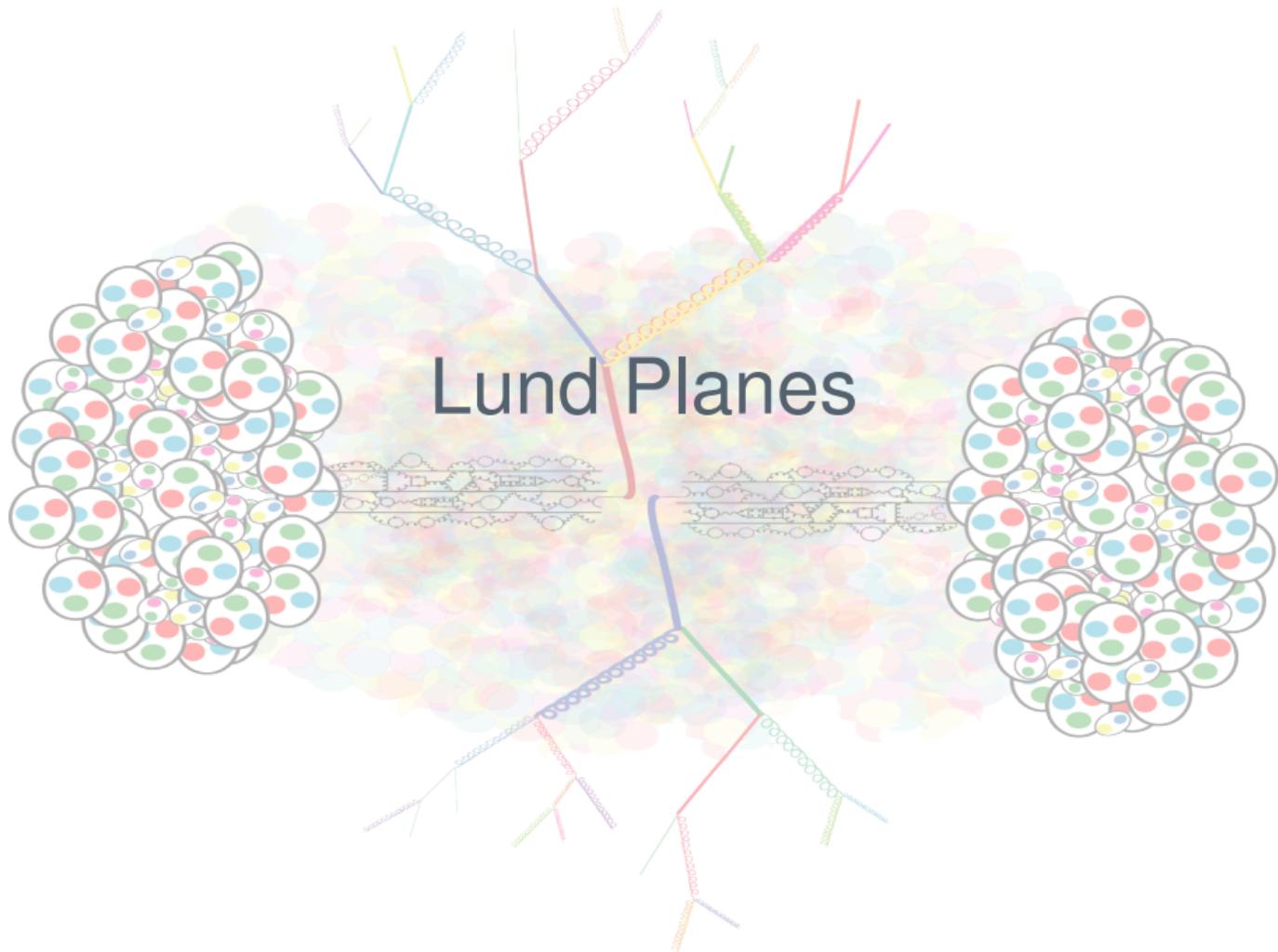
0-10%, $\sqrt{s}=5.02$ TeV, $R=0.4$, $|n_{\text{jet}}|<1.3$, $p_T^{\text{trk}}>0.1$ GeV



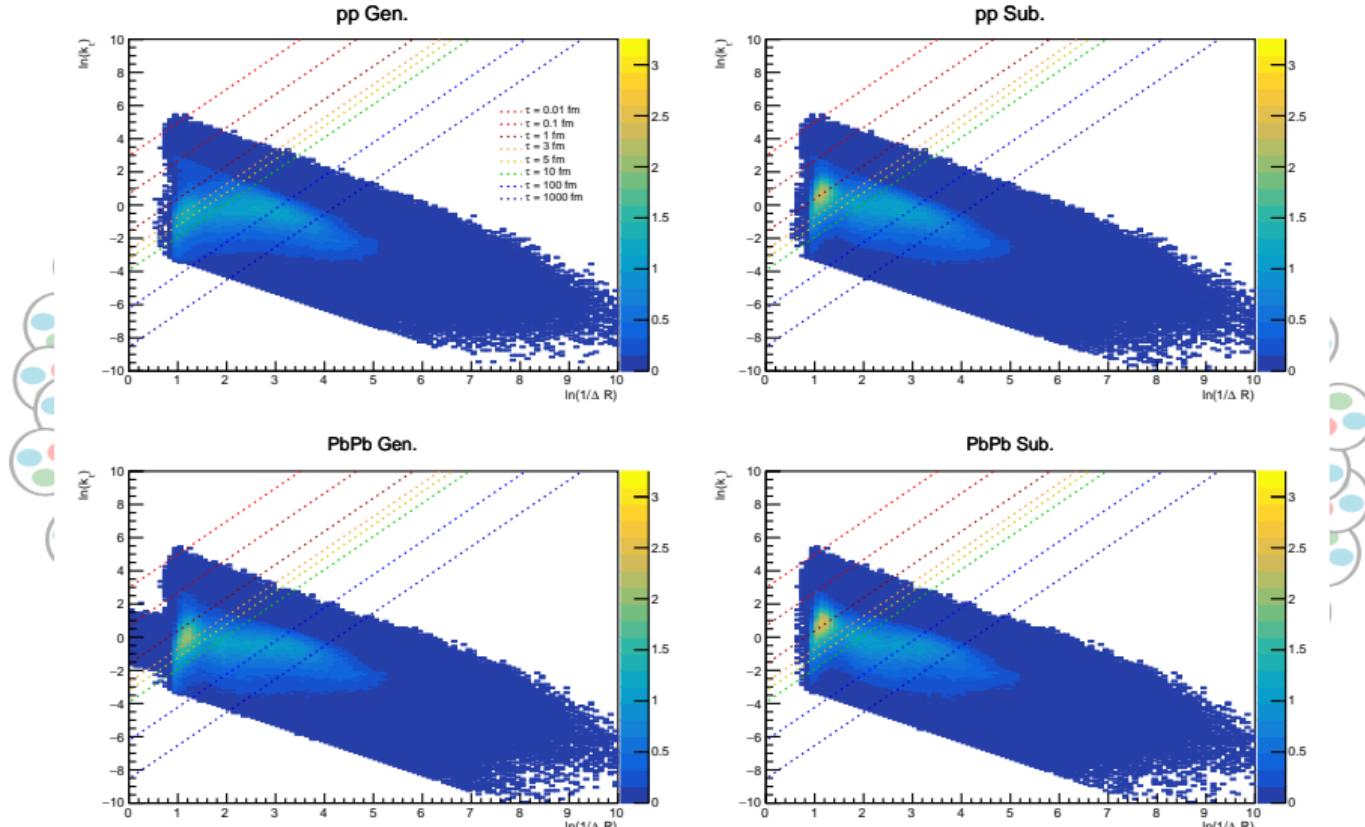
160 GeV < p_T^{jet} < 180 GeV, $\beta=0$, $z_{\text{cut}}=0.1$, $\Delta R_{12}>0.1$



