## How To Win Friends and Influence Functionals The Influence Functional approach to quantum and classical systems

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#### 1 Introduction

- 2 Quantum Influence Functionals
- **3** Classical Influence Functionals

4 Using Influence Functionals

▲口 → ▲母 → ▲目 → ▲目 → ● ● ●

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#### 1 Introduction

2 Quantum Influence Functionals

3 Classical Influence Functionals

4 Using Influence Functionals

▲□ > ▲□ > ▲目 > ▲目 > ▲□ > ▲□ > ▲□ >

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### This Talk

This talk is about a powerful technique for describing the dynamics of an open system known as the influence functional. Here we will discuss:

- The applications of influence functionals
- How influence functionals are defined and used
- The exact stochastic equations that can be derived from them.
- Their utility in establishing rigorous classical limits.

#### QCIF Introduction

### What are Influence functionals?



- Influence functionals are a path integral technique, where the environmental part of an open system is expressed as single functional.
- They have numerous applications, both analytical and numerical.

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## Spin Boson Model

Mappings

- Qubit in environment
- Kondo model
- Bio-molecular friction transfer

#### Applications

- Quantum computing
- Josephson junctions
- Exotic matter



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## Equations Derived With Influence Functionals

- One particularly useful application of influence functionals is their use in deriving exact equations.
- One example is the Stochastic Liouville Equation

Stochastic Liouville Equation

$$i\hbar\partial_{t}\tilde{\rho}\left(t\right) = \left[\hat{H}_{Q}\left(t\right),\tilde{\rho}\left(t\right)\right] - \eta\left(t\right)\left[\hat{q}\left(t\right),\tilde{\rho}\left(t\right)\right] - \frac{\hbar}{2}\nu\left(t\right)\left\{\hat{q}\left(t\right),\tilde{\rho}\left(t\right)\right\}$$

Generalised Langevin Equation

$$m\ddot{q}(t) = -V'(q,t) - 2\int_{0}^{t} dt' \dot{q}(t')\gamma(t-t') + \eta_{\rm cl}(t)$$

## Equations Derived With Influence Functionals

- One particularly useful application of influence functionals is their use in deriving exact equations.
- One example is the Stochastic Liouville Equation

### Classical Limit?

- The SLE and GLE are clearly closely related to each other.
- If we take the classical limit in a heuristic manner, we find that  $\lim_{\hbar \to 0} SLE$  leads to:

$$m\ddot{q}(t) = -V'(q,t) + \eta_{\rm cl}(t)$$

Generalised Langevin Equation

$$m\ddot{q}(t) = -V'(q,t) - 2\int_{0}^{t} dt' \dot{q}(t')\gamma(t-t') + \eta_{\rm cl}(t)$$

#### 1 Introduction

- 2 Quantum Influence Functionals
- **3** Classical Influence Functionals

**4** Using Influence Functionals

▲口 → ▲御 → ▲画 → ▲画 → ▲回 →

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#### 1 Introduction

#### 2 Quantum Influence Functionals

3 Classical Influence Functionals

4 Using Influence Functionals

▲日▼▲□▼▲□▼▲□▼ ▲□ ● ●

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# Evolving The Density Matrix

 For a global system described with canonical coordinates q, p and x, k, the total Hamiltonian may be characterised as

 $H_{\rm tot} = H_Q + H_X + V_{QX}$ 

To find \$\heta\_Q(t)\$, we evolve \$\heta\_0^{tot}\$ before tracing over the environment.



# Evolving The Density Matrix

For a global system described

### The Influence of the Environment

Understanding the effect of an environment on an open system is important, as under ordinary circumstances a system's internal dynamics cannot *cancel the interaction with its surroundings...* 

To find \$\heta\_Q(t)\$, we evolve \$\heta\_0^{tot}\$ before tracing over the environment.



Environment (X)

#### Brexit Means Brexit



## The Goal of Influence Functionals

$$\rho(t_{0}) \xrightarrow{U_{cl}(t_{1} - t_{0})} \rho(t_{1})$$

$$\left| \begin{array}{c} Tr_{X} & Tr_{X} \\ U_{Q}[\rho_{X}(t_{0})] \end{array} \right| \\ \rho_{Q}(t_{0}) \xrightarrow{U_{Q}[\rho_{X}(t_{0})]} \rho_{Q}(t_{1})$$

- We would like to describe the evolution of the open system without referring to its environment.
- To do so, we require an effective propagator U<sub>Q</sub>.
- This is achieved with the influence functional.

