



# **Modern Measurement Tools** And the algorithms changing everything...

**D** Keller

### **TENSOR SPIN OBSERVABLES**



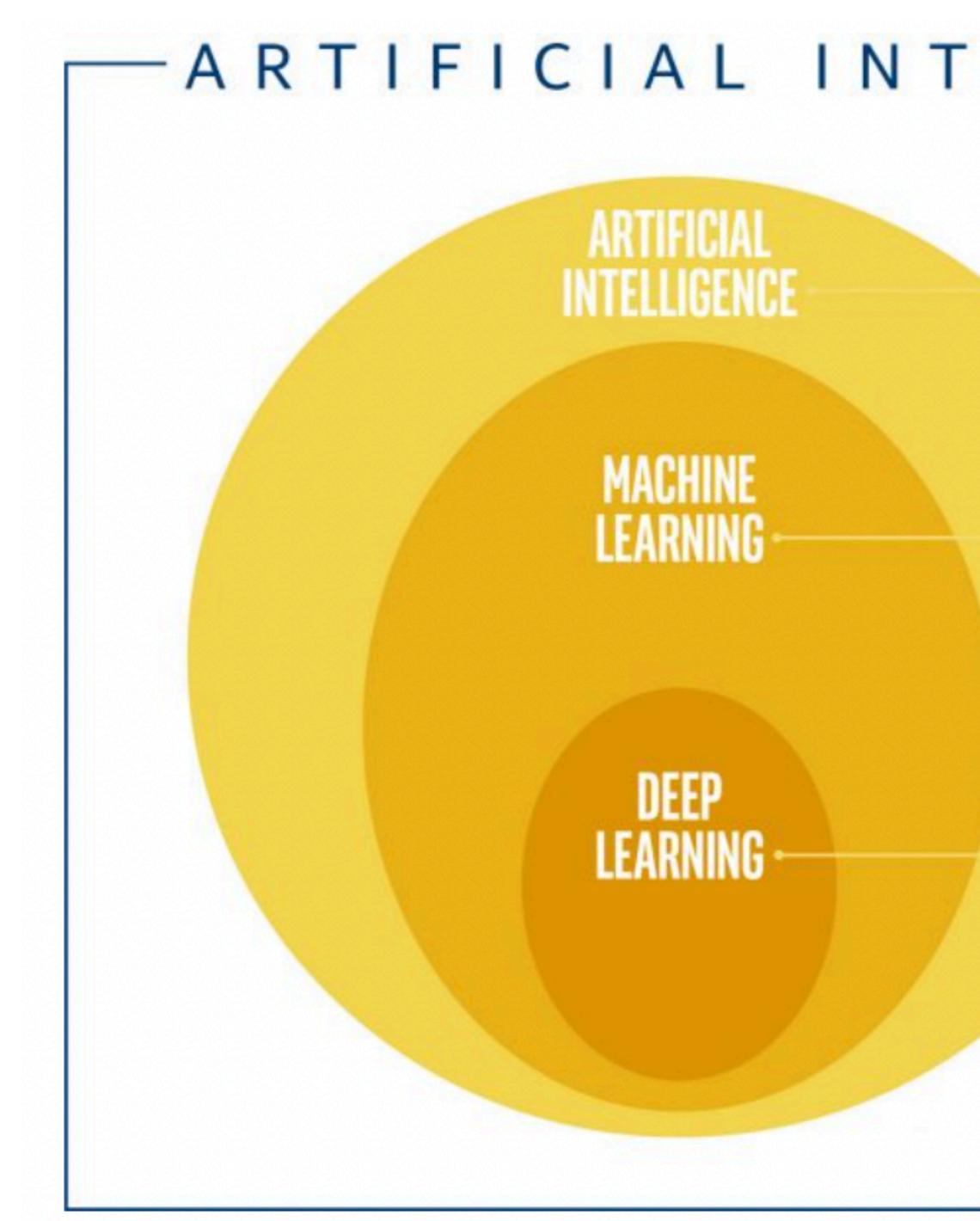






# Contents

- Seems to be something going on in Al
- Examples
- Positioning for the greatest leaps forward
- Why its essential for spin-1



### ARTIFICIAL INTELLIGENCE TERMS-

• Al is an umbrella term for machines capable of perception, logic, and learning.

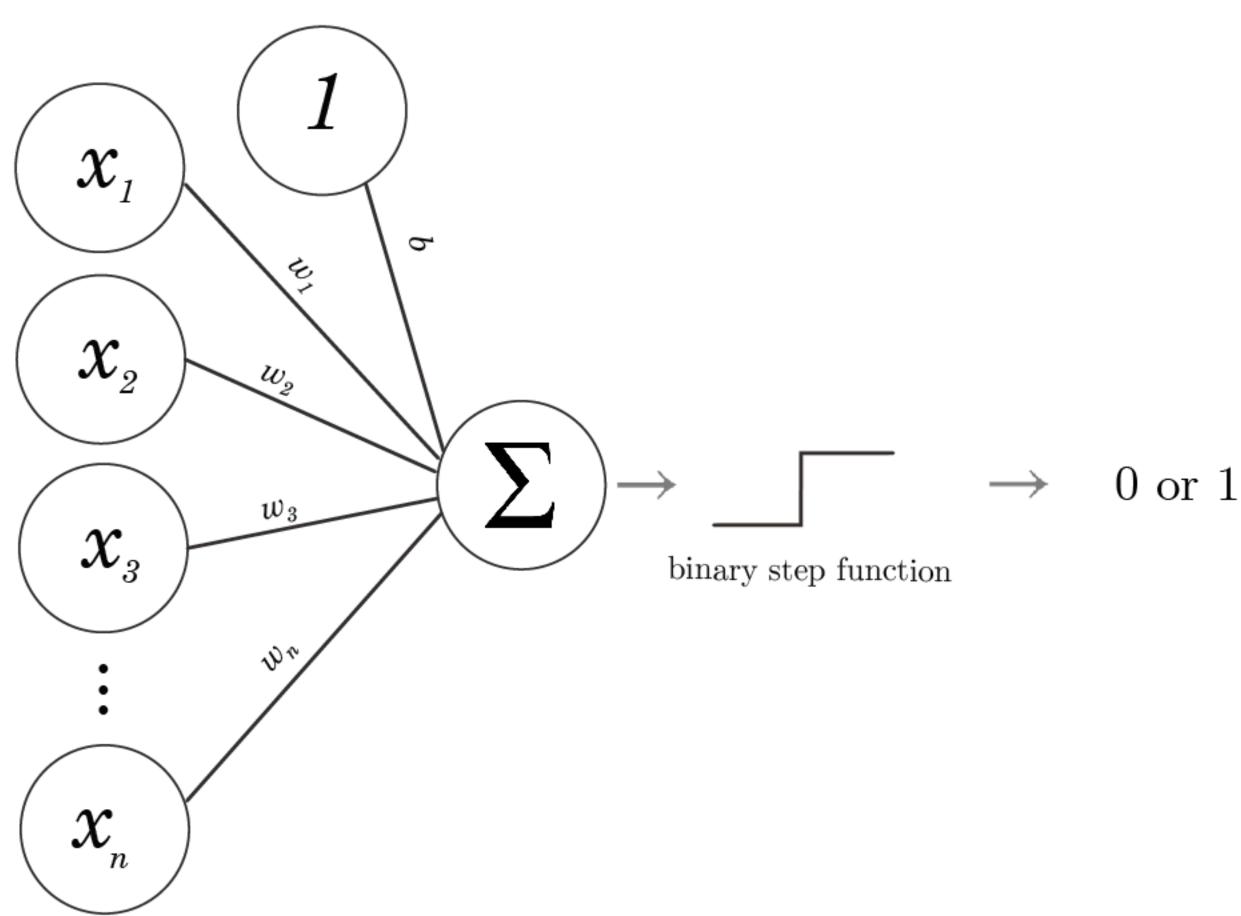
- Machine learning employs algorithms that learn from data to make predictions or decisions, and whose performance improves when exposed to more data over time.
- Deep learning uses many-layered neural networks to build algorithms that find the best way to perform tasks on their own, based on vast sets of data.



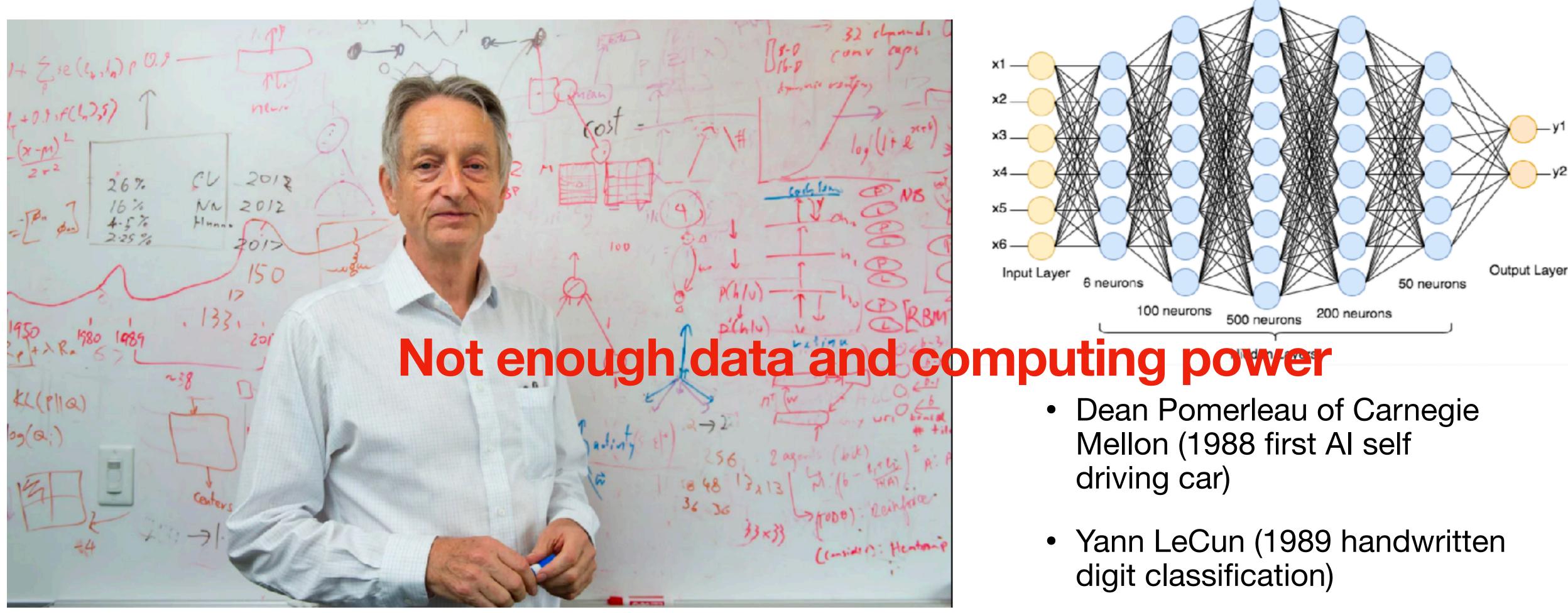
# First Perceptron Paved the way for Al



Frank Rosenblatt in July 1958, the U.S. Office of Naval Research

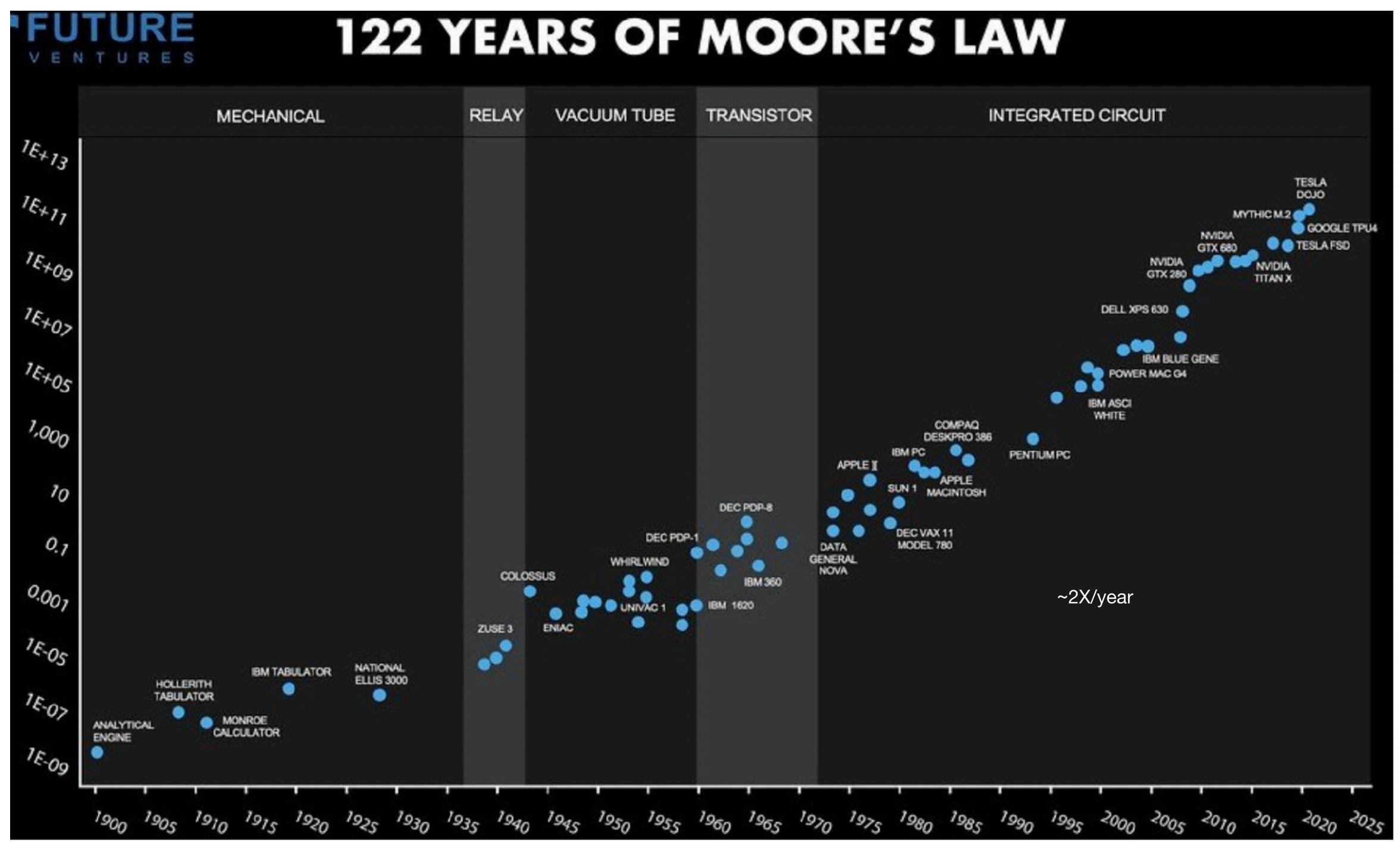


## **Birth of Modern Algorithm** In the mid 80s Geoff Hinton discovered how to make deep ANNs



. . .





## Mores Law Caught up in 2006 **Algorithm Adapted to modern computing**

### A fast learning algorithm for deep belief nets \*

### Geoffrey E. Hinton and Simon Osindero

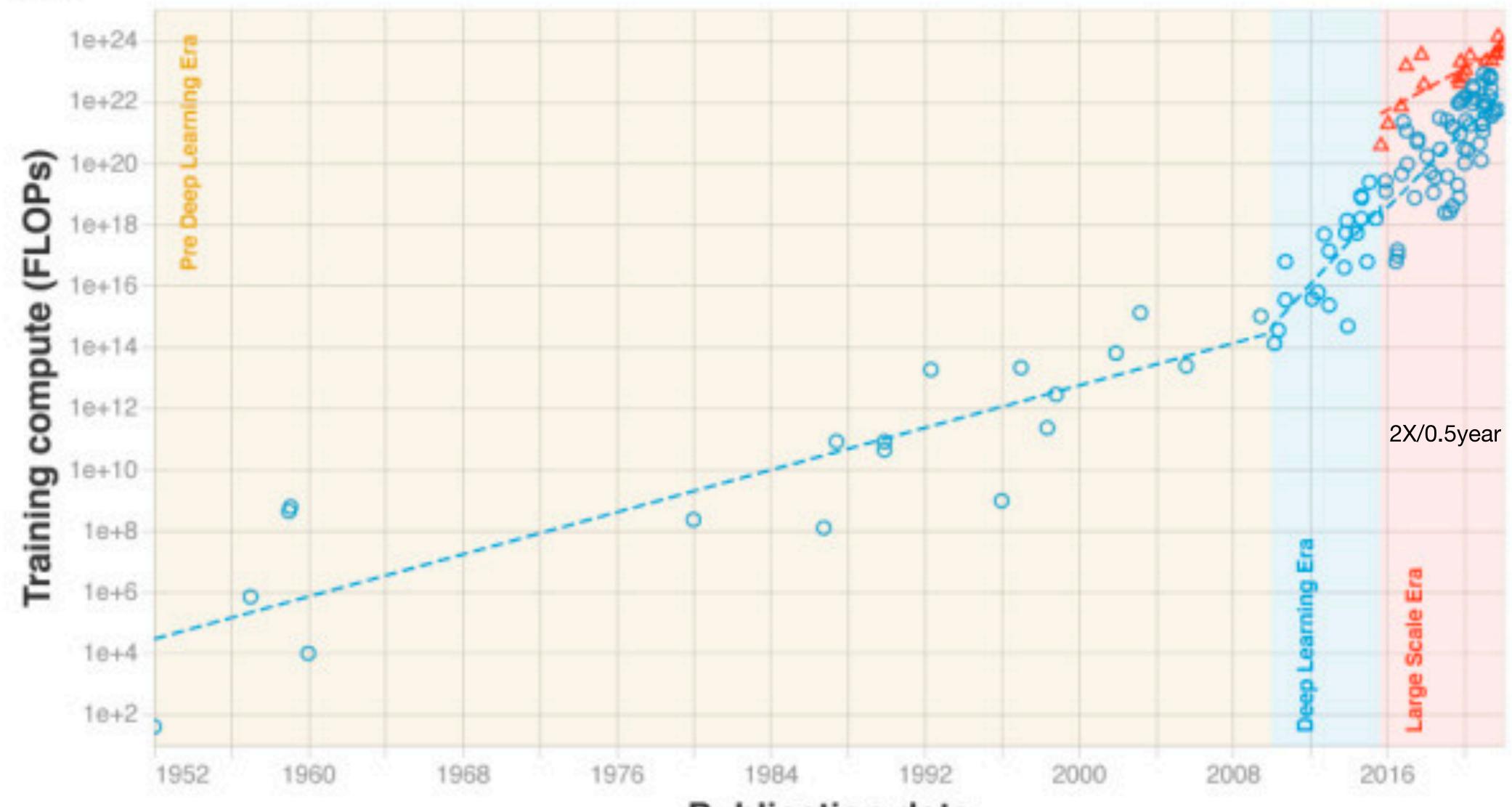
Department of Computer Science University of Toronto 10 Kings College Road Toronto, Canada M5S 3G4 {hinton, osindero}@cs.toronto.edu

- Advancement in Processors, Memory, Storage
- Essential high speed systems become available (parallelism)
- Large scale datasets (the world becomes teaming with data)

### Yee-Whye Teh

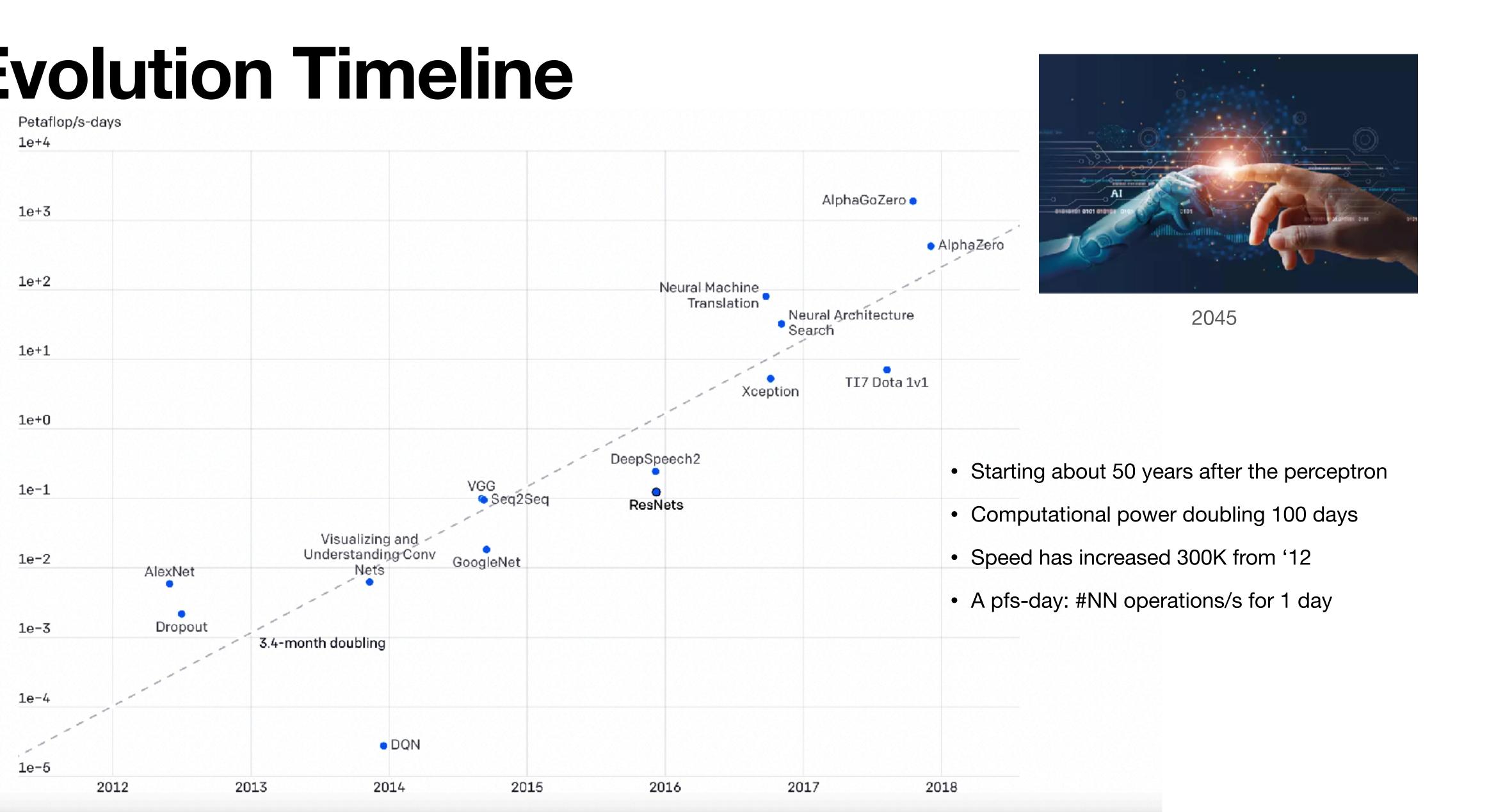
Department of Computer Science National University of Singapore 3 Science Drive 3, Singapore, 117543 tehyw@comp.nus.edu.sg