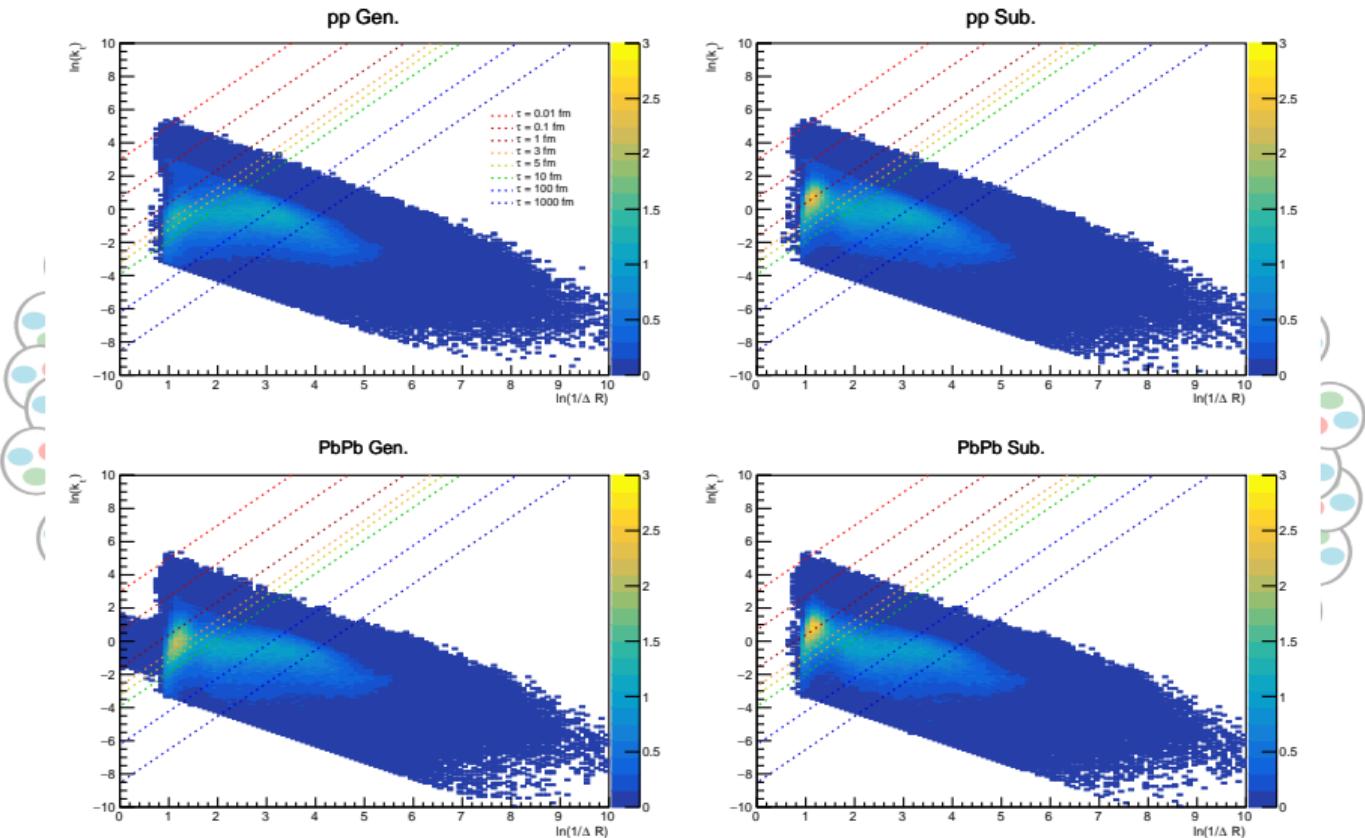
Lund Planes



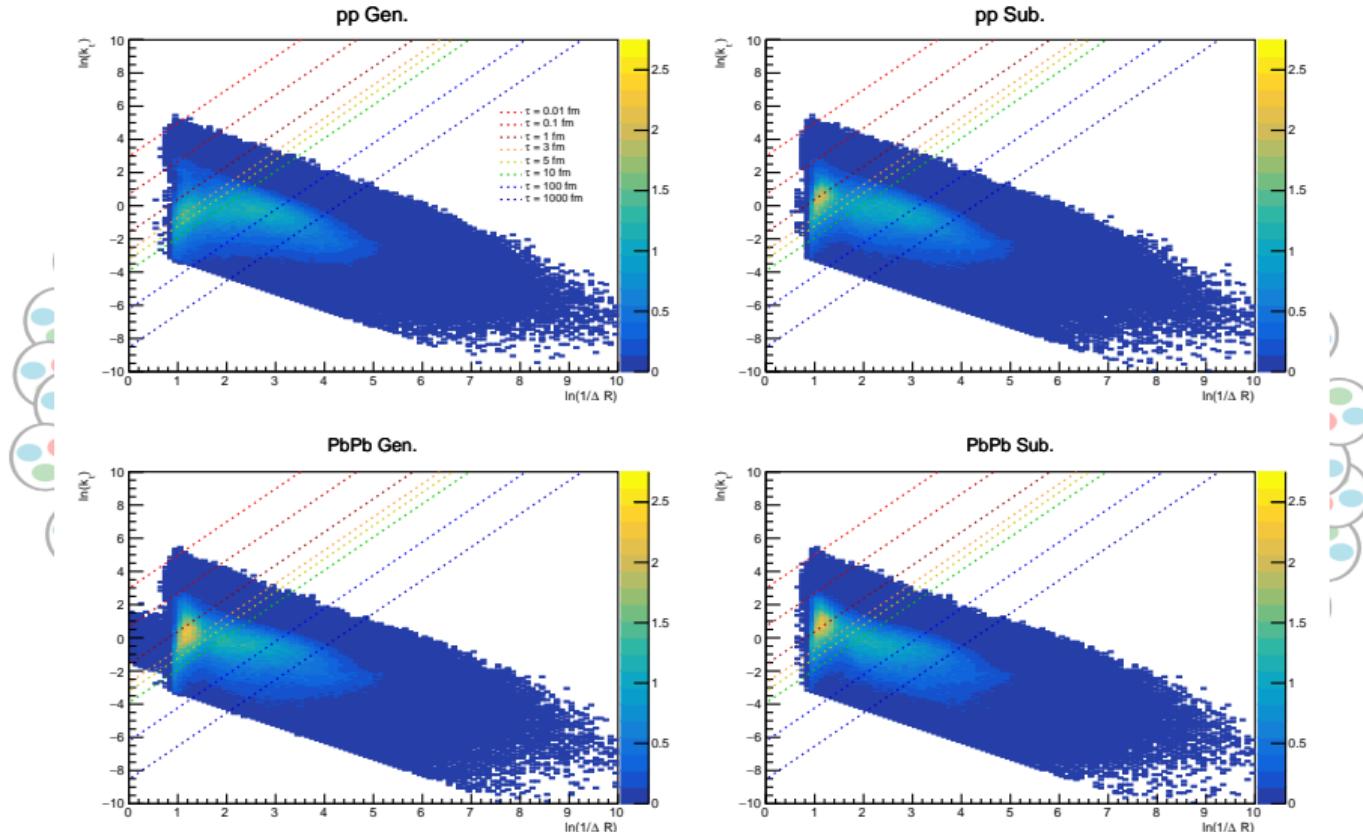
Lund Planes - Full Inclusive



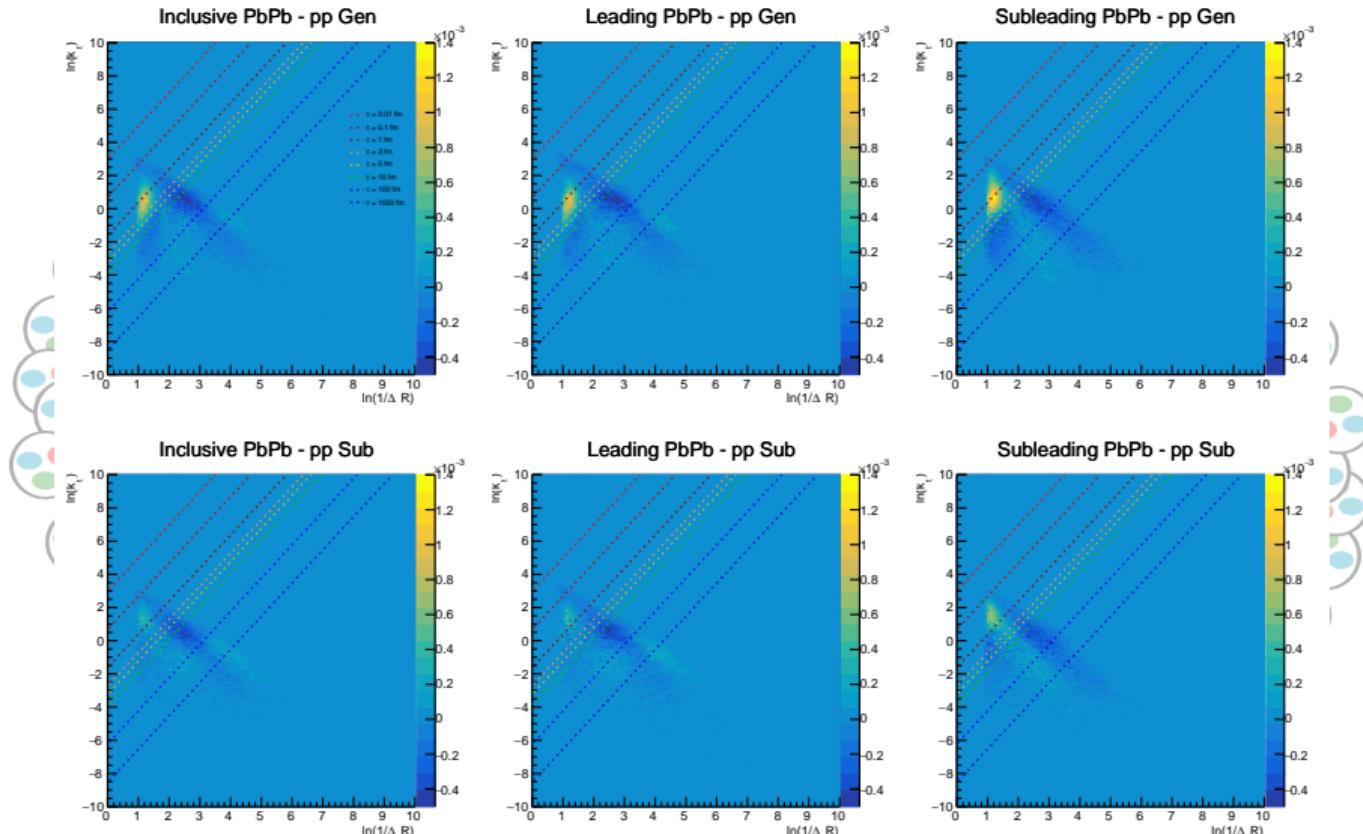
Lund Planes - Full Leading