### The Goal of Influence Functionals



Reduced Density matrix

$$\rho_Q(q,q') = \int \mathrm{d}\bar{x} \mathrm{d}\bar{x}' \mathrm{d}x \, \mathrm{d}\bar{q} \mathrm{d}\bar{q}' \, U\left(q,x,t;\bar{q},\bar{x},0\right)$$

$$\times \rho_0^{\text{tot}}\left(\bar{q}, \bar{x}; \bar{q}', \bar{x}'\right) U\left(\bar{q}', \bar{x}', 0; q', x, t\right)$$

$$\rho_Q(t_0) \xrightarrow{U_Q[\rho_X(t_0)]} \rho_Q(t_1) \xrightarrow{\text{This is achieved with the influence functional}} \rho_Q(t_0)$$

### Path Integrals



- Influence functionals are a path integral technique
- Expressed as a path integral, the propagator of a state is

$$U(q_2, t_2; q_1, t_1) = \int_{q_1}^{q_2} \mathcal{D}q(t) e^{\frac{iS}{\hbar}}$$

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### **Influence Functionals**

- We have an expression for the reduced density matrix, but can we evaluate it?
- Feynman & Vernon (1963) developed a powerful formalism for dealing with systems of this type, using path integrals to describe the system of interest without reference to the environment.

$$egin{split} & 
ho_{tf}\left(q;q'
ight) = rac{1}{Z}\int\mathrm{d}ar{q}\mathrm{d}ar{q}'\mathcal{D}q\left(t
ight)\mathcal{D}q'\left(t
ight)\left\{\mathcal{F}\left[q\left(t
ight),q'\left(t
ight)
ight\}
ight. \ & imes
ho_{0}\left(ar{q};ar{q}'
ight)\exp\left[rac{i}{\hbar}S_{q}\left[q\left(t
ight)
ight] - rac{i}{\hbar}S_{q}\left[q'\left(t
ight)
ight]
ight]
ight\} \end{split}$$

### Influence Functionals

- We have an expression for the reduced density matrix, but can we evaluate it?
- Feynman & Vernon (1963) developed a powerful formalism for dealing with systems of this type, using path integrals to describe the system of interest without reference to the System Action
- $S_{q}\left[q\left(t
  ight)
  ight]$  is the action of the isolated system evolving under the Hamiltonian  $H_{\mathrm{tot}}=H_{Q}$

$$\times \rho_{0}\left(\bar{q};\bar{q}'\right)\exp\left[\frac{i}{\hbar}S_{q}\left[q\left(t\right)\right]-\frac{i}{\hbar}S_{q}\left[q'\left(t\right)\right]\right]\right\}$$

## Influence Functionals

#### Influence Functional

 $\mathcal{F}[q(t),q'(t)]$  is the *Influence Functional*. It characterises the environment's effect on the system.

$$\mathcal{F}\left[q\left(t\right),q'\left(t'\right)\right] = \int \mathcal{D}\bar{X}(t)\rho_X(x_0;x'_0)\exp\left(iS_{\mathcal{F}}/\hbar\right)$$
$$\mathcal{D}\bar{X}(t) = \mathrm{d}x_0\mathrm{d}x'_0\mathrm{d}x\mathcal{D}x(t)\mathcal{D}x'(t)$$
$$S_{\mathcal{F}} = S_X\left[x\left(t\right)\right] - S_X\left[x'\left(t\right)\right] + S_{QX}\left[q\left(t\right),x\left(t\right)\right] - S_{QX}\left[q'\left(t\right),x'\left(t\right)\right]$$

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# Using the Influence Functional

- Influence functionals can be evaluated numerically, but in some circumstances it is possible to derive analytic expressions.
- In this case they may be used to derive effective equations of motion for the reduced system.

• if  $\mathcal{F}\left[q\left(t\right),q'\left(t'\right)\right]$  can be decomposed into a product of the form

$$F\left[q\left(t\right),q'\left(t'\right)\right] = \exp\left(\frac{i}{\hbar}\Phi_{1}\left[q\left(t\right)\right]\right)\exp\left(\frac{i}{\hbar}\Phi_{2}\left[q'\left(t'\right)\right]\right)$$

 $\hfill\blacksquare$  Then the effective propagator  $U_Q$  into a product of the form

$$U_{\mathbf{Q}}\left[q\left(t\right),q'\left(t'\right)\right]=\tilde{U}_{Q}\left[q\left(t\right)\right]\tilde{U}_{\mathbf{Q}}^{\dagger}\left[q'\left(t'\right)\right]$$

• from which an effective equation of motion may be found.