### Training compute (FLOPs) of milestone Machine Learning systems over time n = 118

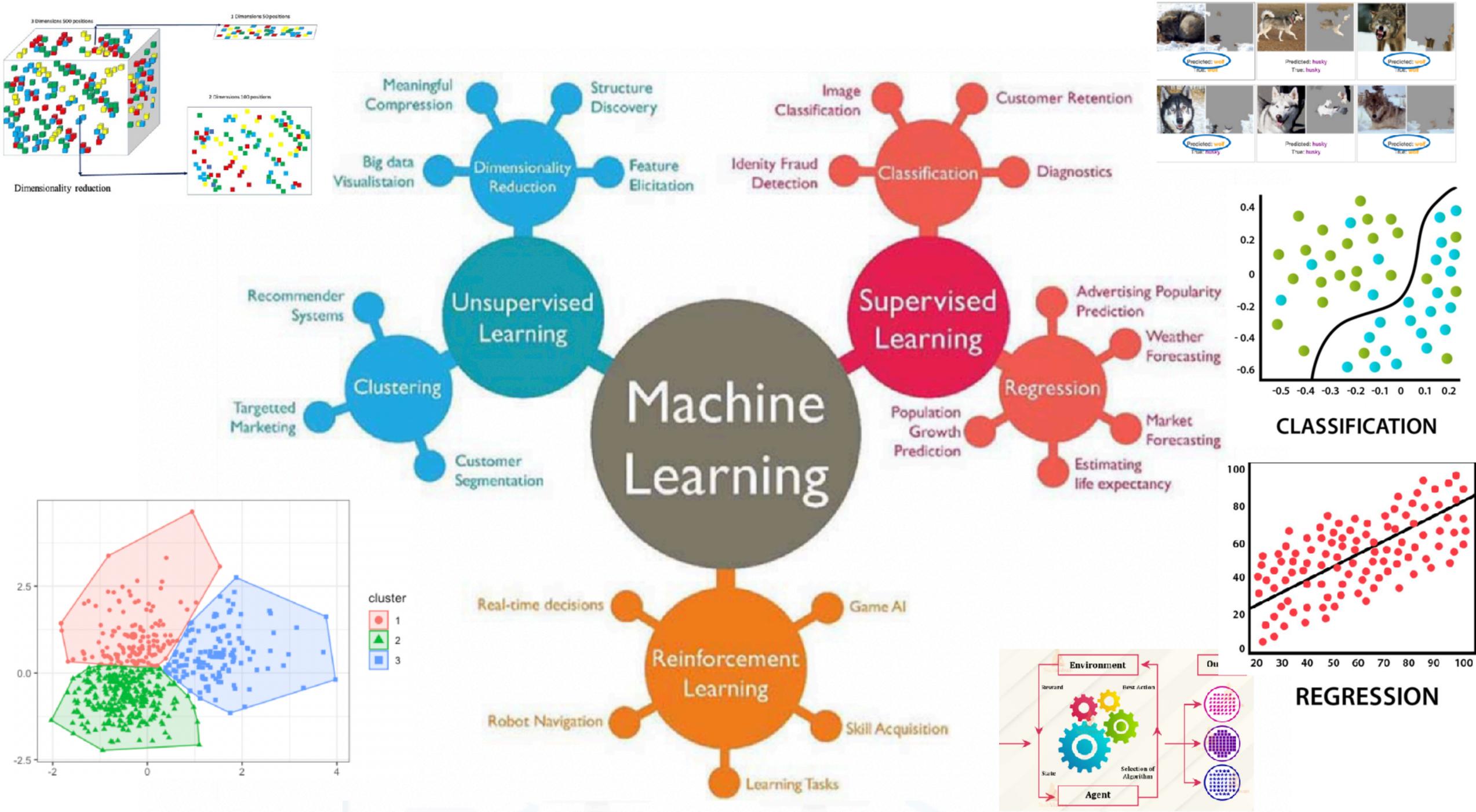


### **Publication date**

# **Evolution Timeline**



R. Kurzweil

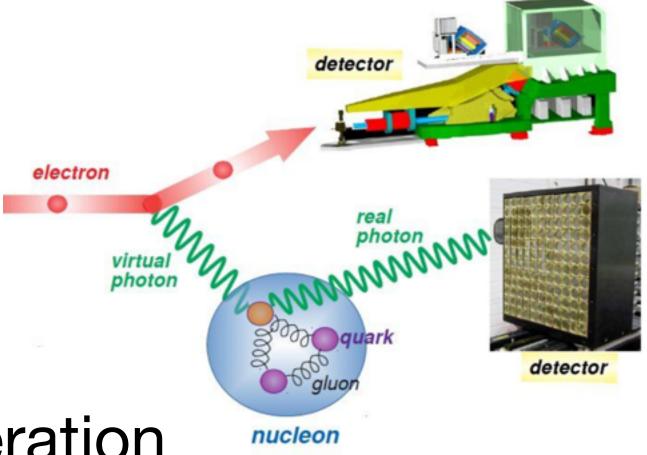


## **Basic DNN Concepts** That are changing the way we do physics...

- Extract more information with more inputs (neurons, layers, variables, data)
- Lightning fast inference (specialized hardware to parallelize)
- Ultimately adaptive and accurate (Universal Approximation Theorem)

## **Machine Learning** In Nuclear and Particle Physics

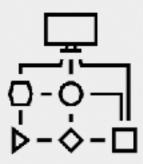
- Event-level Classification
- Trigger and Pattern Recognition
- Tracking/Event Reconstruction
- Cluster Reconstruction in Calorimeters
- Regression of detector drifts
- Phenomenological Extraction



- Simulation acceleration
- Instrumentation Automation
- Detector/cryostat Design
- Online Monitoring/Optimization
- Detector Readout Optimization
- Modeling \*

## **Configure Experiments for DNN optimization One project at a time**

- Detector characterization and performance tuning with DNNs
  - calibration, efficiencies, acceptance
- Raw data (ACD/TDC) straight to Physics
  - Suggests the concept of Intelligent Detectors
  - Optimization of beam time
- Inference using GPU is fast
  - Keep up with data rates
  - Specialize I/O pipeline



### Al Inference Workloads

Researchers are continuing to evolve and expand the size, complexity, and diversity of AI models.



## Rethinking the Way We do Research Getting the most from computing means *Redesigning Everything*

- Raw information is more advantageous for DNN analysis
  - Need to start at the DAQ and tracking level
  - Very fast online monitoring can now perform full chain analysis
  - Anomaly detection on incoming data
  - Real time systematic quantification

## **Some Examples In Polarized Targets**

- Traveling-wave electron linac
- Irradiated to  $10^{17} e^{-/cm^2}$
- 14 GeV 10  $\mu A$  under Liquid Argon (~87 K)
- Proton knocked out to from free radicals
- Also form color centers
- Material color is correlated to the dose
- Optimized for field and temperature

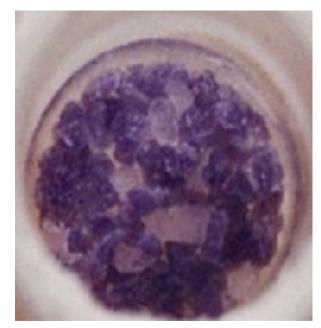
### Irradiation Performed at NIST (MIRF Accelerator)

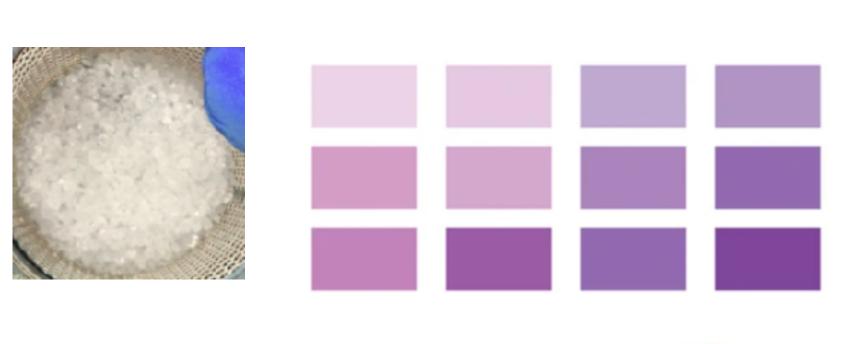




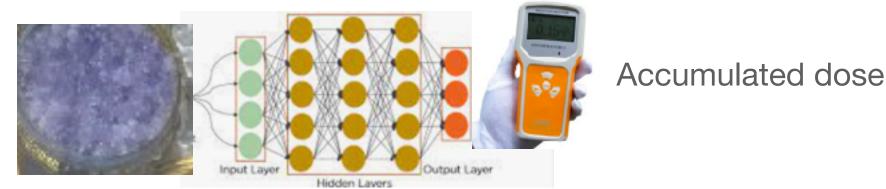








**Material Photo** 



### Al in Online Monitoring Fast Reconstruction

🔖 DOX\_ele 🌺 DOXp\_ele

b0V\_ele ≹D0Vp\_ele D2U\_ele

- D2Up\_ele D2X\_ele D2Xp\_ele D2V\_ele D2Vp\_ele D2Vp\_ele D3pU\_ele D3pUp\_ele D3pX\_ele

D3pVp\_ele D3pVp\_ele D3pVp\_ele D3mUp\_ele D3mUp\_ele D3mX\_clo D3mXp\_ele D3mV\_ele D3mV\_ele D3mV\_ele

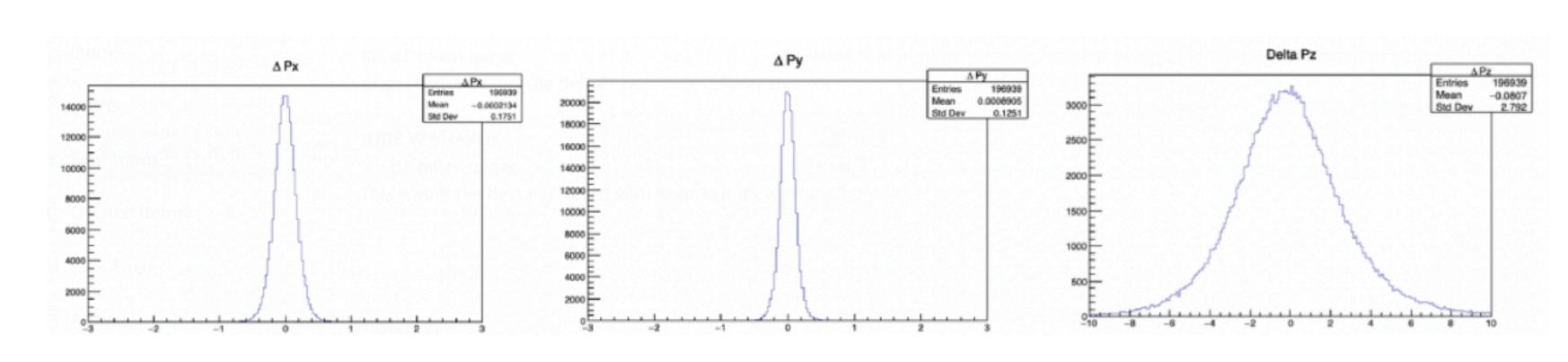
🔖 DOU\_drift

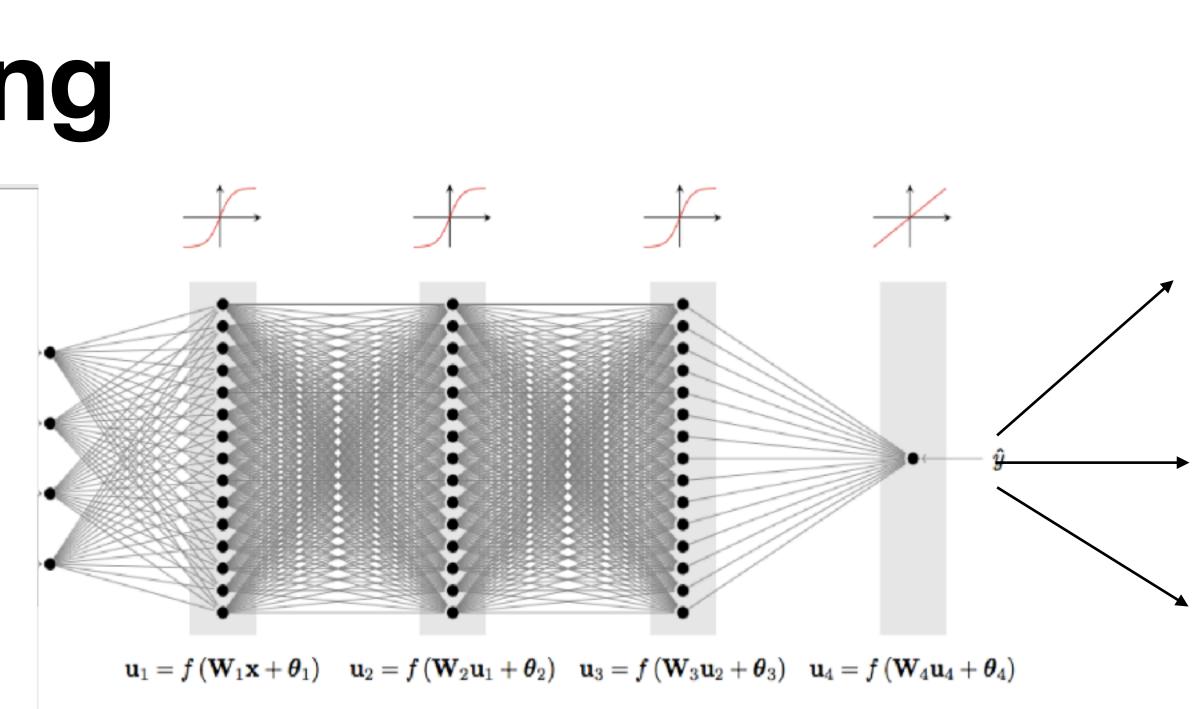
- 🍢 DOUp\_drift - 💸 DOX\_drift

DOXp\_drift DOV\_drift DOVp\_drift D2U\_drift D2Up\_drift

$$A = \frac{N_L - N_R}{N_L + N_R}$$

- Detector element failure
- Target-beam miss alignment
- Cell twisting
- Faulty position
- Target cell damage