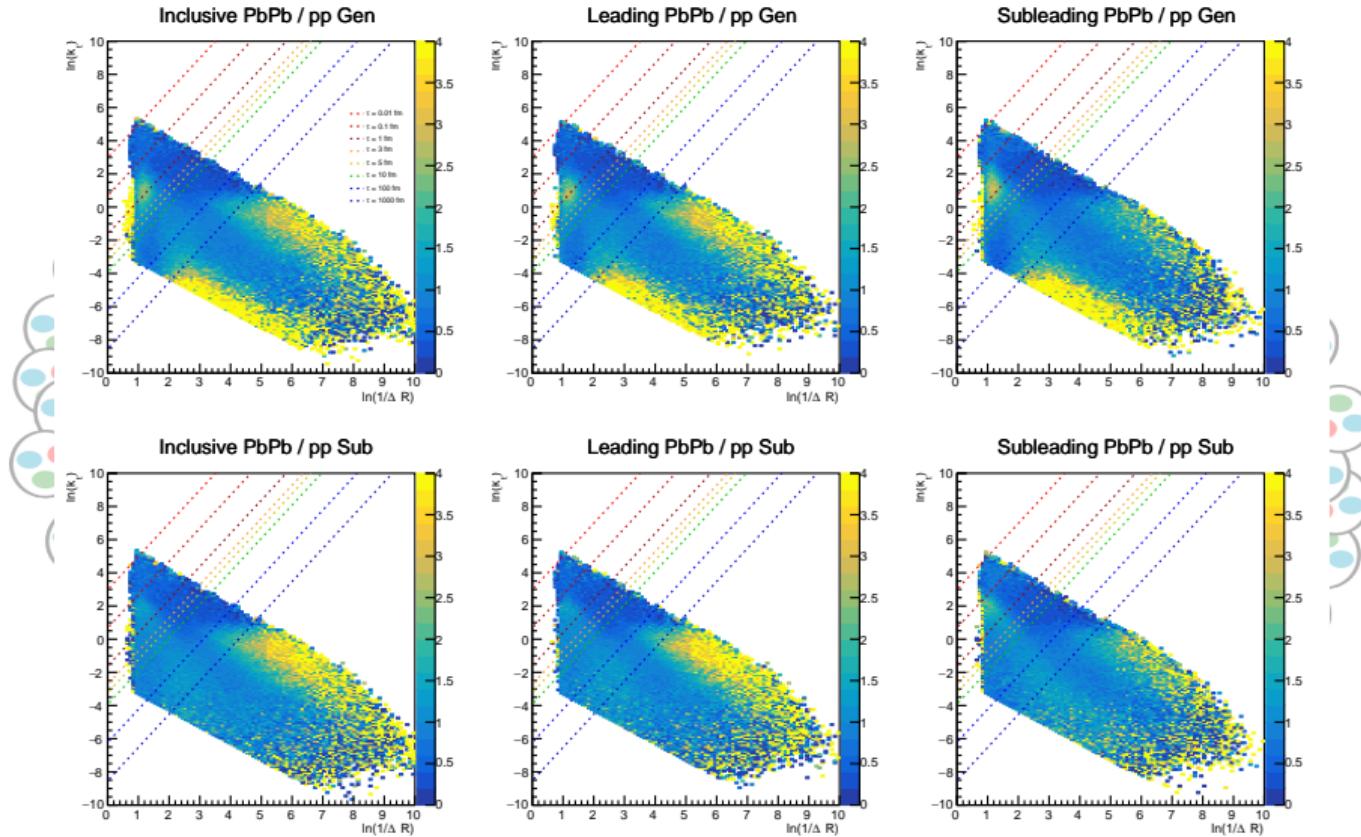
Lund Planes - Full Subleading



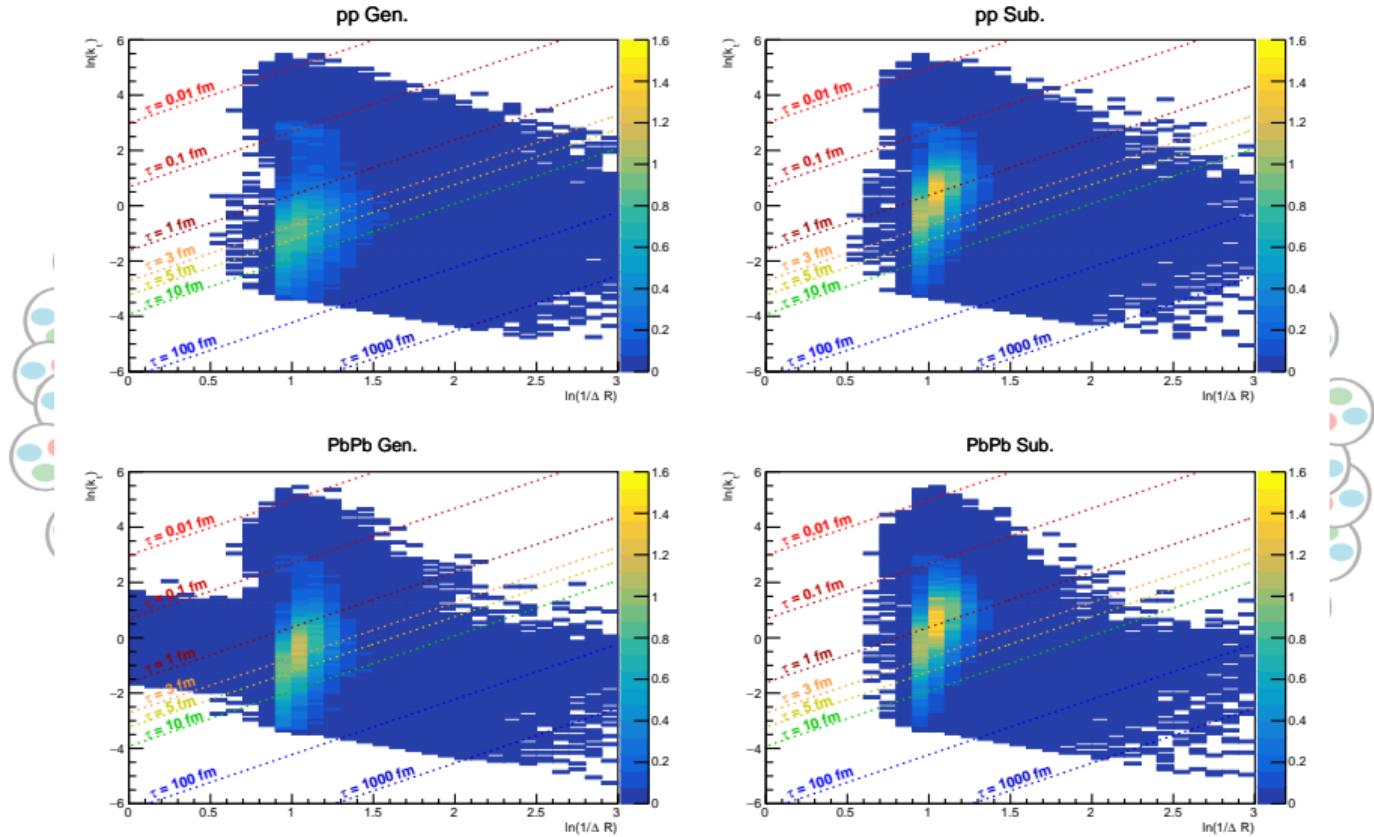
Lund Planes - Full Difference



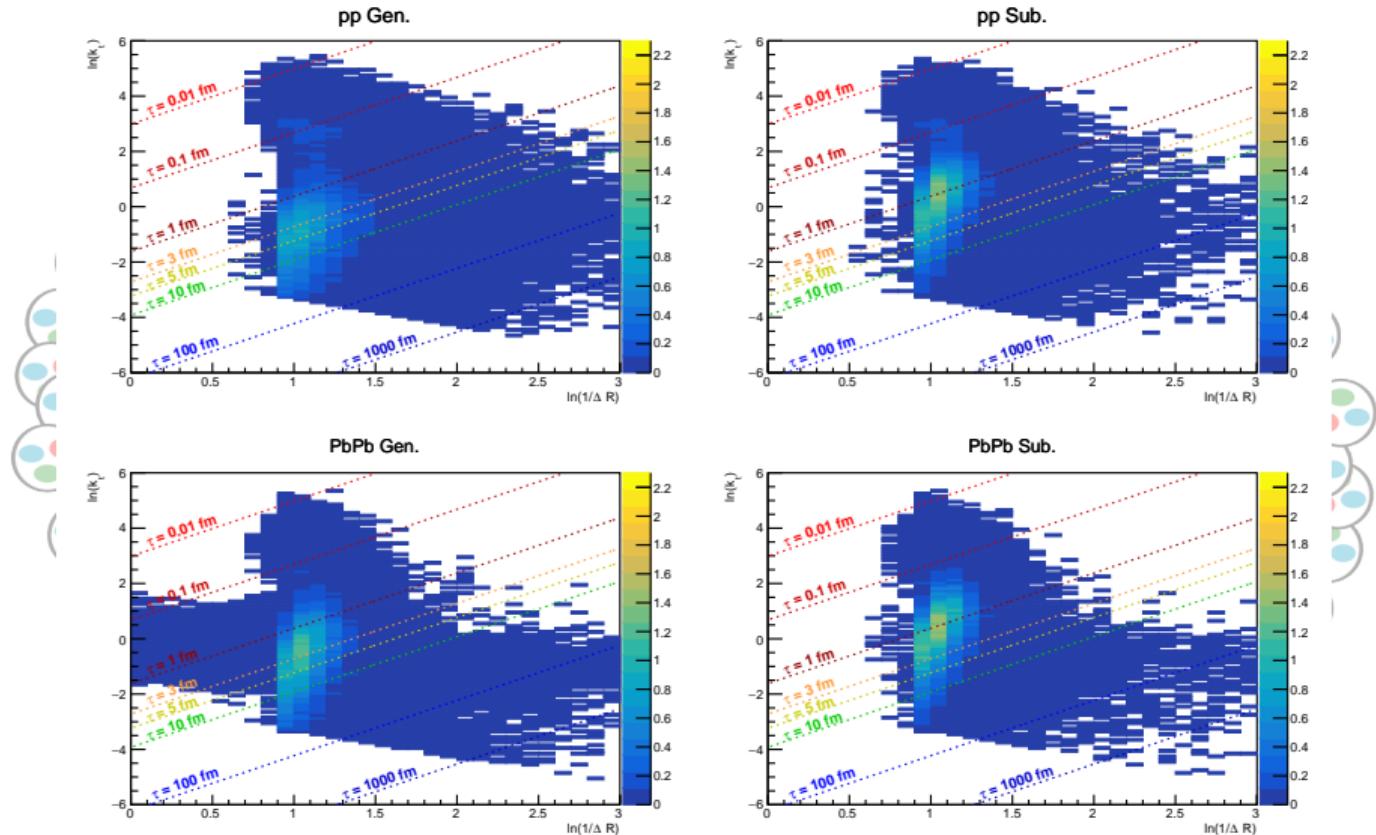