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#### 1 Introduction

- 2 Quantum Influence Functionals
- **3** Classical Influence Functionals

4 Using Influence Functionals

▲口 → ▲御 → ▲臣 → ▲臣 → ▲回 →

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#### 1 Introduction

#### 2 Quantum Influence Functionals

#### **3** Classical Influence Functionals

4 Using Influence Functionals

▲口 → ▲御 → ▲臣 → ▲臣 → ▲回 → ▲

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The Path Integral Formulation of Your Life

- Influence functionals do not have to be restricted to quantum mechanics!
- A connection can be made to the classical limit of quantum results using the Classical Influence Functional
- Doing so requires a Hilbert space formulation of classical mechanics, in order to construct a classical path integral

## What is Koopman von-Neumann mechanics?

- Koopman von-Neumann (KvN) mechanics was proposed in 1932 as a Hilbert space formulation of classical mechanics, providing an operational framework to assess classical problems.
- In both KvN and quantum mechanics, the propagator is a unitary transformation of the form:

$$\hat{U}(t) = \mathrm{e}^{-i\hat{A}t}$$





## What is Koopman von-Neumann mechanics?

 Koopman von-Neumann (KvN) mechanics was proposed in 1932 as a Hilbert space formulation of classical mechanics, providing an operational framework to assess classical problems

Bopp Operators

 $\hat{\lambda}$  and  $\hat{ heta}$  are *Bopp operators*, defined by their commutation relations:

$$\begin{bmatrix} \hat{x}, \hat{\lambda} \end{bmatrix} = \begin{bmatrix} \hat{p}, \hat{\theta} \end{bmatrix} = i$$
$$\begin{bmatrix} \hat{\lambda}, \hat{\theta} \end{bmatrix} = \begin{bmatrix} \hat{\lambda}, \hat{p} \end{bmatrix} = \begin{bmatrix} \hat{\theta}, \hat{x} \end{bmatrix} = 0$$

$$\phi = \{H, \phi\}$$

$$\hat{A} = \hat{K} = \frac{\hat{p}}{m} \hat{\lambda} - \hat{V}'(x) \hat{\theta}$$

$$\phi = -iH\phi$$

$$\hat{A} = \hat{H}$$

### Constructing a Classical Path Integral

- In order to derive the Classical influence functional, we require a Classical Path Integral.
- Given the KvN propagator

$$\hat{U}_{\rm cl} = {\rm e}^{-it\hat{K}}$$

We can find a representation for it in phase space

$$U_{\rm cl}(q_f, p_f, t_f; q_i, p_i) = \left\langle q_f, p_f \left| \mathrm{e}^{-it_f \hat{K}} \right| q_i, p_i \right\rangle.$$

Just like in the quantum case, this propagator can be expressed as a path integral:

$$U_{\rm cl}\left(q_f, p_f, t_f; q_i, p_i\right) = \int_{x_i, p_i}^{x_f, p_f} \underbrace{\mathcal{D}q\mathcal{D}p\mathcal{D}\lambda\mathcal{D}\theta}_{\mathcal{D}Q} \, e^{iR}$$

Since the classical wavefunction and probability density are evolved by the same equation, this propagator can be used to evolve *both*.

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### Constructing a Classical Path Integral

- In order to derive the Classical influence functional, we require a Classical Path Integral.
- Given the KvN propagator

$$\hat{U}_{\rm cl} = {\rm e}^{-it\hat{K}}$$

The Classical "Quantum Action"

$$R = \int_{0}^{t_{f}} \mathrm{d}t \left[ \lambda\left(t\right) \left(\dot{x}\left(t\right) - \frac{p\left(t\right)}{m}\right) + \theta\left(t\right) \left(\dot{p}\left(t\right) + V'\left(x,t\right)\right) \right]$$

$$U_{\rm cl}\left(q_f, p_f, t_f; q_i, p_i\right) = \int_{x_i, p_i}^{x_f, p_f} \underbrace{\mathcal{D}q\mathcal{D}p\mathcal{D}\lambda\mathcal{D}\theta}_{\mathcal{D}Q} \, \mathrm{e}^{iR}$$

• Since the classical wavefunction and probability density are evolved by the same equation, this propagator can be used to evolve *both*.