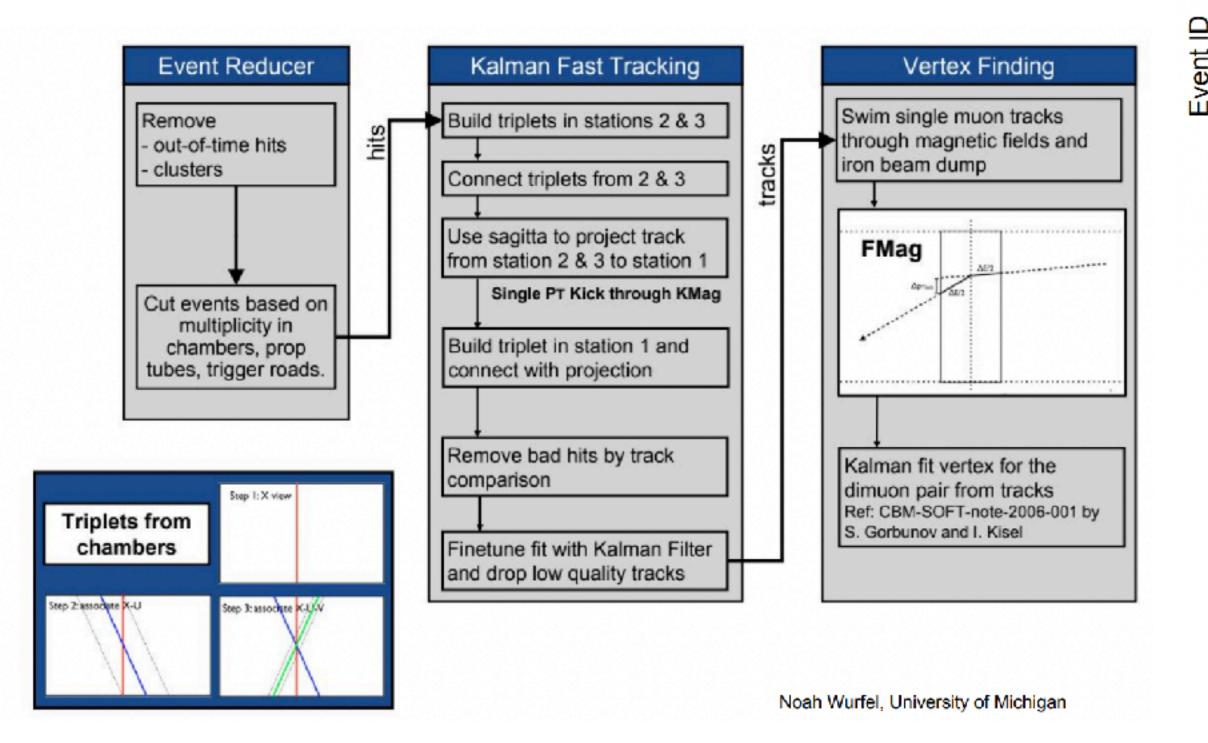
**Arthur Conover** 



Pz

Px

### **Al in Online Reconstruction Fast Reconstruction** 200



1 CPU: 110 minutes for 40K

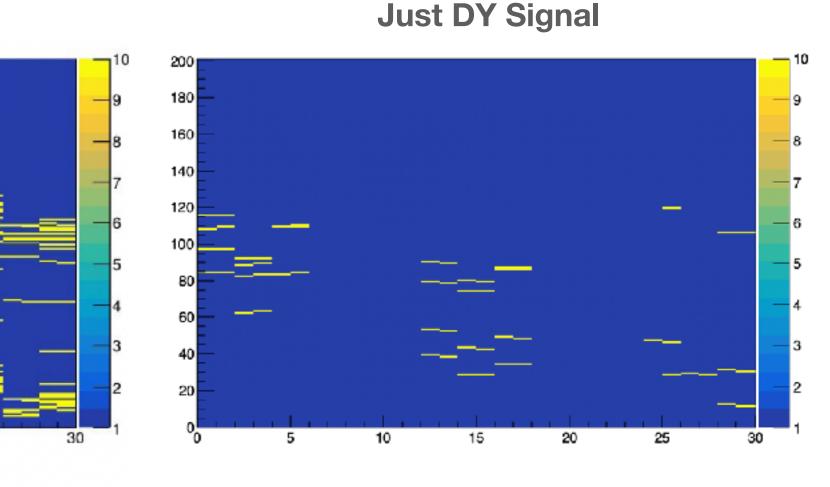
**Background and Signal** 

180

160

140

5

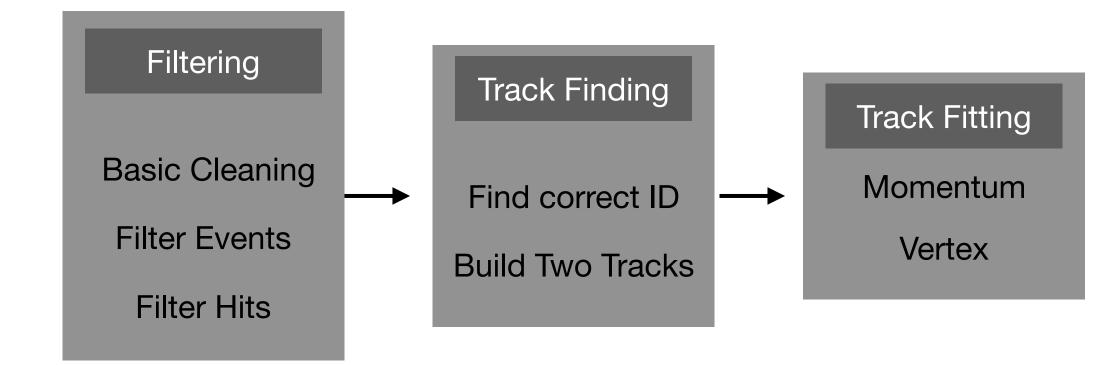


Detector ID

10

20

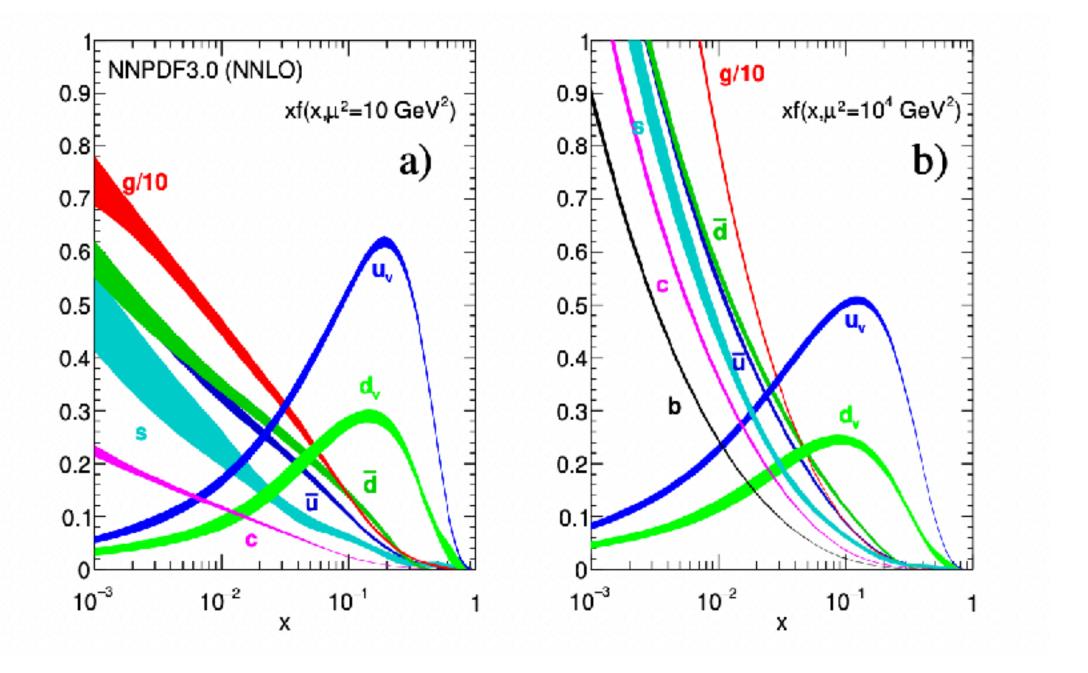
25



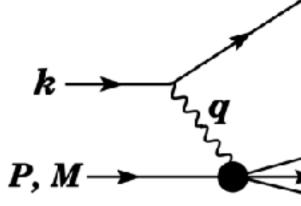
1 CPU: 48 seconds for 40K

# **Parton Distribution Functions**

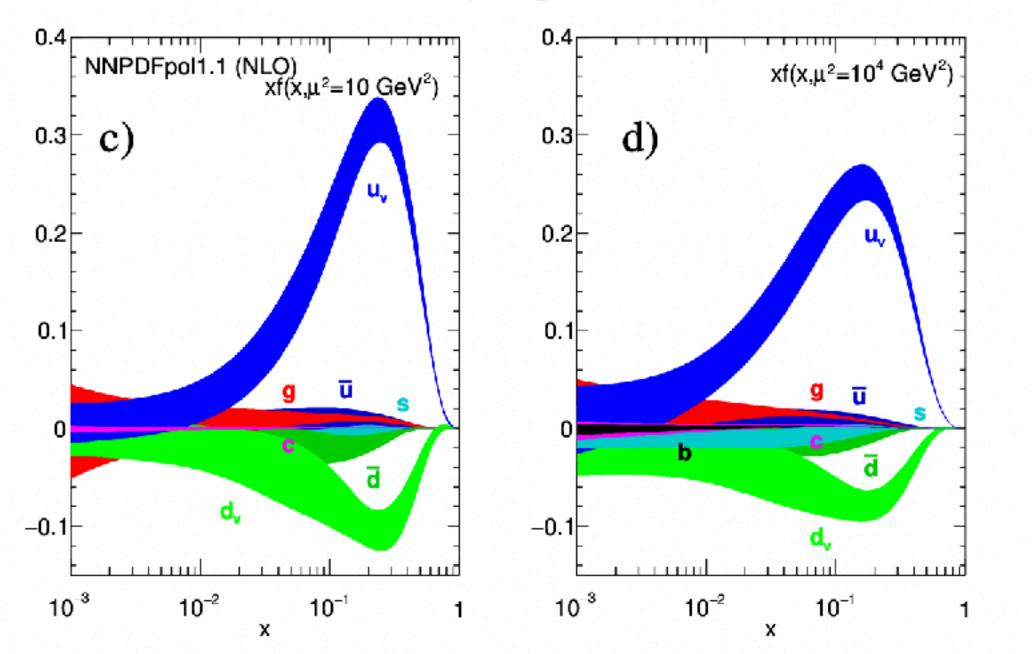
### HERA and LHC programs



- In DIS resolving power goes like  $\hbar/q$ , q = 100 GeV  $\rightarrow 0.002$  fm
- Consider the parts in a collinear with the nucleon momentum so each parton caries x
- PDF represent probability density (number densities as they are normalized to the number of partons)



RHIC program



E. R. Nocera et al. (NNPDF), Nucl. Phys. B887, 276 (2014), [arXiv:1406.5539]

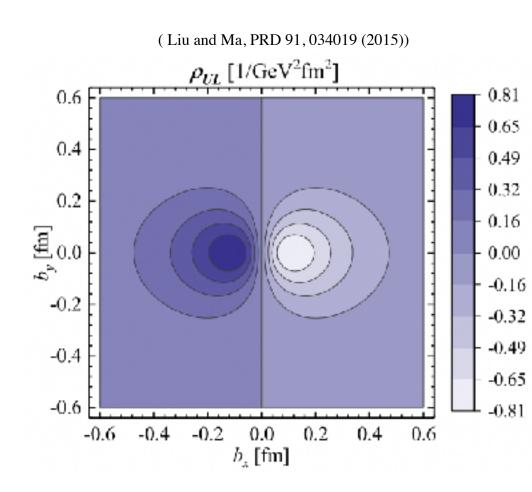


## **Some Issues in Spin** In Phenomenology (Understanding Femtoscale Dynamics)

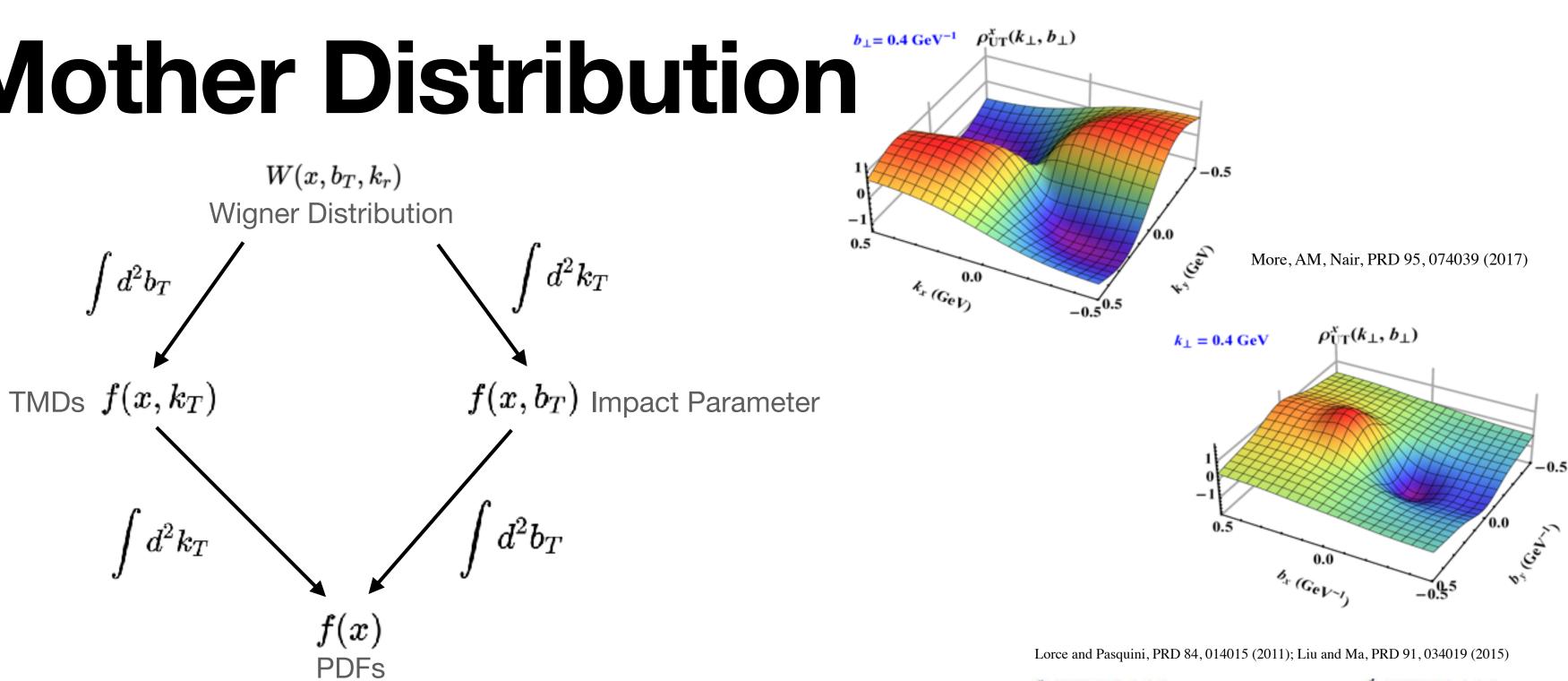
- Inverse Problem: Determine definitive measures of proton structures using experimental information, Lattice Calculations, and Phenomenology
  - Extraction of GPDs while eliminating the reliance of model fits
  - Extraction of TMDs without assuming a Gaussian factorized form
- Curse of Dimensionality: Understanding the Mother Function (Wigner?) in terms of processes and physical observables (interpretation yields inherent sparsity)
  - How can we impose constraints at the higher-level to interpret dynamics and geometry
  - How do we best obtain information from experiments that gets us the farthest

# **Candidate Mother Distribution**

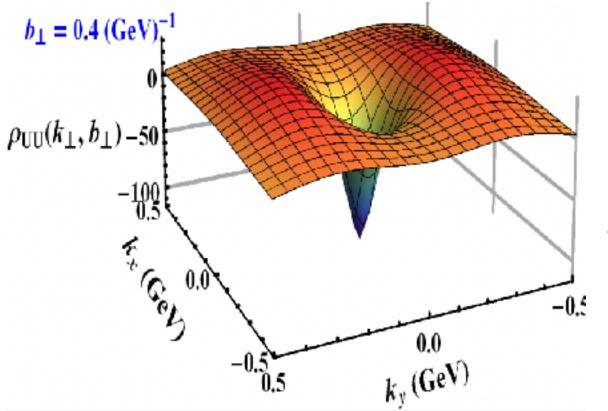
 $W(x,b_T,k_r)$ 





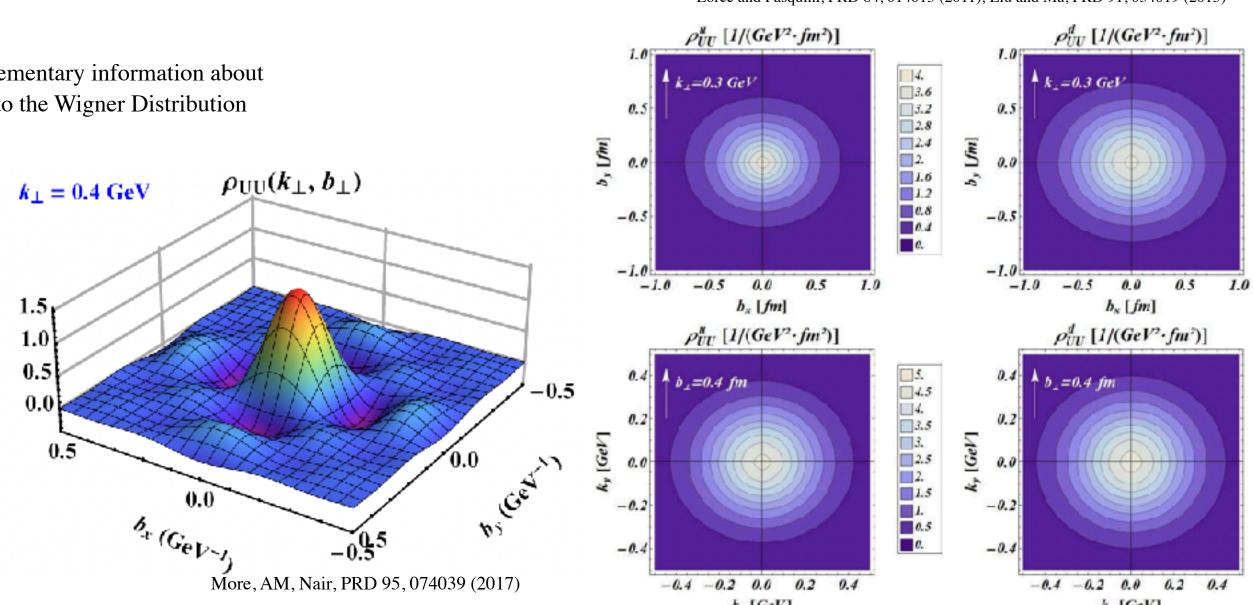


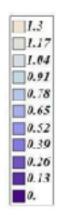
TMDs and Impact Parameters give complementary information about partons and are fundamentally connected to the Wigner Distribution



Husimi distributions have a Gaussian regularization factor in the integrand that keeps them positive in the entire range of transverse space coordinate

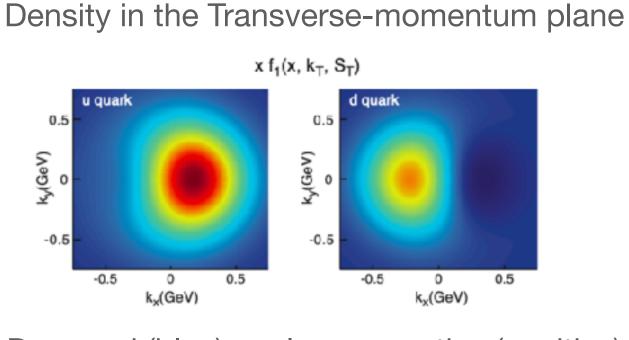
> Zhi-Lei Ma and Zhun Lu Phys. Rev. D 98, 054024







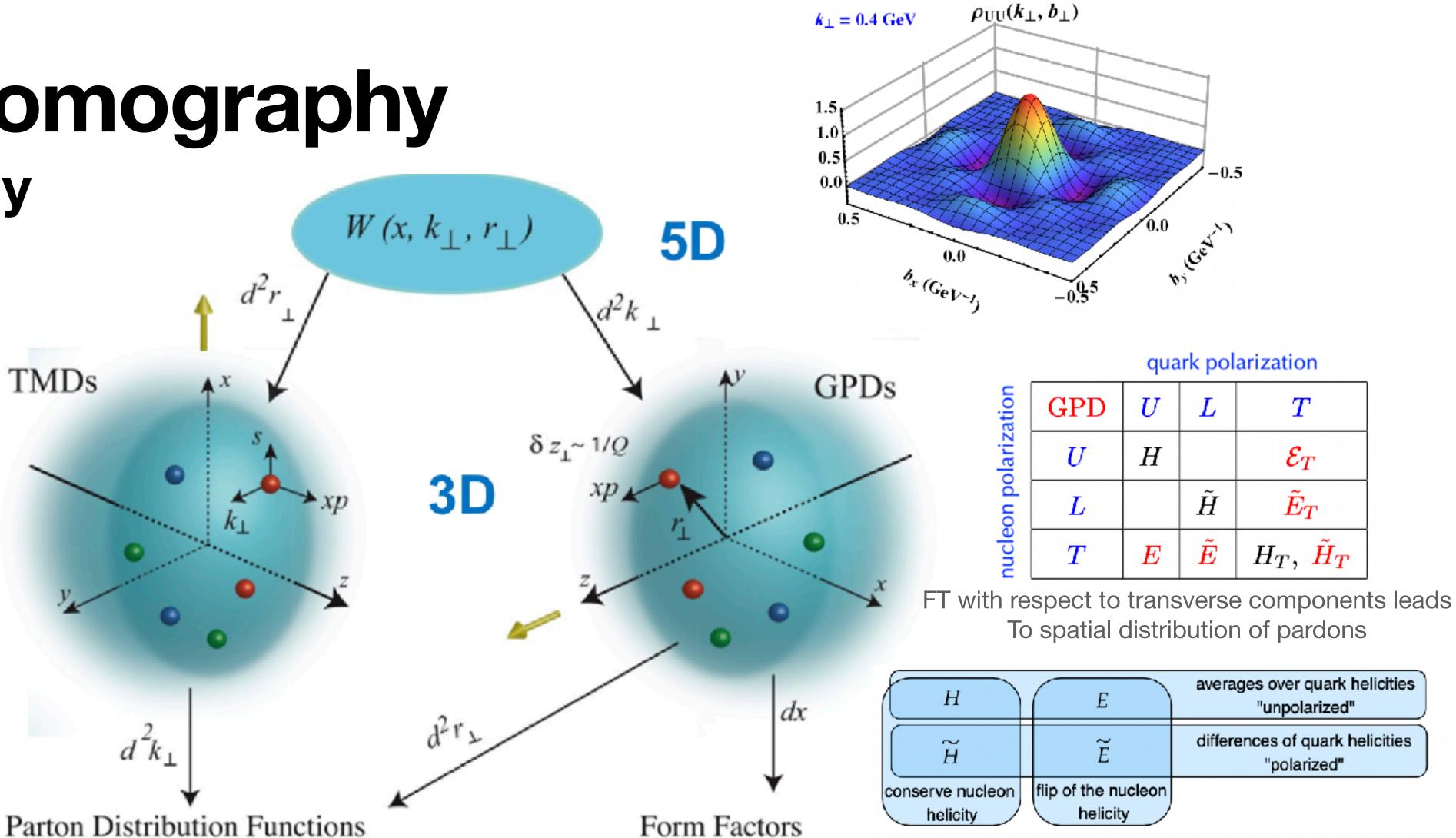
## **Nucleon Tomography Or Femtography**



Deep red (blue) are large negative (positive)

### quark polarization

	TMD	U	L	T
מוולמו	U	$f_1$		$h_1^\perp$
	L		$g_{1L}$	$h_{1L}^{\perp}$
	T	$f_{1T}^{\perp}$	$g_{1T}$	$h_1,\; oldsymbol{h}_{1T}^\perp$



### **Transverse Momentum Distributions**

- Transverse momentum structure
- Confined Motion of Partons

### **Generalized Parton Distributions**

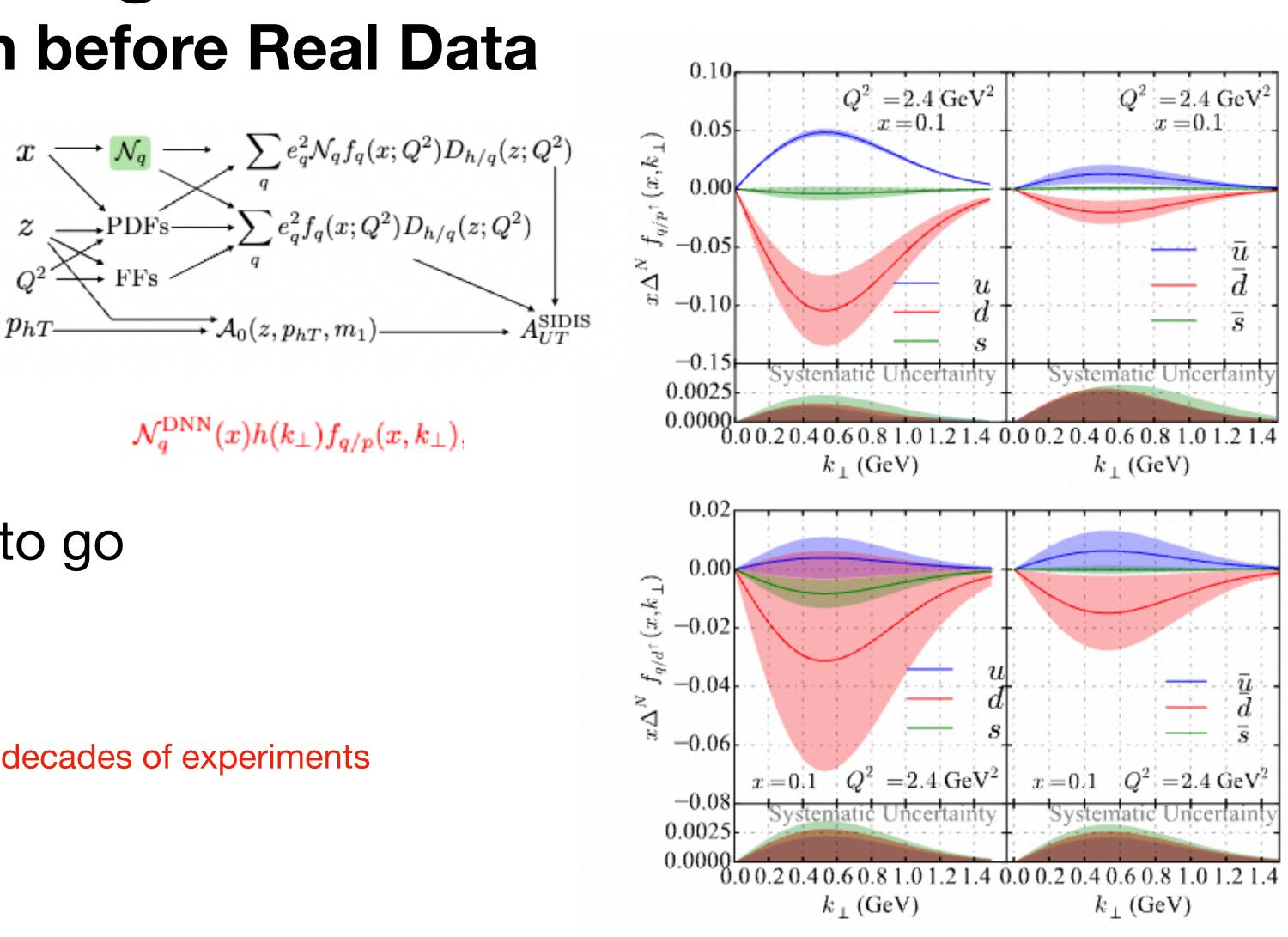
- Spatial Imaging of internal structure
- Form factors and generalized longitudinal structure