Lund Planes - Full Ratio



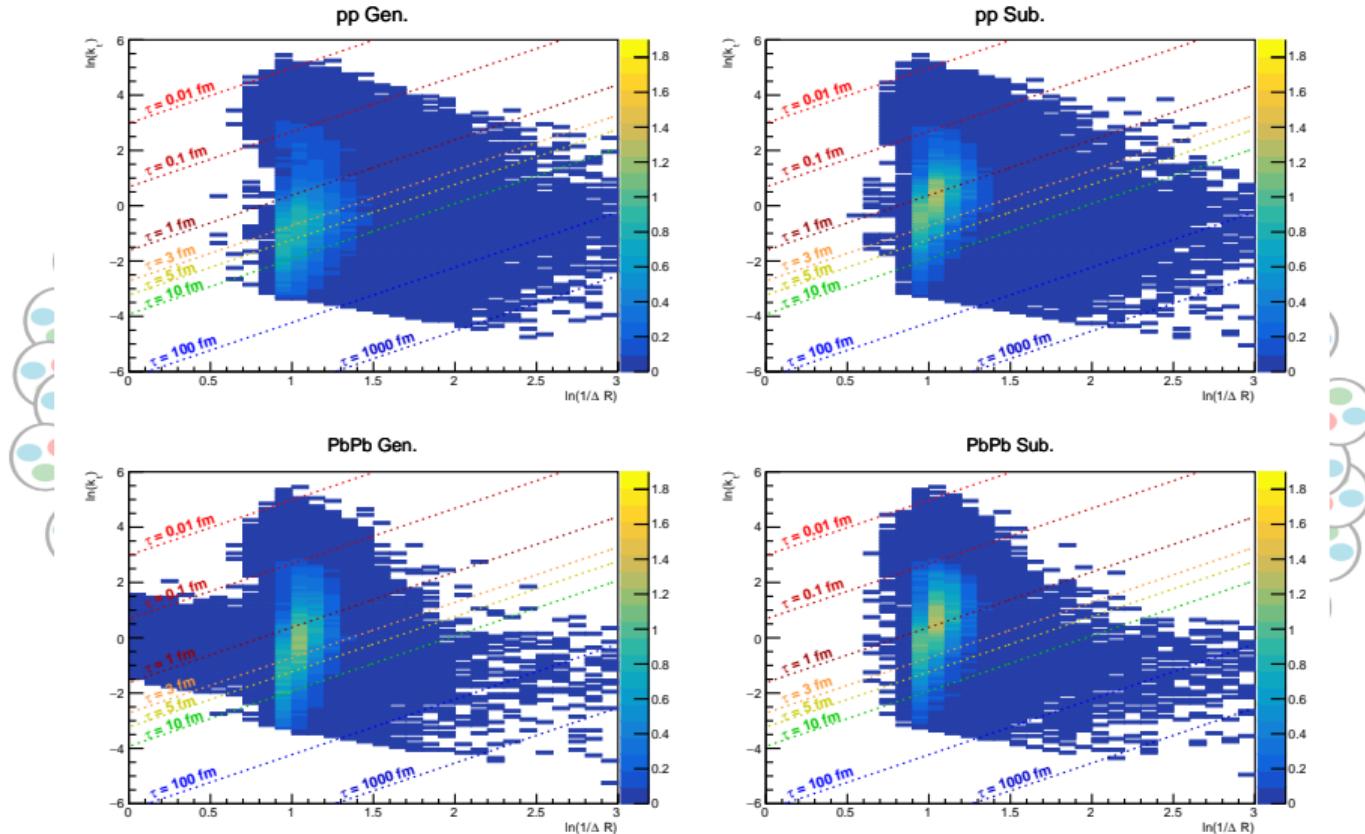
Lund Planes - First Splitting Inclusive



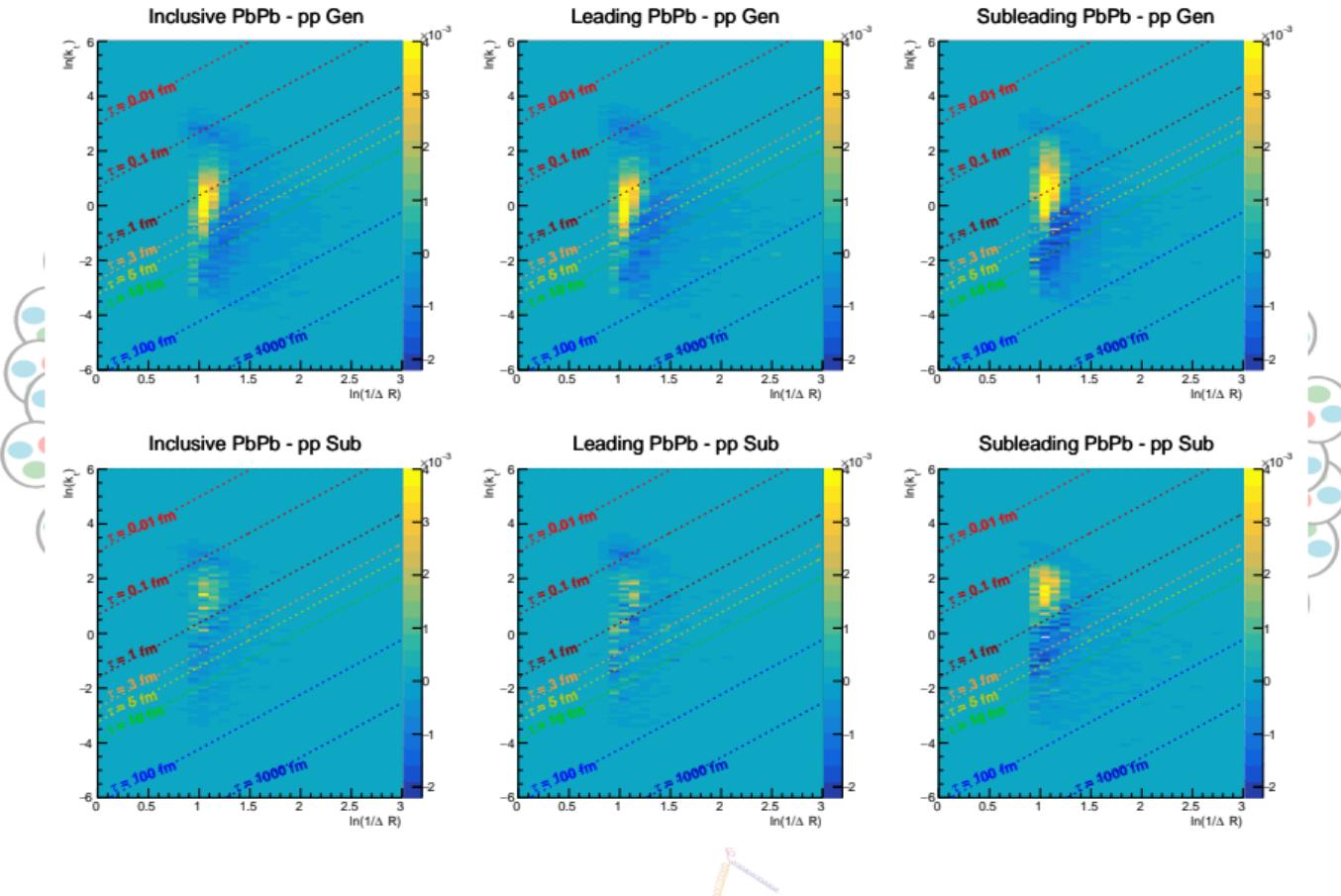
Lund Planes - First Splitting Leading