- Classical path integral for total system is as expected (a delta functional).
- The path integral describing a *reduced* system is much more interesting.
- The process of tracing out the environment results in a non-trivial sum of trajectories.

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### **Classical Influence Functional**

Evolving the composite system with the path integral propagator, and tracing out the environment gives:

$$\rho_Q(q_f, p_f, t_f) = \int \mathrm{d}x_f \mathrm{d}k_f \left( \int \mathcal{D}Q \mathcal{D}X \mathrm{d}q_0 \mathrm{d}p_0 \mathrm{d}x_0 \mathrm{d}k_0 \, \mathrm{e}^{iR} \rho_0 \right)$$

• Using the influence functional it is possible to describe an *effective* propagator for the reduced system  $U_Q [\rho_X(t_0)]$ .

$$U_{Q}(q_{f}, p_{f}, t_{f}) = \int \mathcal{D}q(t)\mathcal{D}\theta_{Q}(t) \mathcal{F}\left[q(t), p(t), \theta_{Q}(t)\right] \exp\left(i\int_{0}^{t_{f}} \mathrm{d}t \left[\theta_{Q}(t)\left(m\ddot{q} + \frac{\partial V_{Q}}{\partial q}\right)\right]\right)$$

## Classical Influence Functional

#### • Evolving the composite system with the path integral propagator, and tracing out the

The form of this propagator depends on the influence functional, which is in turn a functional of the initial environment state.

$$\mathcal{F}[q(t), p(t), \theta_Q(t)] = \int \mathrm{d}x_0 \mathrm{d}k_0 \mathrm{d}x_f \mathrm{d}k_f \mathcal{D}x(t) \mathcal{D}\theta_X(t) \ \rho_X(x_0, k_0, q_0, p_0)$$

$$\times \exp\left(i \int_0^{t_f} \mathrm{d}t \ \left[\theta_X(t) \left(m_k \ddot{x} + \frac{\partial V_{QX}}{\partial x} + \frac{\partial V_X}{\partial x}\right) + \theta_Q(t) \frac{\partial V_{QX}}{\partial q}\right]\right)$$

$$\overline{f_f(t_f, t_f)} = \int \mathcal{D}q(t) \mathcal{D}\theta_Q(t) \ \mathcal{F}[q(t), p(t), \theta_Q(t)] \exp\left(i \int_0^{t_f} \mathrm{d}t \ \left[\theta_Q(t) \left(mq + \frac{1}{\partial q}\right)\right]\right)$$

Under certain circumstances an effective equation of motion may be defined from the influence functional. This is the case when it is possible to express  $\mathcal{F}$  as

$$\mathcal{F}\left[q\left(t\right), p\left(t\right), \theta_{Q}\left(t\right)\right] = \exp\left(i\int_{0}^{t_{f}} \mathrm{d}t \;\theta_{Q}\left(t\right)\chi\left[q(t), p(t)\right]\right) \tag{1}$$

where  $\chi[q(t), p(t)]$  is an arbitrary functional of the phase space coordinates only. In the case, the effective equation of motion will be:

$$m\ddot{q} = -\frac{\partial V_Q}{\partial q} - \chi \left[ q, \dot{q} \right] \tag{2}$$

#### 1 Introduction

- 2 Quantum Influence Functionals
- **3** Classical Influence Functionals

**4** Using Influence Functionals

▲口 → ▲母 → ▲目 → ▲目 → ● ● ●

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#### 1 Introduction

2 Quantum Influence Functionals

3 Classical Influence Functionals

**4** Using Influence Functionals

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## The Effective Propagator

In both the classical and quantum cases, the effective propagator  $U_O$  is now a functional of the environment state at the initial time. The "true" effective propagator for a system depends on the point in time it is being evolved from.