### **TMD Global Fitting Pseudodata Extraction before Real Data**

- Reduce assumptions
- Explore cuts





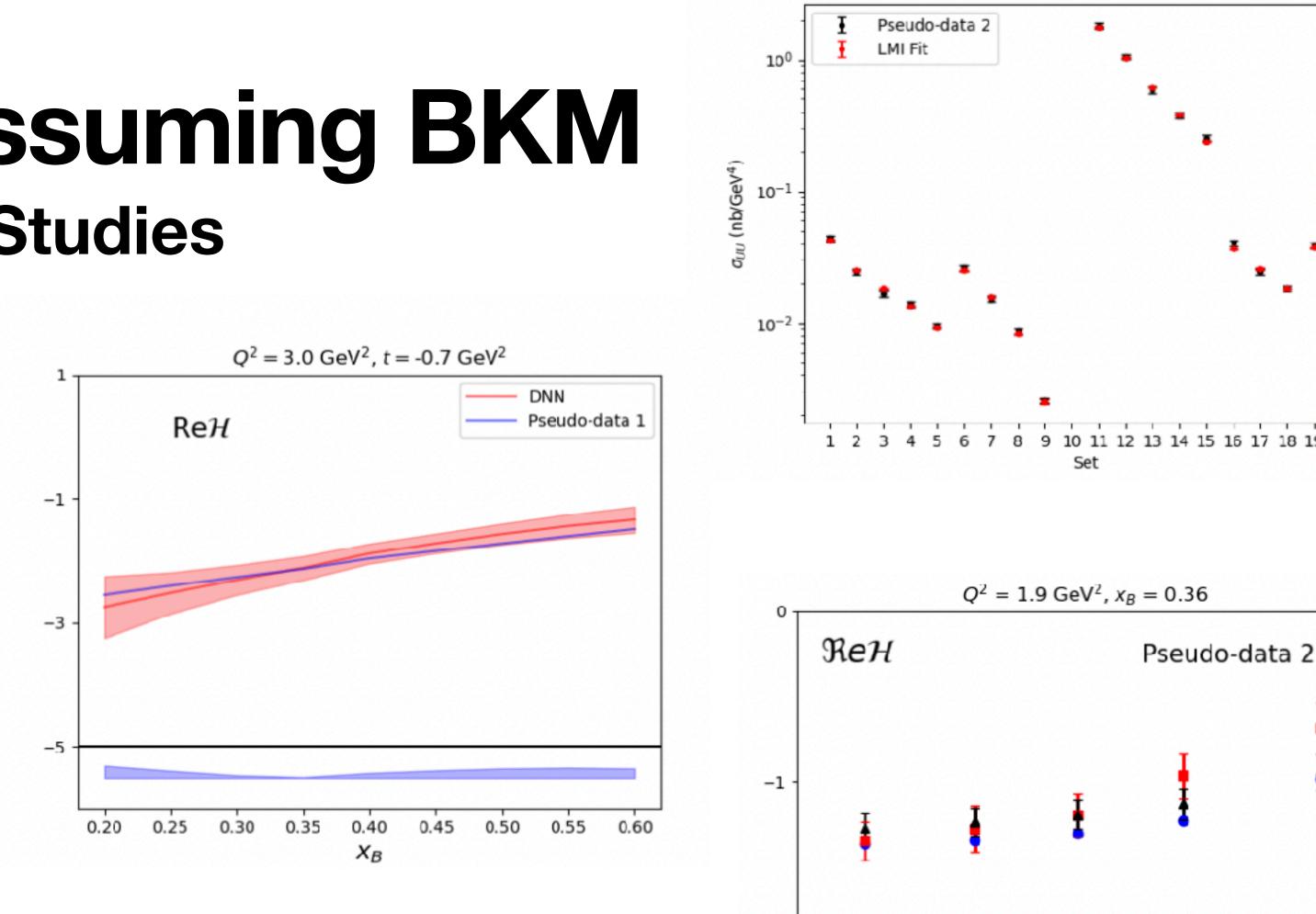
• Still lots of improvement to go

Ridiculously low quality data after decades of experiments

I. Fernando

### **CFF Extraction Assuming BKM** Pains taking Pseudodata Studies

- Still Assume formalism
- Very good local fits
- Improved global extraction



-2

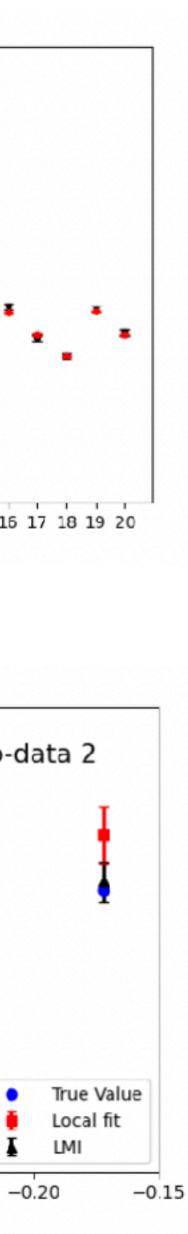
-0.35

-0.30

-0.25

-t (GeV<sup>2</sup>)

But doing local fitting in this traditional way doesn't really make sense!!



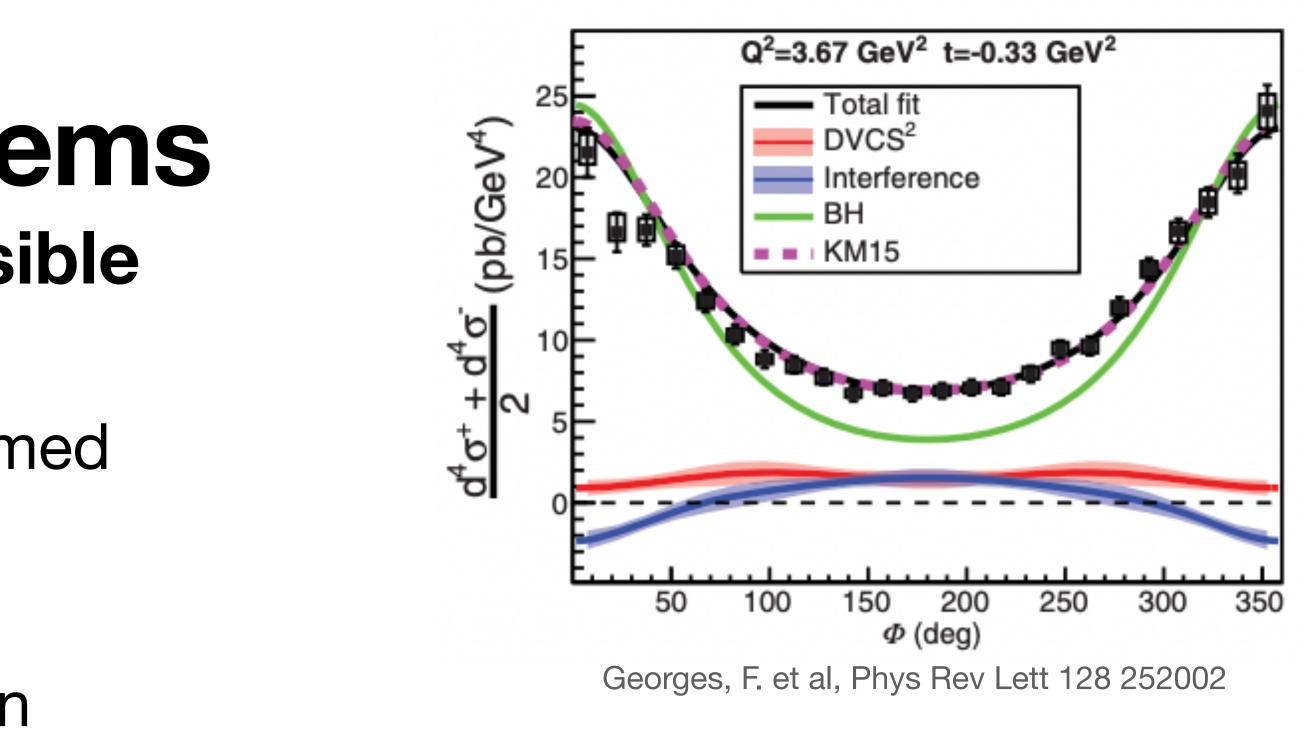
## **Basic ANN Extraction** Local Fit

- The experimental data is use to generate MC replica data
- Have collection of data with know f with unknown set of parameters
- Pass data and dependent variables through the network according to weights and activation function (first iteration weights are random values)
- The output is the first approximation of the desired parameters
- Use these output parameters to calculated *f*. The results are used in the loss function which is use to modify the network and adjusts weights so the error is decreasing

f(x, y, z, a, b, c)

## Long Standing Problems Data should be globally accessible

- Once experiment analysis is performed
  - Stuck with kinematic bins
  - Little to no covariance information
  - Systematic errors inadequately
  - Raw data is lost
  - No storage for future use/analysis/fitting



Same Issue with Polarized Target Data too!!



# **Storage Candidates**

- Compressed root file (Struct format)
- Compressed numpy arrays ullet
- Hierarchical Data Format (HDF5)
- Reduce types: float16, int8, uint8
- Reduce structure root/npy: few dimensions and elements
- Saved raw but not too raw...
  - Level of information
  - I/O speed
  - Compressibility
  - Able to read publicly with standardized data dictionary

Needed to make data available to the world for training AI for everyone!!

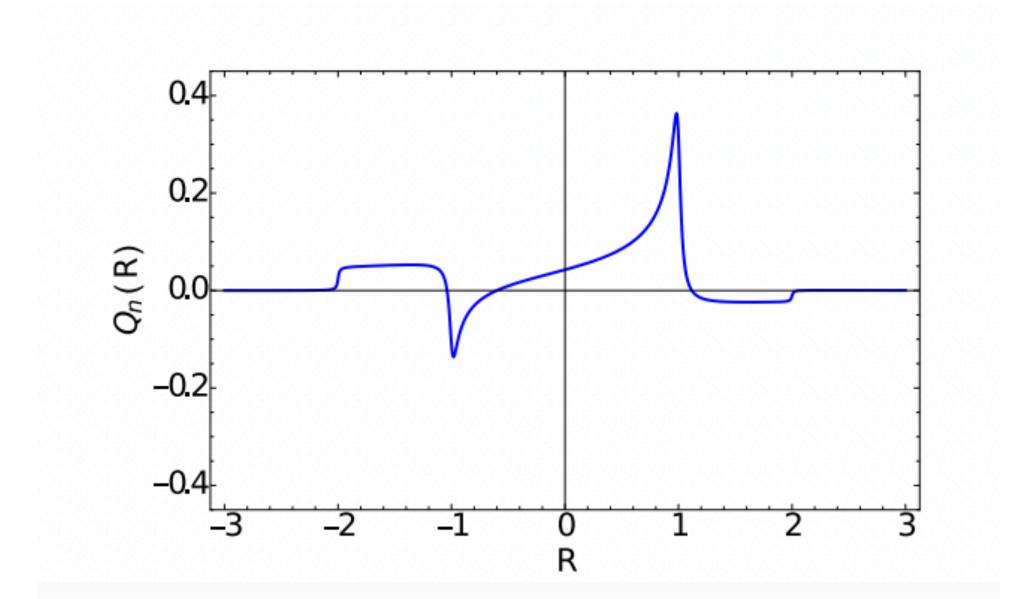
## **New Measurement Approach** How to Measure and What is the Error

- Measure
  - Assume TE and Boltzmann signal studies done well during calibration
  - Use the *3-principles* ss-RF extraction
  - Continue to sweep-measure/sweep-manipulate
- Uncertainty
  - Additional Error from modulating but have tools to improve

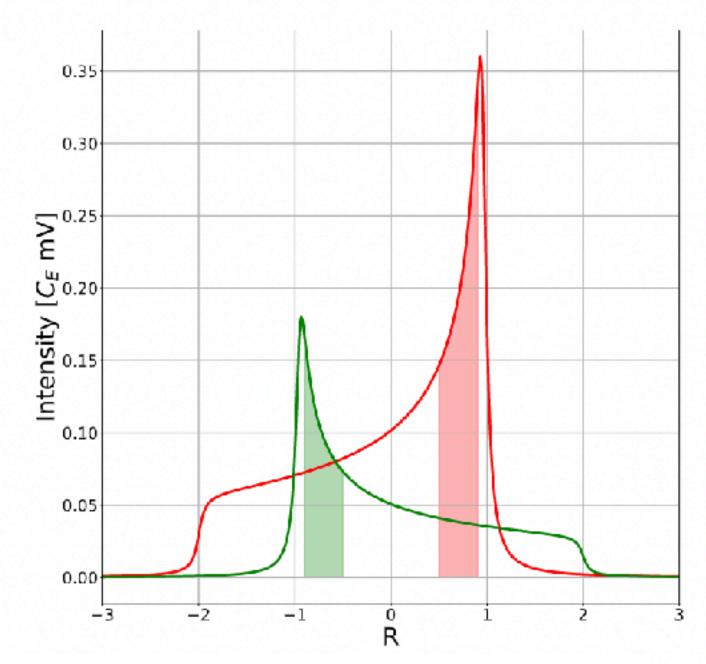
### **The Three Principles** For Enhanced Tensor Polarization that can be measured

- A. Differential Binning
- **B.** Spin Temperature Consistency
- C. Rates Response

https://doi.org/10.1016/j.nima.2020.164504 https://doi.org/10.1016/j.nima.2023.168177