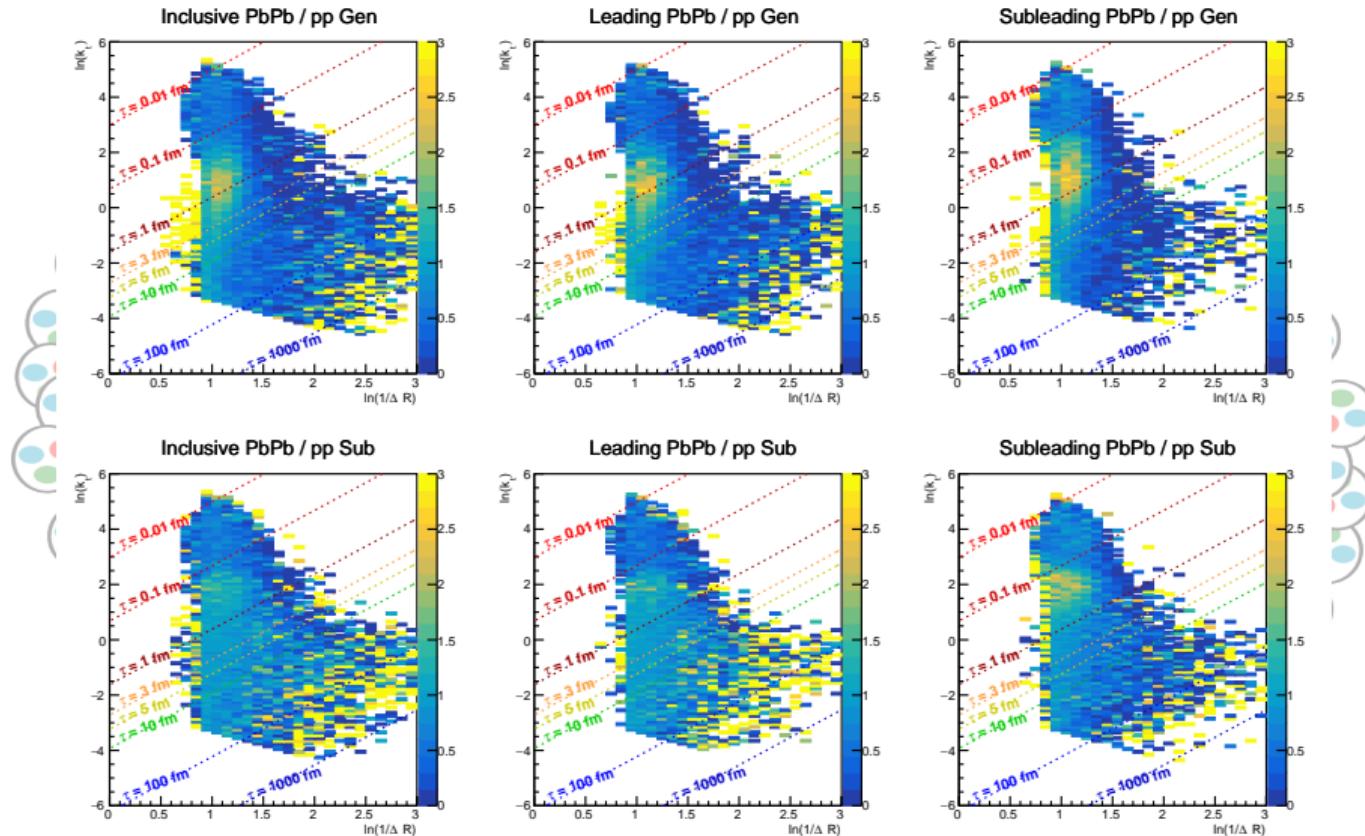
Lund Planes - First Splitting Subleading



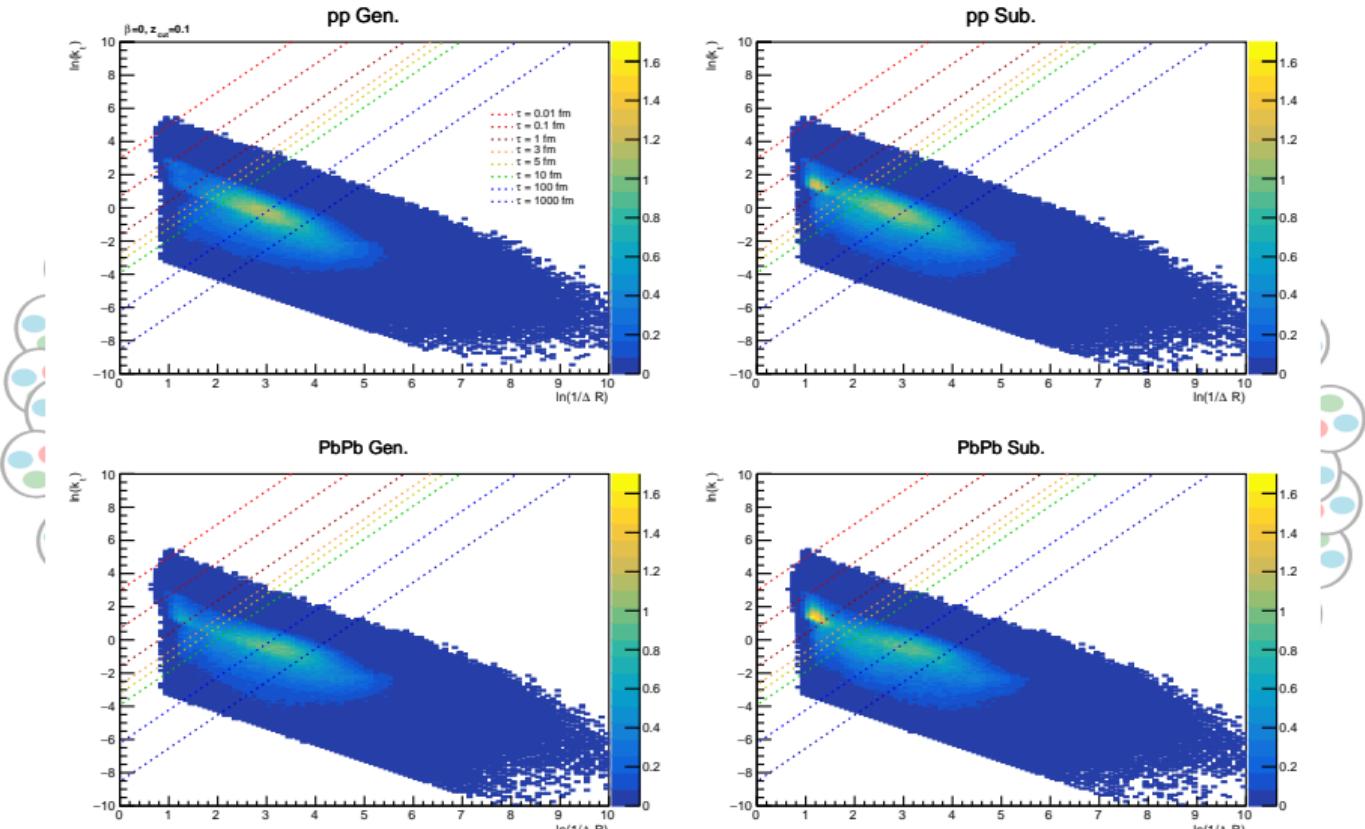
Lund Planes - First Splitting difference