 $U_f = U_Q \left[ \rho_X(t_0) \right]$  $U_b = U_Q^{\dagger} \left[ \rho_X(t_1) \right]$ 



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## **Effective Propagators**

## Applying Influence functionals

- Using influence functionals, it is possible to derive both the Stochastic Liouville equation and Generalised Langevin Equation.
- To do so, we must specify an environment and interaction Hamiltonian.
- We will use the Caldeira-Leggett (CL) model

$$H_{\text{tot}} = H_Q + \frac{1}{2} \sum_n \left( m_n \dot{x}_n^2 + m_n \omega_n^2 x_n^2 \right)$$
  
 $- q \sum_n c_n x_n + \frac{q^2}{2} \sum_n \frac{c_n^2}{m_n \omega_n^2}.$ 

 Furthermore, we will specify that the environment is initially in thermal equilibrium. In both cases, the influence functional can be expressed as

$$\mathcal{F}=e^{\Phi}$$

## Quantum Influence Functional

## Quantum

$$\Phi\left[q(t),q'(t)\right] = \frac{i}{2\hbar} \int_{0}^{t_{f}} dt \int_{0}^{t_{f}} dt' K^{R} \left(t-t'\right) \epsilon\left(t\right) \epsilon\left(t'\right) \\ - \frac{1}{\hbar} \int_{0}^{t_{f}} dt \int_{0}^{t_{f}} dt' \left[\theta\left(t-t'\right) K^{I} \left(t-t'\right)\right] \epsilon\left(t\right) y\left(t'\right) \\ \epsilon\left(t\right) = q\left(t\right) - q'\left(t\right) \qquad y\left(t\right) = \frac{1}{2} \left(q\left(t\right) + q'\left(t\right)\right) \\ K^{R} \left(t-t'\right) = \int_{0}^{\infty} d\omega \ I\left(\omega\right) \coth\left(\frac{1}{2}\hbar\beta\omega\right) \cos\left(\omega t\right) \\ K^{I} \left(t\right) = -\int_{0}^{\infty} d\omega \ I\left(\omega\right) \sin\left(\omega t\right)$$

## **Classical Influence Functional**

## Classical

$$\Phi\left[q\left(t\right), p\left(t\right), \theta_{Q}\left(t\right)\right] = 2i \int_{0}^{t_{f}} \mathrm{d}t \ \theta_{Q}\left(t\right) \int_{0}^{t} \mathrm{d}t' q(t') \frac{\mathrm{d}\gamma\left(t-t'\right)}{\mathrm{d}t'} - \int^{t_{f}} \mathrm{d}t \int^{t_{f}} \mathrm{d}t' \ \theta_{Q}\left(t\right) k_{B}T\gamma\left(t-t'\right) \theta_{Q}\left(t'\right) \gamma\left(t-t'\right) = \int_{0}^{\infty} \frac{\mathrm{d}\omega}{\omega\pi} I\left(\omega\right) \cos\left(t-t'\right)$$

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In order to use the influence functional as part of an effective equation of motion, it must conform to the following functional form:

$$\mathcal{F}[q(t), p(t), \theta_Q(t)] = \exp\left(i\int_0^{t_f} \mathrm{d}t \ \theta_Q(t) \chi[q(t), p(t)]\right)$$

Classical

Quantum

$$\mathcal{F}\left[q\left(t\right),q'\left(t'\right)\right] = \exp\left(\frac{i}{\hbar}\Phi_{1}\left[q\left(t\right)\right]\right)\exp\left(\frac{i}{\hbar}\Phi_{2}\left[q'\left(t'\right)\right]\right)$$

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In order to use the influence functional as part of an effective equation of motion, it must conform to the following functional form:

Classical

#### Problem

There is a problem here. Neither the quantum or classical influence functional is of a form from which an equation of motion can be derived. Is there a solution?

$$\mathcal{F}\left[q\left(t\right),q'\left(t'\right)\right] = \exp\left(\frac{\pi}{\hbar}\Phi_{1}\left[q\left(t\right)\right]\right)\exp\left(\frac{\pi}{\hbar}\Phi_{2}\left[q'\left(t'\right)\right]\right)$$

## The Hubbard-Stratonovich Transformation



Use the Hubbard-Stratonovich Transformation!

The HS transformation can be considered as converting a system of two body potentials into a set of independent particles in a fluctuating field.

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## The Hubbard-Stratonovich Transformation

#### Fourier-Transforming a Gaussian



into a set of independent particles in a fluctuating field.