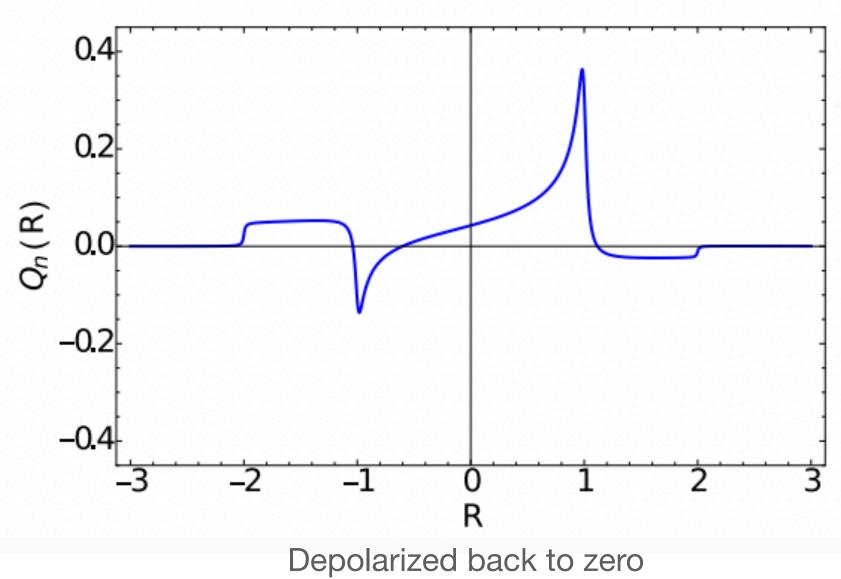


# **Differential Binning**



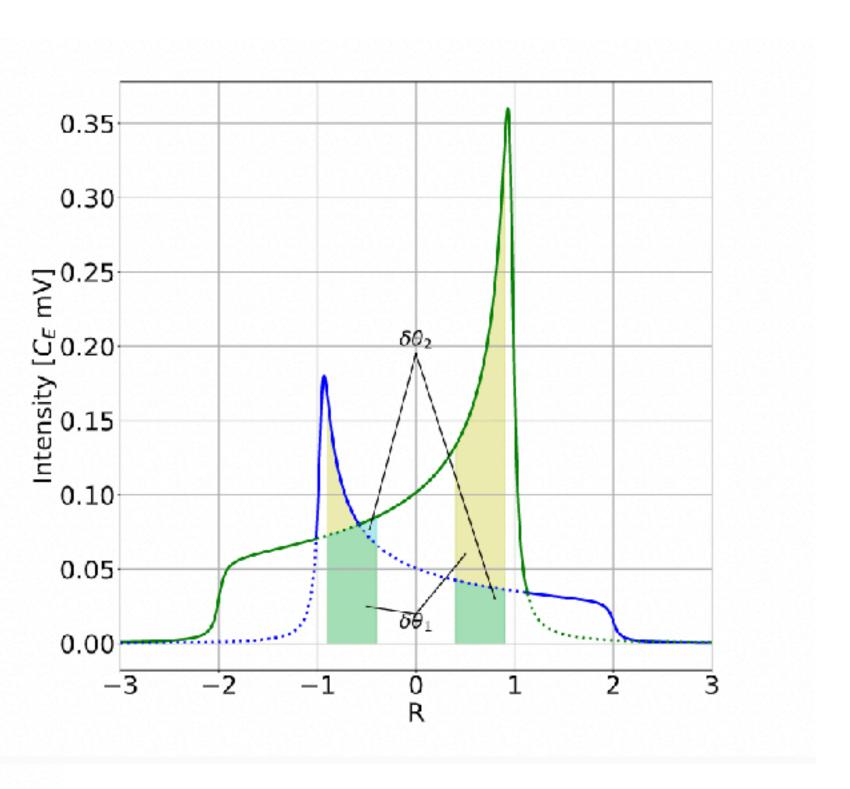
P(R) = $P(\theta) =$ 

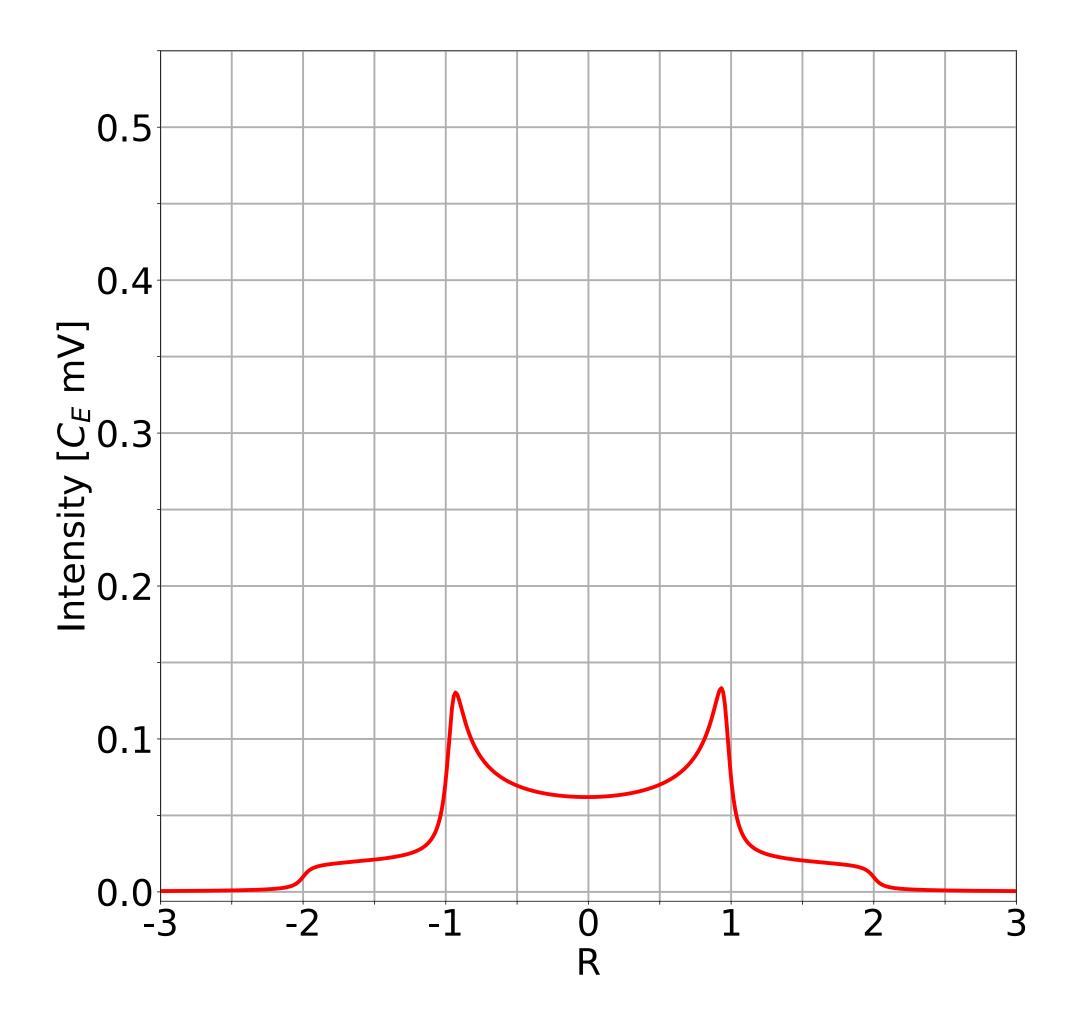


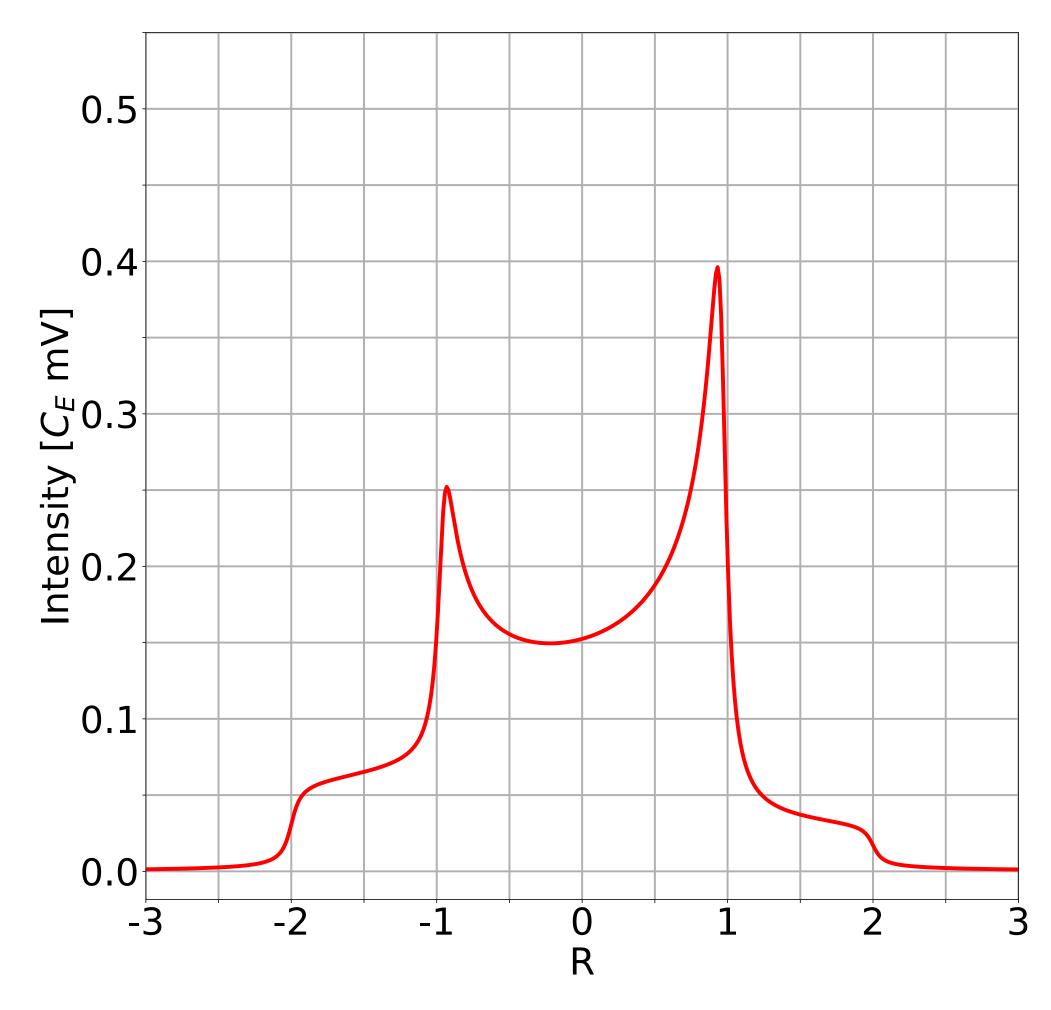


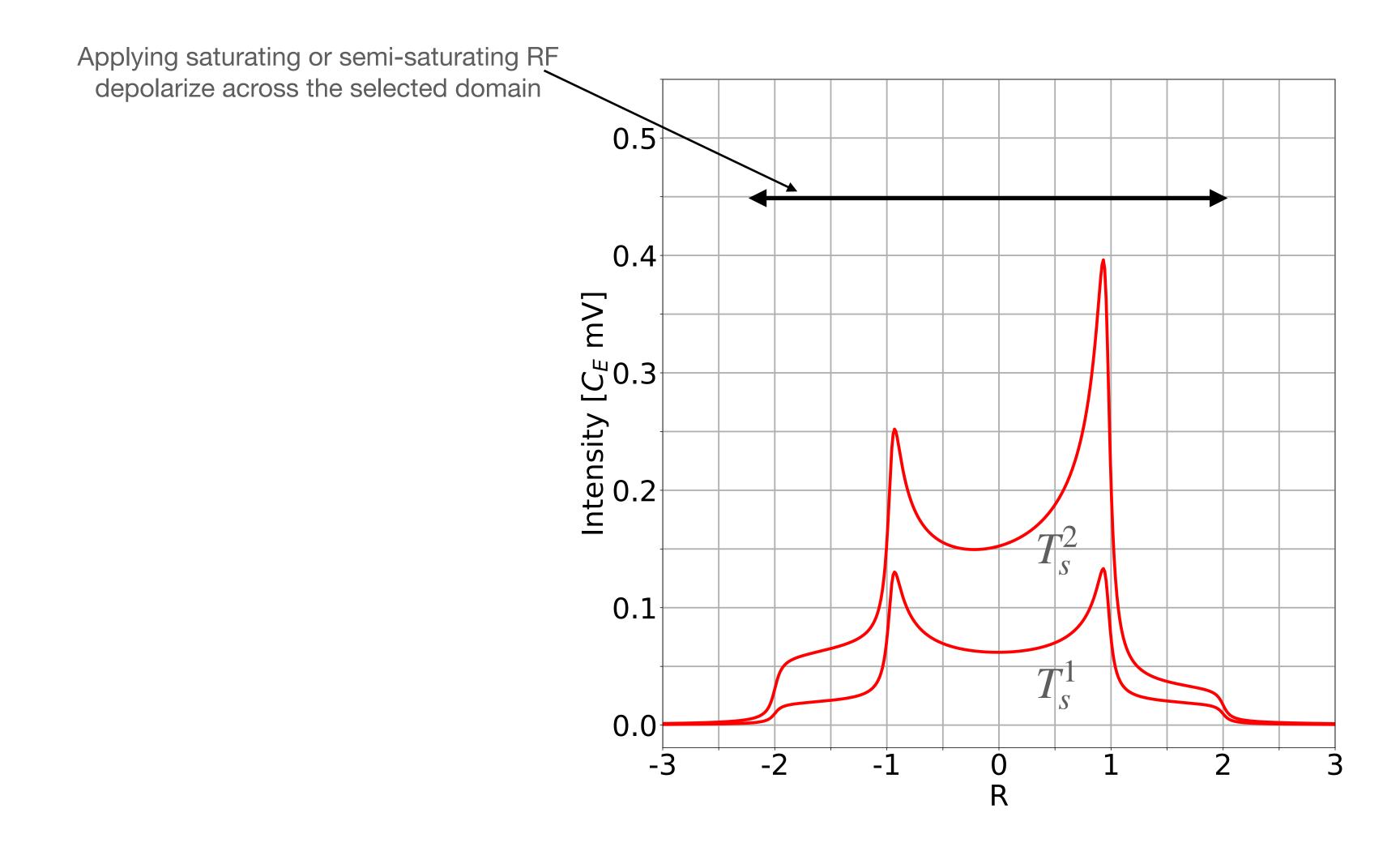
= 
$$C(I_{+}(R) + I_{-}(R))$$
  
=  $C(I_{+}(\theta) + I_{-}(\theta))$ 

$$= C(I_{+}(R) - I_{-}(R))$$



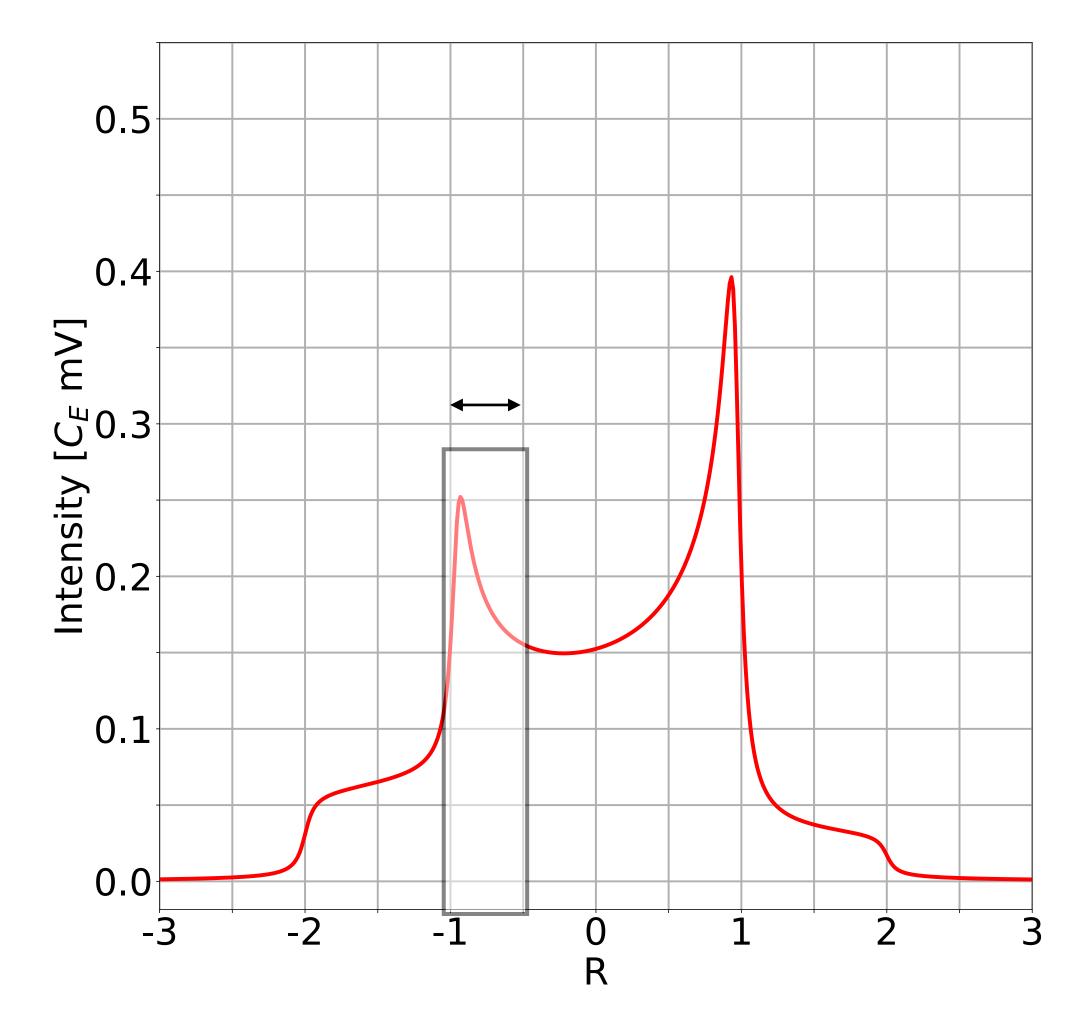


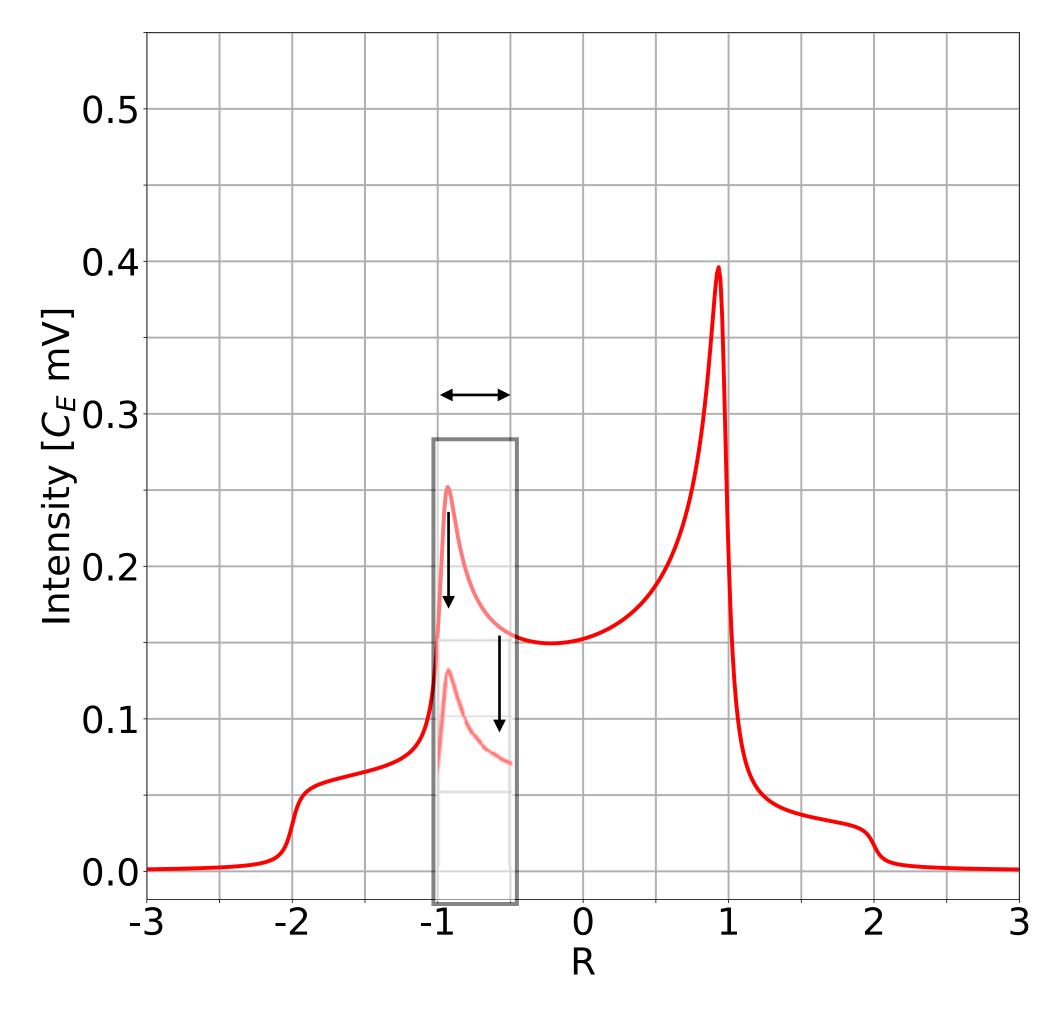


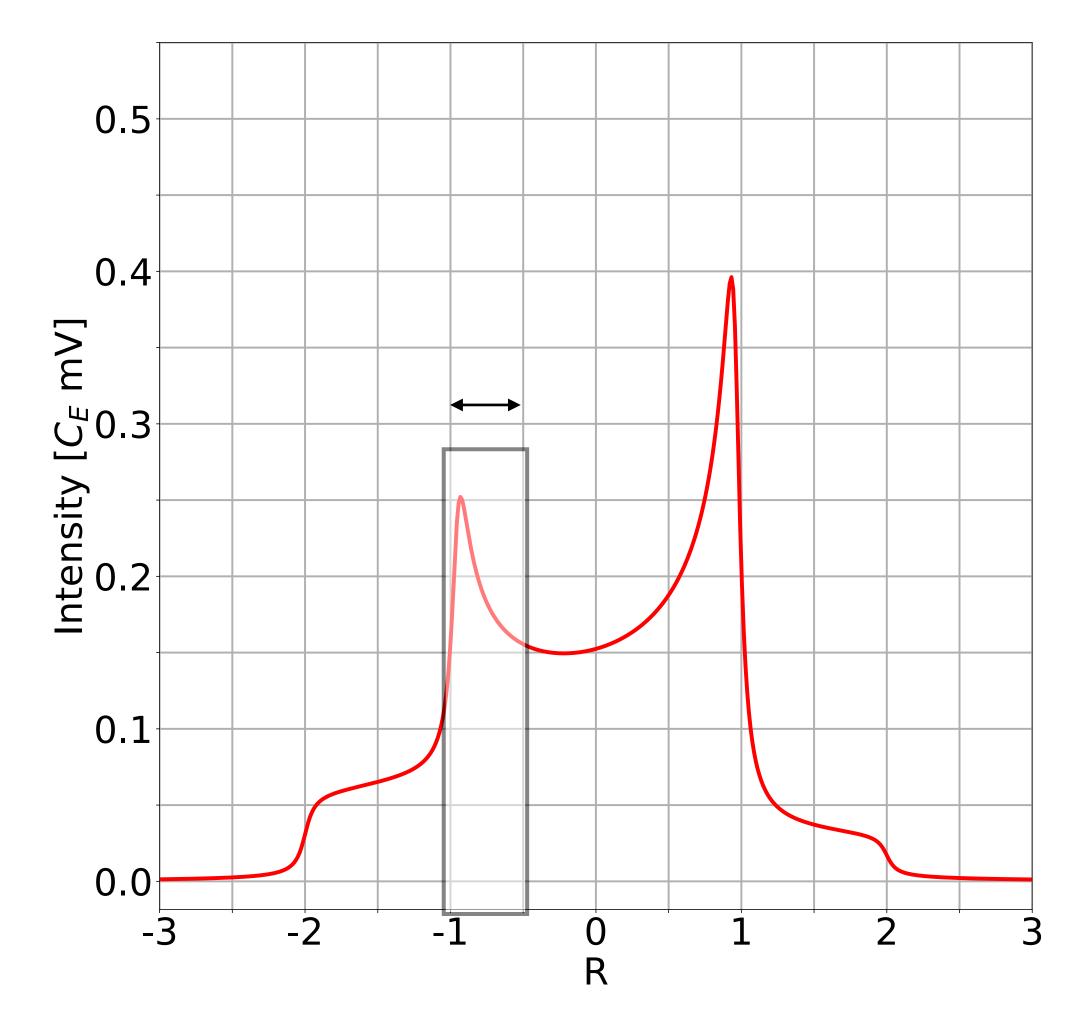


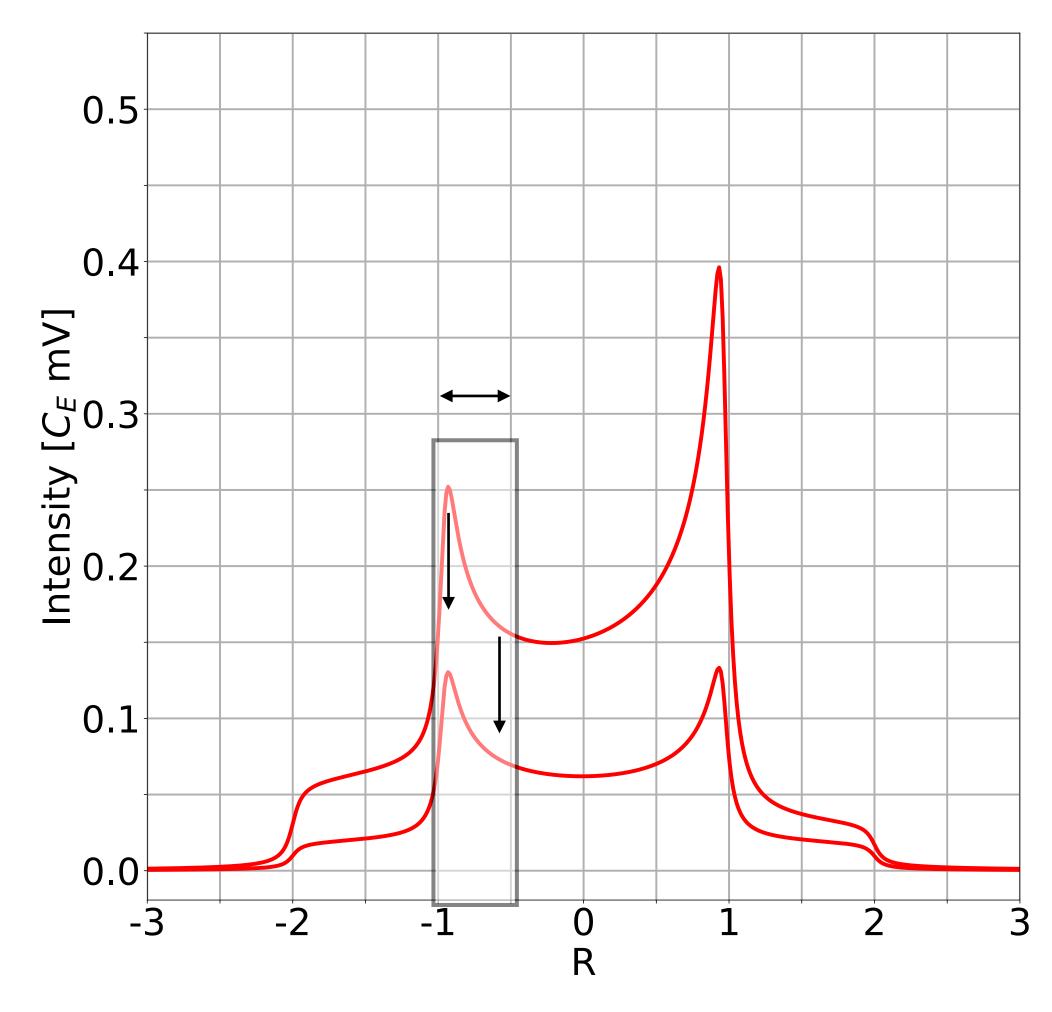
 $\omega_m \gg 2\pi/T_1$ 

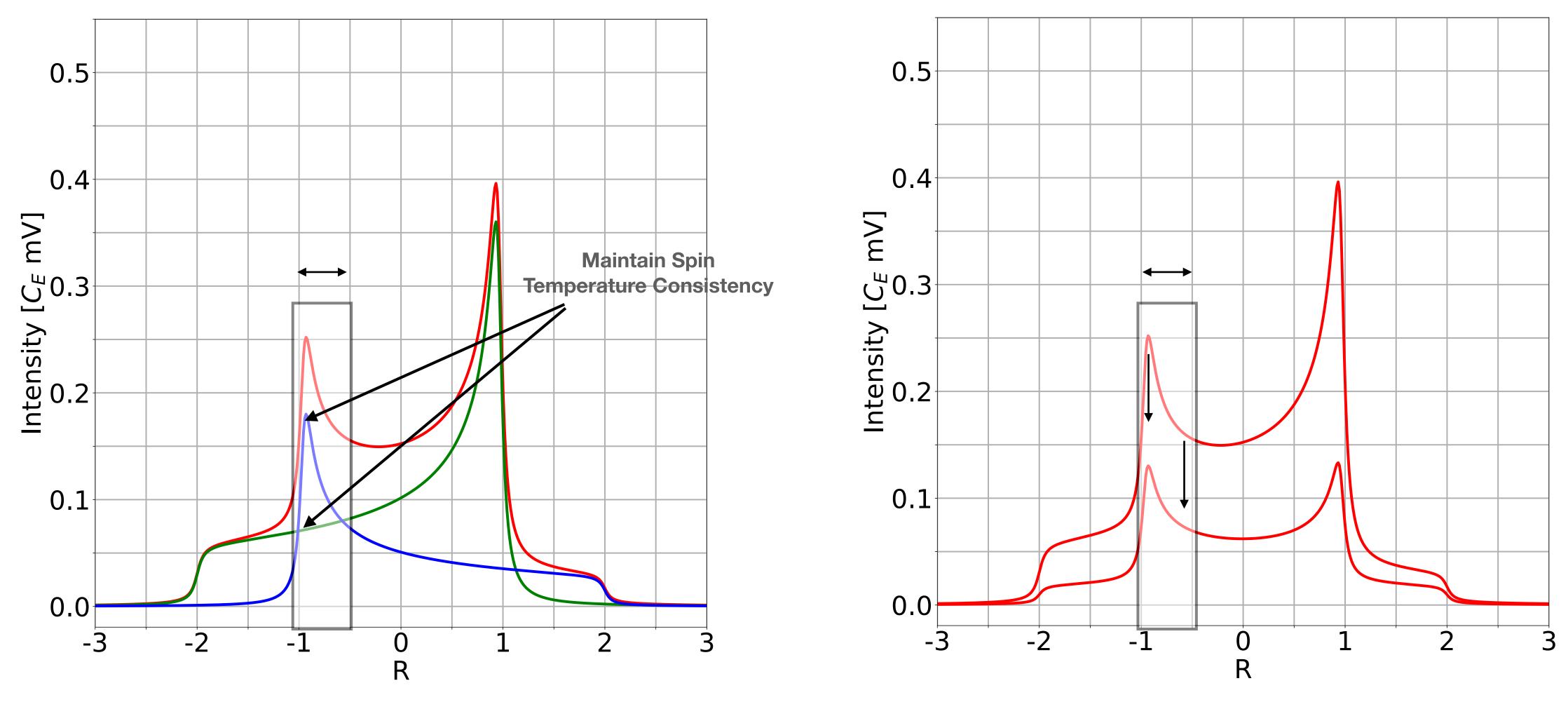
Fast enough that we treat this As the application of a homogeneous field











Principle: If you know the sum you know the difference

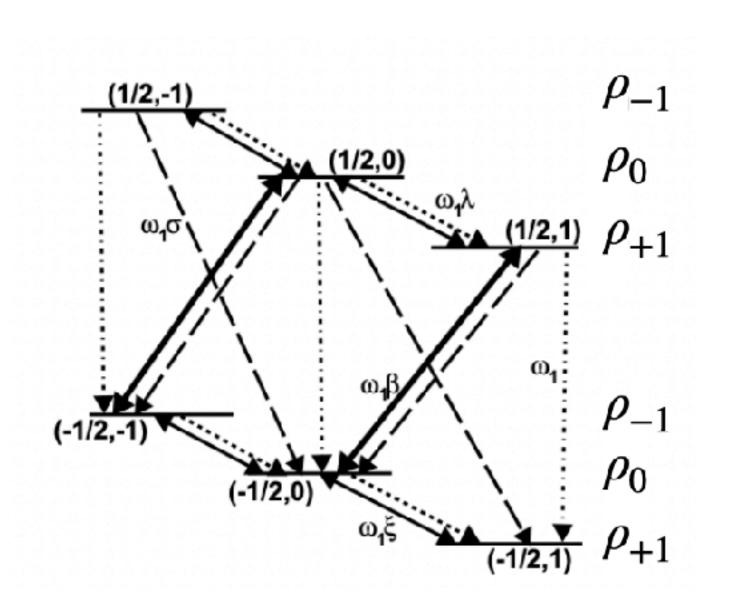
### **Rate Response** Or why you can get rid of models

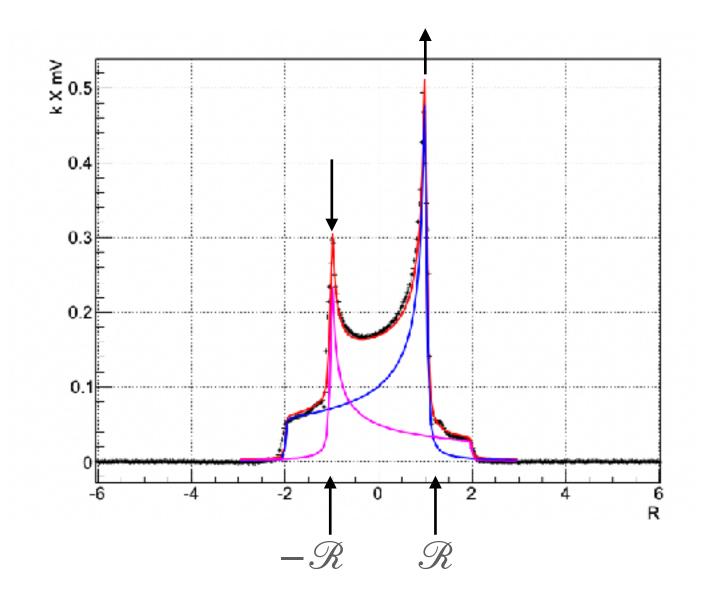
$$\dot{I}_{-}(-\mathcal{R}) = -\frac{1}{2}\dot{I}_{+}(\mathcal{R}) \qquad \qquad \dot{I}_{+}(-\mathcal{R}) = -\frac{1}{2}\dot{I}_{-}(\mathcal{R})$$

$$A_{gained} = \frac{1}{2} A_{lost}$$

https://doi.org/10.1016/j.nima.2023.168177

 $\widehat{\mathcal{R}}) = -2C\xi\rho_+$  $\widehat{\mathcal{R}}) = C\xi\rho_+$ 





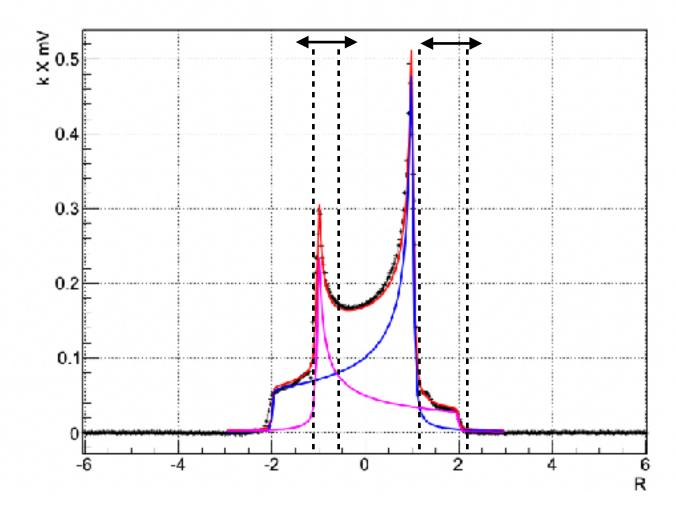
## **Putting These Conditions Together Simple Measuring Tools**

Boltzmann

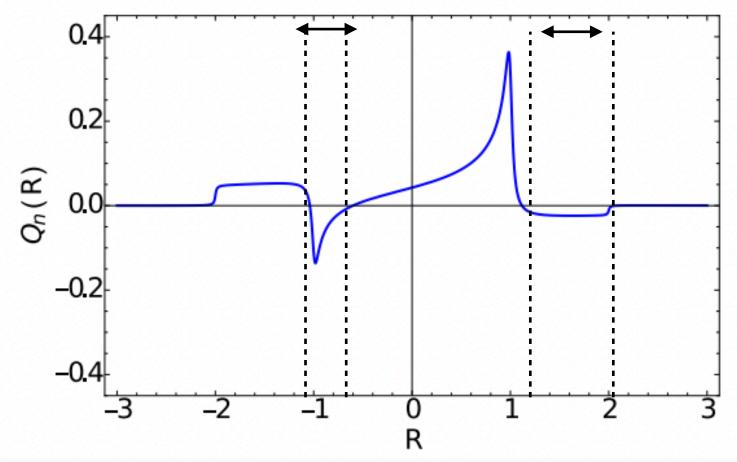
• Apply 
$$A_{gained} = \frac{1}{2} A_{lost}$$

- Configure for any vector polarization and the particular RF region
- You're Done!!

Universally True Any lineshape Any material



• The difference (Q) in intensities can by easily calculated using area dependent



### Caveats What is exact and what is approximation

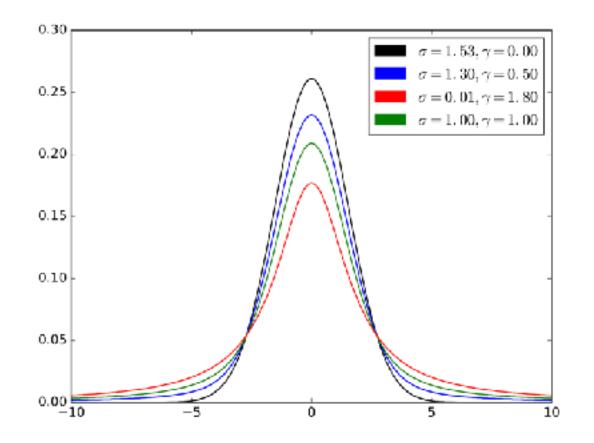