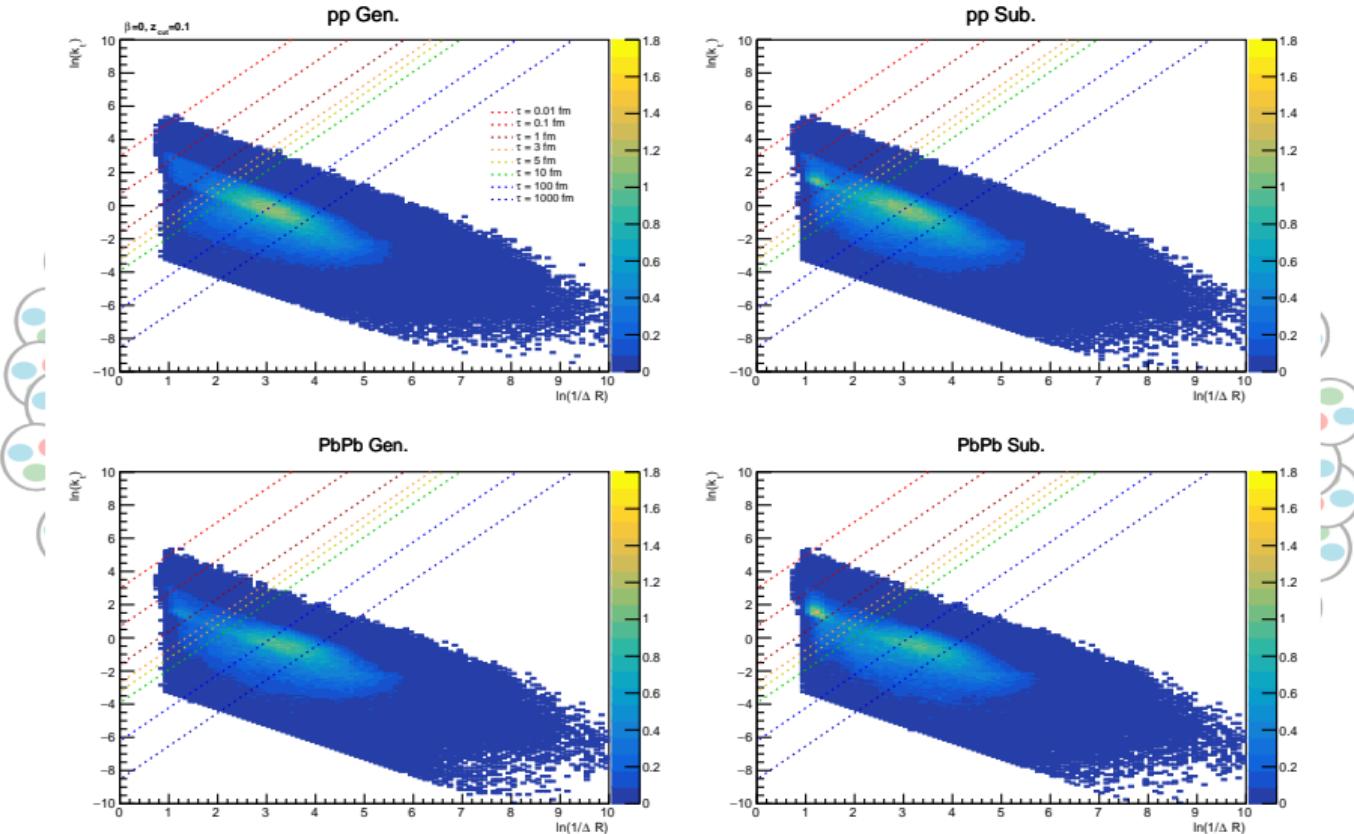
Lund Planes - First Splitting Ratio



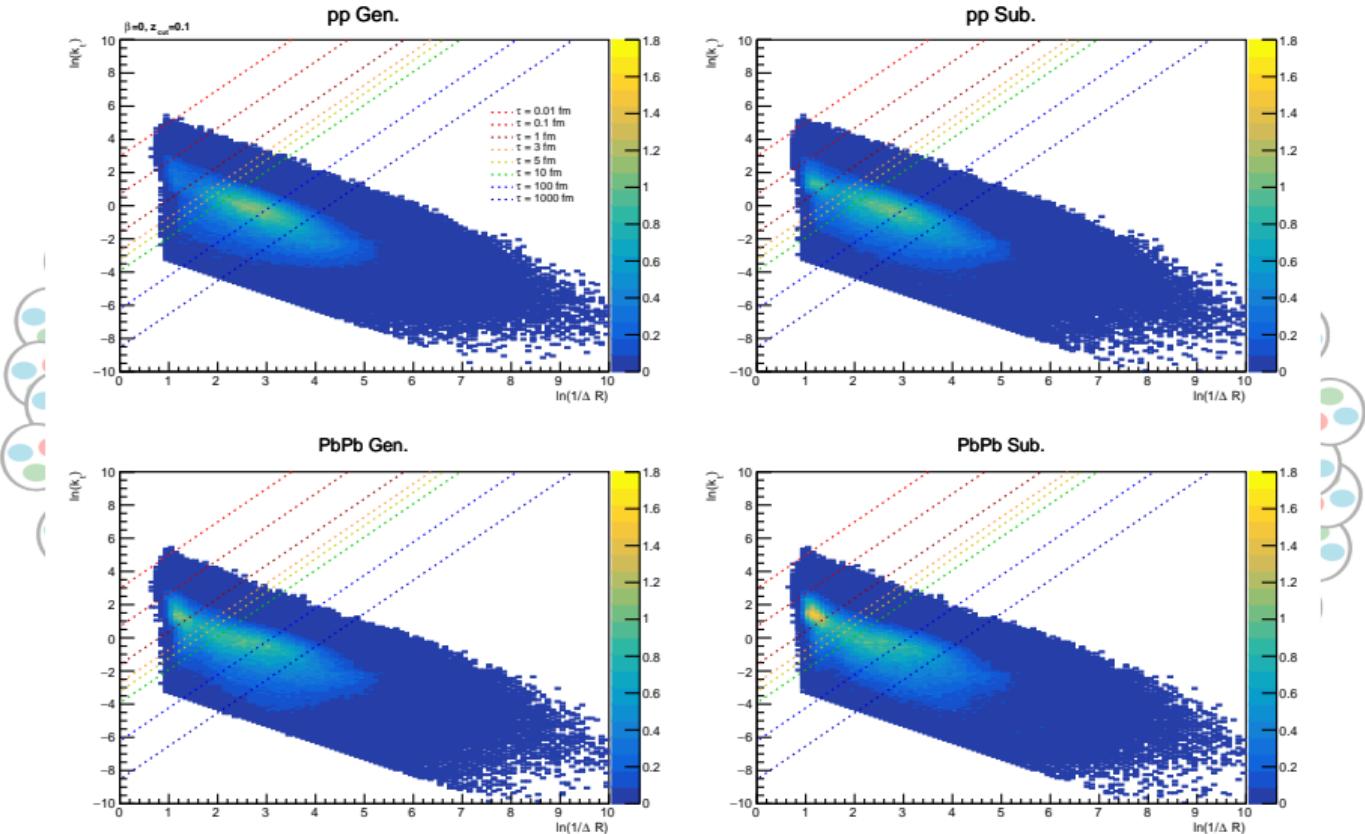
Lund Planes SD - Full Inclusive



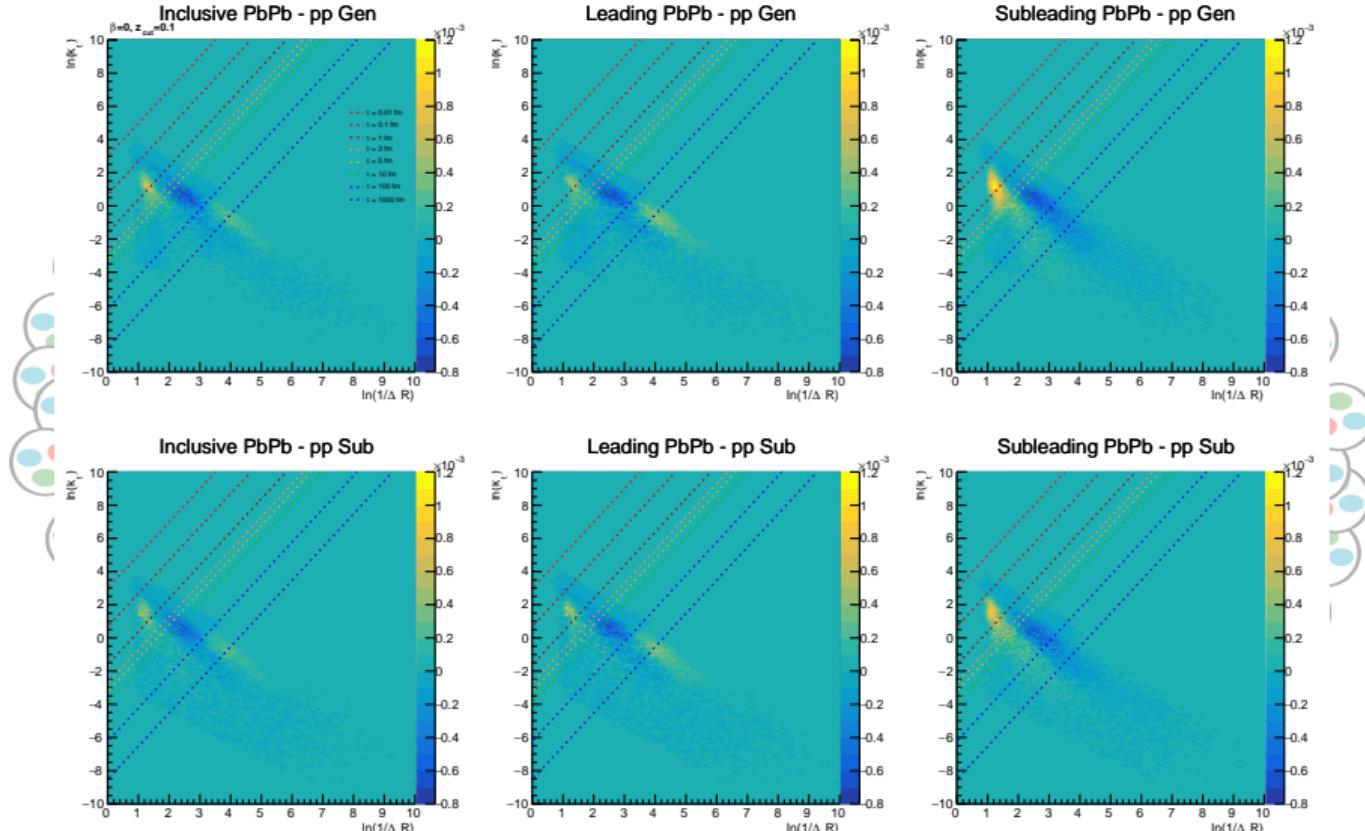
Lund Planes SD - Full Leading



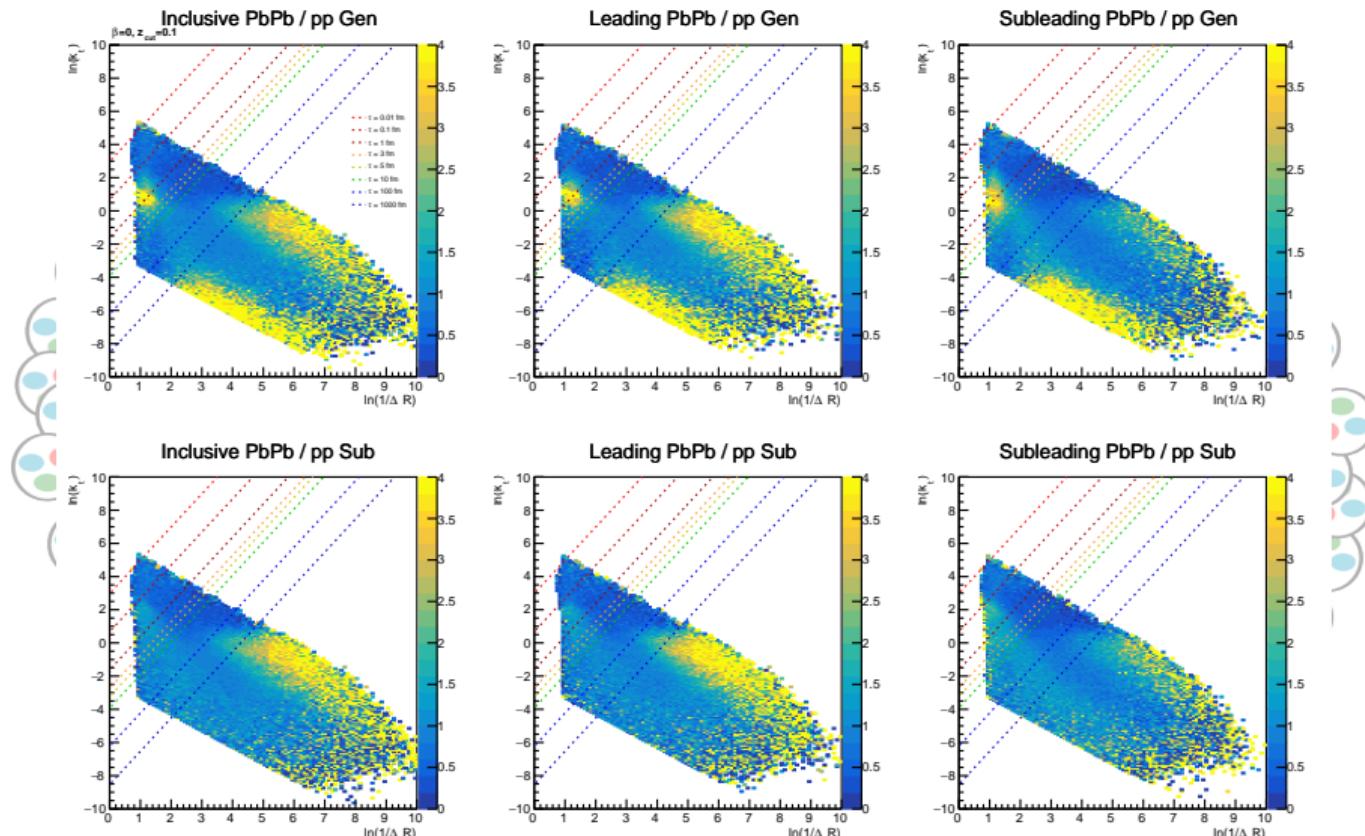