### Trajectories vs Distribution

### Transformed Influence Functionals

### **Classical Propagator**

$$\tilde{U}_{cl} = \int_{q_0,\dot{q}_0}^{q_f,\dot{q}_f} \mathcal{D}q(t)\delta\left[m\ddot{q}(t) + V'(q,t) + 2\int_0^t dt'\,\dot{q}(t')\gamma\left(t-t'\right) - \eta_{cl}\left(t\right)\right]$$

#### Quantum Propagator

$$\hat{U}^{\pm}\left(t_{f}\right) = \hat{T}\exp\left(-\frac{i}{\hbar}\int_{0}^{t_{f}}\hat{L}_{Q}\left(t\right) - \left[\eta\left(t\right) \pm \frac{\hbar}{2}\nu\left(t\right)\right]\hat{q}\left(t\right)\mathsf{d}t\right)$$

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### Transformed Influence Functionals

Classical Propagator Making Some Noise

$$\left\langle \eta\left(t\right)\eta\left(t'\right)\right\rangle_{r} = \hbar \int_{0}^{\infty} \frac{\mathrm{d}\omega}{\pi} I\left(\omega\right) \coth\left(\frac{1}{2}\omega\hbar\beta\right) \cos\left(\omega\left(t-t'\right)\right)$$

$$\left\langle \eta(t)\nu\left(t'\right)\right\rangle_{r} = -2i\Theta\left(t-t'\right)\int_{0}^{\infty} \frac{\mathrm{d}\omega}{\pi} I\left(\omega\right) \sin\left(\omega\left(t-t'\right)\right)$$

$$\left\langle \eta_{\mathrm{cl}}\left(t\right)\eta_{\mathrm{cl}}\left(t'\right)\right\rangle = \lim_{\hbar\to 0}\left\langle \eta\left(t\right)\eta\left(t'\right)\right\rangle = \gamma(t-t')$$

### Equations of Motions

#### Stochastic Liouville Equation

$$i\hbar\partial_{t}\tilde{\rho}\left(t\right) = \left[\hat{H}_{Q}\left(t\right),\tilde{\rho}\left(t\right)\right] - \eta\left(t\right)\left[\hat{q}\left(t\right),\tilde{\rho}\left(t\right)\right] - \frac{\hbar}{2}\nu\left(t\right)\left\{\hat{q}\left(t\right),\tilde{\rho}\left(t\right)\right\}$$

#### Generalised Langevin Equation

$$m\ddot{q}(t) = -V'(q,t) - 2\int_{0}^{t} dt' \dot{q}(t')\gamma(t-t') + \eta_{\rm cl}(t)$$

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### **Classical Limit**

• To show the SLE is equivalent in the classical limit to the GLE, we take the *effective* propagator of the reduced quantum system

$$\tilde{\rho}_{t_f}(q;q') = \int \mathrm{d}\bar{q} \mathrm{d}\bar{q}' \; \tilde{U}_{\text{eff}}\left(q,q',t_f;\bar{q},\bar{q}',0\right) \tilde{\rho}_0\left(\bar{q};\bar{q}'\right)$$

- Here  $\tilde{U}_{\text{eff}}(q,q',t_f;\bar{q},\bar{q}',0)$  is  $\hat{U}^+(t_f)\hat{U}^-(t_f)$  in path integral form.
- It is then possible to show:

$$\lim_{\hbar \to 0} \tilde{U}_{\text{eff}}\left(q, q', t_f; \bar{q}, \bar{q}', 0\right) = \tilde{U}_{\text{cl}}$$

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### **Classical Limit**

To show the SLE is equivalent in the classical limit to the GLE, we take the effective propagator of the reduced quantum system

Propagator classical limit

$$\begin{split} \lim_{\hbar \to 0} \tilde{U}_{\text{eff}} &= \int_{q_0, \dot{q}_0}^{q_f, \dot{q}_f} \mathcal{D}q(t) \ \delta \left[ m\ddot{q}\left(t\right) + V'\left(q, t\right) - \eta_{\text{cl}}\left(t\right) \right] \exp\left( i \int_0^{t_f} \mathrm{d}t \ q\left(t\right) \nu_{\text{cl}}\left(t\right) \right) \\ &\left\langle \eta_{\text{cl}}\left(t\right) \nu_{\text{cl}}\left(t'\right) \right\rangle_r = -2i\Theta\left(t - t'\right) \frac{\mathrm{d}\gamma\left(t - t'\right)}{\mathrm{d}t} \end{split}$$

# Summing up



- Influence functionals are a useful technique in the analysis of physical systems.
- One application is in the derivation of exact classical and quantum stochastic equations.
- The formalism also helps to link classical results as the limit of their quantum equivalents.

#### QCIF | Using Influence Functionals

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