- Everything just laid out is exact for any polarization mechanism, any line shape, and any material and so **not model dependent**
- pathways and not transverse (spin-spin, like spin diffusion)
  - hole using a Voigt (convolution of Gaussian and Lorentzian)

• Everything just laid out is in reference to longitudinal (spin-lattice) relaxation

To take into account the transverse relaxation pathways one needs to fit the

• These fits are sensitive to Q-factor of coil, degree of tuning and matching of RF circuit, amplification parameters, and transverse relaxation of material

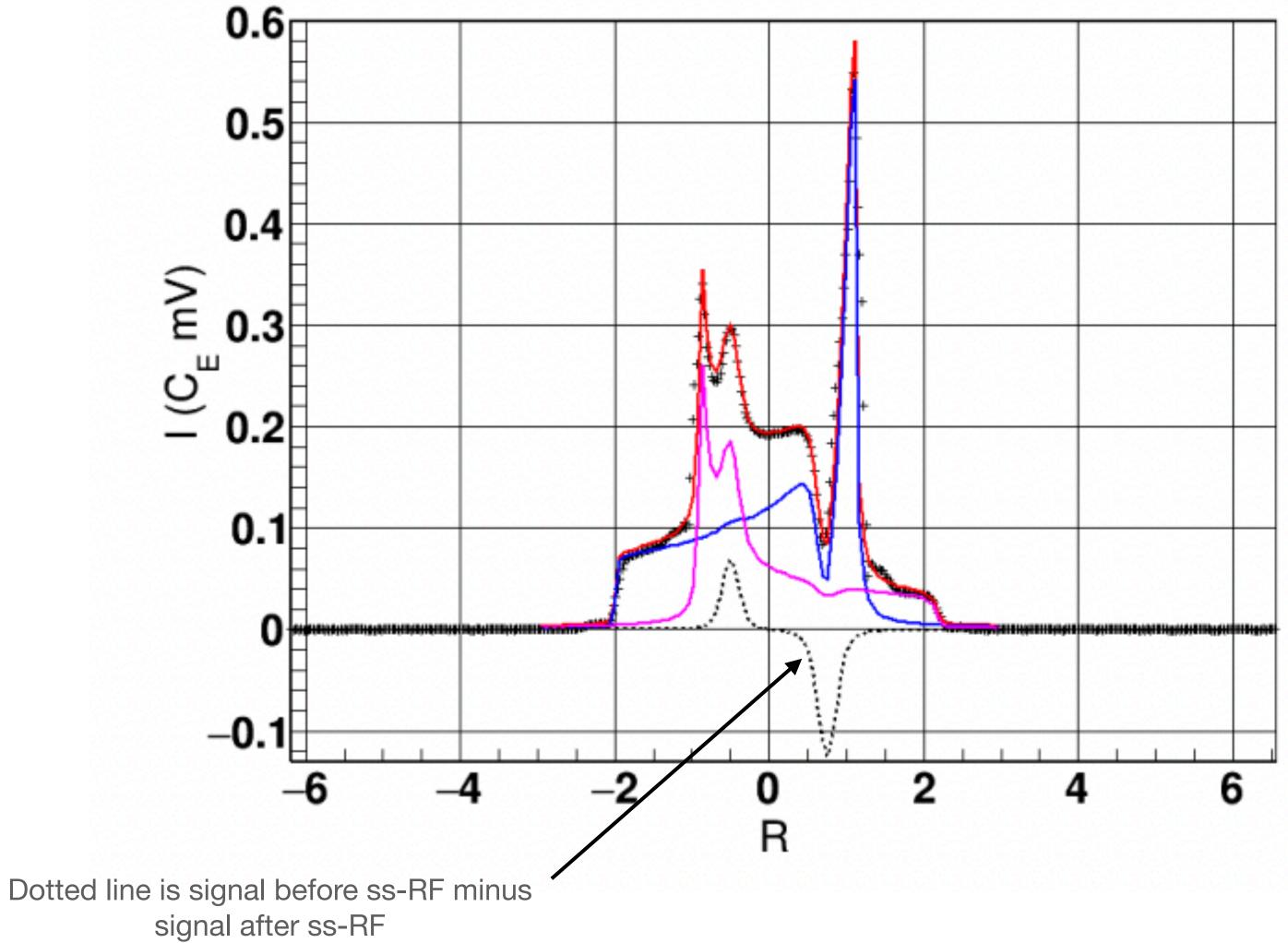
### **Addressing Transverse Pathways Voigt Profile**



$$V(x;\sigma,\gamma)\equiv\int_{-\infty}^{\infty}G(x';\sigma)L(x-x';\gamma)\,dx'$$

$$G(x;\sigma)\equiv rac{e^{-x^2/(2\sigma^2)}}{\sigma\sqrt{2\pi}}$$

$$L(x;\gamma)\equiv rac{\gamma}{\pi(x^2+\gamma^2)}$$



# **Practical Aspects of Doing This with NMR** ss-RF Q-meter based prototype

- Set the single sweep
- RF switch to turn off Q-meter and run ss-RF
- Then run and change ss-RF power/duration
  - But measurements and response must be fast or errors will overwhelm

- Possible without a new style of NMR
  - Yes!!

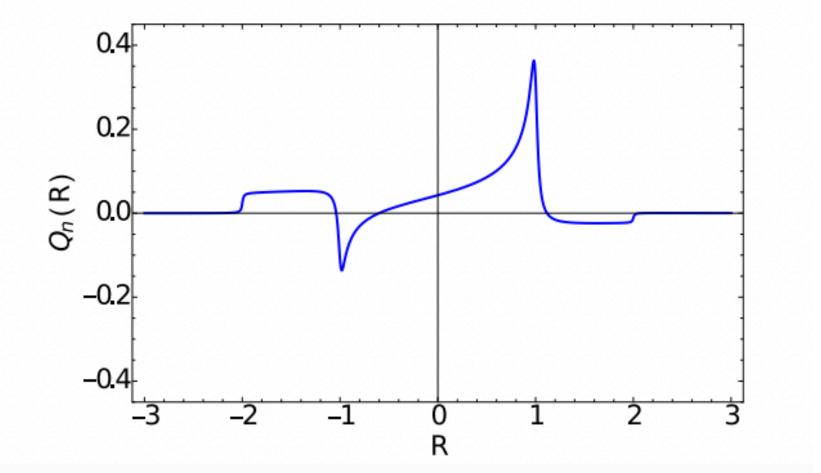
### **General Idea For ss-RF NMR**

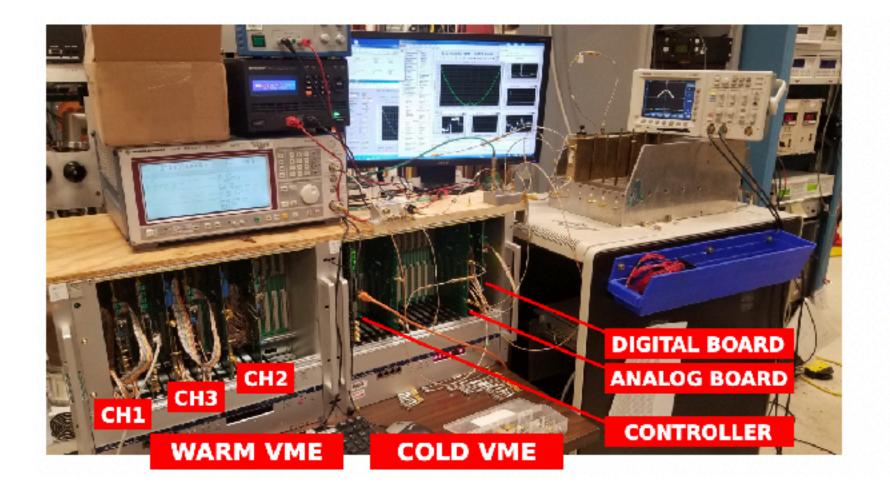
**Design Needed** 

1068 107.2 107.0 Frequency (M Hz)

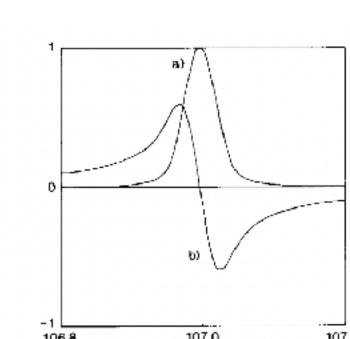
- Absorption/Dispersion
- Fast Phase Sampling
- ss-RF power profile
- Separation of RF range

- A. Measure A/D 1000 phases
- B. Al inference (streaming covariance)
- C. ss-RF Enhance Q per sweep





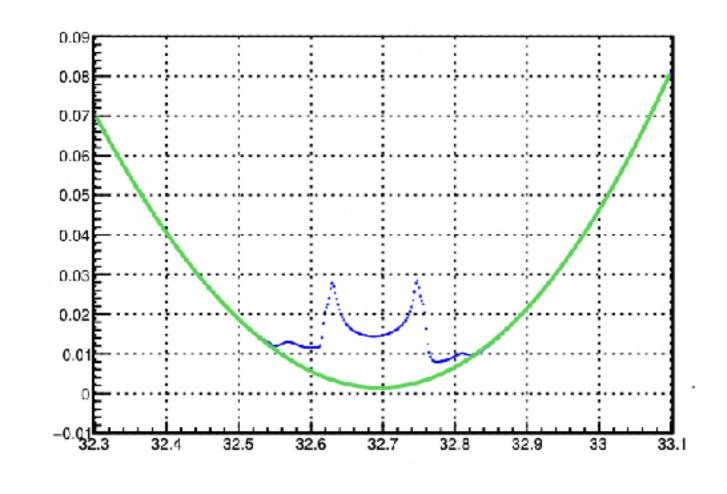
- D. goto A.