Lund Planes SD - Full Subleading



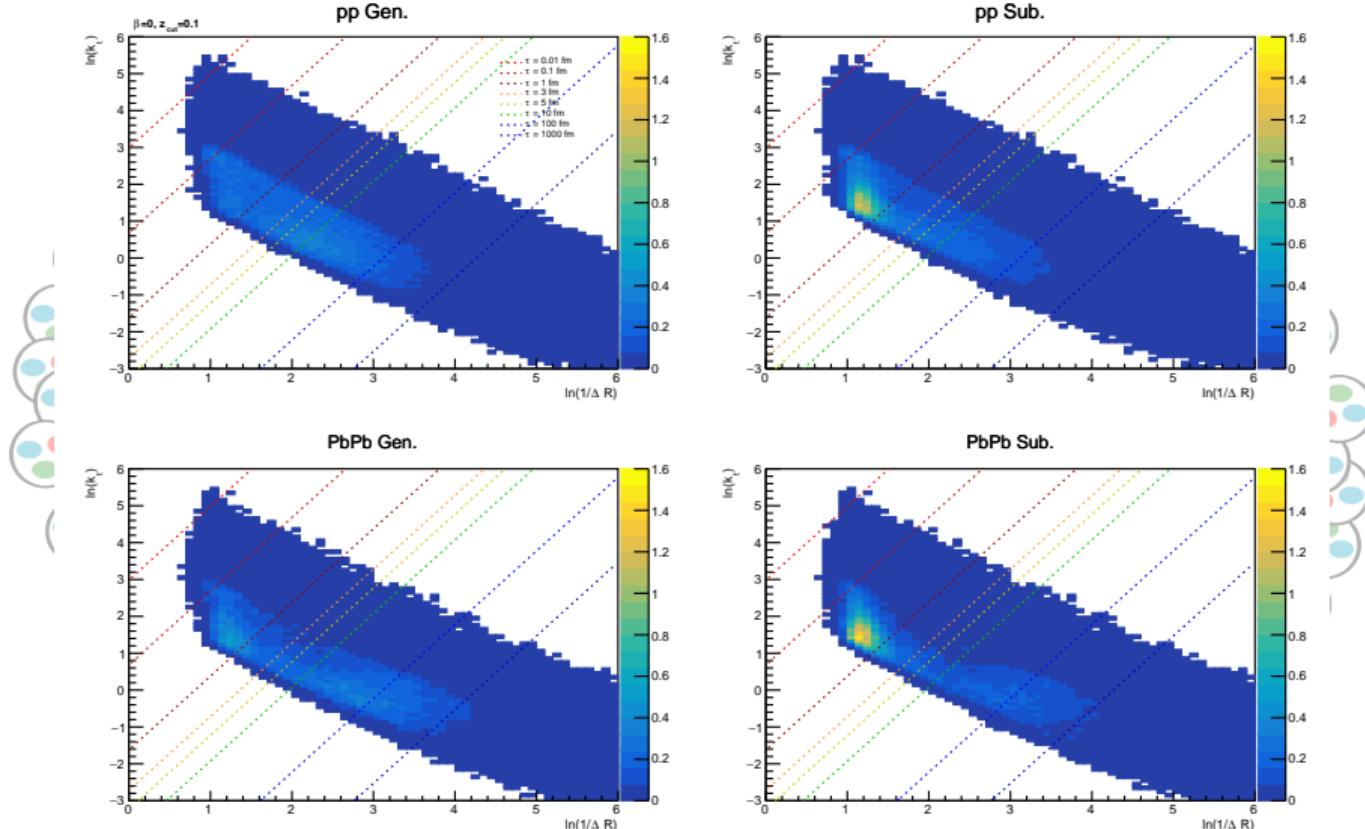
Lund Planes SD - Full Difference



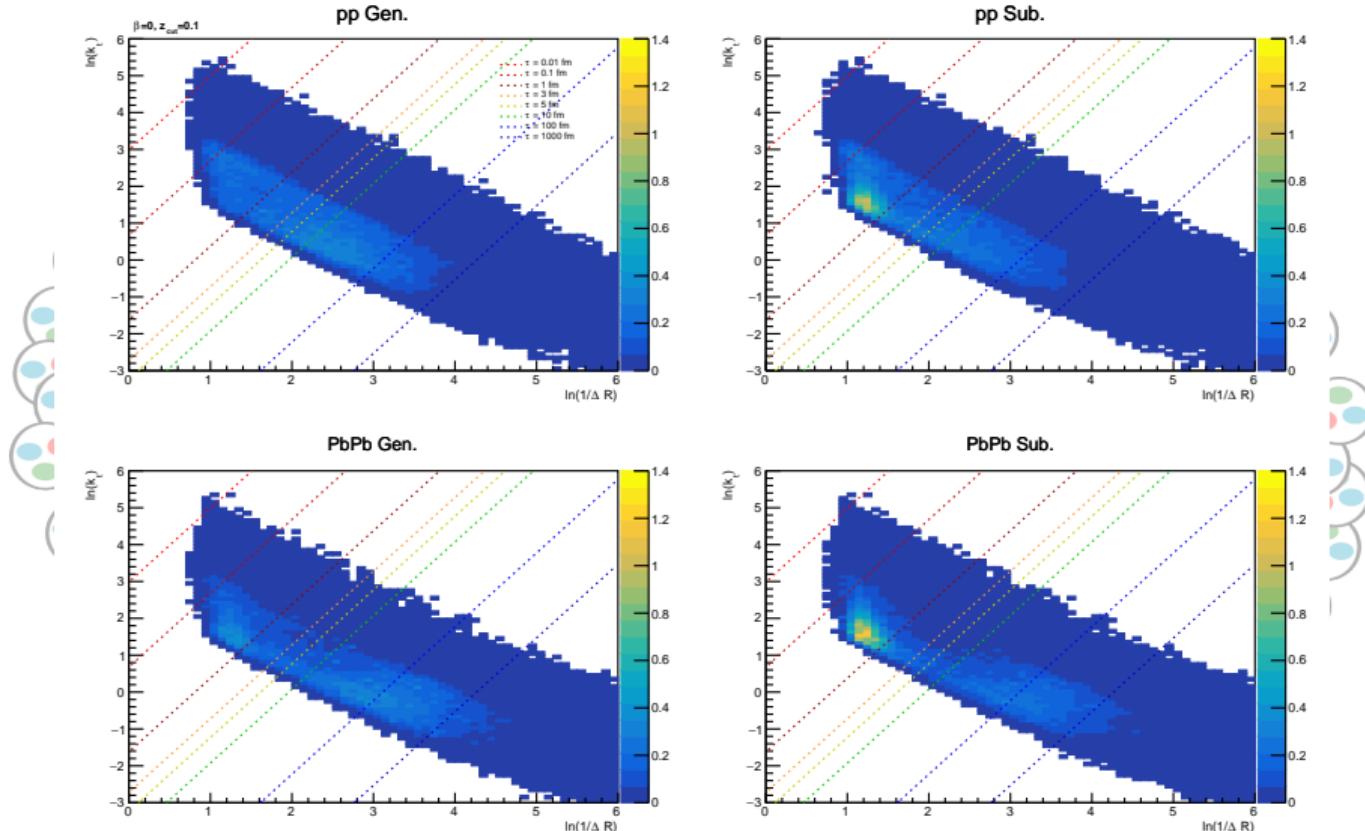
Lund Planes SD - Full Ratio



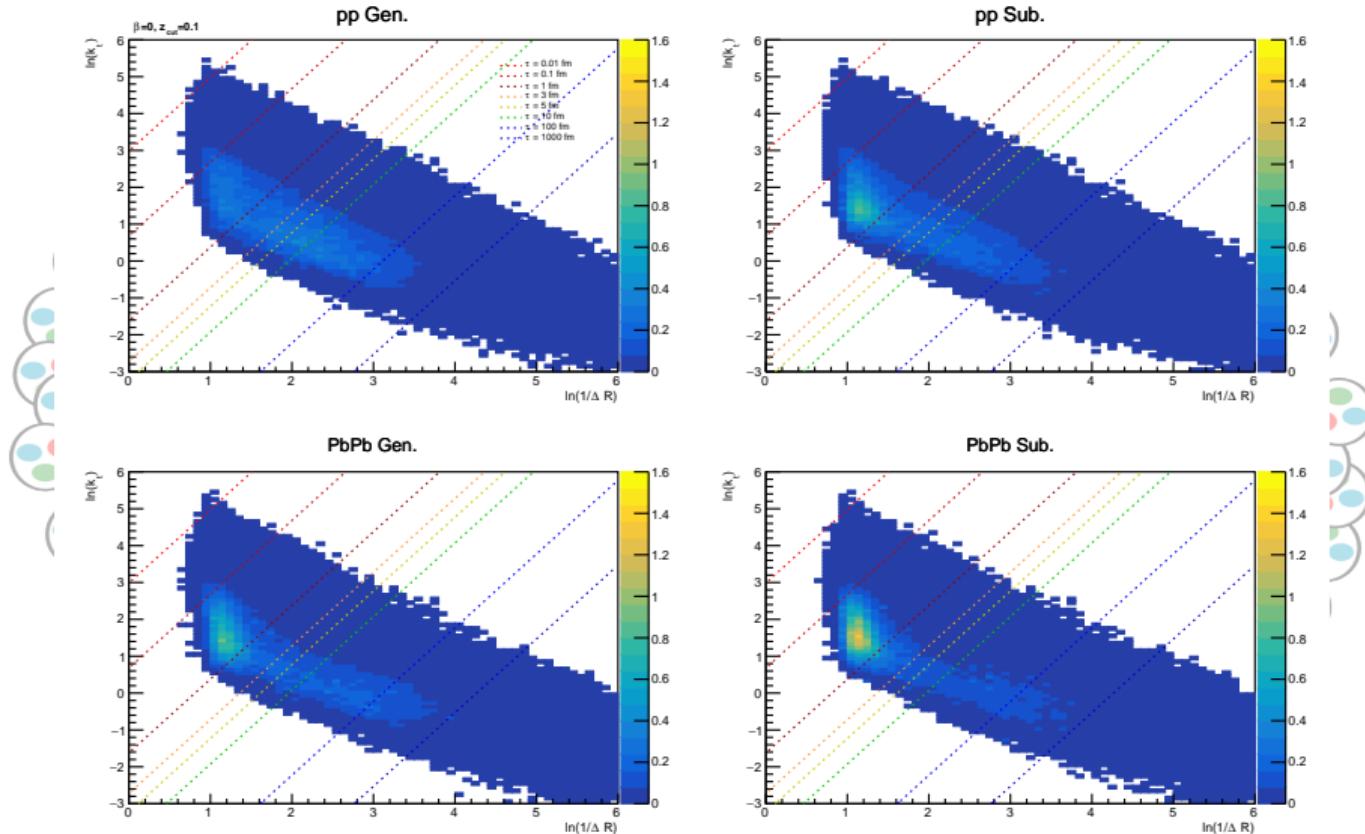