Standard Error in Experiments: 4% Theoretical Limit: 0.8%

**Original Liverpool design** 

- Phase Sensitive detector
- **Constant Current**
- Non-destructive (low amplitude)
- Full spectral range

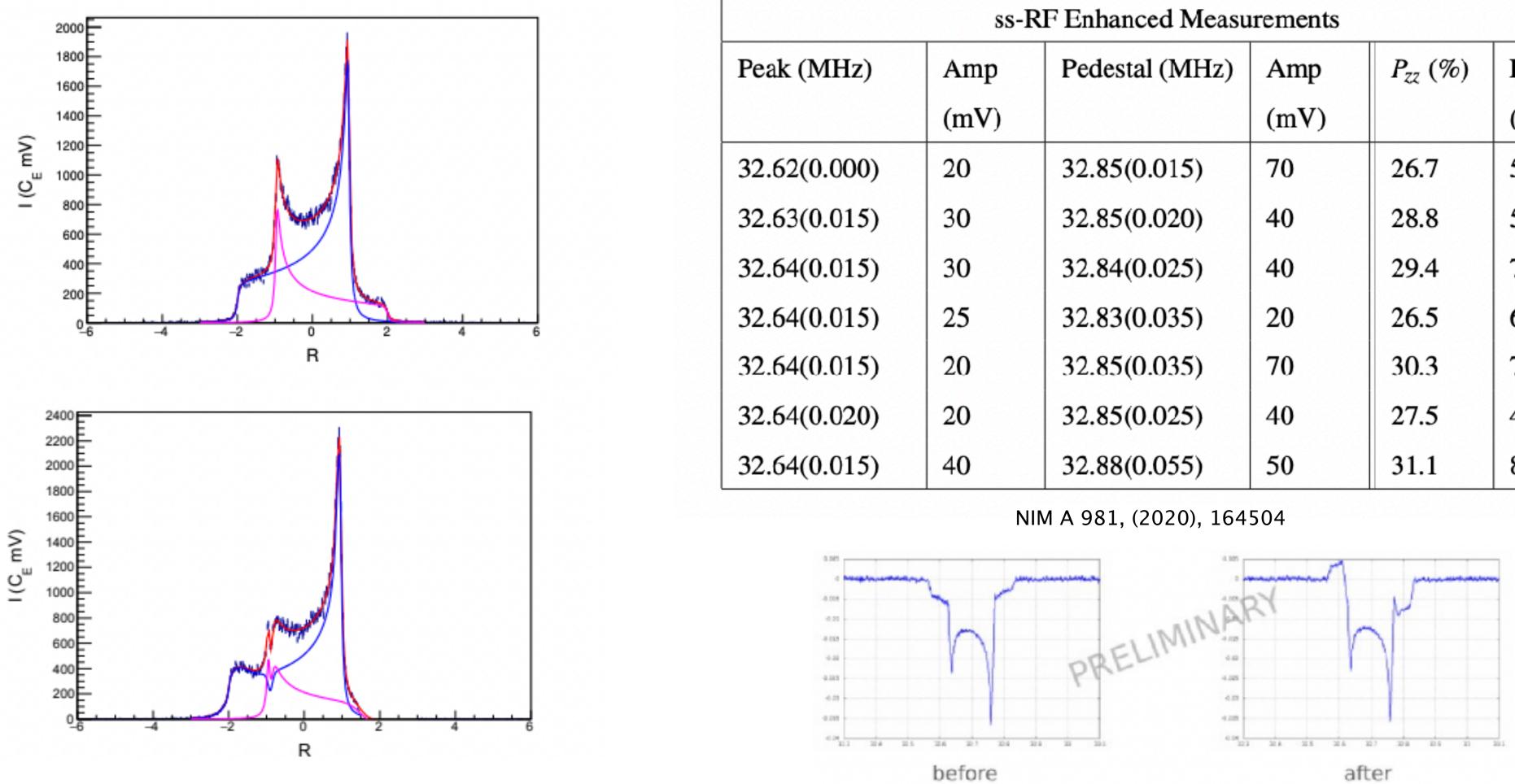




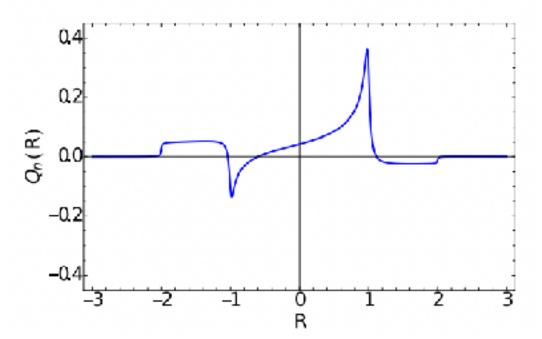
# Status of New ss-RF based NMR As of now

- Initial prototype used in cooldowns (large errors and no AI)
- Generic first round LabView based software/simulation
- New AI-GPU based extraction (Devin Seay)
- High-level design complete
- Applied for NSF funds to build
- Acquired funding
- Acquired hardware
- Constructed
- Commissioned

## **Measurements of Tensor Enhancement Experimental results (all with irradiated d-Butanol)**

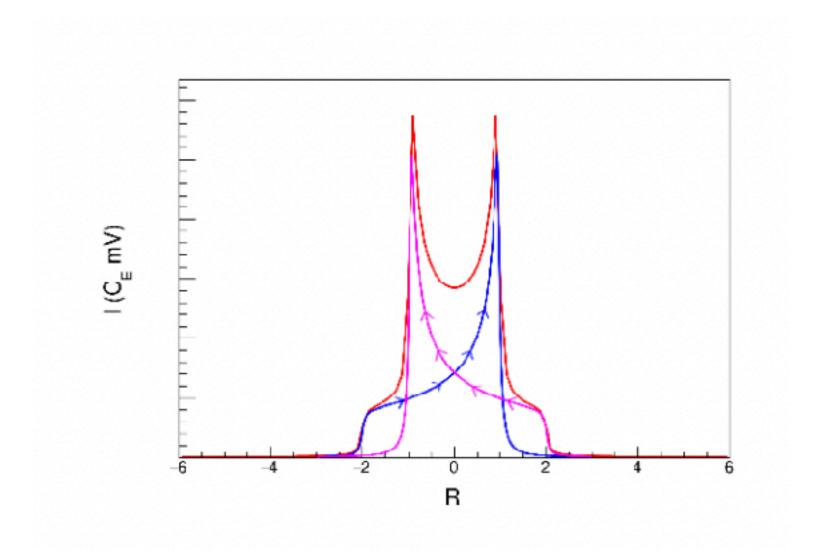


ss-RF Enhanced Measurements										
	Amp	Pedestal (MHz)	Amp	P <sub>zz</sub> (%)	Error					
	(mV)		(mV)		(%)					
	20	32.85(0.015)	70	26.7	5.4					
	30	32.85(0.020)	40	28.8	5.7					
	30	32.84(0.025)	40	29.4	7.2					
	25	32.83(0.035)	20	26.5	6.8					
	20	32.85(0.035)	70	30.3	7.8					
	20	32.85(0.025)	40	27.5	4.7					
	40	32.88(0.055)	50	31.1	8.5					

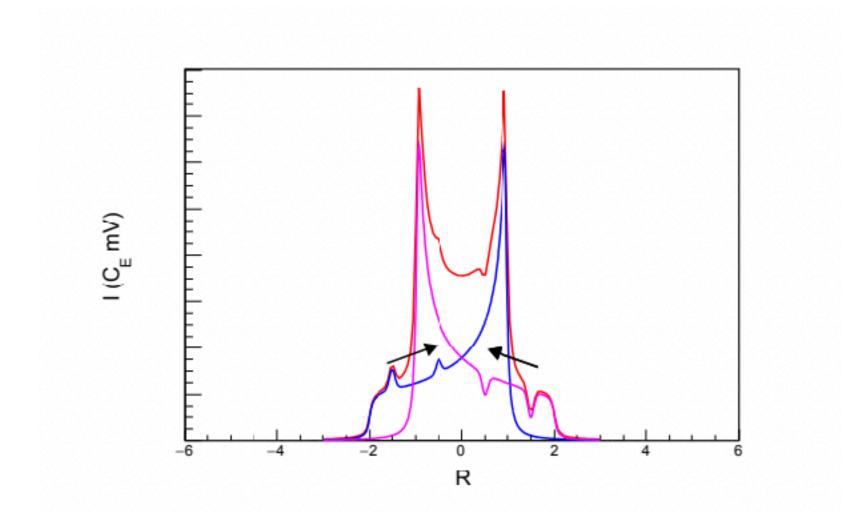


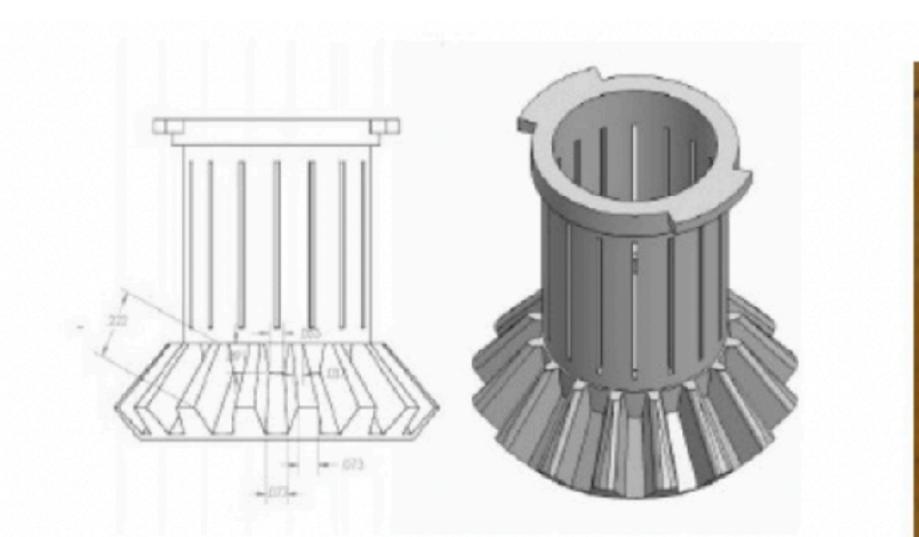
# **Rotating Targets (work still in progress)** And results (slow rotation)

- Rotate to TRY to burn one entire absorption line

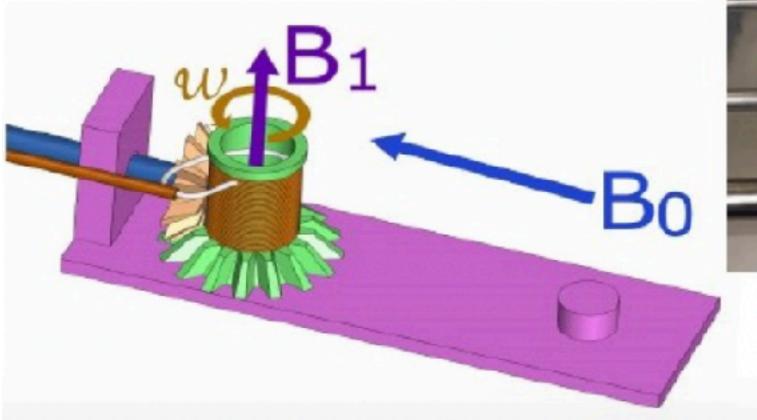


Spin Diffusion fights repopulates with rotation but changes for every angle





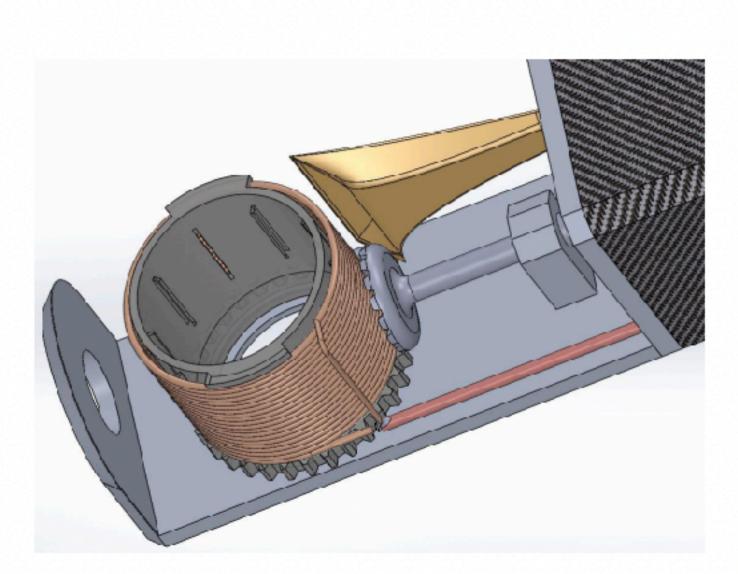
- Kel-F (C<sub>2</sub>ClF<sub>3</sub>)<sub>n</sub> cup and driving gear
- Motor outside cryostat
- NMR coil around cup
- Already used with several designs at UVA
- 1 Hz achieved with no problem
- Fixed beam spot



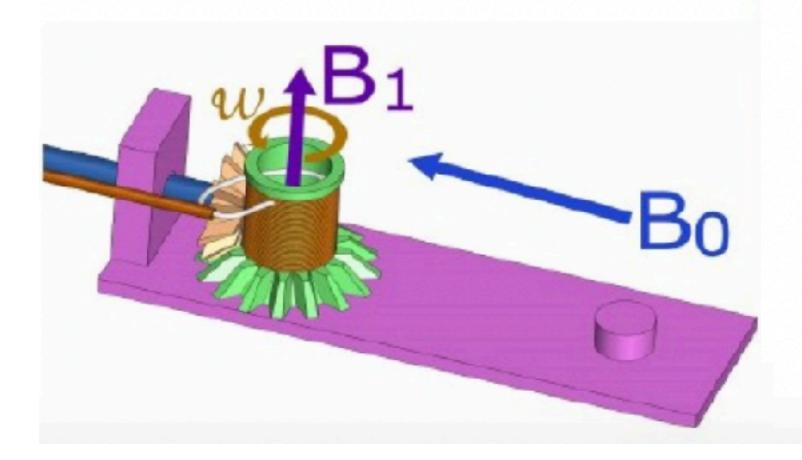


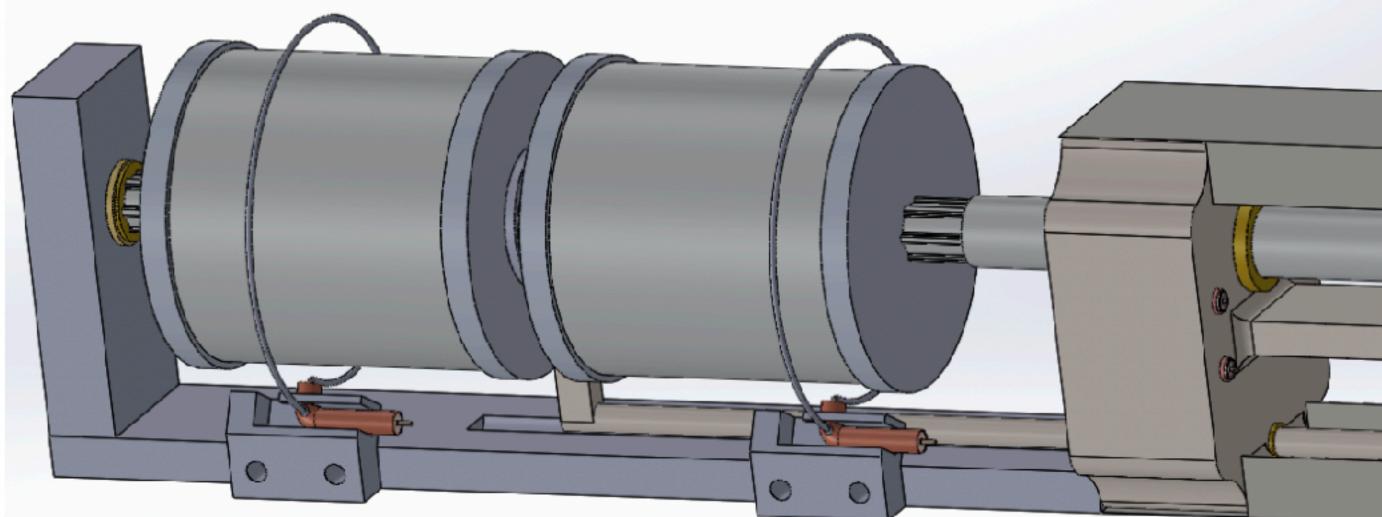






- Motor outside cryostat
- NMR coil around cup
- Already used with several designs at UVA
- 1 Hz achieved with no problem
- Fixed beam spot

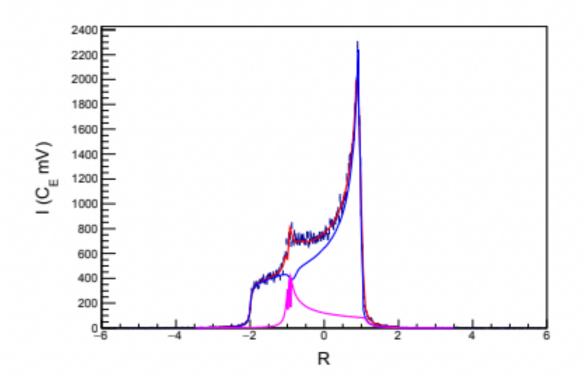








### **Rotation Results** 10% relative uncertainty is the best we can do with rotation (no AI)



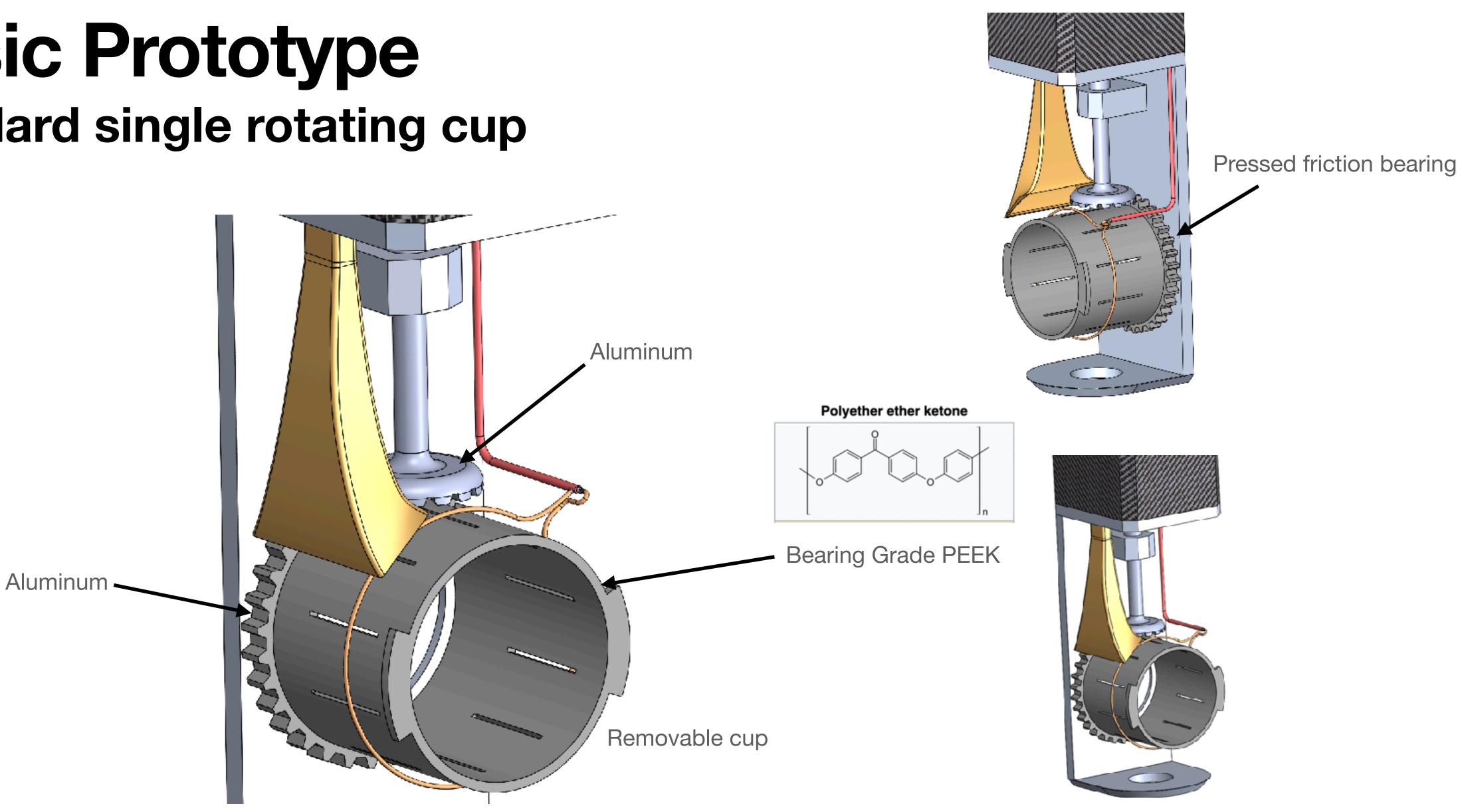
At <40° with respects to B

Rotation rate rss-RF Enhanced Measurements						
$\Omega^{-1}$	Peak (MHz)	Amp	Pedestal (MHz)	Amp	P <sub>zz</sub> (%)	Error
		(mV)		(mV)		(%)
50	32.65(0.010)	15	32.85(0.015)	45	35.7	8.4
44	32.66(0.000)	10	32.88(0.015)	40	36.5	9.7
40	32.65(0.000)	15	32.88(0.015)	40	36.3	9.3

NIM A 981, (2020), 164504

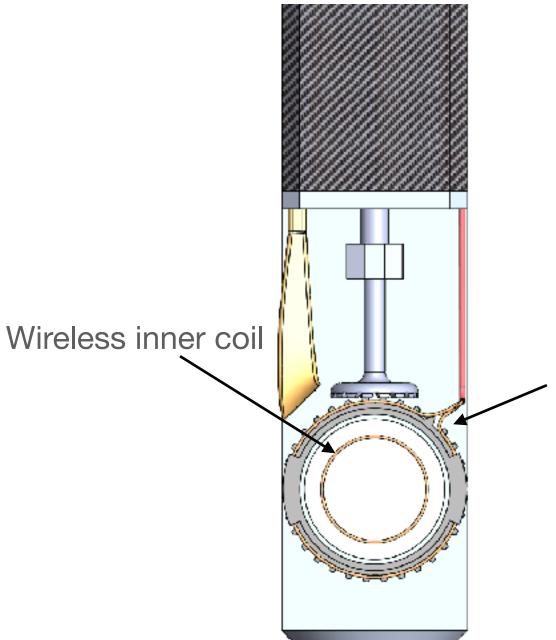


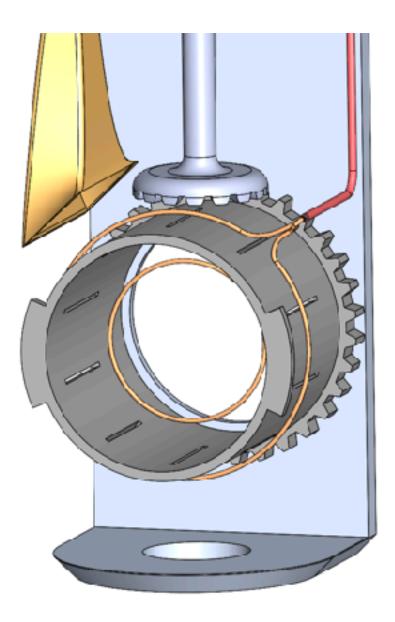
### **Basic Prototype** Standard single rotating cup



# Wireless NMR coil for improved signal **Critical for Target Calibrations**

- Poor signal to noise during **TE diminishes FOM**
- Inner coil inductively coupled to the static coil
  - Matched
  - Tuned
  - Balanced geometry





# **General Outlook**

- First Generation
  - b1 structure function (Hall C)
  - Azz + T20 (Hall C)
  - DY Transversity (FNAL)
- Second Generation (beyond 3 years)
  - $f_{1LL}$  in SIDIS (Hall A)
  - Tensor polarized DVCS (Hall C)
  - SIDIS Transversity (Hall A)
  - Photon Tensor polarized observables (Hall D)

# Thank You

# **Backup stuff**

### **Al in Polarization Measurements Continuous Wave NMR**

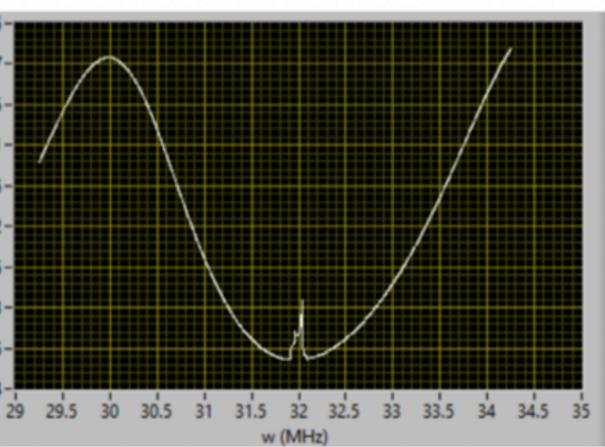
**Deuteron lineshape** 

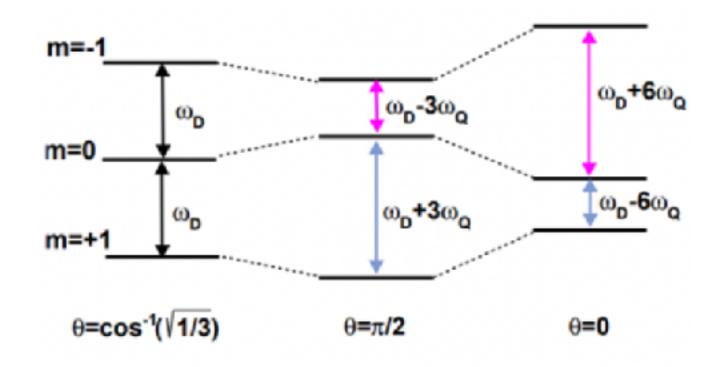
$$\mathscr{F} = \frac{1}{2\pi\mathscr{X}} \left[ 2\cos(\alpha/2) \left( \arctan\left(\frac{\mathscr{Y}^2 - \mathscr{X}^2}{2\mathscr{Y}\mathscr{X}\sin(\alpha/2)}\right) + \frac{\pi}{2} \right) + \sin(\alpha/2) \ln\left(\frac{\mathscr{Y}^2 + \mathscr{X}^2 + 2\mathscr{Y}\mathscr{X}\cos(\alpha/2)}{\mathscr{Y}^2 + \mathscr{X}^2 - 2\mathscr{Y}\mathscr{X}\cos(\alpha/2)} \right) \right],$$
  
$$\mathscr{X}^2 = \sqrt{\Gamma^2 + (1 - \varepsilon R - \eta \cos 2\phi)^2} \quad \mathscr{Y} = \sqrt{3 - \eta \cos 2\phi}$$
  
$$\cos \alpha = (1 - \varepsilon \dot{R} - \eta \cos 2\phi)/\mathscr{X}^2 \quad \Gamma \sim 0.05 \quad \eta \cos 2\phi \sim 0.04$$

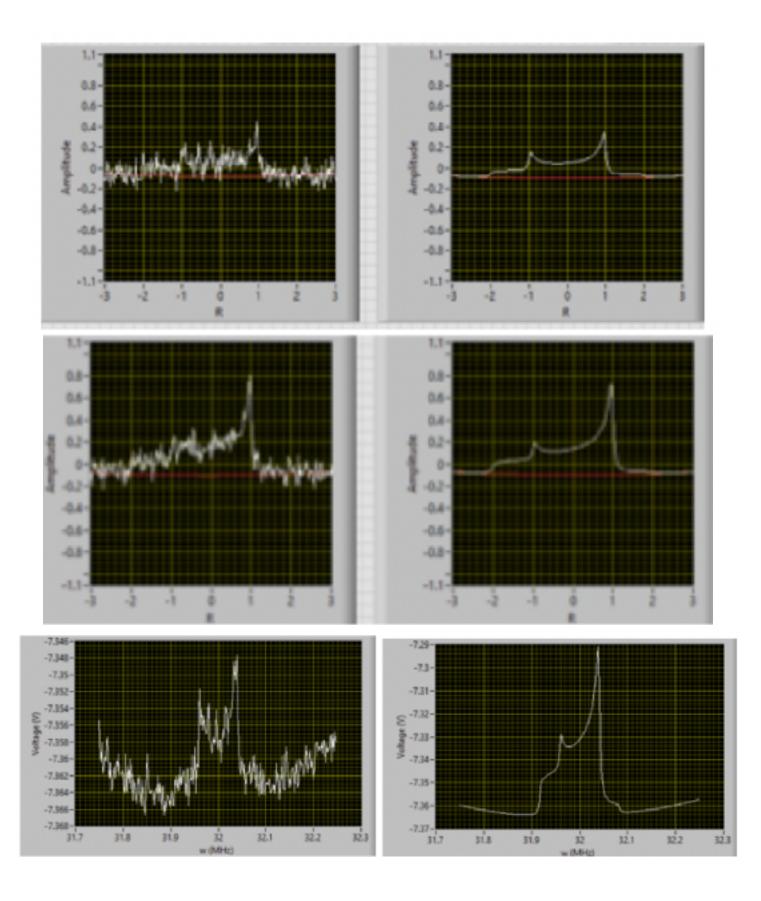
$$\mathscr{X}^2 = \sqrt{\Gamma^2 + (1 - \varepsilon R - \eta \cos 2\phi)^2}$$

$$\cos \alpha = (1 - \varepsilon R - \eta \cos 2\phi)/\mathscr{X}^2 \Gamma \sim$$
  
Q-Curve

-7.29--6.95 -7--7.3--7.05--7.31--7.1 € <sup>-7.32</sup> Coltage () \$ -7.34 -7.25--7.35--7.3--7.36--7.35--7.37--7.4-31.9 31.7 31.8 32.2 32.1 32.3 32 w (MHz)



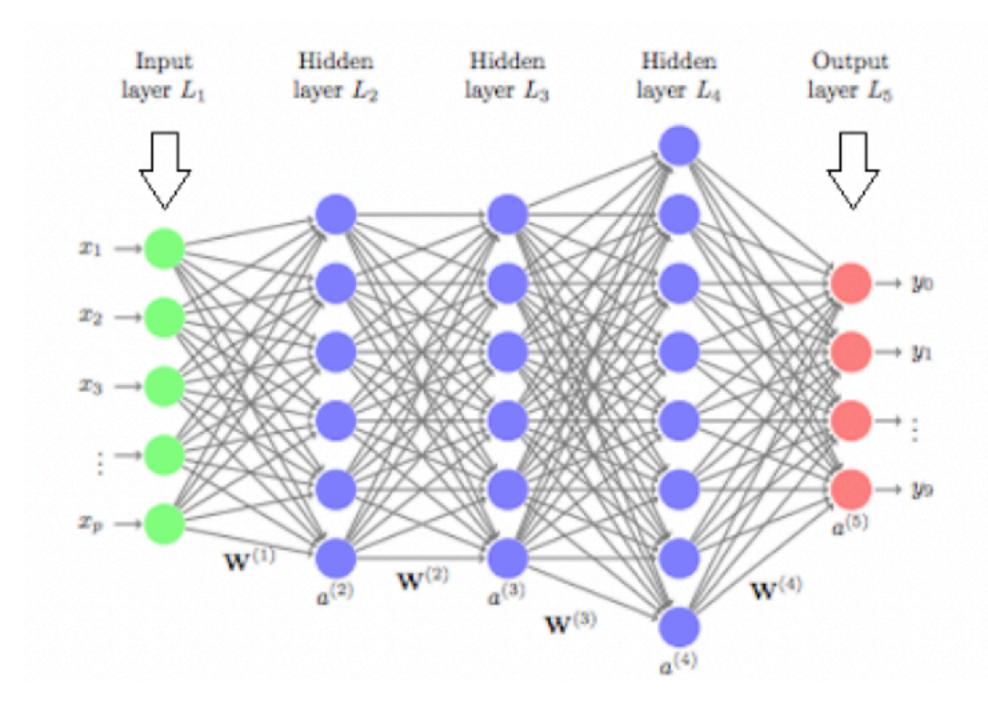




**Devin Seay** 

# **Building a ANN** Simplified

- Determine type of problem
- Prepare (engineer training) data
- Configure ANN (architecture, activation, loss, optimizer, learning rate, batch size)
- Train ANN
- Improve performance (tune hyperparameters)
- Test, study, probe limitations,... •



### Rate Response Or why you can get rid of models

$$I_{-}(-\mathcal{R}) = C(\rho_{0} - \rho_{-}) \qquad I_{+}(-\mathcal{R}) = C(\rho_{+} - \rho_{0})$$

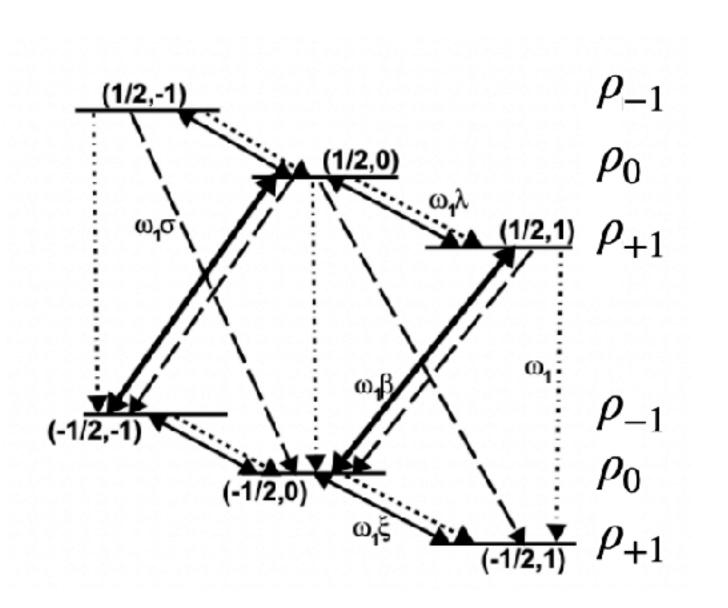
$$I_{-}(-\mathcal{R}) - \dot{I}_{-}(-\mathcal{R}) \qquad I_{+}(-\mathcal{R}) - \dot{I}_{0}(-\mathcal{R})$$

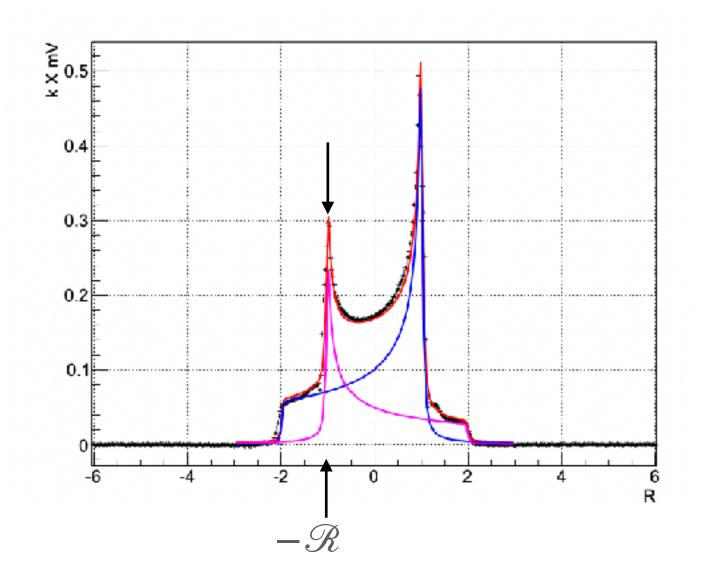
$$= C[(\rho_{0} - \xi\rho_{0}) - (\rho_{-} + \xi\rho_{0})] \qquad = C[(\rho_{+} - \xi\rho_{+}) - (\rho_{0} + \xi\rho_{+})]$$

$$= C[(\rho_{0} - \rho_{-}) - 2\xi\rho_{0}] \qquad = C[(\rho_{+} - \rho_{0}) - 2\xi\rho_{+}]$$

$$\dot{I}_{-}(-\mathcal{R}) = -2C\xi\rho_{0} \qquad \dot{I}_{+}(-\mathcal{R}) = -2C\xi\rho_{+}$$

$$A_{gained} = \frac{1}{2} A_{lost}$$





### **Rate Response** Or why you can get rid of models

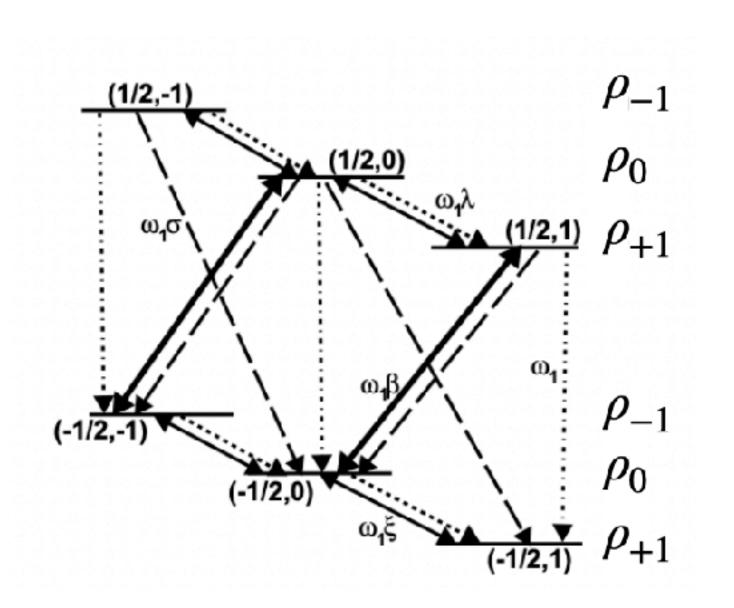
$$I_{-}(-\mathcal{R}) = C(\rho_{0} - \rho_{-}) \qquad I_{+}(-\mathcal{R}) = C(\rho_{+} - \rho_{0})$$

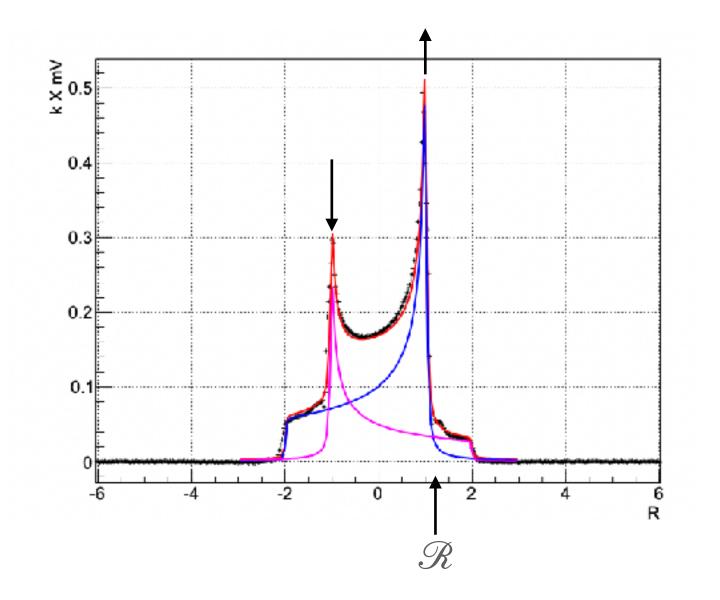
$$I_{+}(\mathcal{R}) + \dot{I}_{+}(\mathcal{R}) \qquad I_{-}(\mathcal{R}) + \dot{I}_{-}(\mathcal{R})$$

$$= C[(\rho_{+}) - (\rho_{0} - \xi\rho_{0})] \qquad = C[(\rho_{0} + \xi\rho_{+}) - (\rho_{-})]$$

$$= C[(\rho_{+} - \rho_{0}) + \xi\rho_{0}] \qquad = C[(\rho_{0} - \rho_{-}) + \xi\rho_{+}]$$

$$\dot{I}_{+}(\mathcal{R}) = C\xi\rho_{0} \qquad \dot{I}_{-}(\mathcal{R}) = C\xi\rho_{+}$$



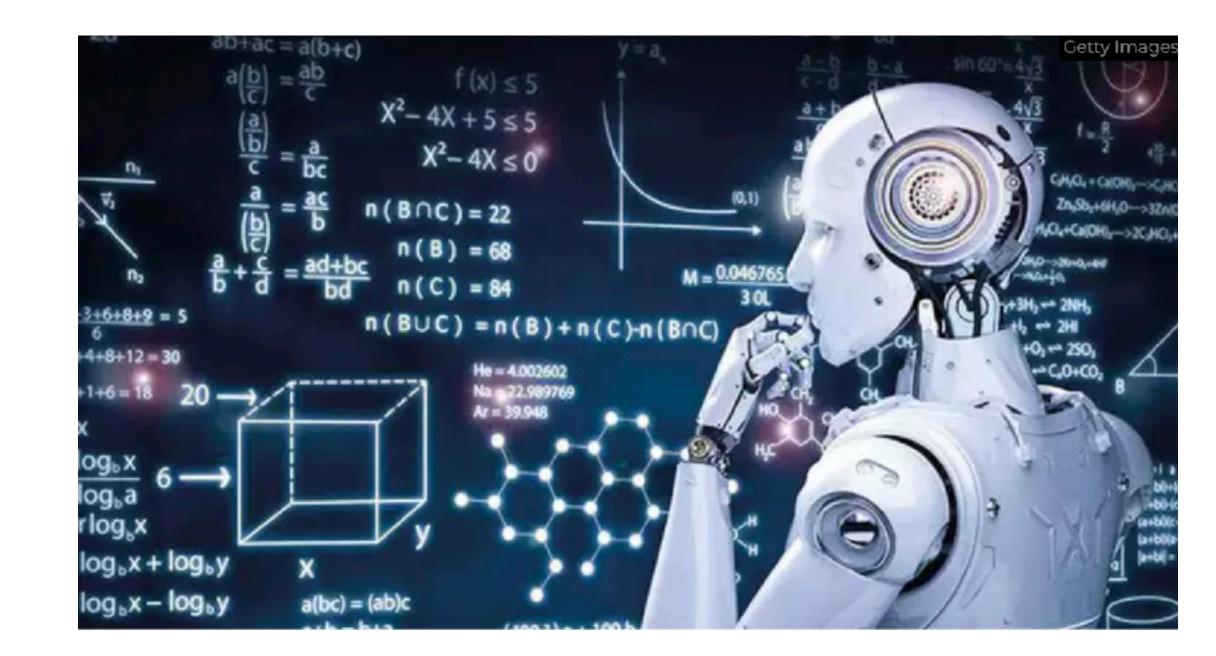


# **Some Important ANNs** With applications to our field

- Feedforward Neural Networks
- Radial basis function Neural Networks
- Self Organizing Neural Networks
- Recurrent Neural Networks
- Convolution Neural Networks
- Modular Neural Networks
- Graph Neural Networks









Bogdan Oancea, Tudorel Andrei, Raluca Mariana Dragoescu arXiv:1408.6923v1

# **Processing Units (Al Chips) Acceleration in Training and Inference (driving the rate of progress)**

- electronic circuitry that executes instructions in a clock cycle. Need a farm to do serious AI.
- extensive graphical and mathematical computations for major parallelization.
- forests (RFs).

• CPU: Central Processing Unit also called a central processor, main processor or just processor, is the

• GPU: Graphics Processing Unit is a specialized processor with dedicated memory that conventionally perform floating point operations required for rendering graphics. Its a single-chip processor used for

• TPU: **Tensor Processing Unit** is an AI accelerator application-specific integrated circuit (ASIC) developed by Google specifically for neural network machine learning, particularly using Google's own TensorFlow software.

• NPU: Neural Processing Unit is a microprocessor that specializes in the acceleration of machine learning algorithms, typically by operating on predictive models such as artificial neural networks (ANNs) or random

• QPU: Quantum processing Unit, also referred to as a quantum chip, is a physical (fabricated) chip that contains a number of interconnected qubits. It is the foundational component of a full quantum computer, which includes the housing environment for the QPU, the control electronics, and many other components.