Lund Planes SD - First Splitting Inclusive



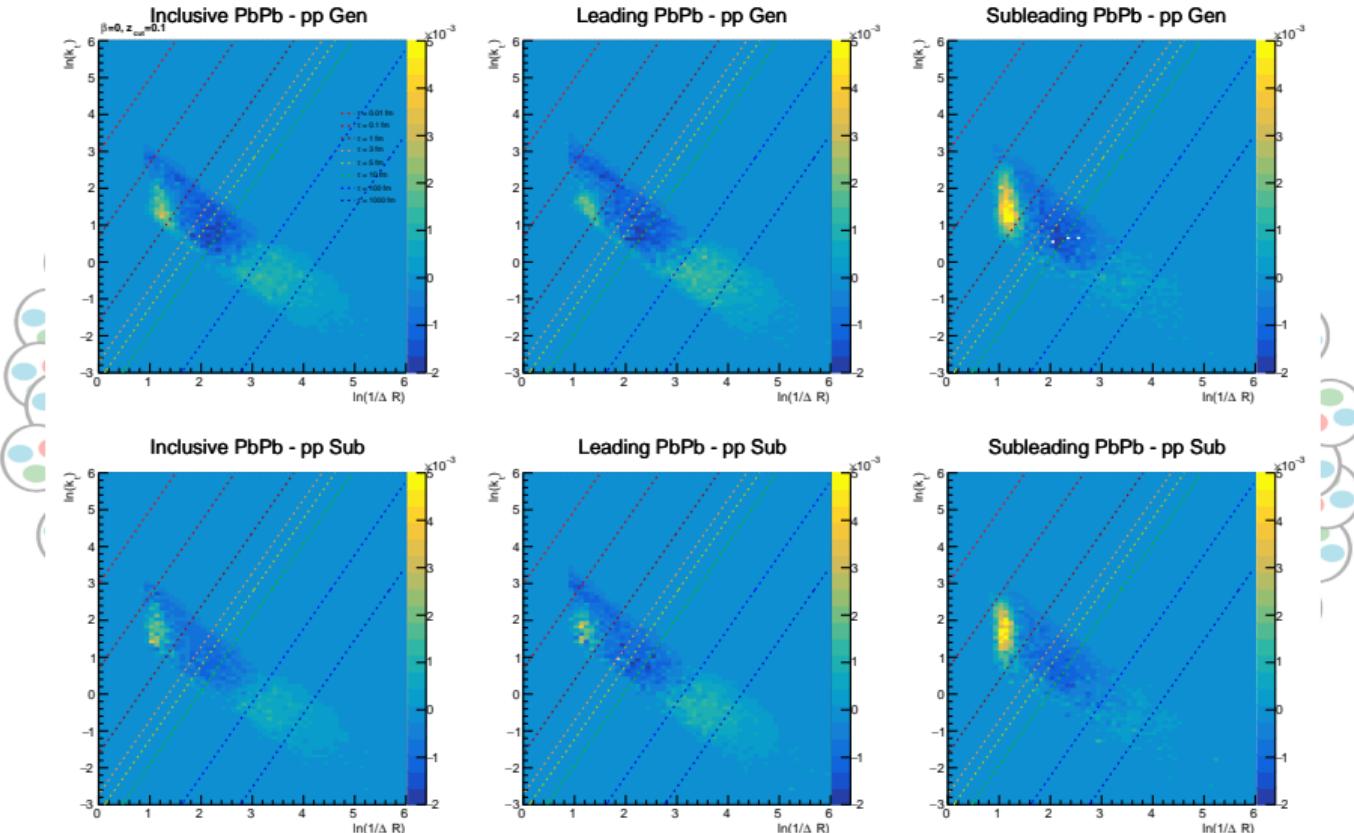
Lund Planes SD - First Splitting Leading



Lund Planes SD - First Splitting Subleading



Lund Planes SD - First Splitting difference



Lund Planes SD - First Splitting Ratio

